## 1 Semistructured Merge

#### 1.1 Early Concepts

1. Every node's origin is set to UNKNOWN beforehand

#### 1.2 Merge Algorithms

```
Algorithm 1: Merge Files
   Input: l, b, r, o
 1 if l.content = b.content then
 o.content \leftarrow r.content;
 3 else if b.content = r.content \lor l.content = r.content then
 4 | o.content \leftarrow l.content;
 5 else
        L \leftarrow \texttt{fileToTree}(l):
 6
 7
        B \leftarrow \texttt{fileToTree}(b);
        R \leftarrow \texttt{fileToTree}(r);
 8
        M \leftarrow \texttt{mergeTrees}(L, B, R);
 9
        H \leftarrow \texttt{getActiveHandlers()};
10
        for
each h \in H do
11
12
        h.handle(M);
13
        o.content \leftarrow \texttt{treeToText}(M);
15 end
```

```
Algorithm 2: Merge Trees

Input: L, B, R
Output: result of merging left, base and right trees

1 Lorigin = LEFT;
2 Borigin = BASE;
3 Rorigin = RIGHT;
4 LB \leftarrow mergeNodes(L, B);
5 M \leftarrow mergeNodes(LB, R);
6 D_B \leftarrow \{b \in B \mid (\neg \exists l \in L)(b.id = l.id) \land (\neg \exists r \in R)(b.id = r.id)\};
7 foreach d \in D_B do
8 | removeNode(d, M);
9 end
10 runTextualMergeOnLeaves(M);
11 return M;
```

```
Algorithm 3: Run Textual Merge On Leaves

Input: T

1 foreach t \in T.children do

2 | runTextualMergeOnLeaves(t);

3 end

4 if T.children = \emptyset \land SEPARATOR \in T.body then

5 | l, b, r \leftarrow split(T.body, SEPARATOR);

6 | l \leftarrow l - MARKER;

7 | T.body \leftarrow textualMerge(l, b, r);

8 end
```

```
Algorithm 4: Merge Nodes
   Input: A. B
   Output: result of merging nodes A and B
 1 if A = null then return B;
 2 if B = null then return A;
 3 if A.type \neq B.type \lor A.id \neq B.id then return null;
 4 M.id \leftarrow A.id;
 5 M.type \leftarrow A.type;
 6 M.origin \leftarrow B.origin;
 7 M.children \leftarrow \emptyset;
 8 if A.children = \emptyset \land B.children = \emptyset then
       if MARKER \in A.body then
           M.body \leftarrow A.body + B.body;
10
       else if A.origin = LEFT \wedge B.origin = BASE then
11
           M.body \leftarrow MARKER + A.body + SEPARATOR + B.body + SEPARATOR;
12
       else if A.origin = LEFT then
13
14
           M.body \leftarrow MARKER + A.body + SEPARATOR + SEPARATOR + B.body;
15
       else
           M.body \leftarrow MARKER + SEPARATOR + A.body + SEPARATOR + B.body;
16
17
       end
       return M;
18
19 else if A.children \neq \emptyset \land B.children \neq \emptyset then
20
       foreach b \in B.children do
           a \leftarrow find(a \in A.children \rightarrow a.type = b.type \land a.id = b.id);
21
22
           if a.origin = UNKNOWN then a.origin \leftarrow A.origin;
           if b.origin = UNKNOWN then b.origin \leftarrow B.origin;
23
           M.children \leftarrow M.children \cup mergeNodes(a, b, step);
24
25
       end
       foreach a \in A.children do
26
           b \leftarrow find(b \in B.children \rightarrow a.type = b.type \land a.id = b.id);
27
           if a.origin = UNKNOWN then a.origin \leftarrow A.origin;
28
           if b = null then M.children \leftarrow M.children \cup a;
29
       end
30
31
       return M;
32 end
зз return null;
```

# 2 Renaming Handler

#### 2.1 Early Concepts

#### 2.1.1 Possibly renamed without body changes nodes

```
R_{wobc}(T,B) = \{b \in B \mid (\neg \exists t \in T)(t.id = b.id)) \land (\exists t \in T)(t.body = b.body)\}
```

#### 2.1.2 Possibly deleted or renamed with body changes nodes

$$DR_{wbc}(T,B) = \{b \in B \mid (\neg \exists t \in T)(t.id = b.id \lor t.body = b.body)\}$$

#### 2.1.3 Nodes IDs similarity

 $a.id \approx b.id \leftrightarrow a.id.name = b.id.name \lor a.id.params = b.id.params$ 

## 2.2 Match Algorithm

```
Algorithm 5: Match Algorithm

Input: L, B, R, M

Output: Set of quadruples (l, b, r, m) consisting of the base node b and its corresponding left node l, right node r and merge node m

1 matches \leftarrow \emptyset;
2 foreach \ b \in DR_{wbc}(L, B) \cup DR_{wbc}(R, B) \cup R_{wobc}(L, B) \cup R_{wobc}(R, B) do

3 |l \leftarrow \text{correspondentNode}(b, L);
4 |r \leftarrow \text{correspondentNode}(b, R);
5 |m \leftarrow \text{mergeNode}(l, r, M)|;
6 |matches \leftarrow matches \cup (l, b, r, m);
7 end
8 return \ matches
```

```
Algorithm 6: Correspondent Node

Input: b, T
Output: b's correspondent node on tree T

1 t \leftarrow findFirst(t \in T \rightarrow t.id = b.id);

2 if t = null then
3 | t \leftarrow findFirst(t \in T \rightarrow t.body = b.body);
4 end
5 if t = null then
6 | t \leftarrow findFirst(t \in T \rightarrow t.body \approx b.body \land t.id \approx b.id);
7 end
8 if t = null then
9 | t \leftarrow findFirst(t \in T \rightarrow t.body = substring(b.body) \lor b.body = substring(t.body));
10 end
11 return t;
```

```
Algorithm 7: Merge Node

Input: 1, r, M
Output: 1 and r's merge node on tree M

1 if l \neq null then
2 | return find(m \in M \rightarrow m.id = l.id);
3 end
4 if r \neq null then
5 | return find(m \in M \rightarrow m.id = r.id);
6 end
7 return null;
```

## 2.3 Handle Algorithms

```
Algorithm 8: Check References and Merge Methods Variant
   Input:
             (l, b, r, m), M
 1 if l.id = b.id \lor r.id = b.id then
       m.body = textualMerge(l, b, r);
        removeUnmatchedNode(l, r, m, M);
 4 else if l.id \neq r.id then
      m.body = conflit(l, b, r);
       removeUnmatchedNode(l, r, m, M)
 6
 7 else if l.body \neq r.body then
       if newReferenceTo(l) \lor newReferenceTo(r) then
          m.body = conflict(l, b, r);
 9
10
       else
          m.body = textualMerge(l, b, r);
11
12
        {\tt removeUnmatchedNode}(\mathit{l},\ \mathit{r},\ \mathit{m},\ \mathit{M})
13
14 end
 Algorithm 9: Merge Methods Variant
   Input: (l, b, r, m), M
 \mathbf{1} \quad m.body = textualMerge(l, b, r)
 removeUnmatchedNode(l, r, m, M);
 Algorithm 10: Check Textual and Keep Both Methods Variant
   Input: (l, b, r, m), M
 1 if l.id = b.id \lor r.id = b.id then
        \textbf{if} \ \texttt{textualMergeHasConflictInvolvingSignature} \textbf{(b)} \ \textbf{then} \\
           m.body = conflict(l, b, r);
 3
           removeUnmatchedNode(l, r, m, M);
       end
 6 else if l.id \neq r.id \land l.body = r.body then
       m.body = conflict(l, b, r);
       removeUnmatchedNode(l, r, m, M);
 9 end
 Algorithm 11: Keep Both Methods Variant
   Input: (l, b, r, m), M
 1 if (l.id = b.id \lor r.id = b.id) \land \texttt{hasConflict}(m) then
 \mathbf{2} \mid removeConflict(m);
 з end
 Algorithm 12: Remove Unmatched Node
   Input: l, r, m, M
 1 if l.id = m.id \land r.id \neq m.id then
 \mathbf{2} removeNode(r, M);
 з end
```

## 3 Initialization Blocks Handler

#### 3.1 Handler Algorithm

```
Algorithm 13: Handle
    Input: L, B, R, M
 1 A_L \leftarrow \{l \in L \mid (\neg \exists b \in B)(l.id = b.id)\};
 2 A_R \leftarrow \{r \in R \mid (\neg \exists b \in B)(r.id = b.id)\};
 3 D_B ← {b \in B \mid (\neg \exists l \in L)(b.id = l.id) \land (\neg \exists r \in R)(b.id = r.id)};
 4 IB_L \leftarrow \{n \in A_L \mid n.type = INITBLOCK\};
 5 IB_R \leftarrow \{n \in A_R \mid n.type = INITBLOCK\};
 6 IB_B ← {n ∈ D_B | n.type = INITBLOCK};
 7 matches \leftarrow \emptyset;
 8 if |IB_L| = 1 \land |IB_R| == 1 \land |IB_B| = 1 then
        matches \leftarrow matches \cup ();
10 else
11
        foreach b \in IB_B do
             l \leftarrow findFirst(l \in IB_L \rightarrow l.body \approx b.body);
12
             r \leftarrow findFirst(r \in IB_R \rightarrow r.body \approx b.body);
13
             IB_L \leftarrow IB_L - l;
14
             IB_R \leftarrow IB_R - r;
15
             if l \neq null \land r \neq null then
16
              matches \leftarrow matches \cup (l, b, r);
17
18
             end
        \quad \mathbf{end} \quad
19
        for
each l \in IB_L do
20
             r \leftarrow findFirst(r \in IB_R \rightarrow r.body \approx l.body);
21
             IB_R \leftarrow IB_R - r;
22
23
             if r \neq null then
              matches \leftarrow matches \cup (l, null, r);
24
             \mathbf{end}
25
26
        end
27 end
28 foreach (l, b, r) \in matches do
        m \leftarrow find(m \in M \rightarrow m.body = l.body);
30
        m.body \leftarrow \texttt{textualMerge}(l.body, b.body, r.body);
        m \leftarrow find(m \in M \rightarrow m.body = r.body);
31
        removeNode(m, M);
32
зз end
```