## **Greedy Algorithms II**

Summer 2018 • Lecture 08/07

#### **A Few Notes**

#### Homework 5

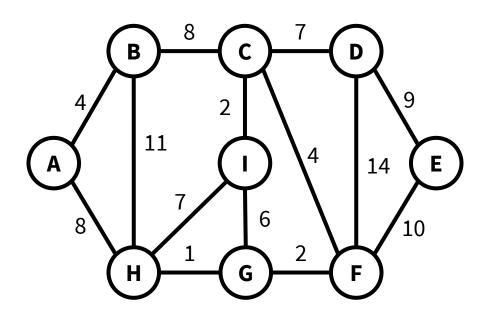
Due 8/10 at 5 p.m. on Gradescope.

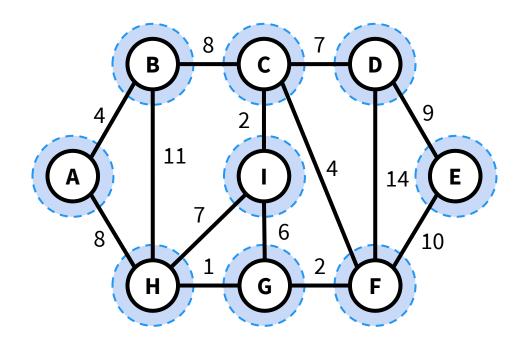
#### **Outline for Today**

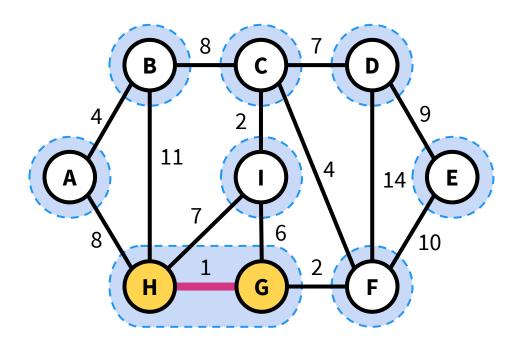
#### Greedy algorithms

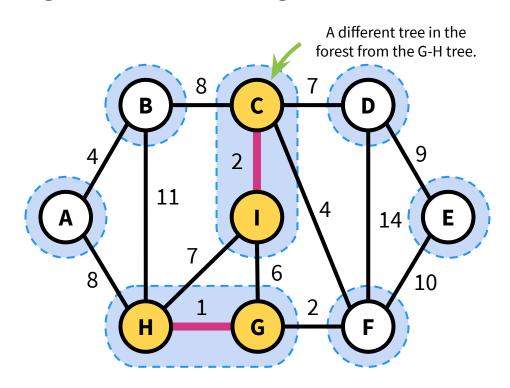
**Activity Selection** 

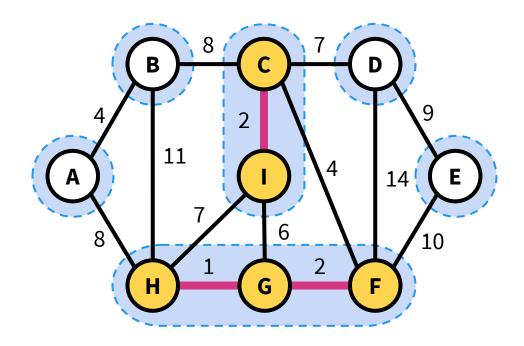
Greedy graph algorithms
Kruskal's Algorithm

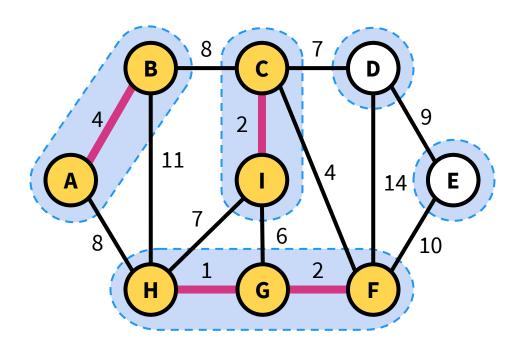


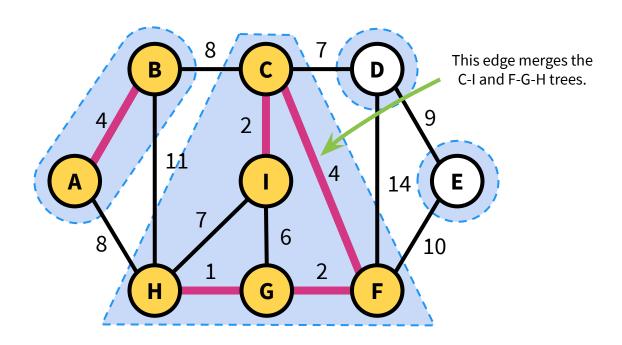


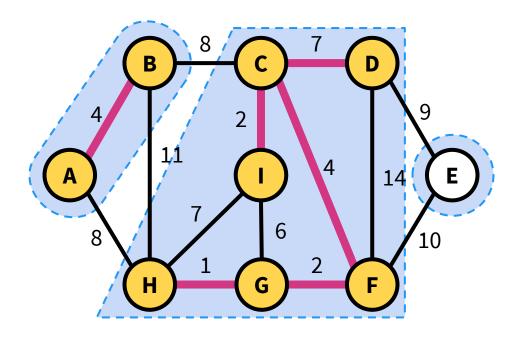


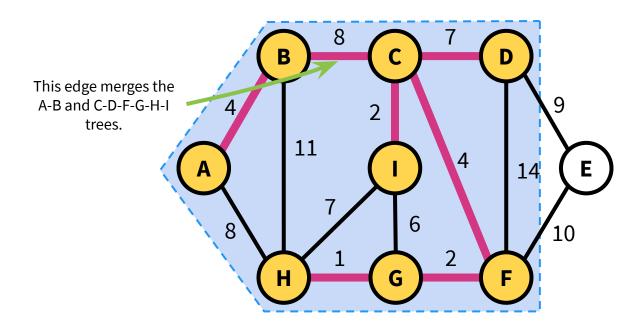


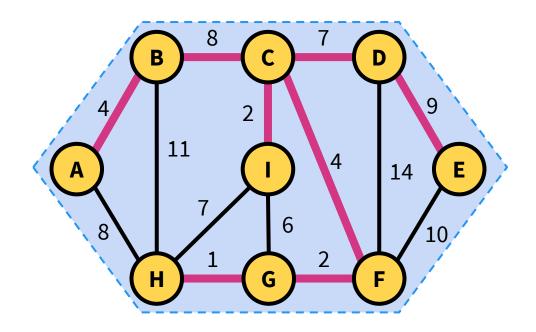












kruskal uses union-find data structure, which supports ...

```
make_set(u): create a set {u} in O(1)
find(u): returns the set containing u in O(1)
union(u,v): merges the sets containing u and v in O(1)
```



Technically, these operations all run in amortized-time  $\alpha(|V|)$ ;  $\alpha(n) \le 4$ , provided n < # of atoms in the universe. We will discuss amortized analysis in greater detail later this quarter.

```
def kruskal(G):
  E_sorted = sort the edges in E by non-decreasing weight
 MST = \{\}
  for v in V:
    make set(v) # put each vertex in its own tree
  for (u, v) in E sorted:
    if find(u) != find(v): # u and v in different trees
      MST.add((u, v))
      union(u, v) # merge u's tree with v's tree
  return MST
```

#### **Runtime:** Using comparison-based sort.

O(|E|log(|V|)) Note  $|E|log(|E|) = O(|E|log(|V|^2)) = O(|E| \cdot 2log(|V|) = O(|E|log(|V|))$ . O(|E|)

Using radix sort

#### Recall our lemma:

Consider a cut that respects a set of edges A, such that there's an MST T containing A, and a light edge (u, v) not in T.

**Lemma:** There exists an MST containing  $A \cup \{(u, v)\}$ .

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kruskal finds an edge (u, v) that merges two trees  $T_1$  and  $T_2$ . Consider the cut  $\{T_1, V - T_1\}$ ; MST respects this cut. By our lemma, there exists a minimum spanning tree containing MST U  $\{(u, v)\}$ .

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Recall, we proved our lemma with an exchange argument!

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After adding the the (n-1)<sup>st</sup> edge, we have a spanning tree; therefore, MST contains a minimum spanning tree.

Recall, we proved our lemma with an exchange argument!

#### Prim's and Kruskal's

	Description	Runtime	Use-cases
Prim's	Grows a tree	O( E log( V )) with red-black tree O( E + V log( V )) with Fibonacci heap	Better on dense graphs
Kruskal's	Grows a forest	O( E log( V )) with union-find O( E ) with union-find and radix sort	Better on sparse graphs and if the edge weights can be radix sorted.

#### Beyond Prim's and Kruskal's

```
Karger-Klein-Tarjan (1995): Las Vegas randomized algorithm O(|E|) expected, O(\min\{|E|\log(|V|),|V|^2\}) worst-case Chazelle (2000): O(|E|\alpha(|V|)) deterministic algorithm
```

function

## **Activity Selection**

## Planning Your Life

You have a list of activities  $(s_1, e_1), (s_2, e_2), ..., (s_n, e_n)$  denoted by their start and end times.

All activities are equally attractive to you, and you want to maximize the number of activities you do.

**Task:** Choose the largest number of non-overlapping activities possible.

What are a few ways of picking activities greedily? 🤥

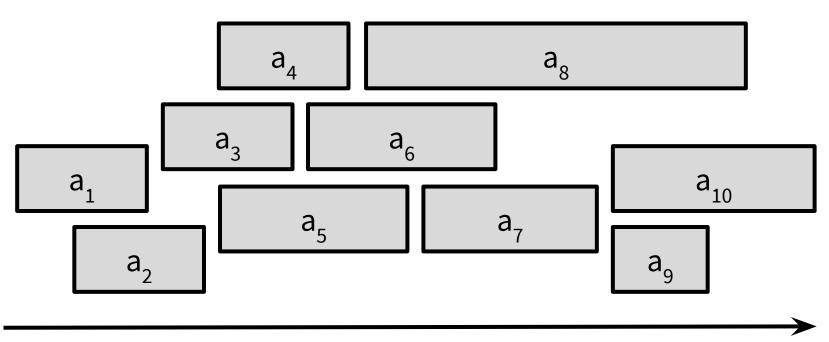


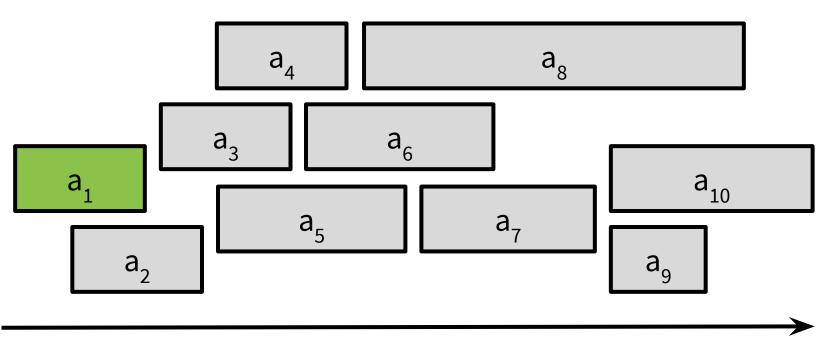
**Be impulsive:** choose activities in ascending order of start times.

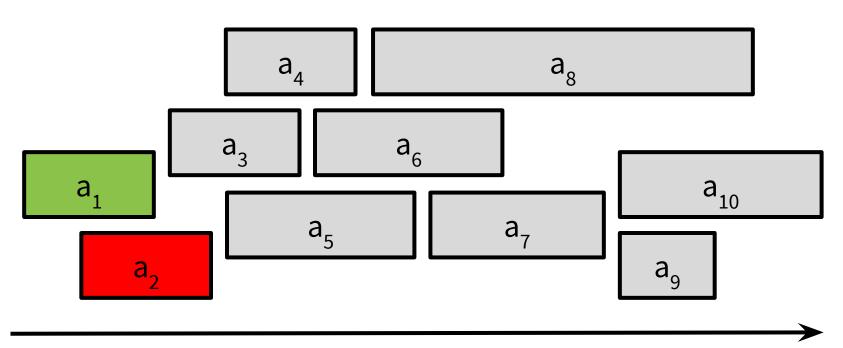
**Avoid commitment:** choose activities in ascending order of length.

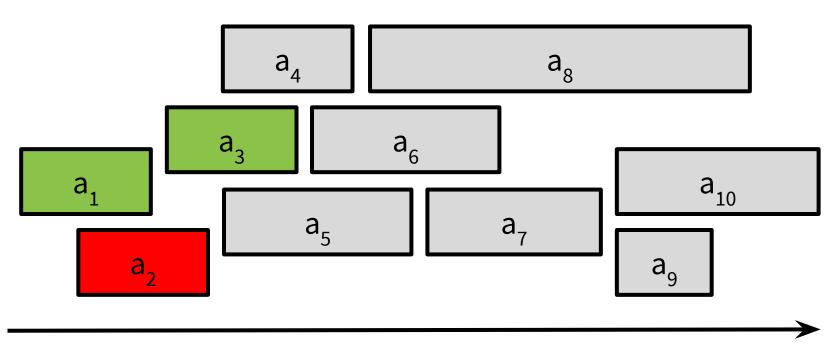
**Finish fast:** choose activities in ascending order of end times.

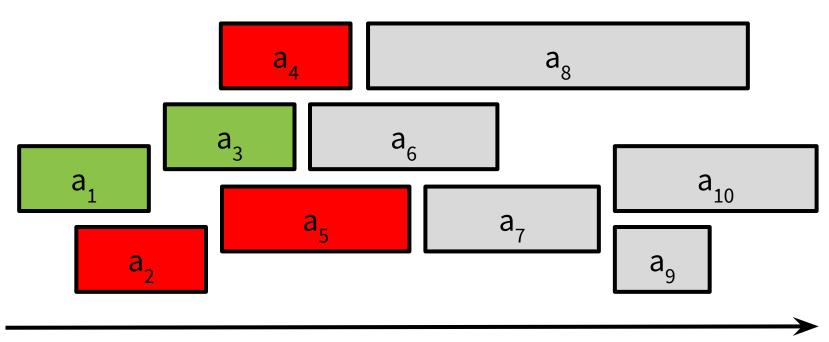
Only the third one seems to work.

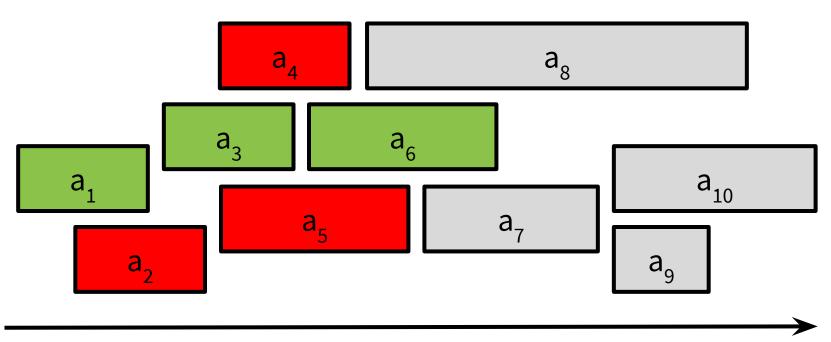


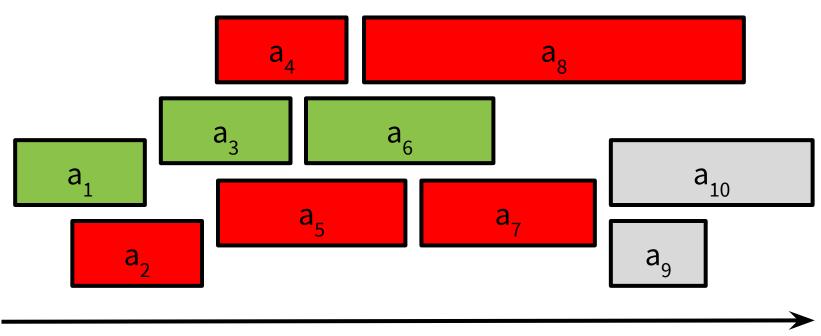


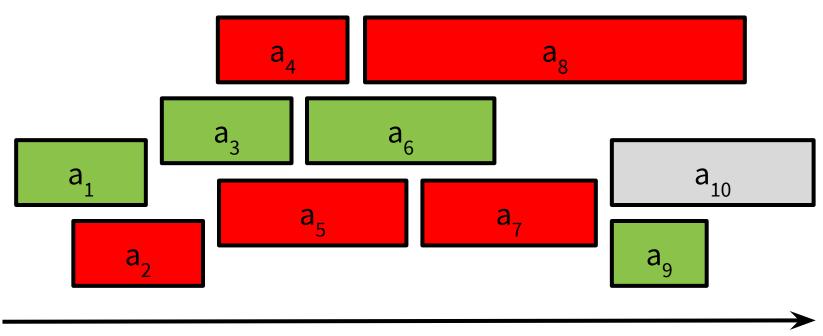


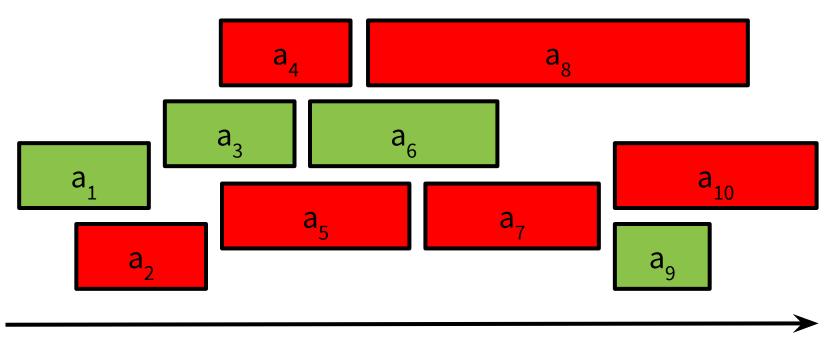












```
def activity_selection(activities):
    sort activities into ascending order by end time
    S = {}
    U = set of activities
    while U not empty:
        choose any activity with the earliest finishing time
        add that activity to S
        remove other activities that overlap with it from U
    return S
```

Runtime: O(n log(n))

We need to prove two properties about the algorithm to guarantee correctness.

- (1) **Feasibility.** The algorithm finds a feasible schedule of activities (i.e. it doesn't "schedule conflicting activities").
- (2) **Optimality.** The algorithm finds an optimal schedule of activities (i.e. there isn't a better schedule available).

Lemma: The schedule produced by activity\_selection is a feasible schedule.

Intuition: Use induction to show that at each step, the set U only contains activities that don't conflict with activities selected from S.

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To prove that the schedule S produced by the algorithm is optimal, we will use another "greedy stays ahead" argument.

- (1) Find intermediate values that evaluate the solution produced by any algorithm, including the greedy one. **Here, the end\_time of the kth activity chosen.**
- (2) Show the greedy algorithm produces values at least as good as any solution's (using induction).
- (3) Prove that since the greedy algorithm produces values at least as good as any solution's, it must be optimal (using direct proof or proof by contradiction).

How might we prove that activity\_selection finds an optimal schedule of activities?

**Intuition:** Consider an arbitrary optimal schedule S\*, then show that our greedy algorithm produces a schedule S no worse than S\*.

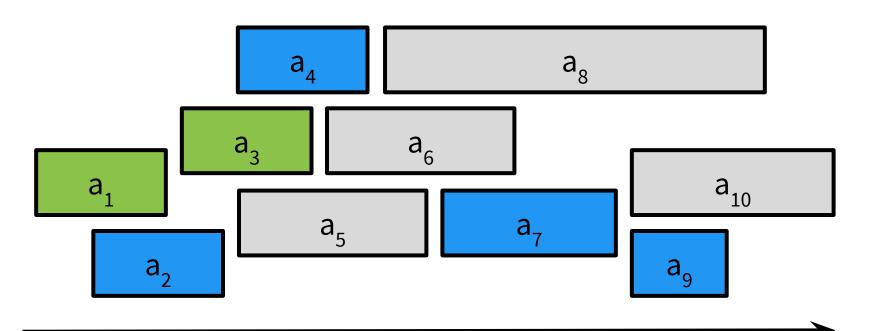
Let f(i, S) denote the time that the ith activity finishes in schedule S.

Lemma: For any  $1 \le i \le |S|$ , we have  $f(i, S) \le f(i, S^*)$ .

i.e. After scheduling i activities according to the greedy algorithm, you will be at most as late as if you scheduled i activities according to an optimal solution.

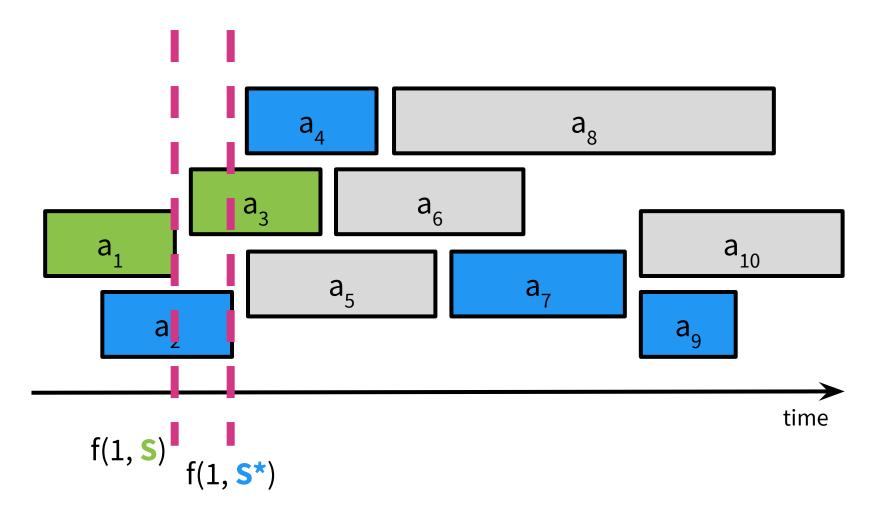
Let's formalize this using induction!

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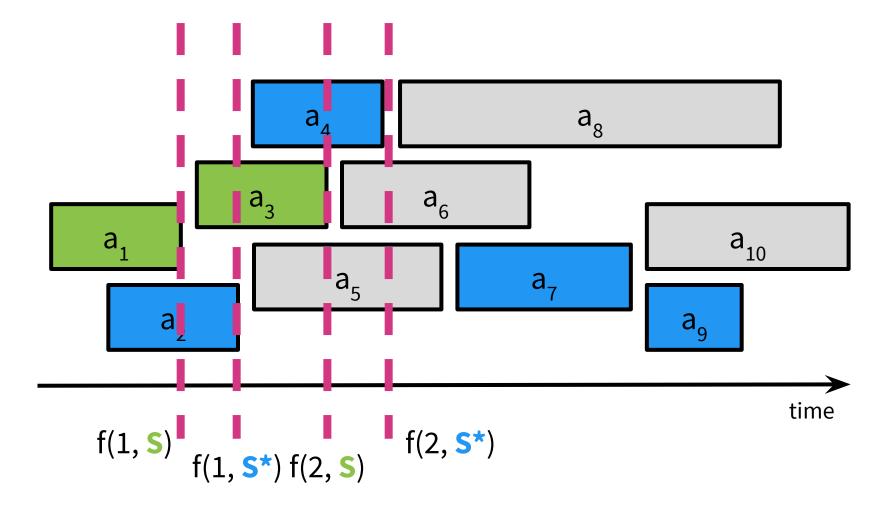


time

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**Lemma:** For all  $1 \le i \le |S|$ , we have  $f(i, S) \le f(i, S^*)$ .

**Proof:** We proceed by induction.

As a base case, the first activity the greedy algorithm selects must be an activity that ends no later than any other activity, so  $f(1, S) \le f(1, S^*)$ .

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For the inductive step, assume that the claim holds for some  $1 \le i < |S|$ . We will prove the claims holds for i + 1. Since  $f(i, S) \le f(i, S^*)$ , the ith activity in S finishes before the ith activity in S\*.

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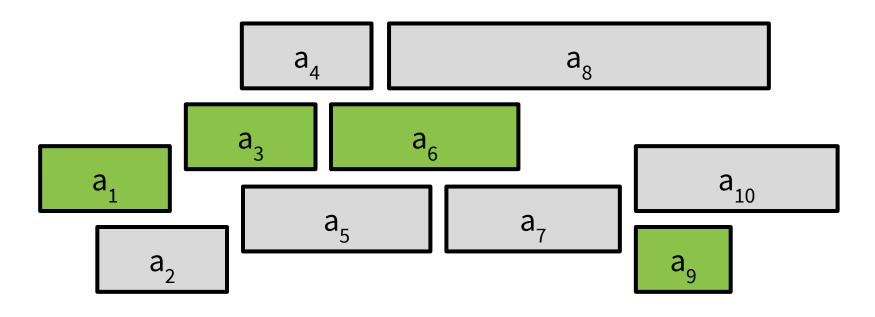
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Therefore, the (i+1)st activity in S\* must be in U when the greedy algorithm selects the activity in U with the lowest end time, we have  $f(i+1, S) \le f(i+1, S^*)$ , completing the induction.

Bringing it home: By contradiction, suppose there was an S\* with more activities than our solution S.

Since for all  $1 \le i \le |S|$ , we have  $f(i, S) \le f(i, S^*)$  it must be the case than the  $|S|+1^{st}$  activity has a start time after the end time of the last activity in S. **Impossible!** 



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**Theorem:** activity\_selection produces an optimal solution.

**Proof:** Since S\* is optimal, we have  $|S| \le |S^*|$ . We will prove  $|S| = |S^*|$ .

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In Frog Hopping, we proved this step using a direct proof. Here, we use a proof by contradiction. You should be able to structure the direct proof here too.

We need to prove two properties about the algorithm to guarantee correctness.

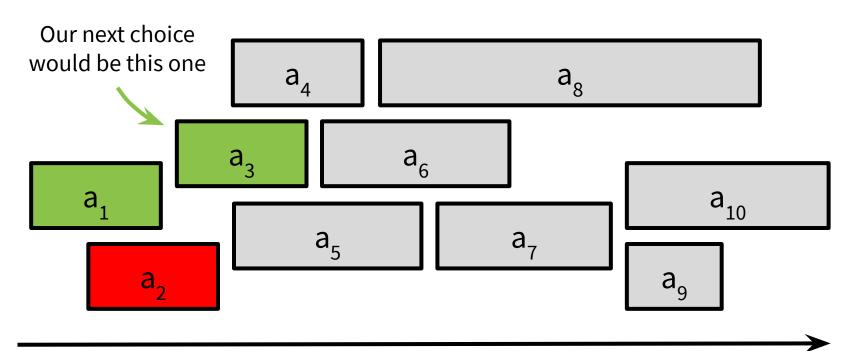
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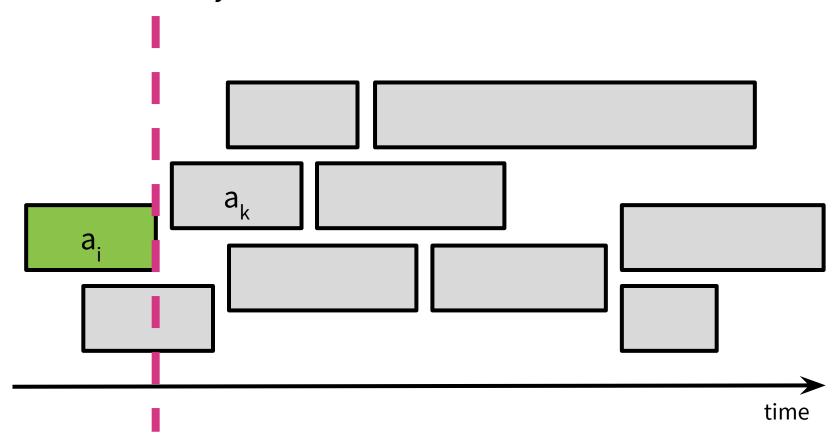
Whenever we make a choice, we don't rule out an optimal solution.



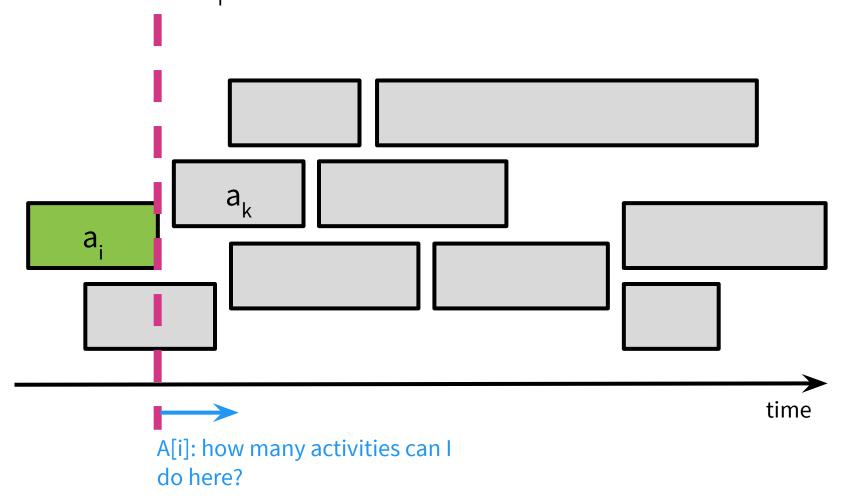
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There's some optimal solution that contains our next choice Our next choice would be this one  $a_4$  $a_8$  $a_3$  $a_6$ a<sub>10</sub> a<sub>1</sub>  $a_7$  $a_5$ 

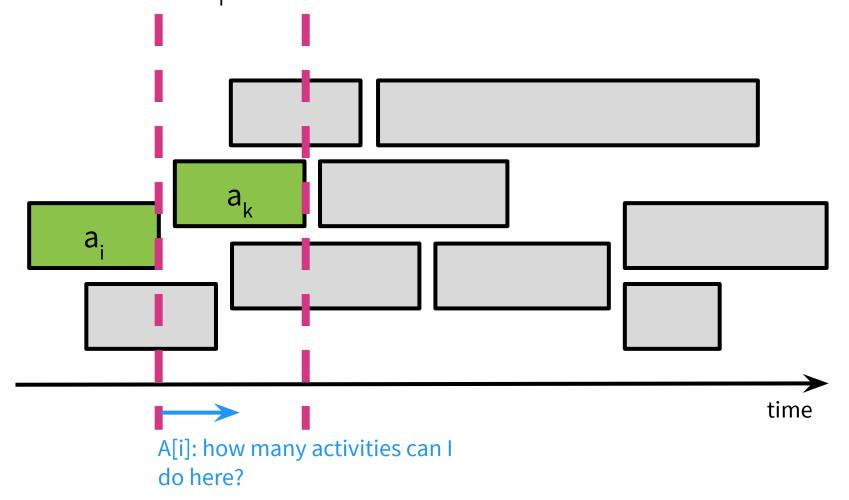
Subproblem(i): Let A[i] be the number of activities you can do after activity i finishes.



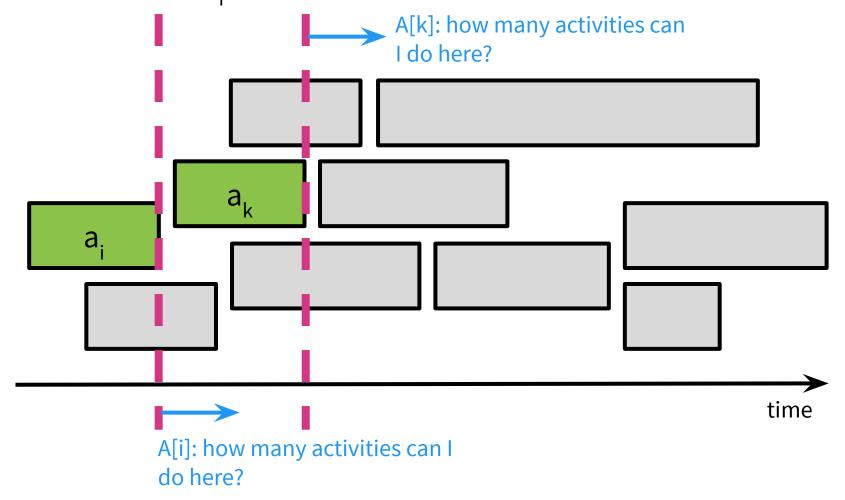
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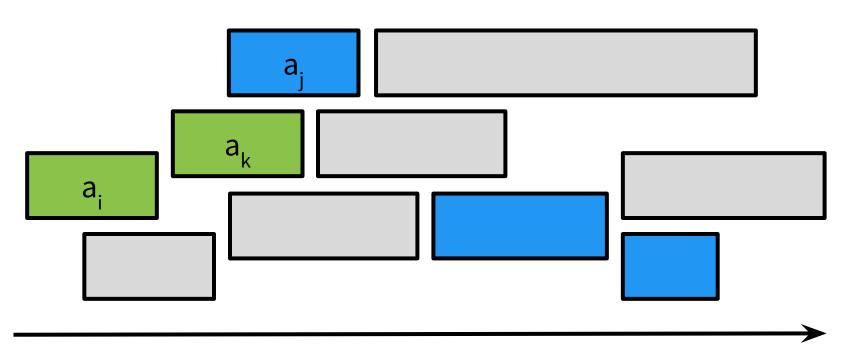


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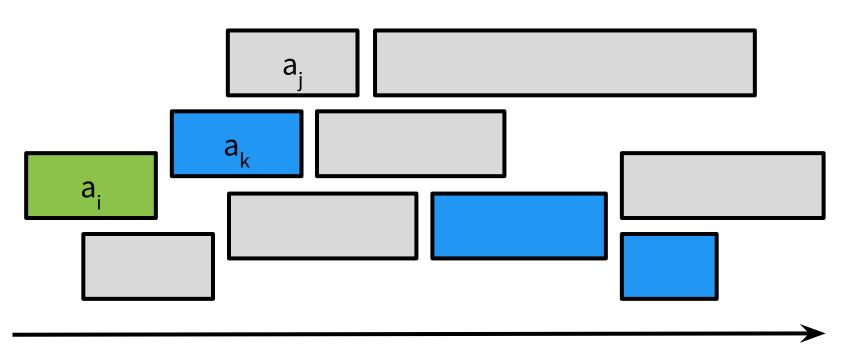
First,  $A[i] \ge A[k] + 1$  since we have a solution with A[k] + 1 activities.

Suppose toward contradiction that A[i] > A[k] + 1 i.e. there's some better solution to Subproblem(i) that doesn't use  $a_k$ .

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Suppose toward contradiction that A[i] > A[k] + 1 i.e. there's some better solution to Subproblem(i) that doesn't use  $a_k$ . Let  $a_j$  be the activity that ends first in that better solution. Exchange  $a_k$  for  $a_j$  in that better solution. Now you have a solution of the same size but it Includes  $a_k$  so it must have size  $\leq A[k] + 1$  (contradiction!).

