0.1 Initialization Blocks Handler

0.1.1 Handler Algorithm

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Algorithm 1: Handle
    Input: L, B, R, M
 1 IB_L \leftarrow \{n \in A_L \mid n.type = INITBLOCK\};
 2 IB_R \leftarrow \{n \in A_R \mid n.type = INITBLOCK\};
 \mathbf{3} \ IB_B \leftarrow \{n \in D_B \mid n.type = INITBLOCK\};
 4 matches \leftarrow \emptyset;
 5 if |IB_L| = 1 \land |IB_B| == 1 \land |IB_R| = 1 then
        matches \leftarrow matches \cup (IB_{L_1}, IB_{B_1}, IB_{R_1});
 7 else
        foreach b \in IB_B do
 8
             l \leftarrow findFirst(l \in IB_L \rightarrow l.body \approx b.body);
 9
             r \leftarrow findFirst(r \in IB_R \rightarrow r.body \approx b.body);
10
11
             IB_L \leftarrow IB_L - l;
             IB_R \leftarrow IB_R - r;
12
             if l \neq null \land r \neq null then
13
              matches \leftarrow matches \cup (l, b, r);
14
             \quad \text{end} \quad
15
16
        end
        foreach l \in IB_L do
17
             r \leftarrow findFirst(r \in IB_R \rightarrow r.body \approx l.body);
18
             IB_R \leftarrow IB_R - r;
19
             if r \neq null then
20
              matches \leftarrow matches \cup (l, null, r);
21
22
             end
23
        end
24 end
25 foreach (l, b, r) \in matches do
        m \leftarrow find(m \in M \rightarrow m.body = l.body);
        m.body \leftarrow \texttt{textualMerge}(l.body, b.body, r.body);
27
        m \leftarrow find(m \in M \rightarrow m.body = r.body);
28
        removeNode(m, M);
30 end
```