0.1 Type Ambiguity Error Handler

0.1.1 Handler Algorithm

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Algorithm 1: Handle
   Input: L, B, R, M
 1 ID_L \leftarrow \{n \in A_L \mid n.type = IMPORTDECL\};
 2 ID_R \leftarrow \{n \in A_R \mid n.type = IMPORTDECL\};
з if ID_L = \emptyset \lor ID_R = \emptyset then return;
 4 T_L \leftarrow \texttt{treeToText}(L);
 5 T_B \leftarrow \texttt{treeToText}(B);
 6 T_R \leftarrow \texttt{treeToText}(R);
 7 M_U \leftarrow \texttt{textualMerge}(T_L, T_B, T_R);
 s I_L, I_R \leftarrow \texttt{extractInsertions}(M_U);
 9 cs \leftarrow \text{extractConflicts}(M_U);
10 c \leftarrow \text{compile}(M_U);
11 ps \leftarrow \texttt{problems}(c);
12 foreach l \in ID_L do
13
        m_l \leftarrow \texttt{extractPackageMember}(l.body);
14
        for
each r \in ID_R do
             m_r \leftarrow \texttt{extractPackageMember}(r.body);
15
             if m_l = m_r then
16
                  p \leftarrow \text{importDeclarationsProblem}(l, r, ps);
17
                  if p \neq \text{null then}
18
                       m \leftarrow \texttt{find}(m \in M \rightarrow m.body = l.body);
19
                       m.body \leftarrow \texttt{conflict}(l.body, \varepsilon, r.body);
20
                       m \leftarrow \text{find}(m \in M \rightarrow m.body = r.body);
21
22
                       removeNode(m, M);
                       ps \leftarrow ps - p;
23
                       break;
\mathbf{24}
25
             else if (m_l = * \lor m_r = *) \land importDeclarationsConflict(l, r, cs) then
26
                  if m_l \neq * then
27
                       I \leftarrow I_R;
28
29
                       m \leftarrow m_l;
                  else
30
                       I \leftarrow I_L;
31
32
                    m \leftarrow m_r;
33
                  end
                  i \leftarrow \mathtt{find}(i \in I \rightarrow IMPORT \notin i \land m \in i);
34
35
                  if i \neq \text{null then}
                       m \leftarrow \text{find}(m \in M \rightarrow m.body = l.body);
36
                       m.body \leftarrow \texttt{conflict}(l.body, \varepsilon, r.body);
37
                       m \leftarrow \text{find}(m \in M \rightarrow m.body = r.body);
38
                       removeNode(m, M);
39
                       break;
40
                  end
41
42
             end
        end
43
44 end
```

```
Algorithm 2: Import Declarations Problem

Input: l, r, ps
Output: compilation problem in ps concerning l and r import declarations, if there is one

1 for each p \in ps do
2 | if p.type = COLLISION then
3 | for each a \in p.arguments do
4 | if a \in l.body \lor a \in r.body then return p;
5 | end
6 | else if p.type = AMBIGUITY then return p;
7 end
8 return null;
```

Algorithm 3: Import Declarations Conflict

Input: l, r, cs

Output: wether there is an unstructured conflict in cs concerning l and r import declarations

- 1 for each $c \in cs$ do
- **2** | **if** $l.body \in c.left \land r.body \in c.right$ **then return true**;
- 3 end
- 4 return false;