0.1 Renaming Handler

0.1.1 Early Concepts

• Possibly renamed without body changes nodes:

```
R_{wobc}(T, B) = \{b \in B \mid (\neg \exists t \in T)(t.id = b.id)) \land (\exists t \in T)(t.body = b.body)\}
```

• Possibly deleted or renamed with body changes nodes:

```
DR_{wbc}(T, B) = \{b \in B \mid (\neg \exists t \in T)(t.id = b.id \lor t.body = b.body)\}
```

• Nodes IDs similarity:

 $a.id \approx b.id \leftrightarrow a.id.name = b.id.name \lor a.id.params = b.id.params$

0.1.2 Match Algorithm

```
Algorithm 1: Match Algorithm

Input: L, B, R, M

Output: Set of quadruples (l, b, r, m) consisting of the base node b and its corresponding left node l, right node r and merge node m

1 matches \leftarrow \emptyset;
2 foreach b \in DR_{wbc}(L, B) \cup DR_{wbc}(R, B) \cup R_{wobc}(L, B) \cup R_{wobc}(R, B) do

3 | l \leftarrow \text{correspondentNode}(b, L);
4 | r \leftarrow \text{correspondentNode}(b, R);
5 | m \leftarrow \text{mergeNode}(l, r, M);
6 | matches \leftarrow matches \cup (l, b, r, m);
7 end
8 return matches
```

```
Algorithm 2: Correspondent Node

Input: b, T
Output: b's correspondent node on tree T

1 t \leftarrow findFirst(t \in T \rightarrow t.id = b.id);
2 if t = null then
3 | t \leftarrow findFirst(t \in T \rightarrow t.body = b.body);
4 end
5 if t = null then
6 | t \leftarrow findFirst(t \in T \rightarrow t.body \approx b.body \land t.id \approx b.id);
7 end
8 if t = null then
9 | t \leftarrow findFirst(t \in T \rightarrow t.body = substring(b.body) \lor b.body = substring(t.body));
10 end
11 return t;
```

```
Algorithm 3: Merge Node

Input: 1, r, M
Output: 1 and r's merge node on tree M

1 if l \neq null then
2 | return find(m \in M \rightarrow m.id = l.id);
3 end
4 if r \neq null then
5 | return find(m \in M \rightarrow m.id = r.id);
6 end
7 return null;
```

0.1.3 Handler Algorithms

```
Algorithm 4: Check References and Merge Methods Variant
   Input:
             (l, b, r, m), M
 1 if l.id = b.id \lor r.id = b.id then
       m.body = textualMerge(l, b, r);
       	exttt{removeUnmatchedNode}(	extit{l}, 	extit{r}, 	extit{m}, 	extit{M})
 4 else if l.id \neq r.id then
      m.body = conflit(l.body, b.body, r.body);
       removeUnmatchedNode(l, r, m, M):
 6
 7 else if l.body \neq r.body then
       if newReferenceTo(l) \lor newReferenceTo(r) then
          m.body = conflict(l.body, b.body, r.body);
 9
10
       else
11
          m.body = textualMerge(l, b, r);
12
       removeUnmatchedNode(l, r, m, M)
13
14 end
 Algorithm 5: Merge Methods Variant
   Input: (l, b, r, m), M
 1 \quad m.body = textualMerge(l, b, r)
 removeUnmatchedNode(l, r, m, M);
 Algorithm 6: Check Textual and Keep Both Methods Variant
   Input:
            (l, b, r, m), M
 1 if l.id = b.id \lor r.id = b.id then
        \textbf{if} \ \texttt{textualMergeHasConflictInvolvingSignature} (b) \ \textbf{then} \\
          m.body = conflict(l.body, b.body, r.body); \\
 3
           removeUnmatchedNode(l, r, m, M)
 4
       end
 6 else if l.id \neq r.id \land l.body = r.body then
       m.body = conflict(l.body, b.body, r.body);
       removeUnmatchedNode(l, r, m, M);
 9 end
 Algorithm 7: Keep Both Methods Variant
   Input: (l, b, r, m), M
 1 if (l.id = b.id \lor r.id = b.id) \land \texttt{hasConflict}(m) then
 \mathbf{r}emoveConflict(m);
 з end
 Algorithm 8: Remove Unmatched Node
   Input: l, r, m, M
 1 if l.id = m.id \land r.id \neq m.id then
 \mathbf{r} removeNode(r, M);
 \mathfrak{s} end
```