## 1

#### 1.1

The idea is to scan the array from left to right and update the maximum revenue meanwhile. See algorithm below for details.

```
Algorithm 1 Max Revenue-1,1(\boldsymbol{a})
                                                                                   \triangleright \boldsymbol{a} = \{a_1, a_2, a_3, \dots, a_n\}
 1: procedure Max Revenue-1,1(a):
        result \leftarrow 0, sum \leftarrow 0, i \leftarrow 1
                                                               ▷ sum is our current optimal to maintain
        while i < n+1 do
 3:
             sum \leftarrow sum + a_i
 4:
             if sum>result then
 5:
                 result \leftarrow sum
                                                                       ▶ Update the optimal subsequence
 6:
             if sum<0 then
 7:
                 sum \leftarrow 0
                                                       ▷ Discard the bad subsequence we do not want
 8:
             i \leftarrow i + 1
 9:
        return result
10:
```

Since our algorithm only requires us to scan the array once, clearly the time complexity is O(n).

#### 1.2

The idea is still scanning the array from left to right once, but we will use an array s[n] to store the maximum revenue of a subsequence ending at position  $i, i \in [n]$ .

First we initialize  $s_1, s_2, s_3, \ldots, s_L$ . Then for each element  $a_i, i \in [n]$ , we need to update R - L + 1 elements in s[n], which are  $s_{i+L}, s_{i+L+1}, \ldots, s_{i+R}$ . The initialize rule and update rule are given in the algorithm below.

```
Algorithm 2 Max Revenue(L, R, \boldsymbol{a})
```

```
\triangleright \boldsymbol{a} = \{a_1, a_2, a_3, \dots, a_n\}
 1: procedure MAX REVENUE(L, R, \boldsymbol{a}):
          result \leftarrow 0, i \leftarrow 1 \ s_i \leftarrow 0, \forall i \in [n]
                                                                                                      \triangleright s is described above
          while i < L + 1 do
 3:
               if a_i > 0 then
 4:
                                                                              \triangleright Initialization for the first L elements
                    s_i \leftarrow a_i
 5:
               if a_i > \text{result then}
 6:
                    result\leftarrow a_i
                                                                                                          ▶ Update the result
 7:
 8:
               i \leftarrow i + 1
          i \leftarrow 1
 9:
10:
          while i + L < n + 1 do
               step \leftarrow L
11:
               while i+step< n+1 do
12:
                    if s_i + a[i + \text{step}] > s[i + \text{step}] then
13:
                         s[i+step] = s_i + a[i+step]
14:
                                                                                        \triangleright update the optimal result at i
                    if s[i+step] > result then
15:
                         result \leftarrow s[i+\text{step}]
16:
                    step \leftarrow step + 1
17:
18:
               i \leftarrow i + 1
          return result
19:
```

We need to do R - L + 1 updates at each round and there are n rounds in total, so the time complexity is O((R - L + 1)n). So with the difference between L and R approaching n, our algorithm actually becomes  $O(n^2)$ .

#### 1.3

We still need to scan the array from left to right once, but instead of updating R - L + 1 elements at each iteration, we use a better strategy.

For each  $a_i$ , we look for the largest  $s_j$ ,  $i-R \le j \le i-L$  and use this largerst result to update  $s_i$ . Then by our algorithm in class, we can find all the largest  $s_j$  for our current  $a_i$  with only O(n) time. A detailed algorithm is given below.

```
Algorithm 3 Max Revenue(L, R, \boldsymbol{a})
```

```
\triangleright \boldsymbol{a} = \{a_1, a_2, a_3, \dots, a_n\}
 1: procedure MAX REVENUE(L, R, a):
          \text{result} \leftarrow 0, \ i \leftarrow 1 \ s_i \leftarrow 0, \forall i \in [n]
 3:
          while i < L + 1 do
               if a_i > 0 then
 4:
                                                                         ▶ Initialization is the same as algorithm 2
                    s_i \leftarrow a_i
 5:
               if a_i > \text{result then}
 6:
                                                                                                          ▶ Update the result
                    result\leftarrow a_i
 7:
               i \leftarrow i + 1
 8:
          i \leftarrow L + 1
 9:
          while i < n + 1 do
10:
               \max \leftarrow \text{k-Largest}(\boldsymbol{s}, i - R, i - L)
                                                                   \triangleright Algorithm in class to find max in O(1) time
11:
12:
               if \max + a_i > s_i then
13:
                    s_i \leftarrow \max + a_i
               if s_i > \text{result then}
14:
15:
                    result\leftarrow s_i
               i \leftarrow i+1
16:
17:
          return result
```

The reason why this algorithm is faster is that by using the k-Largest algorithm, we do not have to update R-L+1 times each round. We only need to look up the largest result before a certain element and the look up process is O(1) for each element. As a result, the total running time of our algorithm can be reduced to O(n).

# 2 Optimal Indexing for A Dictionary

## Description of state transition equation:

In the algorithm below, we use  $f(i, j), 1 \le i \le j \le n$  to denote the minimum of total number of comparisons of the best binary search tree consisting of  $a_i, a_{i+1}, \ldots, a_j$ .

We then use dynamic programming to calculate all the f(i, j) and our optimal result is f(1, n) after we finish the calculations.

Note that we define f(i, j) = 0 if i > j.

The algorithm can be described by the folloing state transition equation:

$$f(i,j) = \min_{i \le r \le j} \left\{ f(i,r-1) + f(r+1,j) + \sum_{k=i}^{j} w_k \right\} \quad 1 \le i \le j \le n$$

### How we construct the optimal BST:

This equation only gives the criteria by which we pick the optimal BST each step, below is a detailed description of how the BST is constructed, for the completeness of our algorithm. We can always let  $T_{ij}$  be a sub-BST generated upon the process we calculate f(i, j).

For starters,  $T_{ii}$ ,  $i \in [n]$  denote a sub-BST with only one vertex  $a_i$  as the root. Then as we calculate the state transition equation, by finding the minimum

$$\min_{i \le r \le j} \left\{ f(i, r - 1) + f(r + 1, j) + \sum_{k=i}^{j} w_k \right\}$$

What we are actually doing is to find a new root  $a_r$  to serve as the father of sub-BST  $T_{i,r-1}$  and  $T_{r+1,j}$ . By the time we calculate f(i,j) and construct  $T_{ij}$ , no matter which  $a_r$  we choose as the root, the left sub-BST  $T_{i,r-1}$  and right sub-BST  $T_{r+1,j}$  must have already been constructed. Also, their optimal value must already have been stored in f(i,r-1) and f(r+1,j). Although in some cases the sub-BST might be empty, these cases do not affect our process of construction.

To sum up, as our DP algorithm finished, an optimal binary search tree  $T_{1n}$  is generated by our description above and its minimal number of comparisons is given by f(1,n) meanwhile.