

# SOLUTION OF PLANAR VECTOR EQUATIONS

AYKUT C. SATICI

MECHANICAL AND BIOMEDICAL ENGINEERING, BOISE STATE UNIVERSITY

**Questions.** Consider the planar vector equation

$$(1) \quad u + v + w = 0,$$

or, in terms of unit vectors ( $\hat{u}$ , etc.) and magnitudes ( $|u|$ , etc.),

$$(2) \quad |u| \hat{u} + |v| \hat{v} + |w| \hat{w} = 0.$$

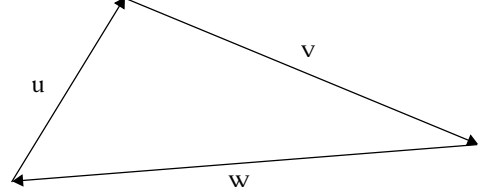


Fig. 1: Graphical Representation

*Case 1.* Find  $w$ , if the magnitude and direction of  $u$  and  $v$  are known.

*Case 2.* Suppose that  $w$  and the directions  $\hat{u}$  and  $\hat{v}$  of  $u$  and  $v$  are known. Determine the magnitudes  $|u|$  and  $|v|$  of  $u$  and  $v$ .

*Case 3.* Suppose that  $w$  and the magnitudes  $|u|$  and  $|v|$  of  $u$  and  $v$  are known. Determine the directions  $\hat{u}$  and  $\hat{v}$  of  $u$  and  $v$ .

*Case 4.* Suppose that  $w$ , the direction  $\hat{u}$  of  $u$ , and the magnitude  $|v|$  of  $v$  are known. Determine the magnitude  $|u|$  of  $u$  and the direction  $\hat{v}$  of  $v$ .

**Solutions.** Let  $\hat{k}$  be a unit vector that points perpendicular to the plane.

*Case 1.* This is the simplest case. Just solve equation (1) for  $w$ :

$$w = -u - v$$

*Case 2.* In order to find  $|u|$ , we take the dot product of each term in equation (2) with  $\hat{v} \times \hat{k}$ . Noting that  $\hat{v} \cdot (\hat{v} \times \hat{k}) = 0$ , we obtain

$$|u| \hat{u} \cdot (\hat{v} \times \hat{k}) + w \cdot (\hat{v} \times \hat{k}) = 0,$$

from which the magnitude  $|u|$  of vector  $u$  is given by

$$|u| = \frac{-w \cdot (\hat{v} \times \hat{k})}{\hat{u} \cdot (\hat{v} \times \hat{k})}.$$

Similarly, the magnitude  $|v|$  of  $v$  is given by

$$|v| = \frac{-w \cdot (\hat{u} \times \hat{k})}{\hat{v} \cdot (\hat{u} \times \hat{k})}.$$

*Case 3.* Let

$$\Delta = \frac{|w|^2 + |v|^2 - |u|^2}{2|w|}.$$

In this case, we can find the vectors  $u$  and  $v$  by

$$\begin{aligned}
u &= \mp \left( \sqrt{|v|^2 - \Delta^2} \right) \left( \hat{w} \times \hat{k} \right) + (\Delta - |w|) \hat{w}, \\
v &= \pm \left( \sqrt{|v|^2 - \Delta^2} \right) \left( \hat{w} \times \hat{k} \right) - \Delta \hat{w},
\end{aligned}$$

where we use the upper set of signs if the vectors  $u, v, w$  are oriented in a counter clockwise manner and we use the lower set of signs if they are oriented in a clockwise manner.

*Case 4.* Let

$$\Delta = w \cdot \left( \hat{u} \times \hat{k} \right).$$

We can find the magnitude  $|u|$  and the direction  $\hat{v}$  by

$$\begin{aligned}
u &= \left( -w \cdot \hat{u} \mp \sqrt{|v|^2 - \Delta^2} \right) \hat{u}, \\
v &= -\Delta \left( \hat{u} \times \hat{k} \right) \pm \left( \sqrt{|v|^2 - \Delta^2} \right) \hat{u},
\end{aligned}$$

where we pick the correct signs by inspecting the mechanism in question.