0.1 New Element Referencing Edited One Handler

0.1.1 Handler Algorithm

Algorithm 1: Handle

Input: L, B, R, M

$T_L \leftarrow$ `treeToText(`L`)`;
$T_B \leftarrow$ `treeToText(`B`)`;
$T_R \leftarrow$ `treeToText(`R`)`;
$M_U \leftarrow$ `textualMerge(`T_L, T_B, T_R`)`;
$cs \leftarrow$ `extractConflicts(`M_U`)`;
$aMFD_L \leftarrow \{l \in A_L \mid l.type = METHODDECL \vee l.type = FIELDDECL\}$;
$aMFD_R \leftarrow \{r \in A_R \mid r.type = METHODDECL \vee r.type = FIELDDECL\}$;
$eMFD_L \leftarrow \{l \in E_L \mid l.type = METHODDECL \vee l.type = FIELDDECL\}$;
$eMFD_R \leftarrow \{r \in E_R \mid r.type = METHODDECL \vee r.type = FIELDDECL\}$;
foreach $a_l \in aMFD_L$ **do**
    foreach $e_r \in eMFD_R$ **do**
        if `nodesConflict(`a_l, e_r, cs`)` $\wedge\ e_r.id.name \in a_l.body$ **then**
            $b \leftarrow$ `find(`$b \in B \rightarrow b.id = e_r.id$`)`;
            $m \leftarrow$ `find(`$m \in M \rightarrow m.body = e_r.body$`)`;
            $m.body \leftarrow$ `conflict(`$e_r.body$, $b.body$, $a_l.body$`)`;
            $m \leftarrow$ `find(`$m \in M \rightarrow m.body = a_l.body$`)`;
            `removeNode(`m, M`)`;
        end
    end
end
foreach $a_r \in aMFD_R$ **do**
    foreach $e_l \in eMFD_L$ **do**
        if `nodesConflict(`a_r, e_l, cs`)` $\wedge\ e_l.id.name \in a_r.body$ **then**
            $b \leftarrow$ `find(`$b \in B \rightarrow b.id = e_l.id$`)`;
            $m \leftarrow$ `find(`$m \in M \rightarrow m.body = e_l.body$`)`;
            $m.body \leftarrow$ `conflict(`$e_l.body$, $b.body$, $a_r.body$`)`;
            $m \leftarrow$ `find(`$m \in M \rightarrow m.body = a_r.body$`)`;
            `removeNode(`m, M`)`;
        end
    end
end

Algorithm 2: Nodes Conflict

Input: a, b, cs
Output: wether there is an unstructured conflict in cs concerning a and b nodes

foreach $c \in cs$ **do**
    if $c.left = a.body \wedge c.right = b.body$ **then return true**;
    if $c.left = b.body \wedge c.right = a.body$ **then return true**;
end
return false;