0.1 Renaming Handler

0.1.1 Early Concepts

1. **Possibly renamed without body changes nodes**:
   $R_{wobc}(T, B) = \{b \in B \mid (\neg\exists t \in T)(t.id = b.id)) \wedge (\exists t \in T)(t.body = b.body)\}$
2. **Possibly deleted or renamed with body changes nodes**:
   $DR_{wbc}(T, B) = \{b \in B \mid (\neg\exists t \in T)(t.id = b.id \vee t.body = b.body)\}$
3. **Nodes IDs similarity**:
   $a.id \approx b.id \leftrightarrow a.id.name = b.id.name \vee a.id.params = b.id.params$

0.1.2 Match Algorithm

Algorithm 1: Match Algorithm

Input: L, B, R, M
Output: Set of quadruples (l, b, r, m) consisting of the base node b and its corresponding left node l, right node r and merge node m

$matches \leftarrow \emptyset$;
foreach $b \in DR_{wbc}(L, B) \cup DR_{wbc}(R, B) \cup R_{wobc}(L, B) \cup R_{wobc}(R, B)$ **do**
  $l \leftarrow$ `correspondentNode(`b`, `L`)`;
  $r \leftarrow$ `correspondentNode(`b`, `R`)`;
  $m \leftarrow$ `mergeNode(`l`, `r`, `M`)`;
  $matches \leftarrow matches \cup (l, b, r, m)$;
end
return *matches*

Algorithm 2: Correspondent Node

Input: b, T
Output: b's correspondent node on tree T

$t \leftarrow findFirst(t \in T \rightarrow t.id = b.id)$;
if $t = null$ **then**
  $t \leftarrow findFirst(t \in T \rightarrow t.body = b.body)$;
end
if $t = null$ **then**
  $t \leftarrow findFirst(t \in T \rightarrow t.body \approx b.body \wedge t.id \approx b.id)$;
end
if $t = null$ **then**
  $t \leftarrow findFirst(t \in T \rightarrow t.body = substring(b.body) \vee b.body = substring(t.body))$;
end
return t;

Algorithm 3: Merge Node

Input: l, r, M
Output: l and r's merge node on tree M

if $l \neq null$ **then**
  return $find(m \in M \rightarrow m.id = l.id)$;
end
if $r \neq null$ **then**
  return $find(m \in M \rightarrow m.id = r.id)$;
end
return *null*;

0.1.3 Handler Algorithms

Algorithm 4: Check References and Merge Methods Variant

Input: (l, b, r, m), M

```
1  if l.id = b.id ∨ r.id = b.id then
2  |  m.body = textualMerge(l, b, r);
3  |  removeUnmatchedNode(l, r, m, M);
4  else if l.id ≠ r.id then
5  |  m.body = conflit(l.body, b.body, r.body);
6  |  removeUnmatchedNode(l, r, m, M);
7  else if l.body ≠ r.body then
8  |  if newReferenceTo(l) ∨ newReferenceTo(r) then
9  |  |  m.body = conflict(l.body, b.body, r.body);
10 |  else
11 |  |  m.body = textualMerge(l, b, r);
12 |  end
13 |  removeUnmatchedNode(l, r, m, M);
14 end
```

Algorithm 5: Merge Methods Variant

Input: (l, b, r, m), M

```
1  m.body = textualMerge(l, b, r);
2  removeUnmatchedNode(l, r, m, M);
```

Algorithm 6: Check Textual and Keep Both Methods Variant

Input: (l, b, r, m), M

```
1  if l.id = b.id ∨ r.id = b.id then
2  |  if textualMergeHasConflictInvolvingSignature(b) then
3  |  |  m.body = conflict(l.body, b.body, r.body);
4  |  |  removeUnmatchedNode(l, r, m, M);
5  |  end
6  else if l.id ≠ r.id ∧ l.body = r.body then
7  |  m.body = conflict(l.body, b.body, r.body);
8  |  removeUnmatchedNode(l, r, m, M);
9  end
```

Algorithm 7: Keep Both Methods Variant

Input: (l, b, r, m), M

```
1  if (l.id = b.id ∨ r.id = b.id) ∧ hasConflict(m) then
2  |  removeConflict(m);
3  end
```

Algorithm 8: Remove Unmatched Node

Input: l, r, m, M

```
1  if l.id = m.id ∧ r.id ≠ m.id then
2  |  removeNode(r, M);
3  end
```