

1 Semistructured Merge

1.1 Early Concepts

1. A_L and A_R are the sets of all the nodes added by left and right, respectively
2. D_L and D_R are the sets of all the nodes deleted by left and right, respectively
3. Every node's origin is set to UNKNOWN beforehand

1.2 Merge Algorithms

Algorithm 1: Merge Files

```
Input: l, b, r, o
1 if  $l.content = b.content$  then
2   |  $o.content \leftarrow r.content$ ;
3 else if  $b.content = r.content \vee l.content = r.content$  then
4   |  $o.content \leftarrow l.content$ ;
5 else
6   |  $L \leftarrow fileToTree(l)$ ;
7   |  $B \leftarrow fileToTree(b)$ ;
8   |  $R \leftarrow fileToTree(r)$ ;
9   |  $M \leftarrow mergeTrees(L, B, R)$ ;
10  |  $H \leftarrow getActiveHandlers()$ ;
11  | foreach  $h \in H$  do
12  |   |  $h.handle(M)$ ;
13  | end
14  |  $o.content \leftarrow treeToText(M)$ ;
15 end
```

Algorithm 2: Merge Trees

```
Input: L, B, R
Output: result of merging left, base and right trees
1  $L.origin = LEFT$ ;
2  $B.origin = BASE$ ;
3  $R.origin = RIGHT$ ;
4  $LB \leftarrow mergeNodes(L, B, LB-STEP)$ ;
5  $M \leftarrow mergeNodes(LB, R, LBR-STEP)$ ;
6  $D_B \leftarrow D_L \cap D_R$ ;
7 foreach  $d \in D_B$  do
8   |  $removeNode(d, M)$ ;
9 end
10  $updateLeafBodies(M)$ ;
11 return  $M$ ;
```

Algorithm 3: Update Leaf Bodies**Input:** T

```
1 foreach  $t \in T.children$  do  
2   | updateLeafBodies( $t$ );  
3 end  
4 if  $T.children = \emptyset \wedge SEPARATOR \in T.body$  then  
5   |  $l, b, r \leftarrow split(T.body, SEPARATOR);$   
6   |  $l \leftarrow l - MARKER;$   
7   |  $T.body \leftarrow textualMerge(l, b, r);$   
8 end
```

Algorithm 4: Merge Nodes**Input:** A, B, step**Output:** result of merging nodes A and B

```

1  if  $A = null$  then return  $B$  ;
2  if  $B = null$  then return  $A$  ;
3  if  $A.type \neq B.type \vee A.id \neq B.id$  then
4  |   return  $null$ ;
5  end
6   $M \leftarrow A$ ;
7   $M.origin \leftarrow B.origin$ ;
8  if  $A.children = \emptyset \wedge B.children = \emptyset$  then
9  |   if  $MARKER \in A.body$  then
10 |     $M.body \leftarrow A.body + B.body$ ;
11 |   else if  $step = LB-STEP$  then
12 |     $M.body \leftarrow MARKER + A.body + SEPARATOR + B.body + SEPARATOR$ ;
13 |   else if  $A.origin = LEFT$  then
14 |     $M.body \leftarrow MARKER + A.body + SEPARATOR + SEPARATOR + B.body$ ;
15 |   else
16 |     $M.body \leftarrow MARKER + SEPARATOR + A.body + SEPARATOR + B.body$ ;
17 |   end
18 |   return  $M$ ;
19 end
20 if  $A.children \neq \emptyset \wedge B.children \neq \emptyset$  then
21 |   foreach  $b \in B.children$  do
22 |     $a \leftarrow find(a \in A.children \rightarrow a.type = b.type \wedge a.id = b.id)$ ;
23 |    if  $a.origin = UNKNOWN$  then  $a.origin \leftarrow A.origin$  ;
24 |    if  $b.origin = UNKNOWN$  then  $b.origin \leftarrow B.origin$  ;
25 |    if  $a = null$  then
26 |    |   if  $step = LB-STEP$  then
27 |    |   |    $D_L \leftarrow D_L \cup b$ ;
28 |    |   |   else
29 |    |   |    $A_R \leftarrow A_R \cup b$ ;
30 |    |   |   end
31 |    |   else if  $step = LB-STEP \wedge a \in A_L$  then
32 |    |   |    $A_R \leftarrow A_R \cup b$ ;
33 |    |   |   end
34 |    |    $m \leftarrow mergeNodes(a, b, step)$ ;
35 |    |    $M.children \leftarrow M.children \cup m$ ;
36 |   end
37 |   foreach  $a \in A.children$  do
38 |     $b \leftarrow find(b \in B.children \rightarrow a.type = b.type \wedge a.id = b.id)$ ;
39 |    if  $b = null$  then
40 |    |    $ls \leftarrow leftSiblings(a)$ ;
41 |    |    $rs \leftarrow rightSiblings(a)$ ;
42 |    |    $M.children \leftarrow ls \cup a \cup rs$ ;
43 |    |   if  $step = LB-STEP$  then  $A_L \leftarrow A_L \cup a$  ;
44 |    |   else if  $a \notin A_L$  then  $D_R \leftarrow D_R \cup a$  ;
45 |    |   end
46 |   end
47 |   return  $M$ ;
48 end
49 return  $null$ ;

```

2 Renaming Handler

2.1 Early Concepts

2.1.1 Possibly renamed without body changes nodes

$$R_{wobc}(T, B) = \{b \in B \mid (\neg \exists t \in T (t.id = b.id)) \wedge (\exists t \in T (t.body = b.body))\}$$

2.1.2 Possibly deleted or renamed with body changes nodes

$$DR_{wbc}(T, B) = \{b \in B \mid \neg \exists t \in T (t.id = b.id \vee t.body = b.body)\}$$

2.2 Match Algorithm

Algorithm 5: Match Algorithm

Input: L, B, R, M
Output: Set of quadruples (l, b, r, m) consisting of the base node b and its corresponding left node l , right node r and merge node m

```

1 matches  $\leftarrow \emptyset$ ;
2 foreach  $b$  in possiblyRenamedOrDeletedBaseNodes(L, B, R) do
3    $l \leftarrow \text{getCorrespondentNode}(b, L)$ ;
4    $r \leftarrow \text{getCorrespondentNode}(b, R)$ ;
5    $m \leftarrow \text{getMergeNode}(l, r, M)$ ;
6   matches  $\leftarrow \text{matches} \cup (l, b, r, m)$ ;
7 end
8 return matches
9 function possiblyRenamedOrDeletedBaseNodes(L, B, R)
10 | return  $DR_{wbc}(L, B) \cup DR_{wbc}(R, B) \cup R_{wobc}(L, B) \cup R_{wobc}(R, B)$ ;
11 end
12 function getCorrespondentNode(b, T)
13 |  $t \leftarrow \text{findFirst}(t \in T \rightarrow t.id = b.id)$ ;
14 | if  $t = \text{null}$  then
15 |    $t \leftarrow \text{findFirst}(t \in T \rightarrow t.body = b.body)$ ;
16 | end
17 | if  $t = \text{null}$  then
18 |    $t \leftarrow \text{findFirst}(t \in T \rightarrow t.body \approx b.body \wedge (t.id.name = b.id.name \vee$ 
19 |      $t.id.params = b.id.params))$ ;
20 | end
21 | if  $t = \text{null}$  then
22 |    $t \leftarrow \text{findFirst}(t \in T \rightarrow t.body = \text{substring}(b.body) \vee b.body = \text{substring}(t.body))$ ;
23 | end
24 | return  $t$ ;
25 function getMergeNode(l, r, M)
26 | if  $l \neq \text{null}$  then
27 |   return  $\text{find}(m \in M \rightarrow m.id = l.id)$ ;
28 | end
29 | if  $r \neq \text{null}$  then
30 |   return  $\text{find}(m \in M \rightarrow m.id = r.id)$ ;
31 | end
32 | return  $\text{null}$ ;
33 end

```

2.3 Handle Algorithms

Algorithm 6: Check References and Merge Methods Variant

```

Input:  $(l, b, r, m), M$ 
1 if  $\text{singleRenamingOrDeletion}(l, b, r)$  then
2    $m.body = \text{textualMerge}(l, b, r);$ 
3    $\text{removeUnmatchedNode}(l, r, m, M);$ 
4 else if  $l.id \neq r.id$  then
5    $m.body = \text{conflict}(l, b, r);$ 
6    $\text{removeUnmatchedNode}(l, r, m, M);$ 
7 else if  $l.body \neq r.body$  then
8   if  $\text{newReferenceTo}(l) \vee \text{newReferenceTo}(r)$  then
9      $m.body = \text{conflict}(l, b, r);$ 
10     $\text{removeUnmatchedNode}(l, r, m, M);$ 
11   else
12      $m.body = \text{textualMerge}(l, b, r);$ 
13      $\text{removeUnmatchedNode}(l, r, m, M);$ 
14   end
15 end
16 function  $\text{singleRenamingOrDeletion}(l, b, r)$ 
17   return  $l.id = b.id \vee r.id = b.id;$ 
18 end
19 function  $\text{removeUnmatchedNode}(l, r, m, M)$ 
20   if  $l.id = m.id \wedge r.id \neq m.id$  then
21      $\text{removeNode}(r, M);$ 
22   end
23 end

```

Algorithm 7: Merge Methods Variant

```

Input:  $(l, b, r, m), M$ 
1  $m.body = \text{textualMerge}(l, b, r);$ 
2  $\text{removeUnmatchedNode}(l, r, m, M);$ 
3 function  $\text{removeUnmatchedNode}(l, r, m, M)$ 
4   if  $l.id = m.id \wedge r.id \neq m.id$  then
5      $\text{removeNode}(r, M);$ 
6   end
7 end

```

Algorithm 8: Check Textual and Keep Both Methods Variant**Input:** $(l, b, r, m), M$

```

1 if singleRenamingOrDeletion( $l, b, r$ ) then
2   if textualMergeHasConflictInvolvingSignature( $b$ ) then
3      $m.body = conflict(l, b, r)$ ;
4     removeUnmatchedNode( $l, r, m, M$ );
5   end
6 else if  $l.id \neq r.id \wedge l.body = r.body$  then
7    $m.body = conflict(l, b, r)$ ;
8   removeUnmatchedNode( $l, r, m, M$ );
9 end
10 function singleRenamingOrDeletion( $l, b, r$ )
11   return  $l.id = b.id \vee r.id = b.id$ ;
12 end
13 function removeUnmatchedNode( $l, r, m, M$ )
14   if  $l.id = m.id \wedge r.id \neq m.id$  then
15     removeNode( $r, M$ );
16   end
17 end

```

Algorithm 9: Keep Both Methods Variant**Input:** $(l, b, r, m), M$

```

1 if singleRenamingOrDeletion( $l, b, r$ )  $\wedge$  hasConflict( $m$ ) then
2   removeConflict( $m$ );
3 end
4 function singleRenamingOrDeletion( $l, b, r$ )
5   return  $l.id = b.id \vee r.id = b.id$ ;
6 end

```