## 0.1 Multiple Initialization Blocks Handler

## 0.1.1 Handler Algorithm

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Algorithm 1: Handle
   Input: L, B, R, M
 1 IB_L \leftarrow \{n \in A_L \mid n.type = INITBLOCK\};
 2 IB_R \leftarrow \{n \in A_R \mid n.type = INITBLOCK\};
 3 IB_B ← \{n \in D_L \cap D_R \mid n.type = INITBLOCK\};
 4 eIB_L \leftarrow \text{editedNodes}(IB_L, IB_B);
 \mathbf{5} \ eIB_R \leftarrow \mathtt{editedNodes}(IB_R, IB_B);
 6 dIB_L \leftarrow \text{deletedNodes}(IB_L, IB_B, eIB_L);
 7 dIB_R \leftarrow \text{deletedNodes}(IB_R, IB_B, eIB_R);
 s for
each b \in IB_B do
        l \leftarrow eIB_L[b];
10
        r \leftarrow eIB_R[b];
        if l \neq null \land r \neq null then
11
            updateMergeTree(l, b, r, M);
12
        else if l \neq null \lor r \neq null then
13
14
            if l \neq null then
                r \leftarrow find(r \in dIB_R \rightarrow r.body = b.body);
15
                if r \neq null then removeNode(b, M);
16
 17
            else
                 l \leftarrow find(l \in dIB_L \rightarrow l.body = b.body);
18
                if l \neq null then removeNode(b, M);
19
20
21
            updateMergeTree(l, b, r, M);
        else
22
            m \leftarrow find(m \in M \rightarrow m.body = b.body);
23
\mathbf{24}
            removeNode(m, M);
        end
25
26 end
27 aIB_L \leftarrow addedNodes(IB_L, IB_B, eIB_L);
28 aIB_R \leftarrow addedNodes(IB_R, IB_B, eIB_R);
29 DEP \leftarrow \text{dependentNodes}(aIB_L, aIB_R);
30 foreach (l, rs) \in DEP do
31
        s \leftarrow \varepsilon;
        for
each r \in rs do
32
            s \leftarrow s + r.body;
33
            m \leftarrow find(m \in M \rightarrow m.body = r.body);
34
            removeNode(r, M);
35
36
37
        m \leftarrow find(m \in M \rightarrow m.body = l.body);
        m.body \leftarrow conflict(l.body, \varepsilon, s);
38
39 end
40 foreach l \in aIB_L do
        foreach r \in aIB_R do
41
            if l.body = r.body then
42
                m \in find(m \in M \rightarrow m.body = r.body);
43
                removeNode(m, M);
44
            end
45
        end
46
47 end
```

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Algorithm 2: Edited Nodes
   Input: IB, IB_B
   Output: map associating a deleted base node b in IB_B and its correspondent added branch
               node a in IB
 1 D \leftarrow \{d \in IB_B \mid (\neg \exists a \in IB)(d.body = a.body)\};
 2 A \leftarrow \{a \in IB \mid (\neg \exists d \in IB_B)(a.body = d.body)\};
 3 matches \leftarrow \emptyset;
 4 foreach a \in A do
       S \leftarrow \{d \in D \mid a.body \approx d.body\};
       b \leftarrow \operatorname{argmax} (\operatorname{similarity}(s.body, a.body));
       if b \neq null then matches \leftarrow matches \cup \{b : a\};
 s end
 9 return matches
 Algorithm 3: Added Nodes
   Input: IB, IB_B, eIB
   Output: set of initilization block nodes added by branch
 1 A \leftarrow \{n \in IB \mid (\neg \exists b \in IB_B)(n.body = b.body)\};
 2 A \leftarrow \{n \in A \mid (\neg \exists e \in eIB)(n.body = e.value.body)\};
 3 return A;
 Algorithm 4: Deleted Nodes
   Input: IB, IB_B, eIB
   Output: set of initialization block nodes deleted by branch
 1 D \leftarrow \{b \in IB_B \mid (\neg \exists n \in IB)(b.body = n.body)\};
 2 D \leftarrow \{n \in D \mid (\neg \exists e \in eIB)(n.body = e.key.body)\};
3 return D;
 Algorithm 5: Update Merge Tree
   Input: l, b, r, M
 1 m \leftarrow find(m \in M \rightarrow m.body = l.body);
 2 m.body \leftarrow \texttt{textualMerge}(l.body, b.body, r.body);
m \leftarrow find(m \in M \rightarrow m.body = r.body);
 4 removeNode(m, M);
 Algorithm 6: Dependent Nodes
   Input: aIB_L, aIB_R
   Output: map associating an added left node l in aIB_L and all added right nodes r in aIB_R
                with common global variables
 1 DEP \leftarrow \emptyset;
 2 foreach l \in aIB_L do
       DEP \leftarrow DEP \cup \{l : \emptyset\};
 3
       V_L \leftarrow \texttt{globalVariables}(l);
 4
       for
each r \in aIB_R do
 5
            V_R \leftarrow \texttt{globalVariables}(r);
 6
           if V_L \cap V_R \neq \emptyset then DEP[l] \leftarrow DEP[l] \cup r;
 7
 8
       end
 9 end
10 return DEP;
```