

# Greedy Algorithms I

Summer 2018 • Lecture 08/02

# A Few Notes

Homework 4

Homework 5

Original soft deadline was 8/9. I'm extending it to 8/10 at 5 p.m. due to the lecture schedule.

# Course Overview

- Algorithmic Analysis
- Divide and Conquer
- Randomized Algorithms
- Tree Algorithms
- Graph Algorithms
- Dynamic Programming
- **Greedy Algorithms**
- Advanced Algorithms

# Outline for Today

## Greedy algorithms

- Frog Hopping

- Minimum Spanning Trees

# Frog Hopping

# Greedy Algorithms

Greedy algorithms construct solutions one step at a time, at each step choosing the locally best option.

**Advantages:** simple to design, often efficient

**Disadvantages:** difficult to verify correctness or optimality

# Freddie the Frog

Freddie the Frog starts at position 0 along a river. His goal is to reach position  $n$ .

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Freddie can hop at most  $r$  units at a time.

**Task:** Find the path Freddie should take to minimize hops, assuming such a path exists.

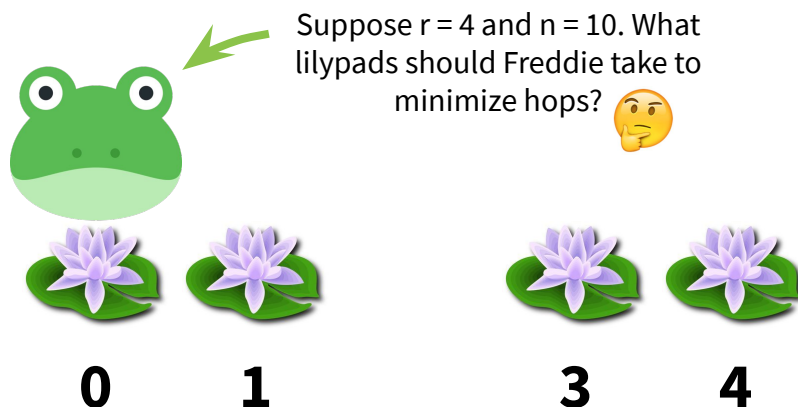
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10



# Frog Hopping

```
def frog_hopping(lilys, r, n):  
    # lilys = [0, 1, 3, 4, 6, 10] in the previous example  
    H = [0] # contains hops  
    cur_lily = {"index": 0, "position": 0}  
    while cur_lily["position"] < n:  
        next_lily = furthest_reachable_lily(  
            cur_lily, lilys, r  
        ) # finds the furthest lilypad still reachable  
          # from cur_lily  
        H.append(next_lily["position"])  
        cur_lily = next_lily  
    return H
```

 You should be able to implement this function yourself.

**Runtime:  $O(n)$**

# Frog Hopping

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- (2) **Optimality.** The algorithm finds an optimal series of hops (i.e. there isn't a better path available).

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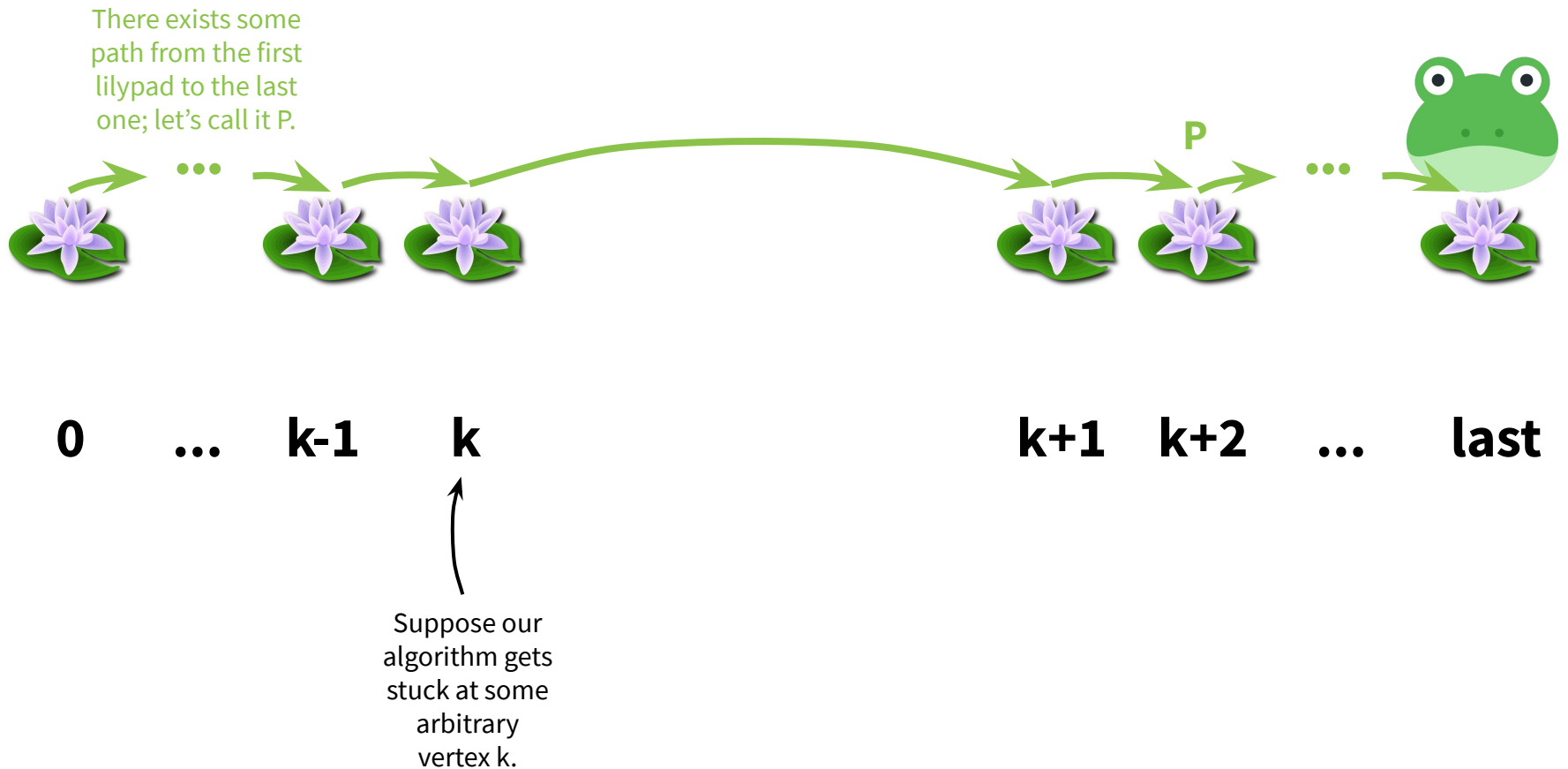
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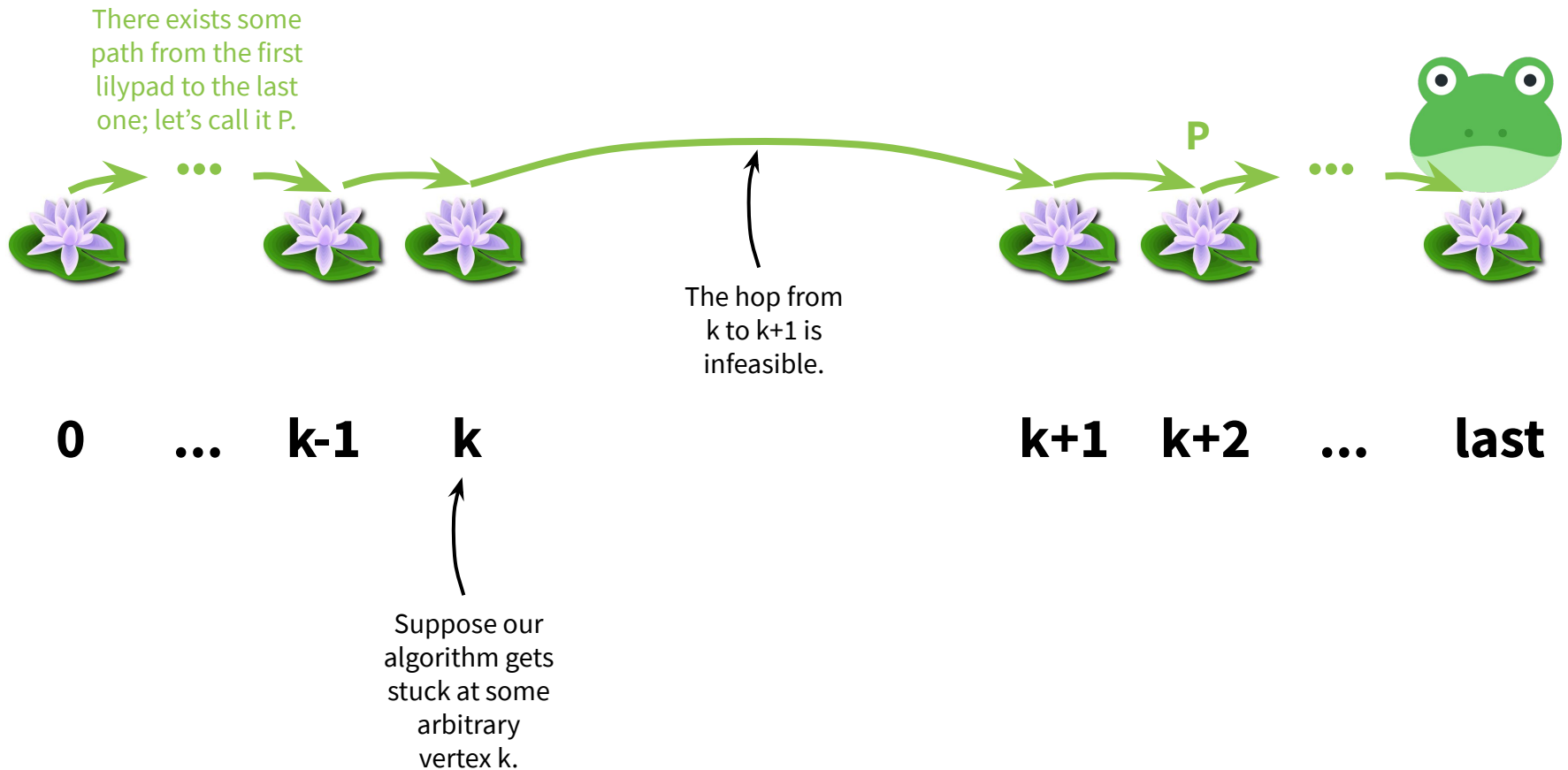
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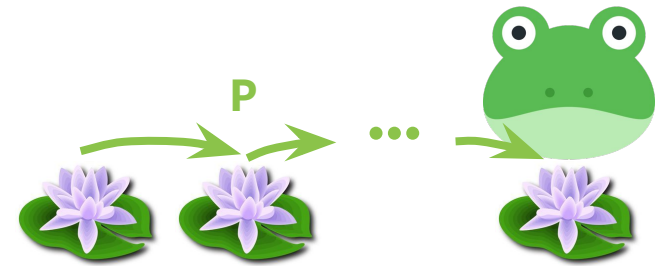
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There exists some path from the first lilypad to the last one; let's call it P.



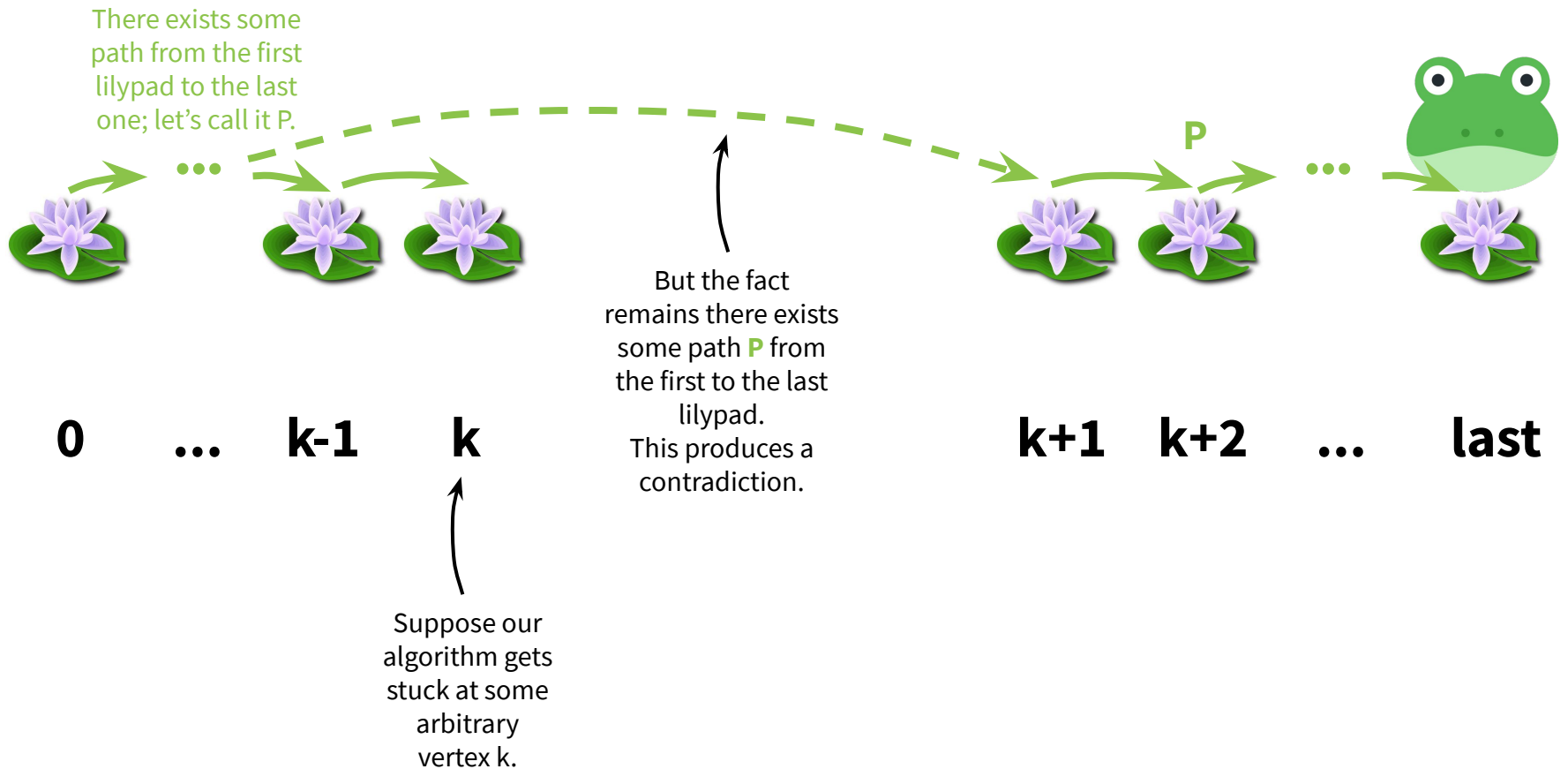
**0    ...    k-1    k**

Suppose our algorithm gets stuck at some arbitrary vertex k.



**k+1    k+2    ...    last**

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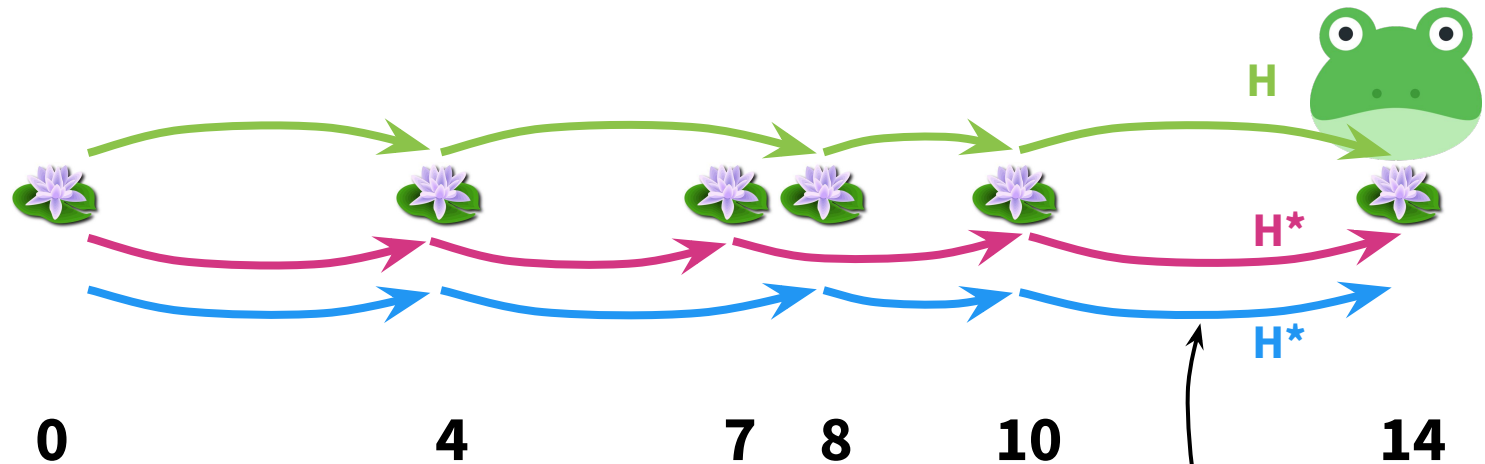
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**Intuition:** Consider an arbitrary optimal series of hops  $H^*$ , then show that our greedy algorithm produces a series of hops  $H$  no worse than  $H^*$ .

# What Does Arbitrary $H^*$ Mean?



There could be many optimal  $H^*$  (this series of lilypads has 2); this proof relies on an arbitrary choice from among this  $H^*$ .

Suppose we choose  $H^*$ .

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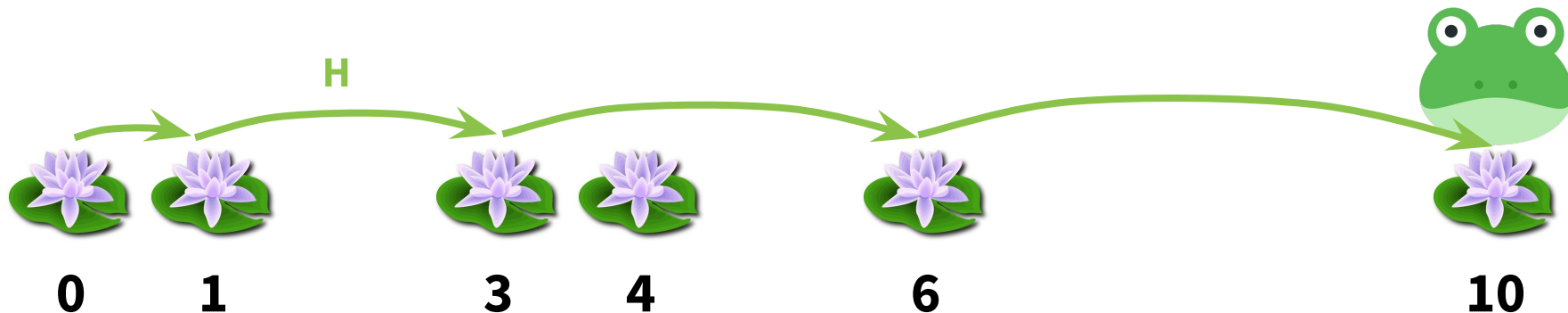


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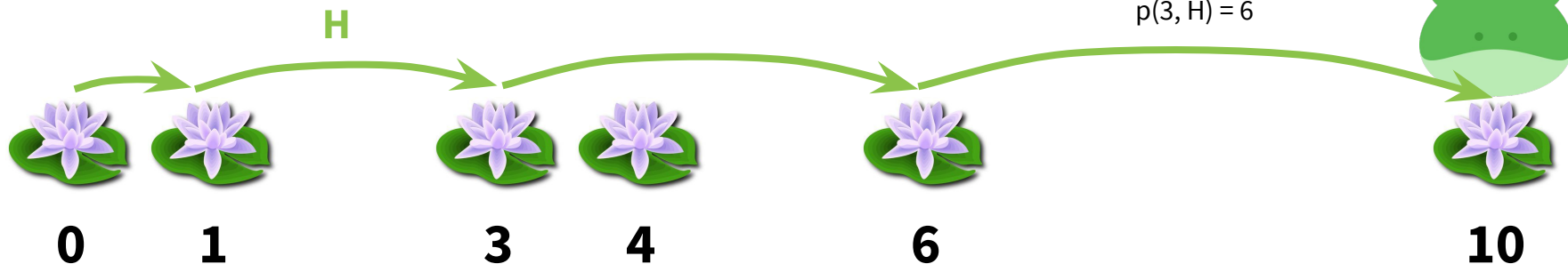
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Let's formalize this using induction.

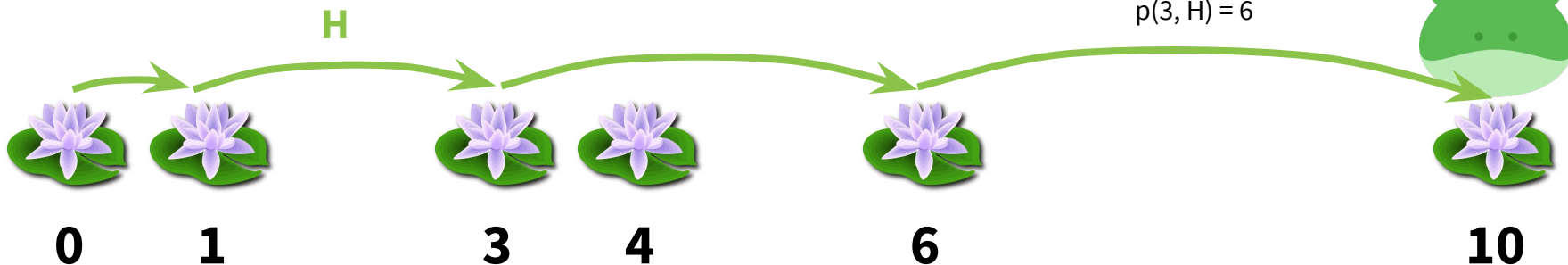
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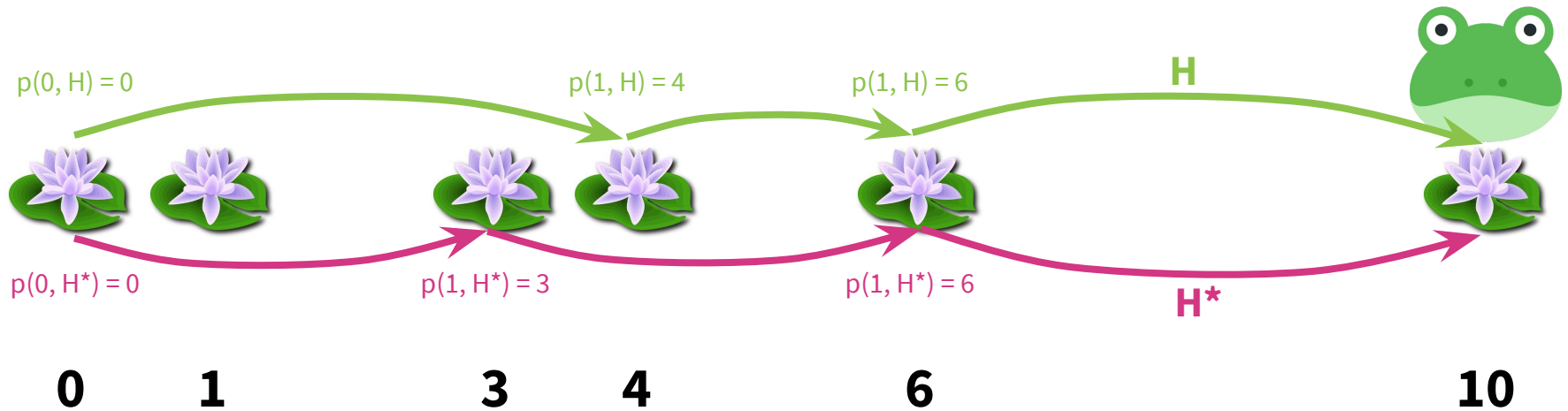
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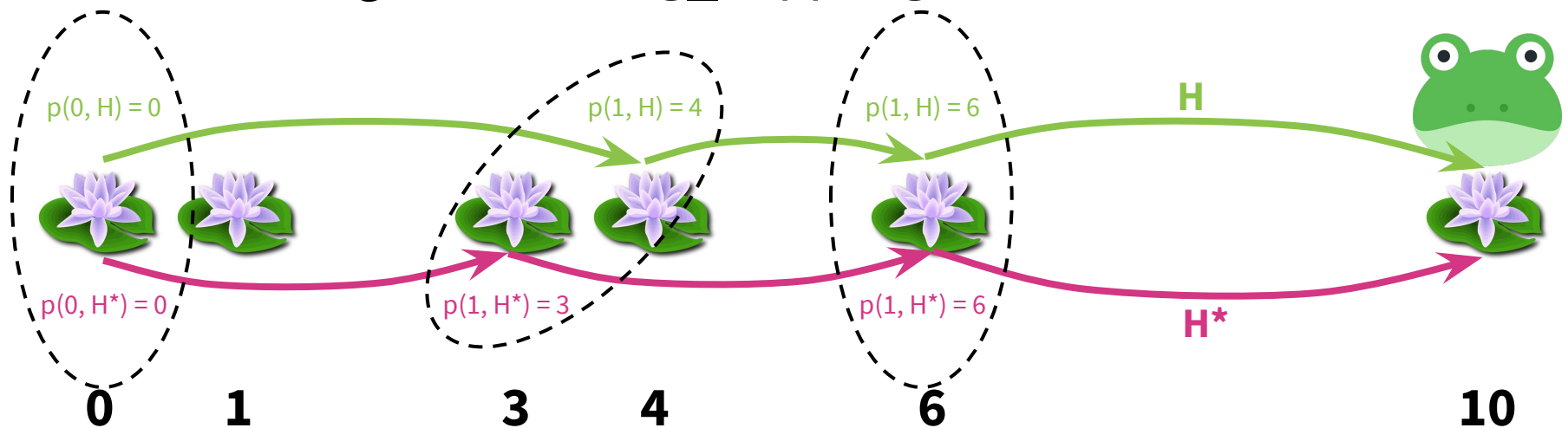
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**Lemma 2:** For all  $0 \leq i \leq |H^*|$ , we have  $p(i, H) \geq p(i, H^*)$ , constructing  $H$  from `frog_hopping`.

**Proof:** We proceed by induction.

As a base case, if  $i = 0$ , then  $p(0, H) = 0 \geq 0 = p(0, H^*)$  since the frog hasn't moved.

For the inductive step, assume that the claim holds for some  $0 \leq i < |H^*|$ . We'll prove the claim holds for  $i + 1$  by considering two cases:

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**Case 2:**  $p(i, H) < p(i+1, H^*)$ . Each hop is of size at most  $r$ , so  $p(i+1, H^*) \leq p(i, H^*) + r$ .

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**Case 1:**  $p(i, H) \geq p(i+1, H^*)$ . Since each hop moves forward, we have  $p(i+1, H) \geq p(i, H)$ , so we have  $p(i+1, H) \geq p(i+1, H^*)$ .

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So  $p(i+1, H) \geq p(i+1, H^*)$ , completing the induction. ■

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Now for the theorem: `frog_hopping` produces an optimal solution for Freddie.

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Since  $H^*$  is an optimal solution, we know that  $|H^*| \leq |H|$ . We will prove  $|H^*| = |H|$ .

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Here, we proved this step using a direct proof. You should be able to structure the proof by contradiction here too.

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We need to prove two properties about the algorithm to guarantee correctness.

(1) **Feasibility.** The algorithm finds a feasible (aka legal) series of hops (i.e. it doesn't "get stuck" or break any rules).



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# Greedy Stays Ahead

The style of proof we just wrote is an example of a **greedy stays ahead** proof.

(1) Find intermediate values that evaluate the solution produced by any algorithm, including the greedy one.

What's our values in `frog_hopping`? 🤔 The position after  $i$  hops.

(2) Show the greedy algorithm produces values at least as good as any solution's (using induction).

(3) Prove that since the greedy algorithm produces values at least as good as any solution's, it must be optimal (using direct proof or proof by contradiction).

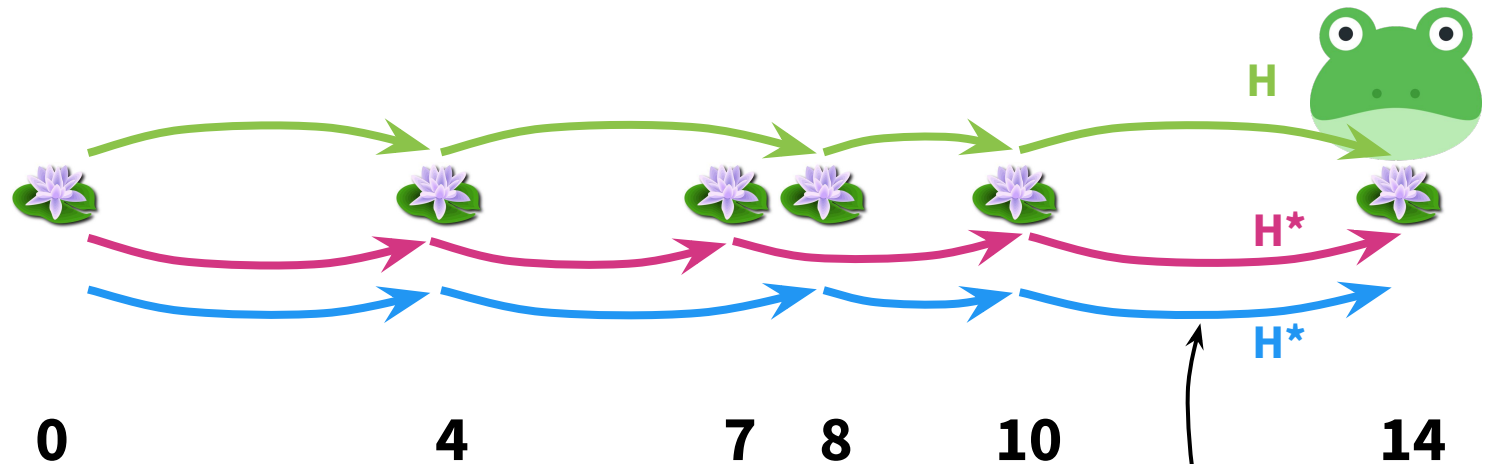
# Greedy Exchange Argument

There's another style of proof that uses **greedy exchange argument**.

If we swap an optimal solution out for the greedy solution, argue that we're still optimal.

# Greedy Exchange Argument

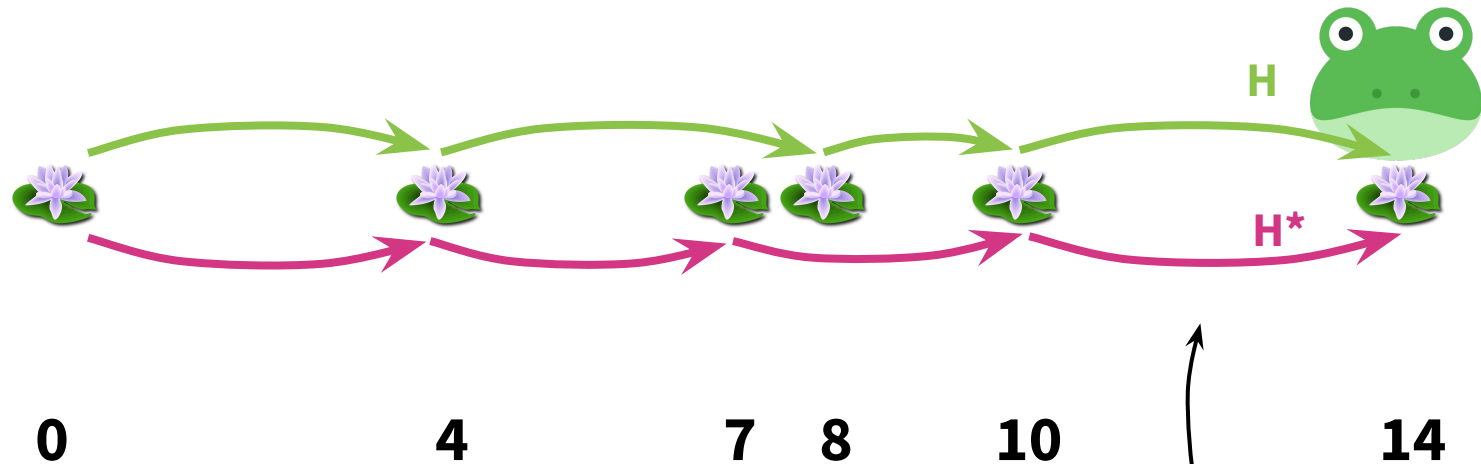
Again, this proof will rely on an arbitrary choice of  $H^*$ .



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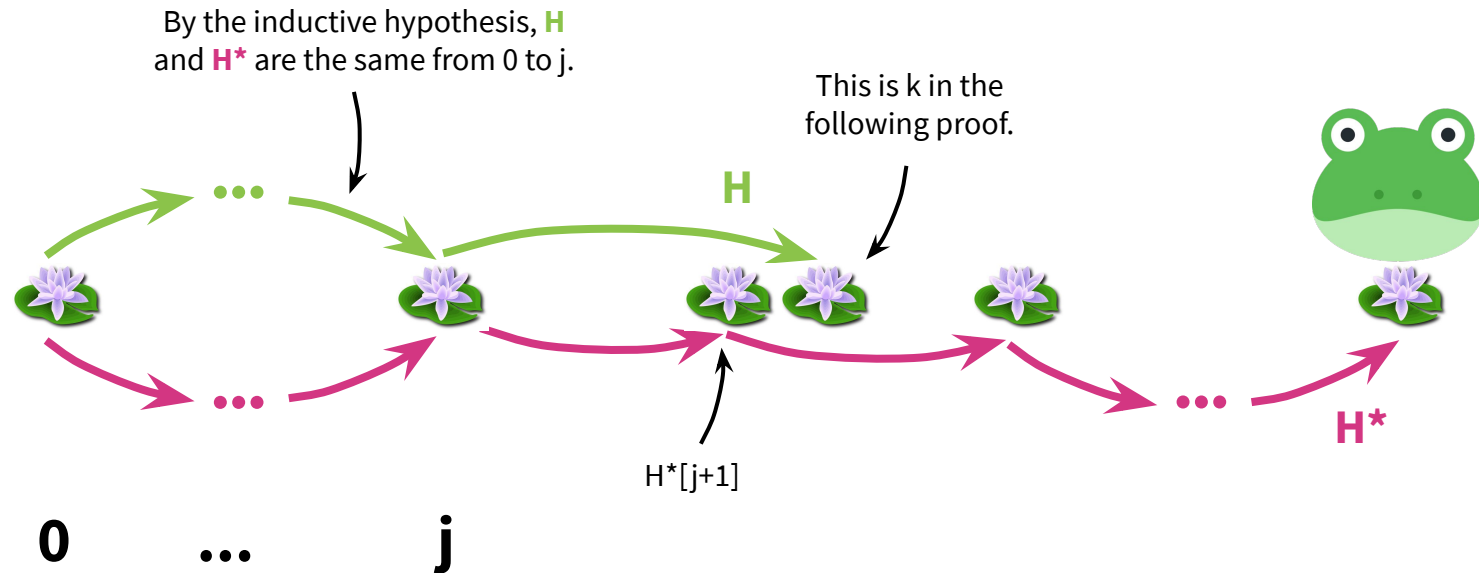
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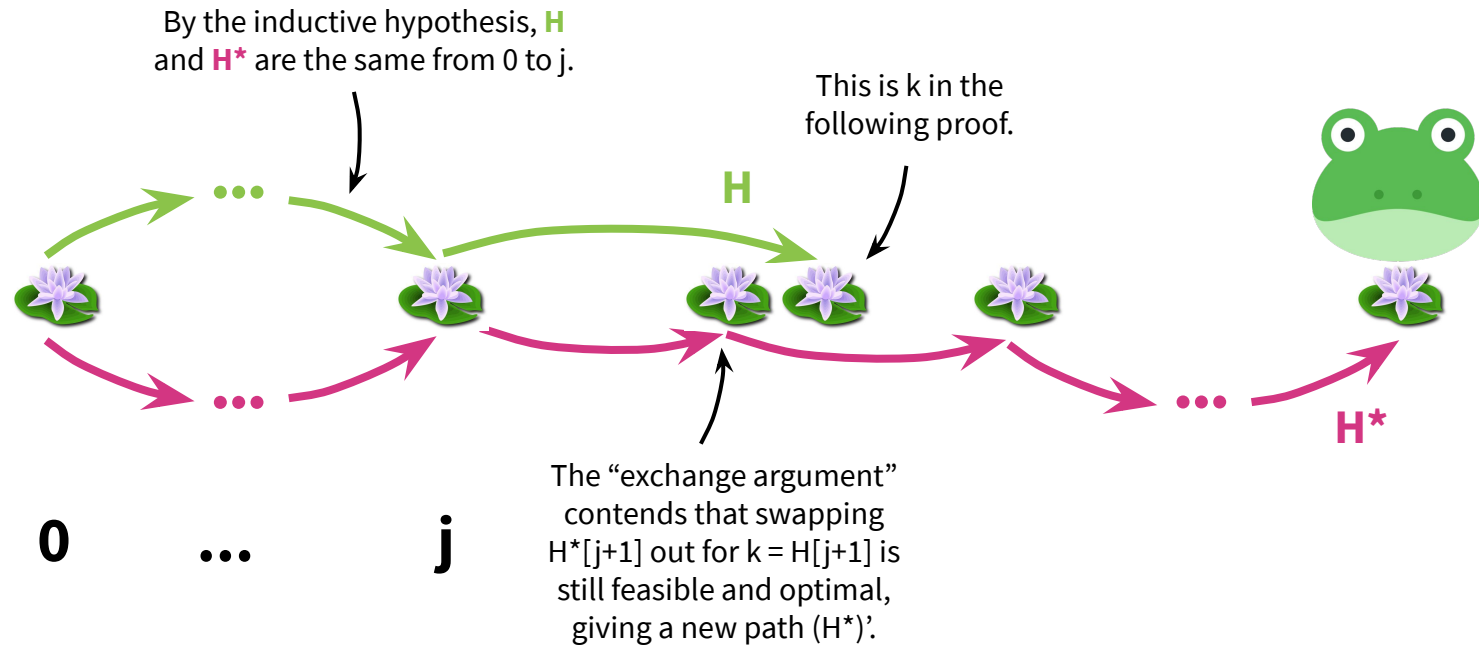
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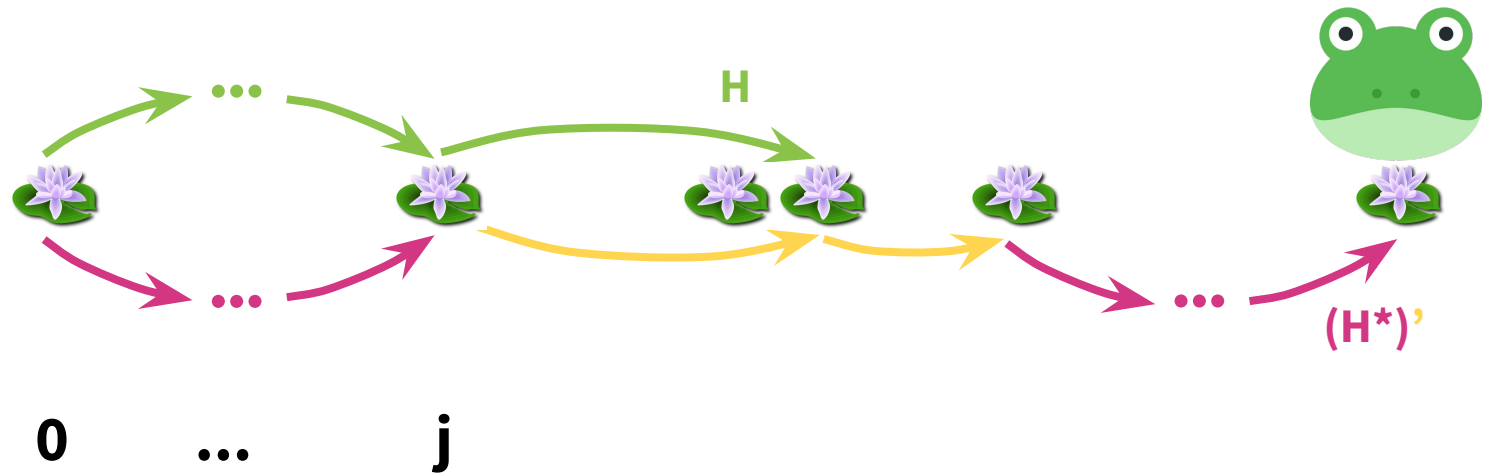


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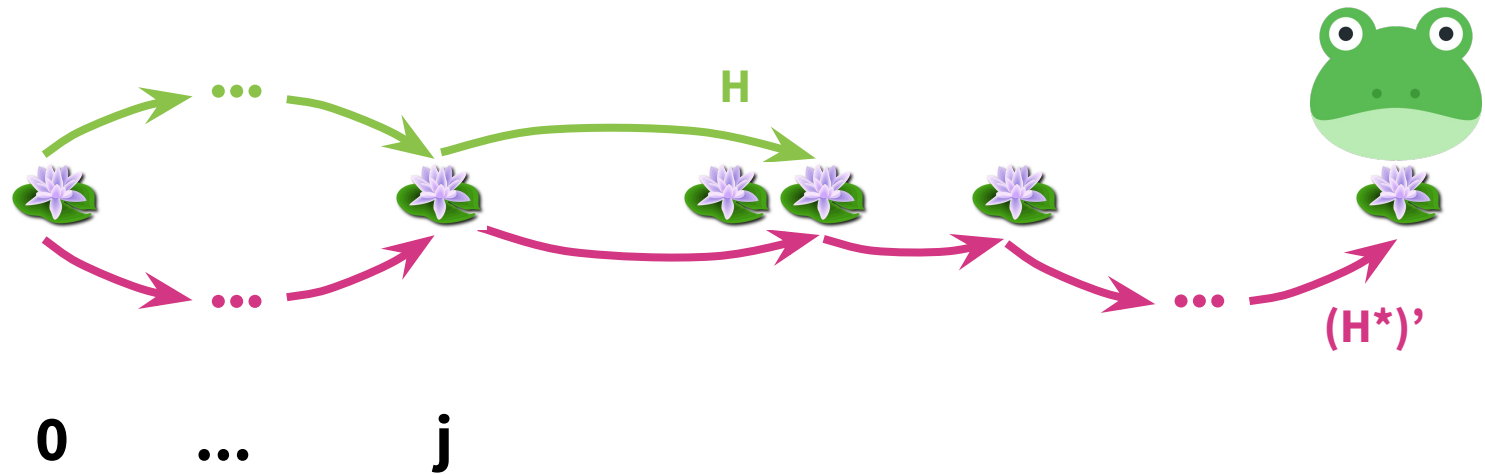




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**3 min break**

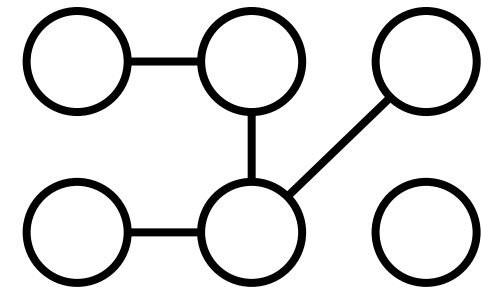
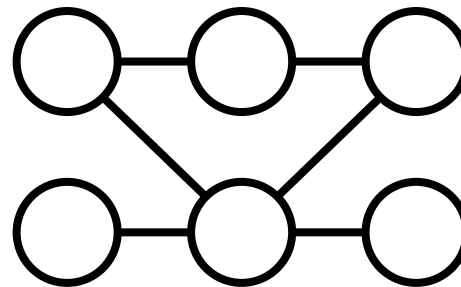
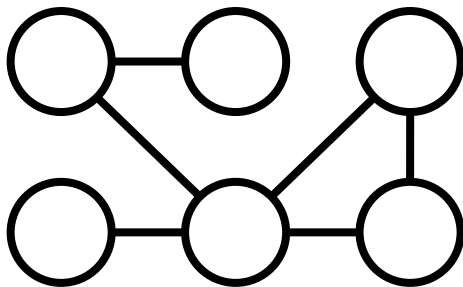
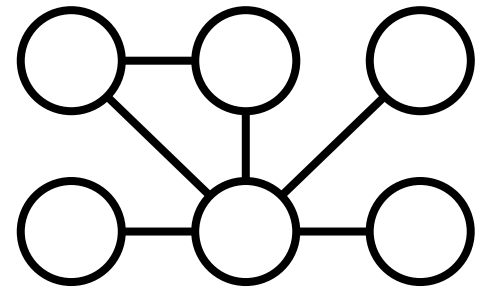
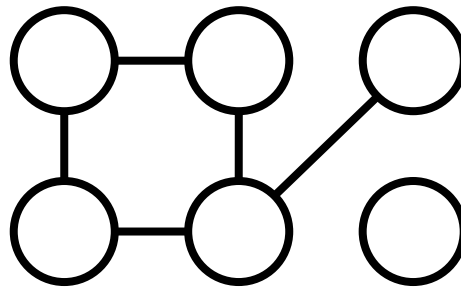
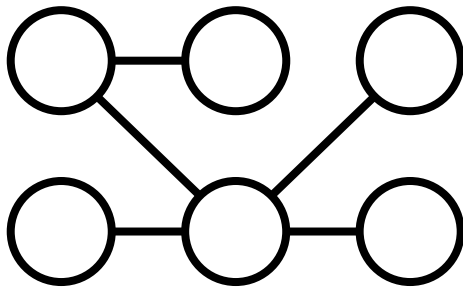
# Minimum Spanning Trees

# MSTs

In Lecture 3, we studied trees with directed edges from parent to children vertices. In this lecture, edges will be undirected.

A tree is an undirected, acyclic, connected graph.

Which of these graphs contain connected components which are trees? 🤔



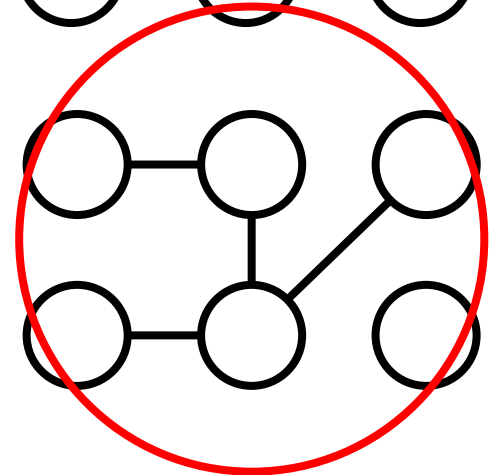
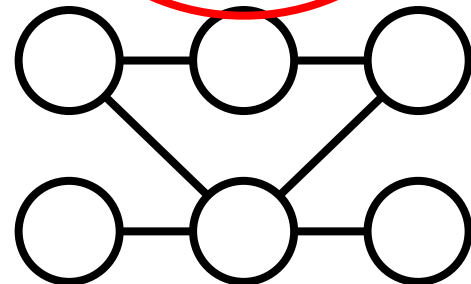
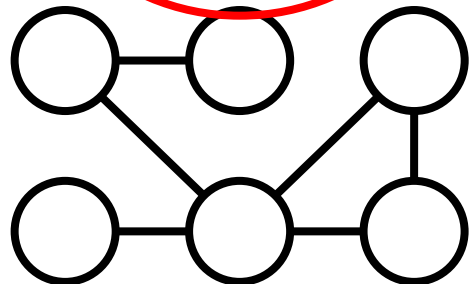
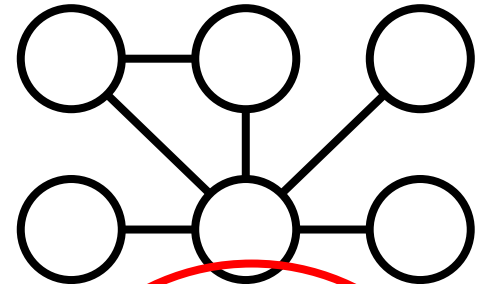
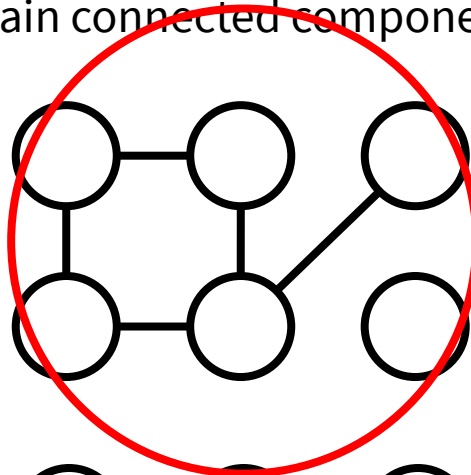
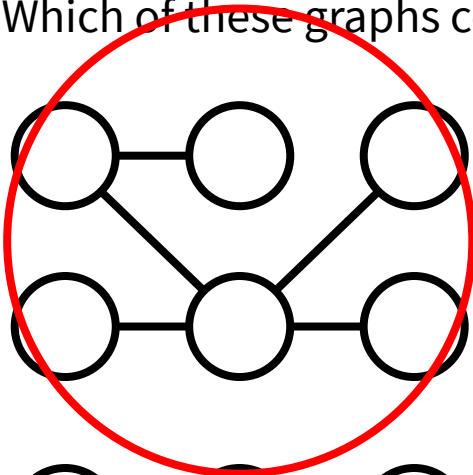
# MSTs

In Lecture 3, we studied trees with directed edges from parent to children vertices. In this lecture, edges will be undirected.



A tree is an undirected, acyclic, connected graph.

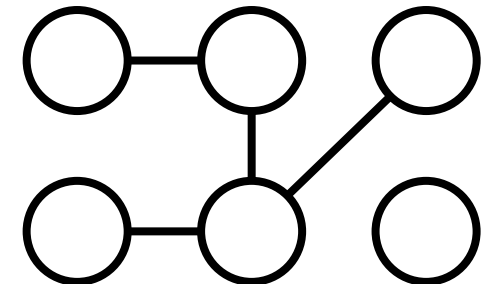
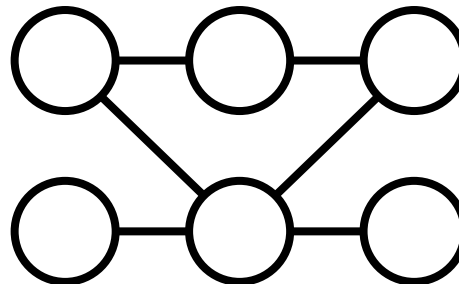
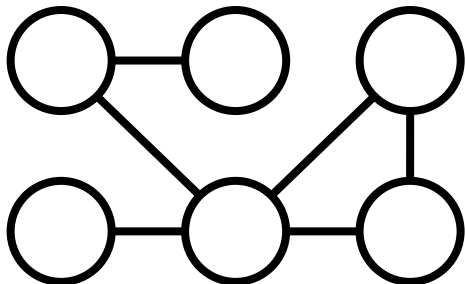
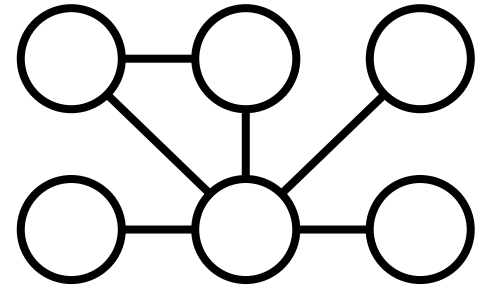
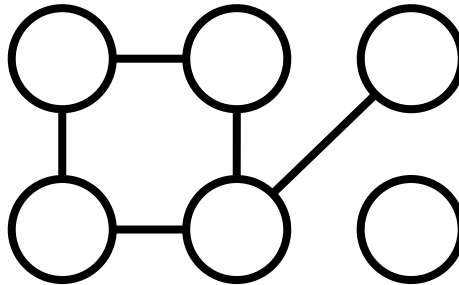
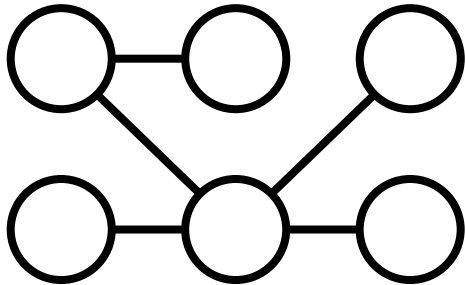
Which of these graphs contain connected components which are trees? 🤔



# MSTs

A spanning tree is a tree that connects all of the vertices.

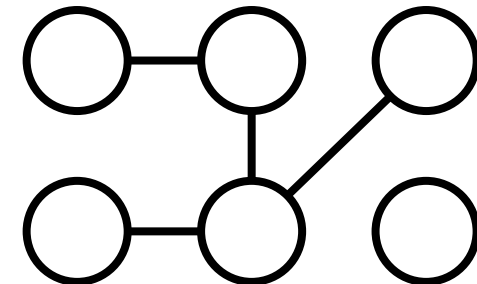
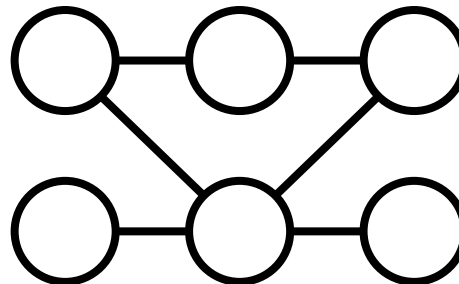
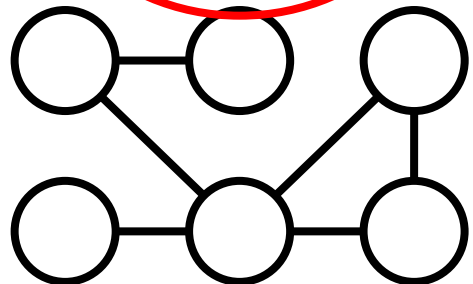
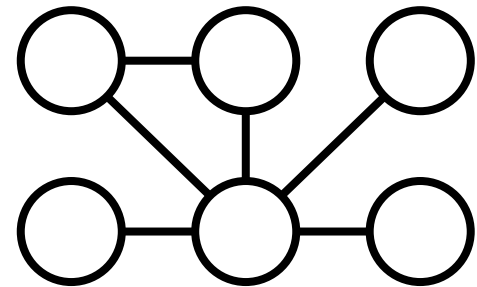
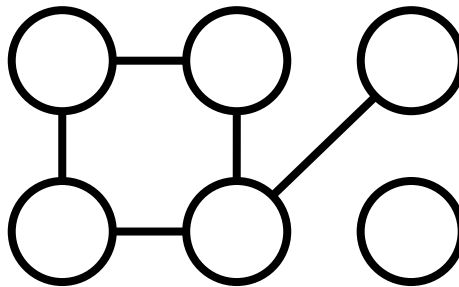
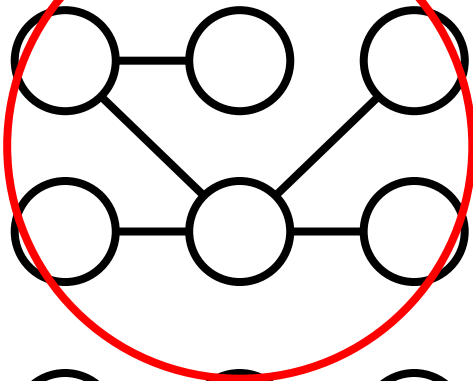
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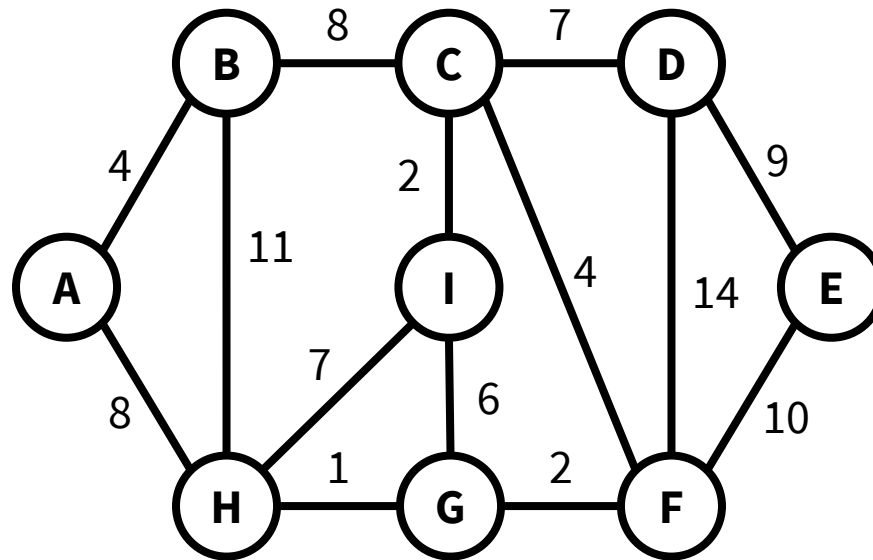


This connected component of the graph is a tree, but it doesn't include all of the vertices.

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The cost of a spanning tree is the sum of the weights on the edges.

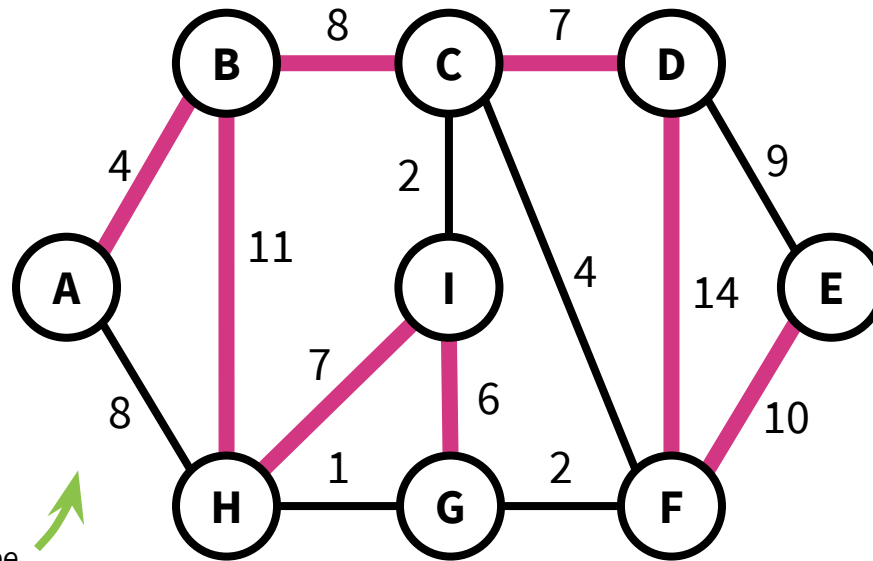




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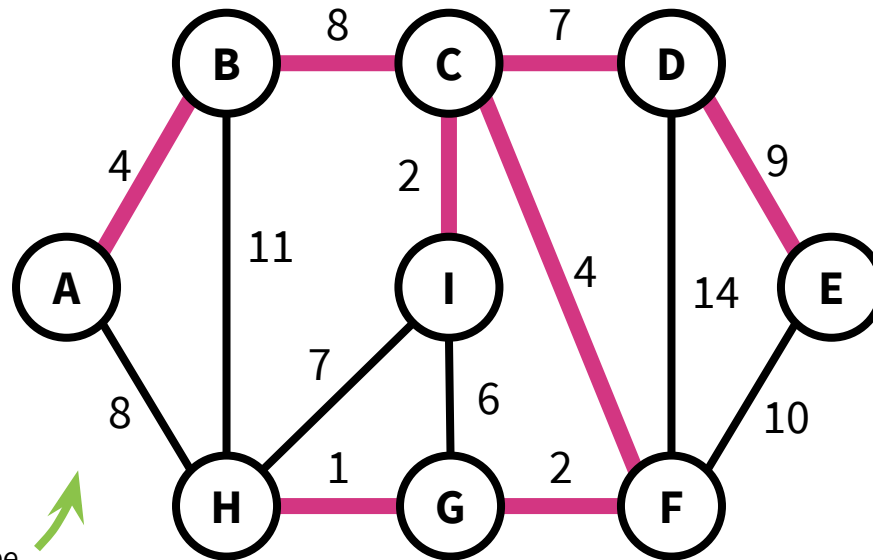


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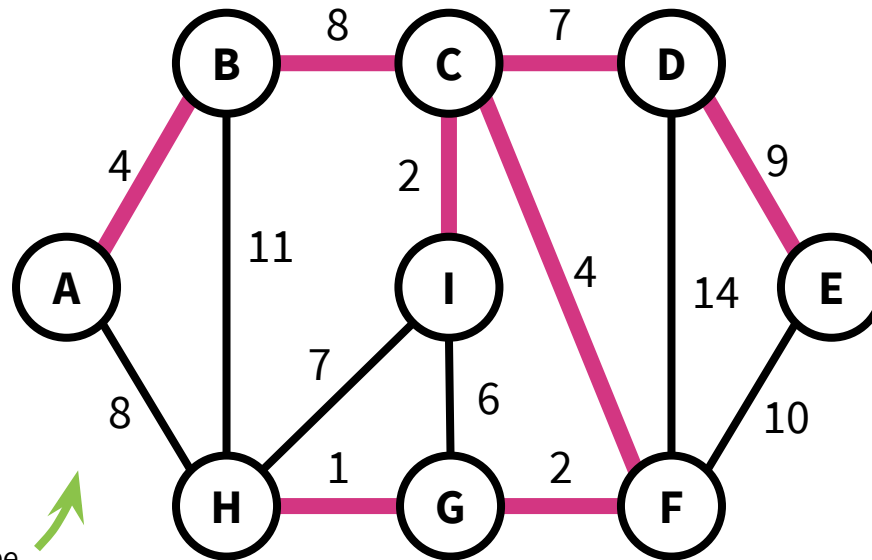


This spanning tree  
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# MSTs

A <sup>minimum</sup> spanning tree is a tree <sup>of minimal cost</sup> that connects all of the vertices.

The cost of a spanning tree is the sum of the weights on the edges.



This spanning tree  
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This is a minimum  
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# MSTs

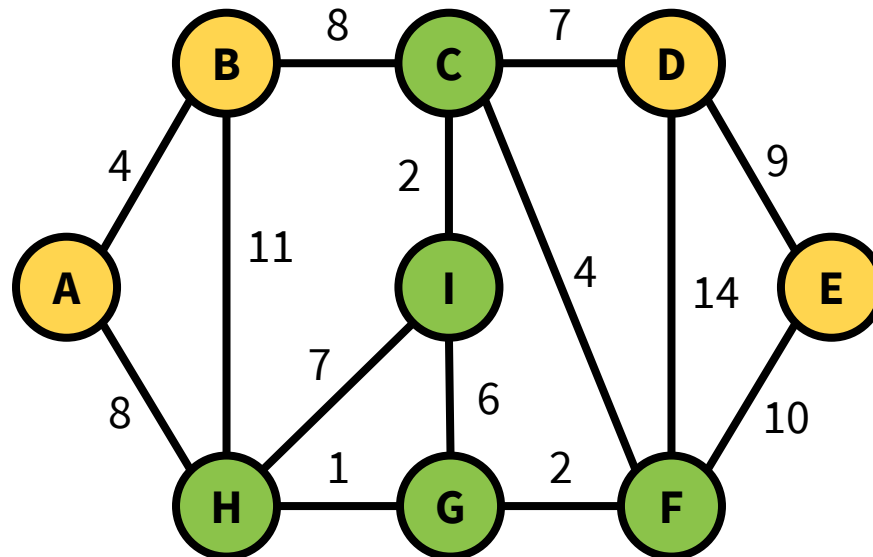
How might we find an MST?

Today, we'll see two greedy algorithms that find an MST.

# MSTs

A **cut** is a partition of the vertices into two nonempty parts.

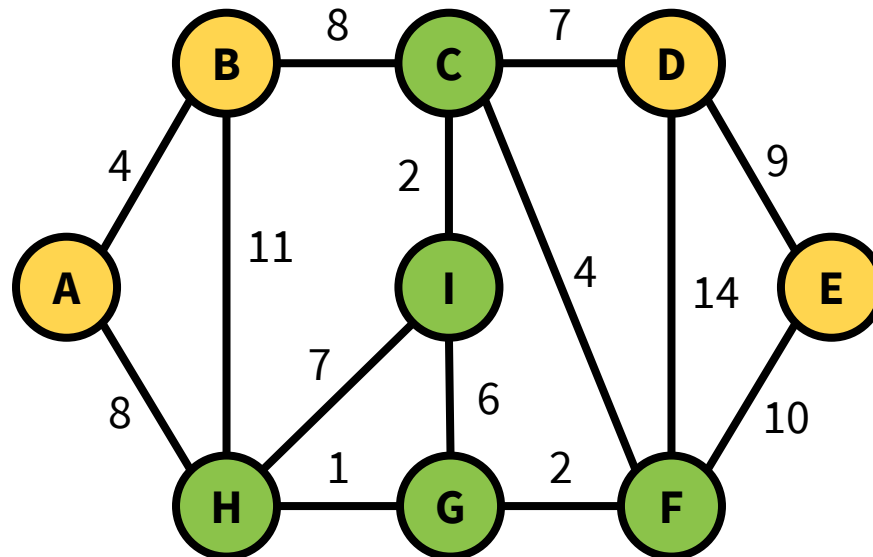
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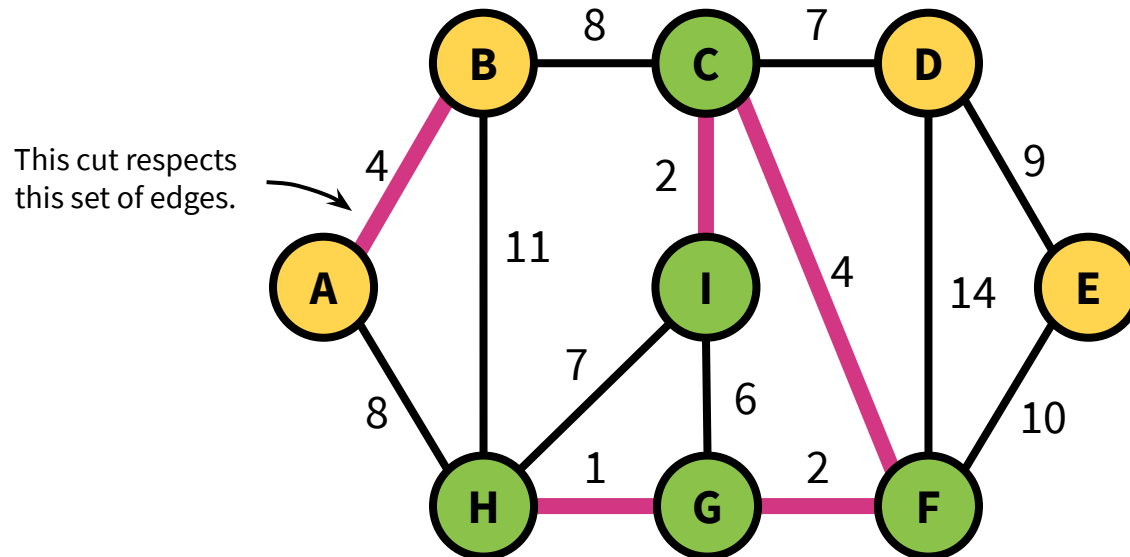


A cut respects a set of edges if no edges in the set cross the cut.

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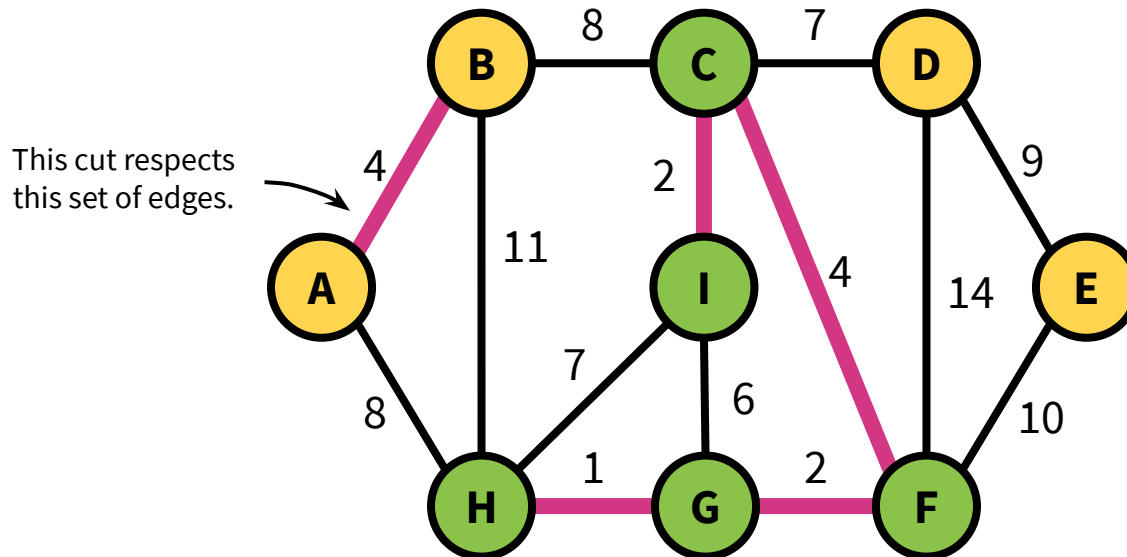


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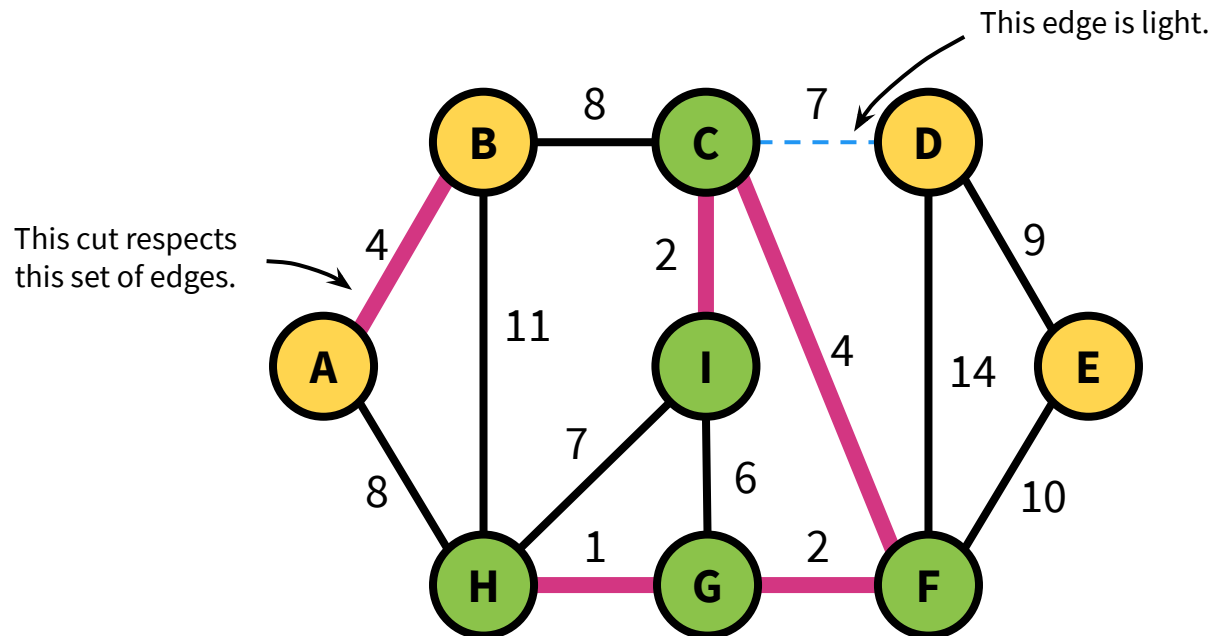
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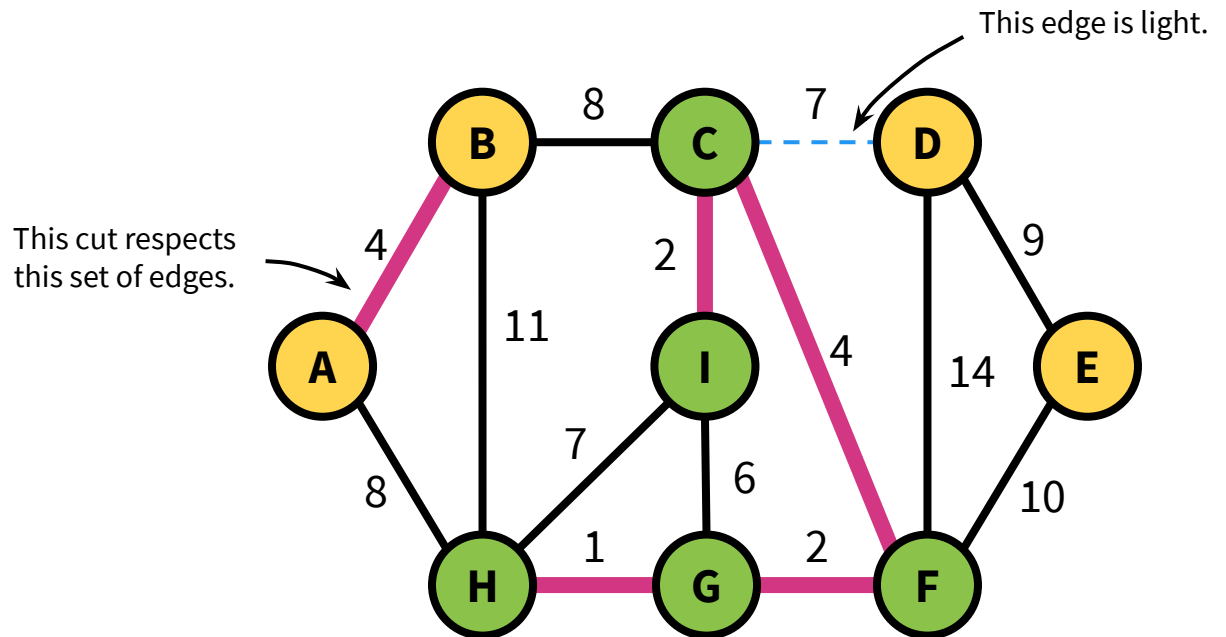
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# Lemma

Consider a cut that respects a set of edges **A**.

Suppose there exists an MST containing **A**.

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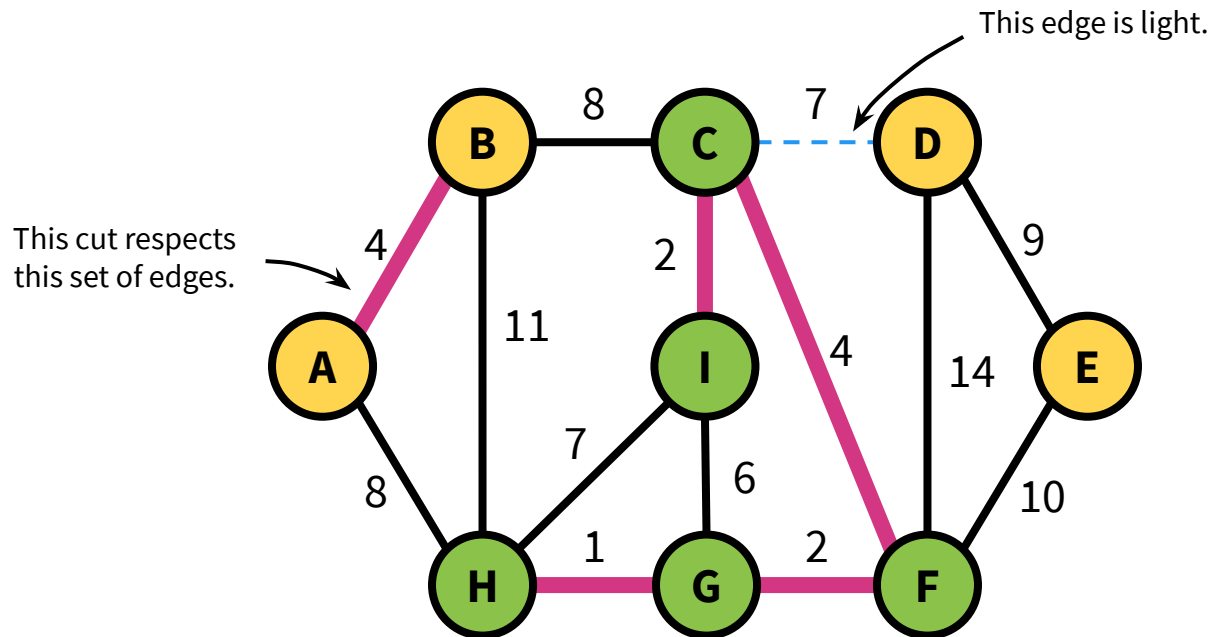
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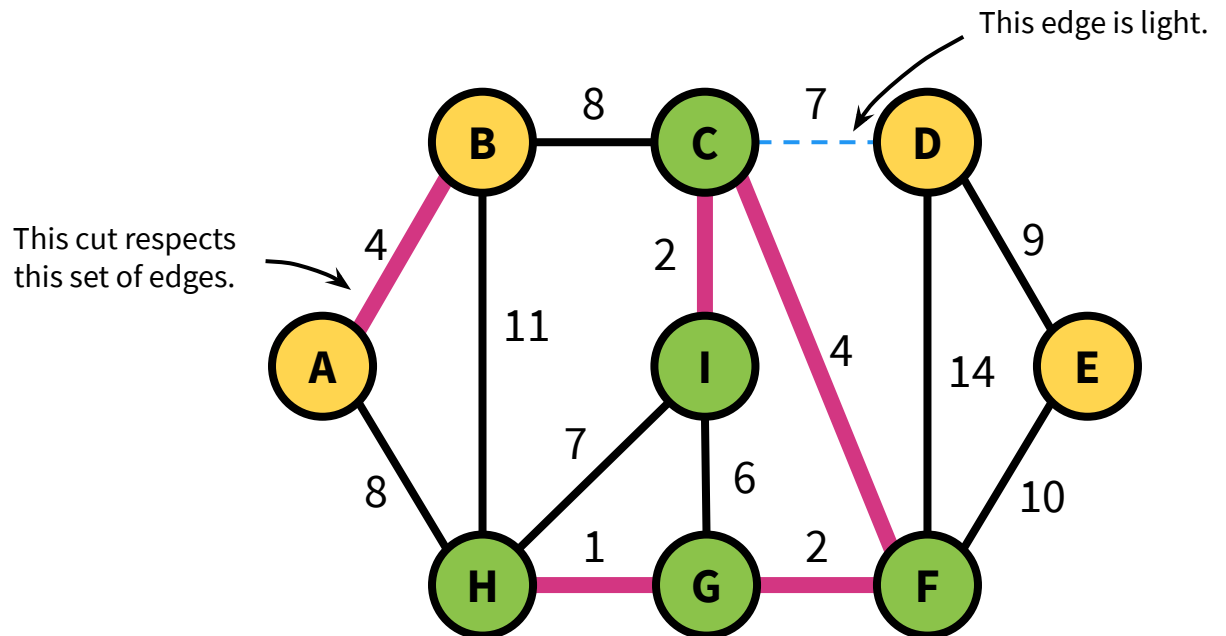
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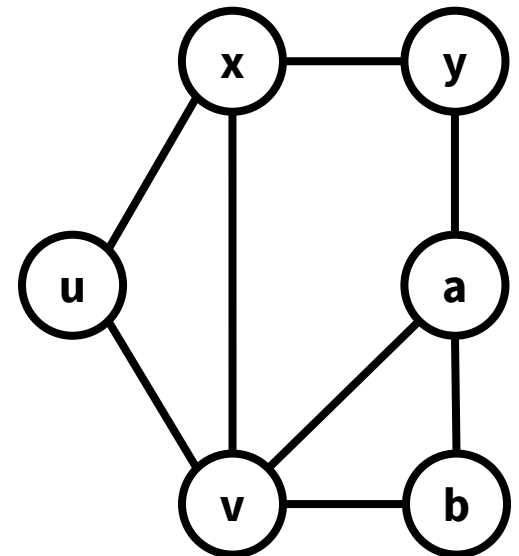


This is precisely the sort of statement we need for a greedy algorithm: If we haven't ruled out the possibility of success so far, then adding a light edge won't rule it out.



# Proof of Lemma

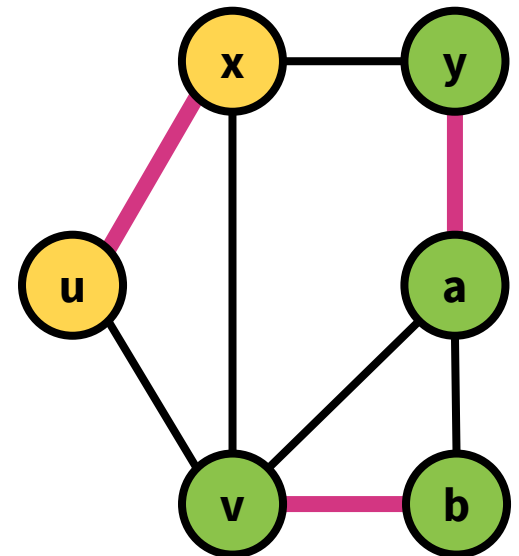
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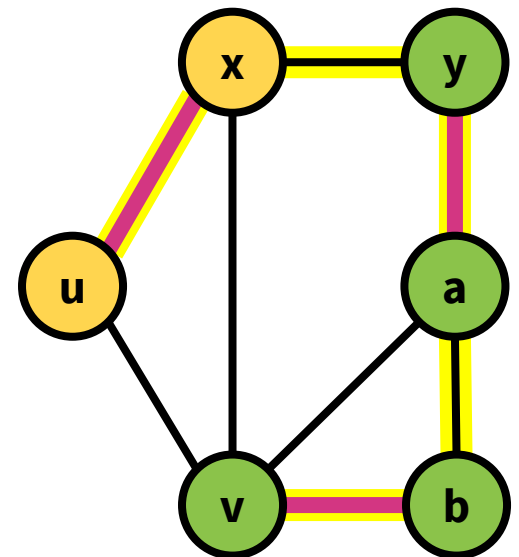
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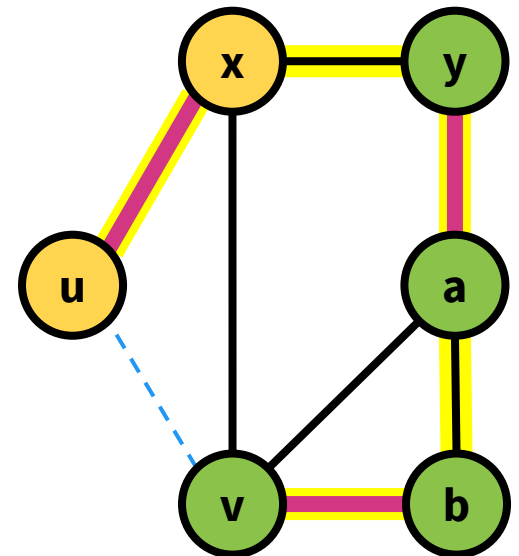
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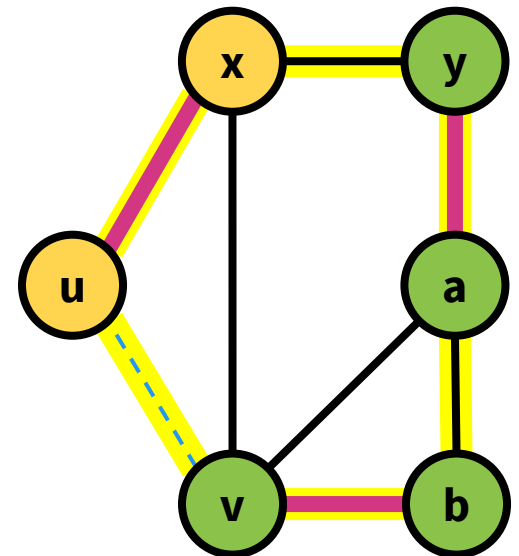


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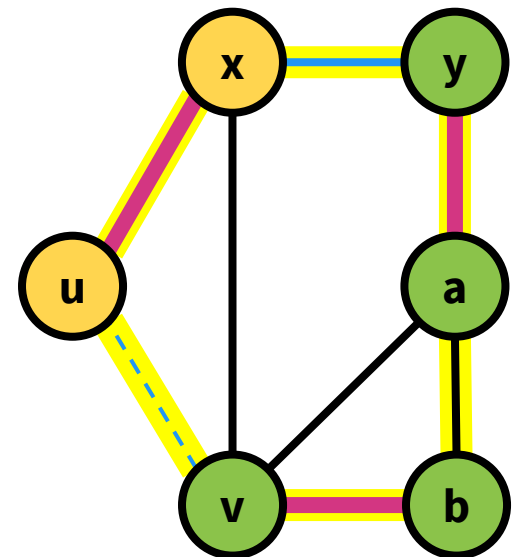
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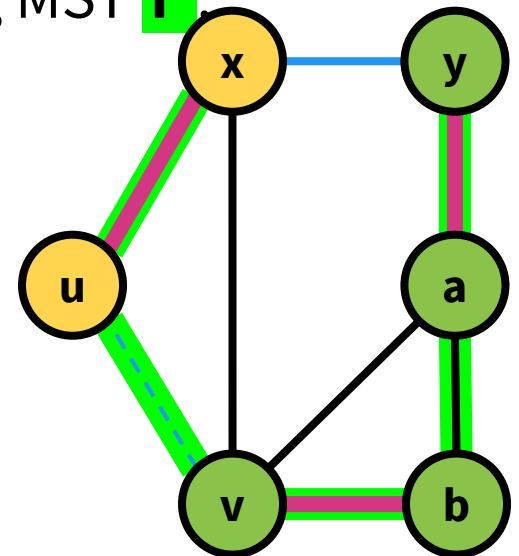
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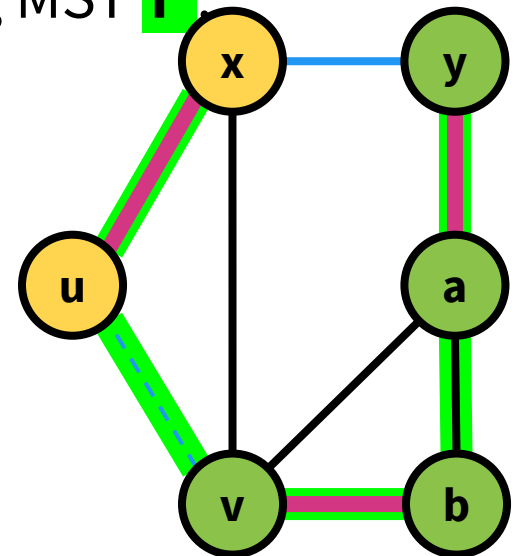
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**Claim:**  $T'$  is still an MST.

Since we deleted  $(x, y)$ ,  $T'$  is still a tree.

Since  $(u, v)$  is light,  $T'$  has cost at most that of  $T$ .



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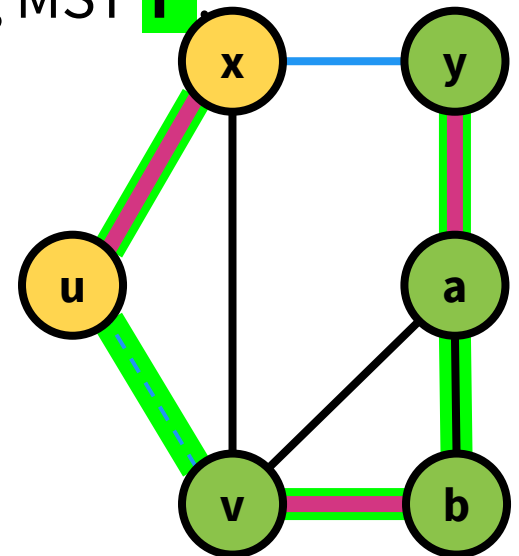
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Thus, there exists an MST containing  $A \cup \{(u, v)\}$ .



# Prim's Algorithm

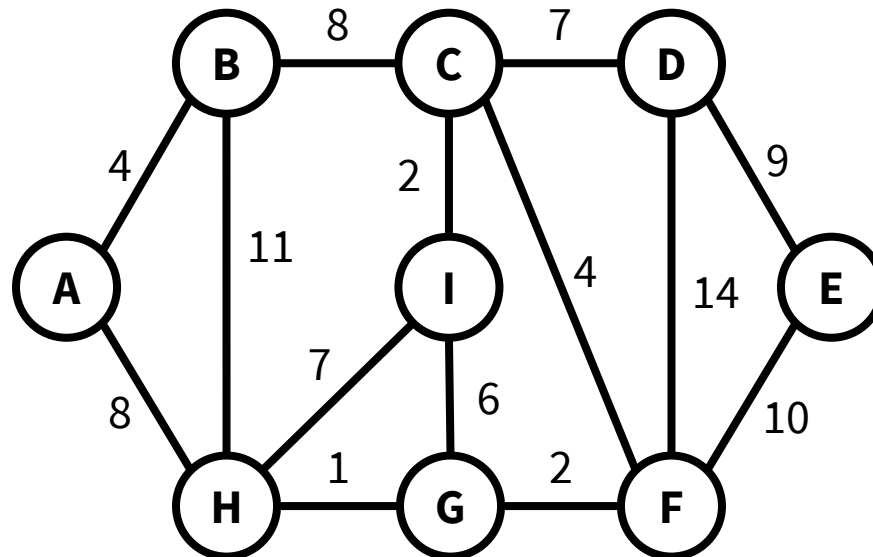
# Any Ideas?

Recall our lemma:

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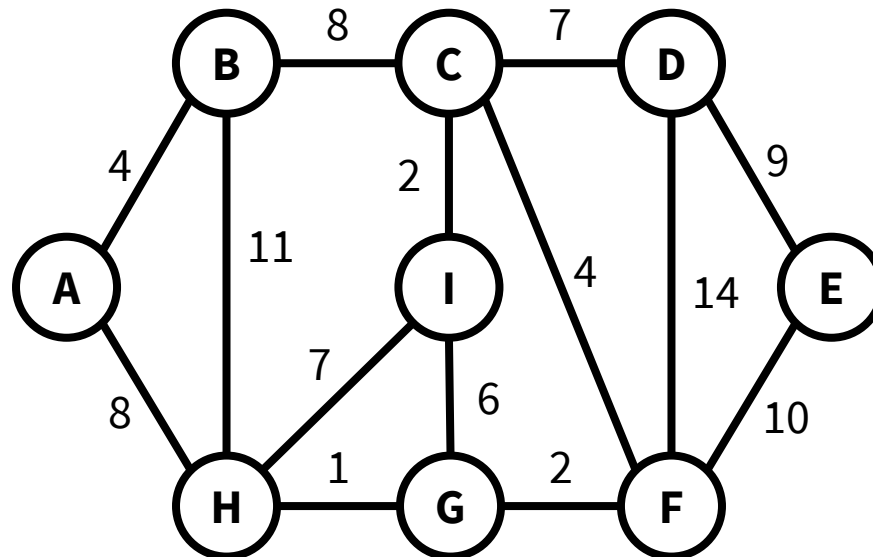
**Lemma:** There exists an MST containing  $\mathbf{A} \cup \{(u, v)\}$ .

Any ideas about what to greedily choose?



# Prim's Algorithm

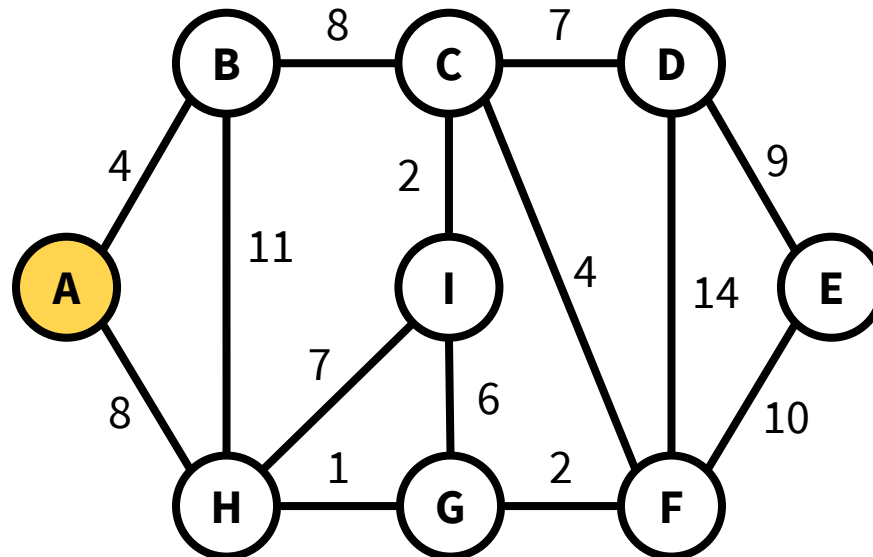
**Main idea:** Extend a single tree of visited vertices by greedily adding the closest vertex.





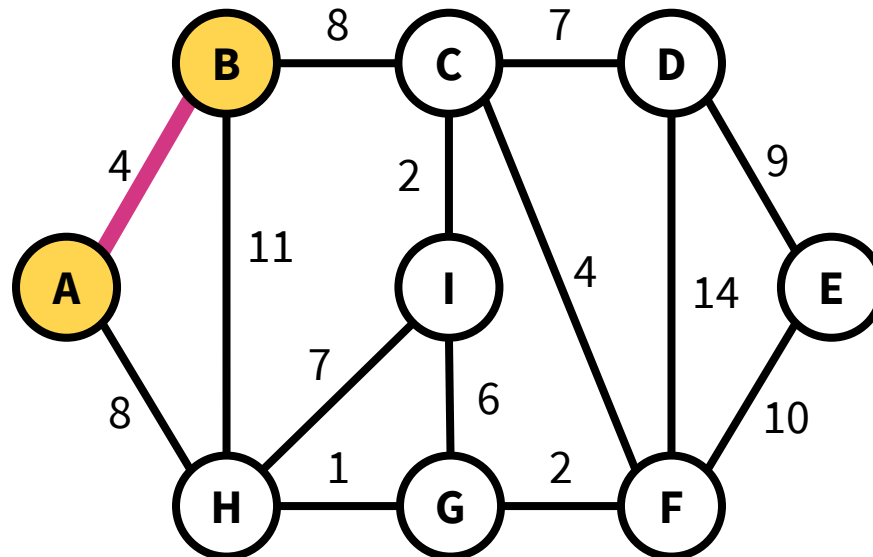
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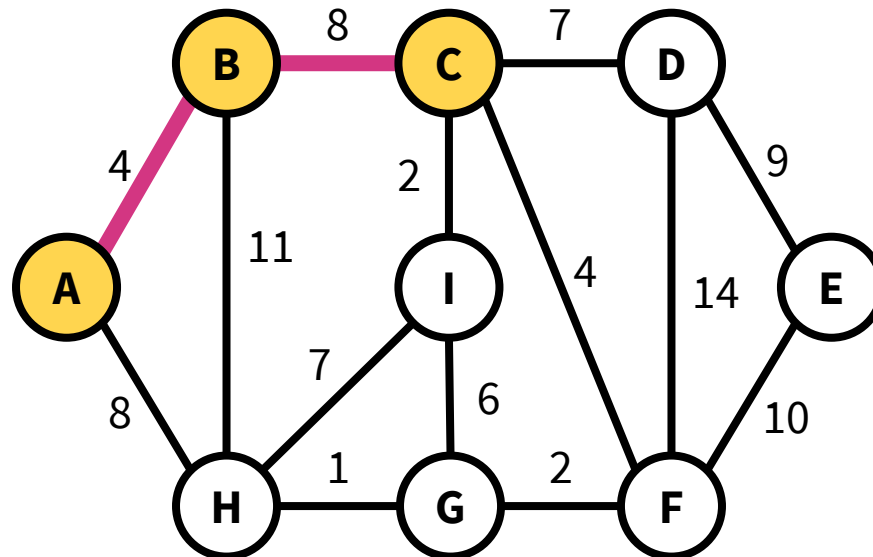
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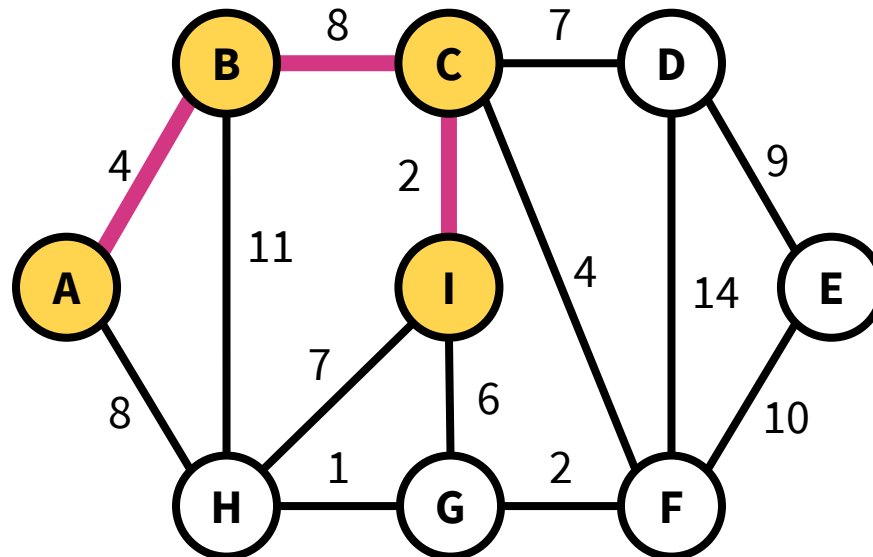
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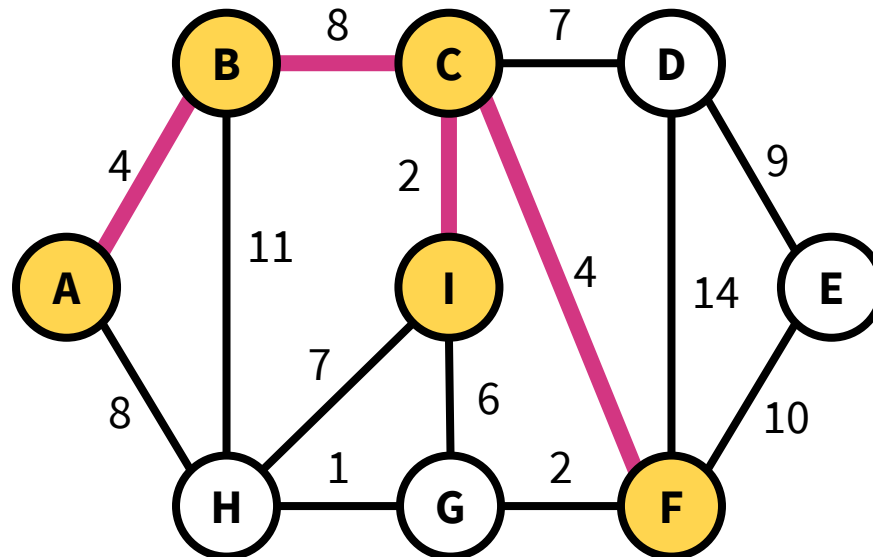
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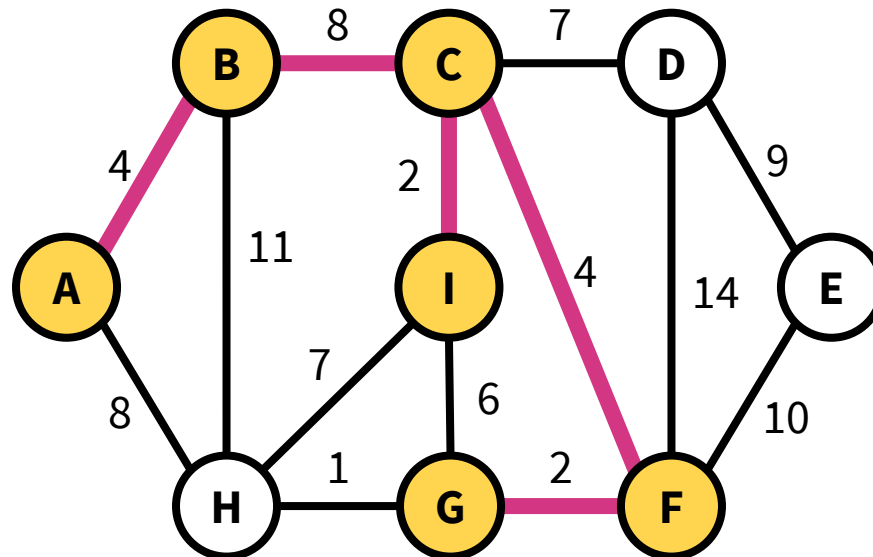
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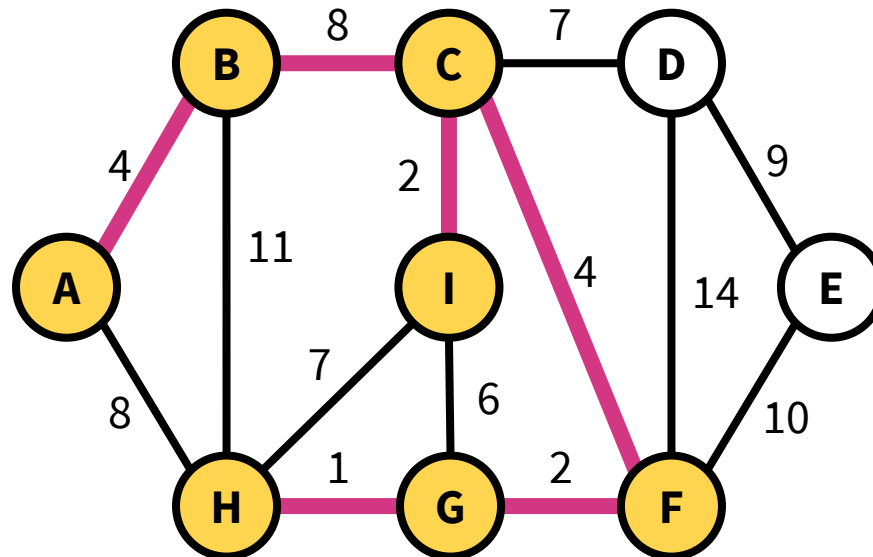
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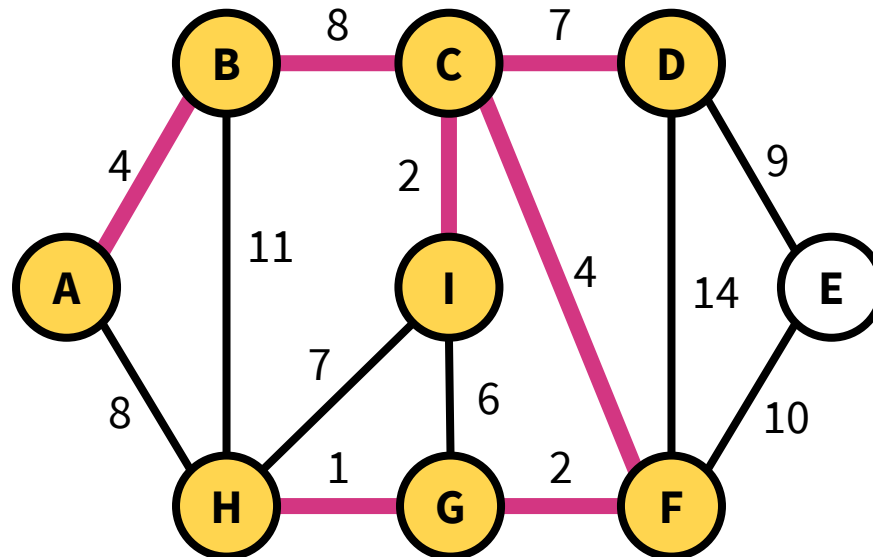
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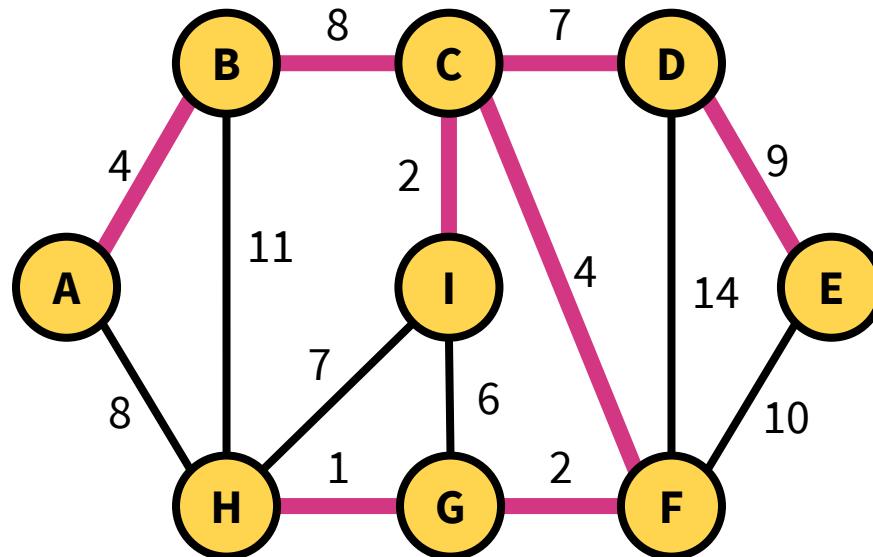
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**Runtime:**  $O(|V| \cdot |E|)$

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# Proving Feasibility

**Theorem:** `prim` finds a feasible spanning tree.

**Proof:**

To prove this statement, we prove the loop invariant: MST contains edges of a spanning tree of the vertices in `visited_vertices`.

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At the termination of the loop, `visited_vertices` contains all of the vertices, so MST contains a spanning tree over the entire graph. ■

# Proving Optimality

Recall our lemma:

Consider a cut that respects a set of edges  $A$ , such that there's an MST  $T$  containing  $A$ , and a light edge  $(u, v)$  not in  $T$ .

**Lemma:** There exists an MST containing  $A \cup \{(u, v)\}$ .

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Consider a cut that respects a set of edges  $A$ , such that there's an MST  $T$  containing  $A$ , and a light edge  $(u, v)$  not in  $T$ .

**Lemma:** There exists an MST containing  $A \cup \{(u, v)\}$ .

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After adding the the  $(n-1)^{st}$  edge, we have a spanning tree; therefore,  $MST$  contains a minimum spanning tree. ■

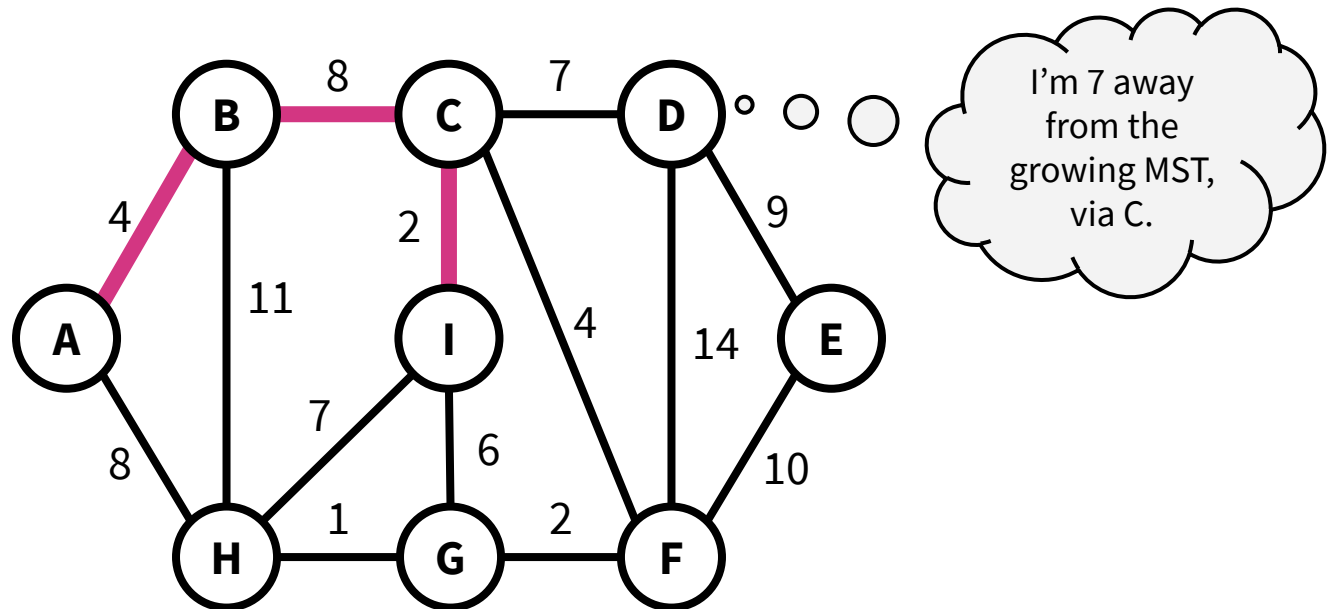


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# Prim's Algorithm

We called the algorithm `slow_prim`. There's a more efficient implementation.

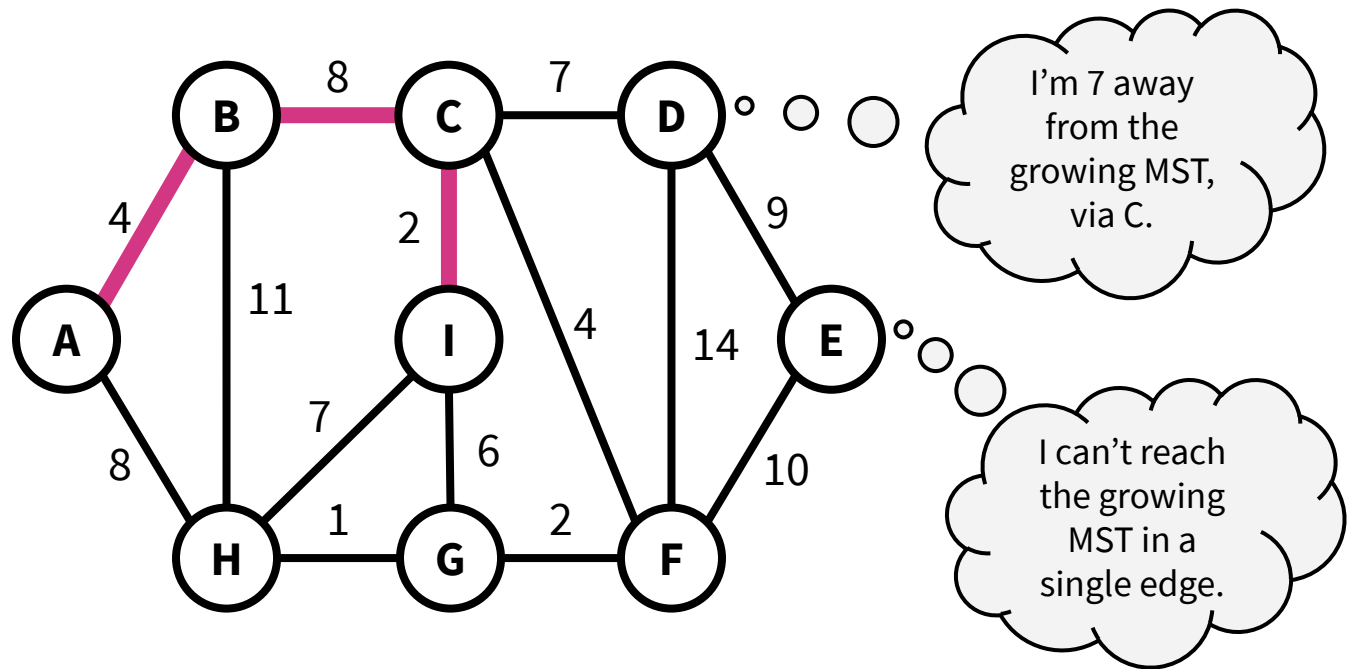
**Main idea:** vertices maintain information about the distance from itself to the growing spanning tree (if one edge away) and how to get there.



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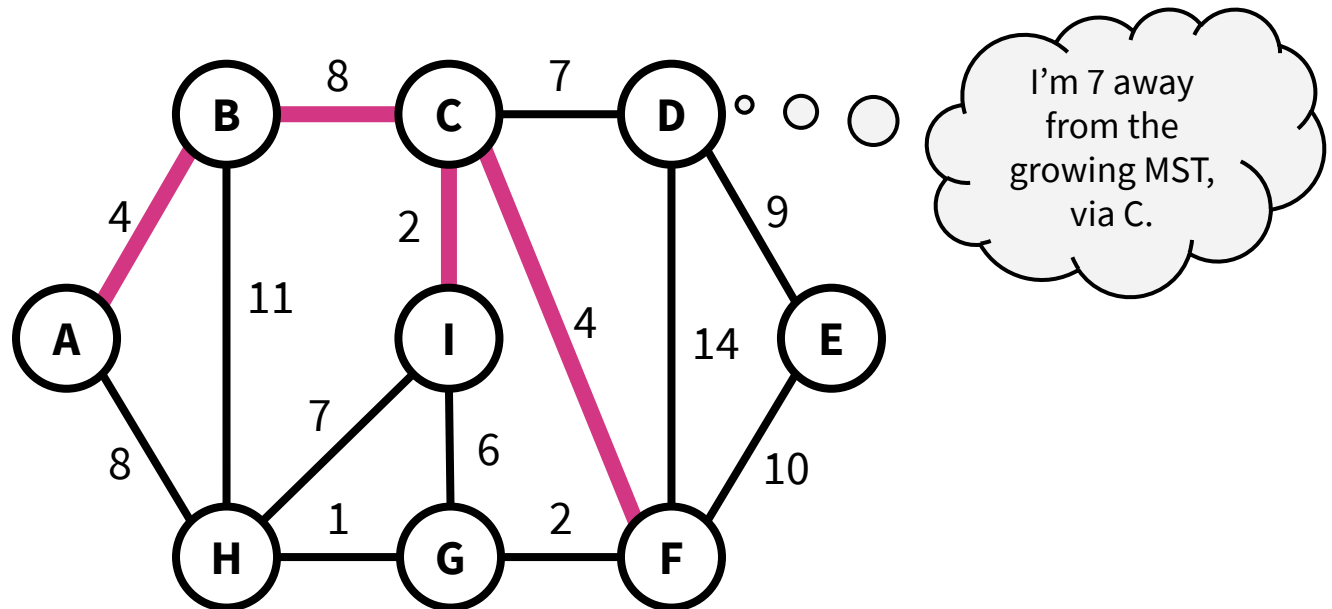
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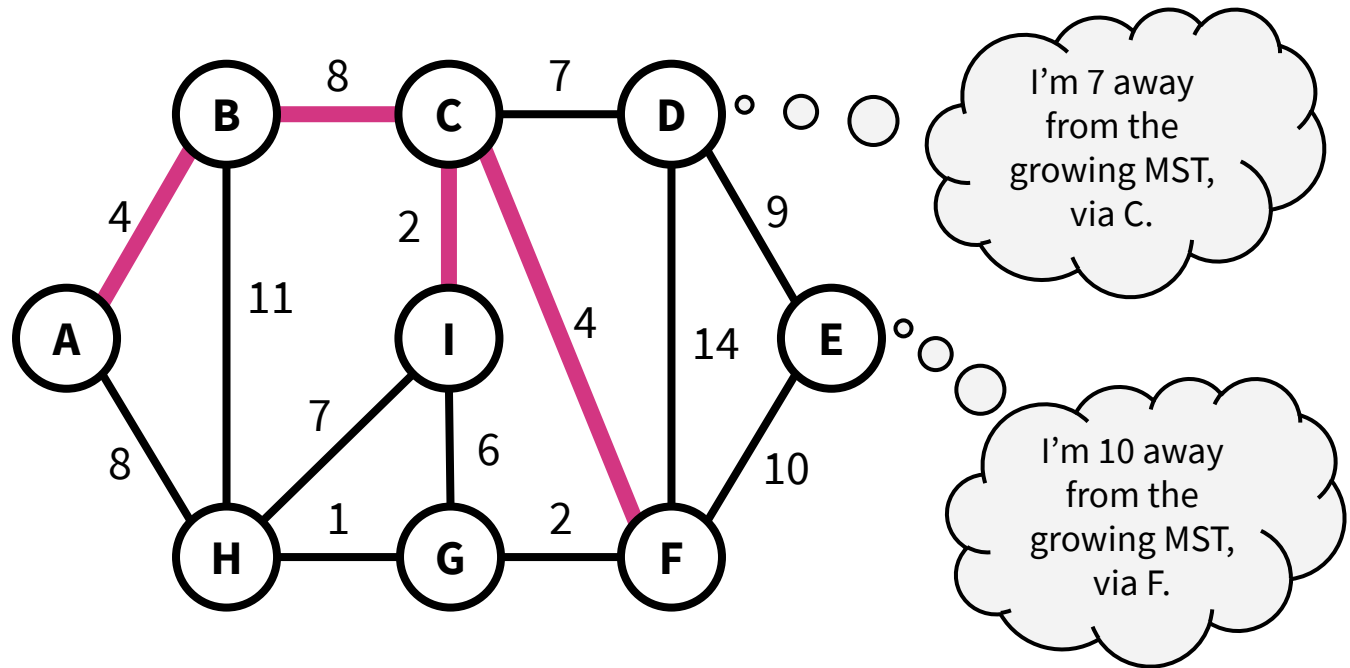
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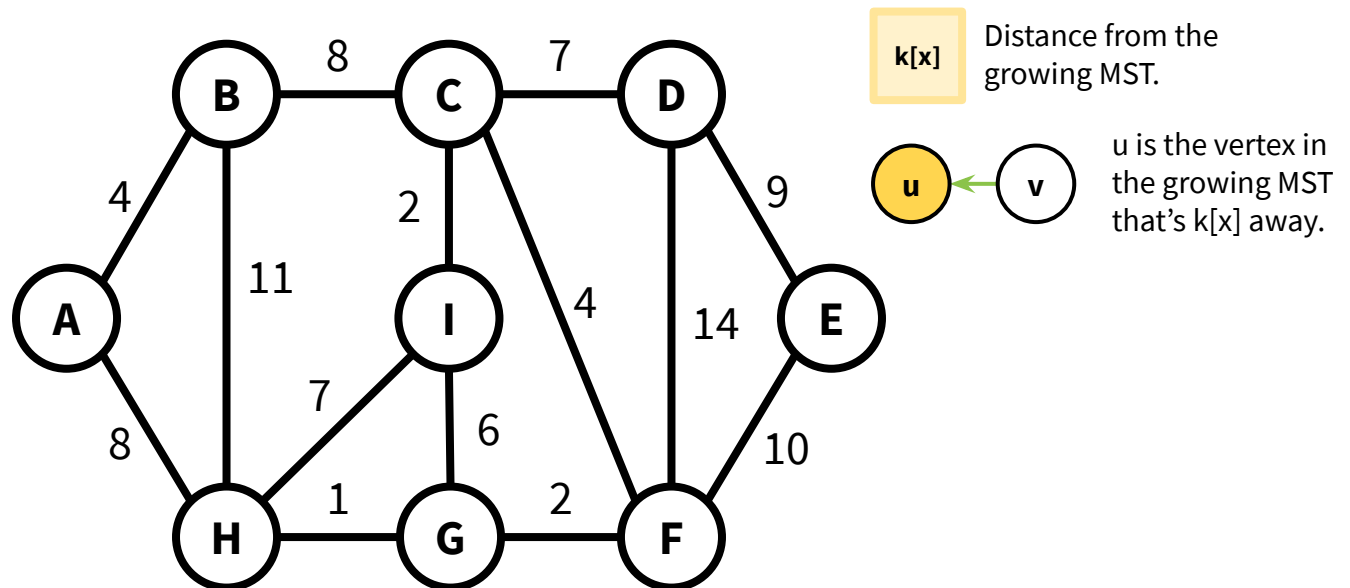
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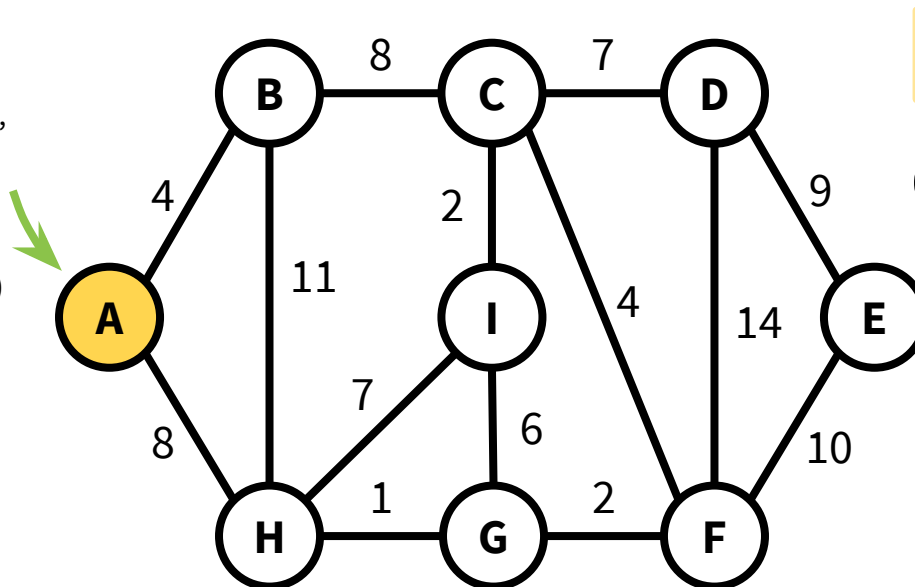


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In addition to visiting A,  
update information of  
its neighbors with:

for  $v$  in  $u$ .neighbors:  
 $k[v] = \min(k[v], w(u, v))$

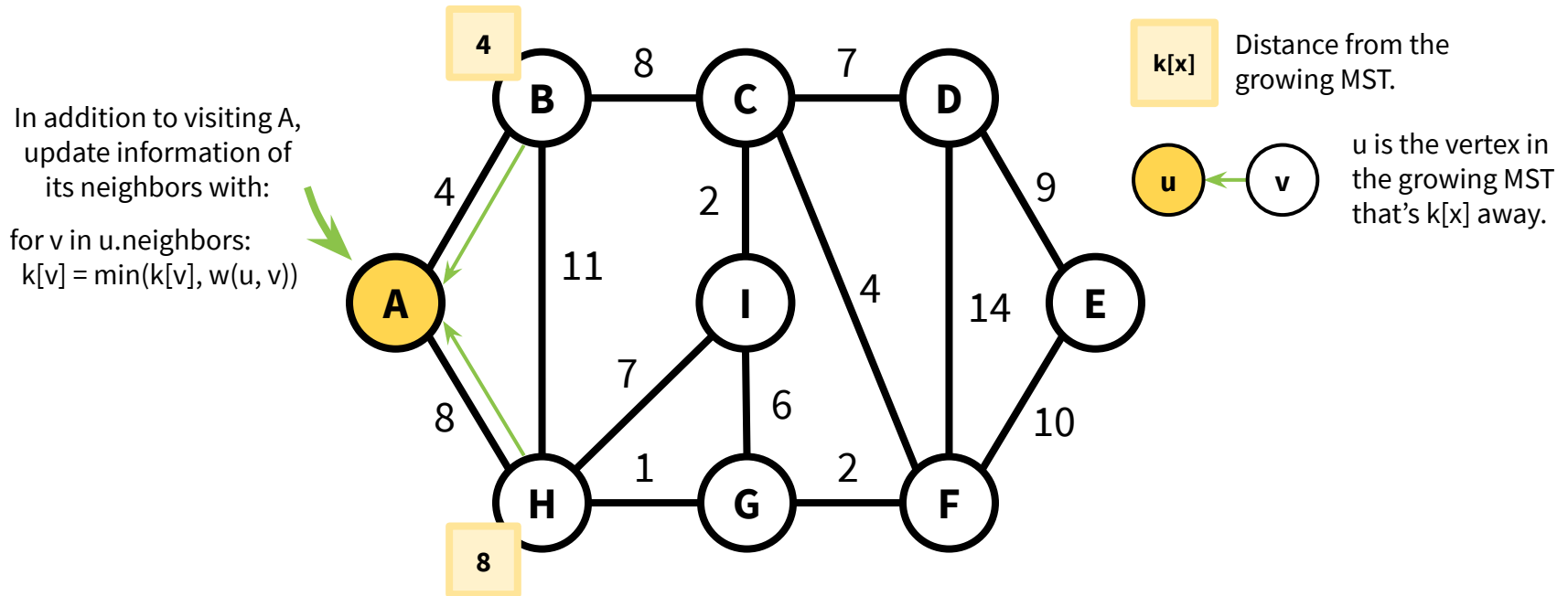


$k[x]$  Distance from the  
growing MST.

$u$   $\leftarrow$   $v$   $u$  is the vertex in  
the growing MST  
that's  $k[x]$  away.

# Prim's Algorithm

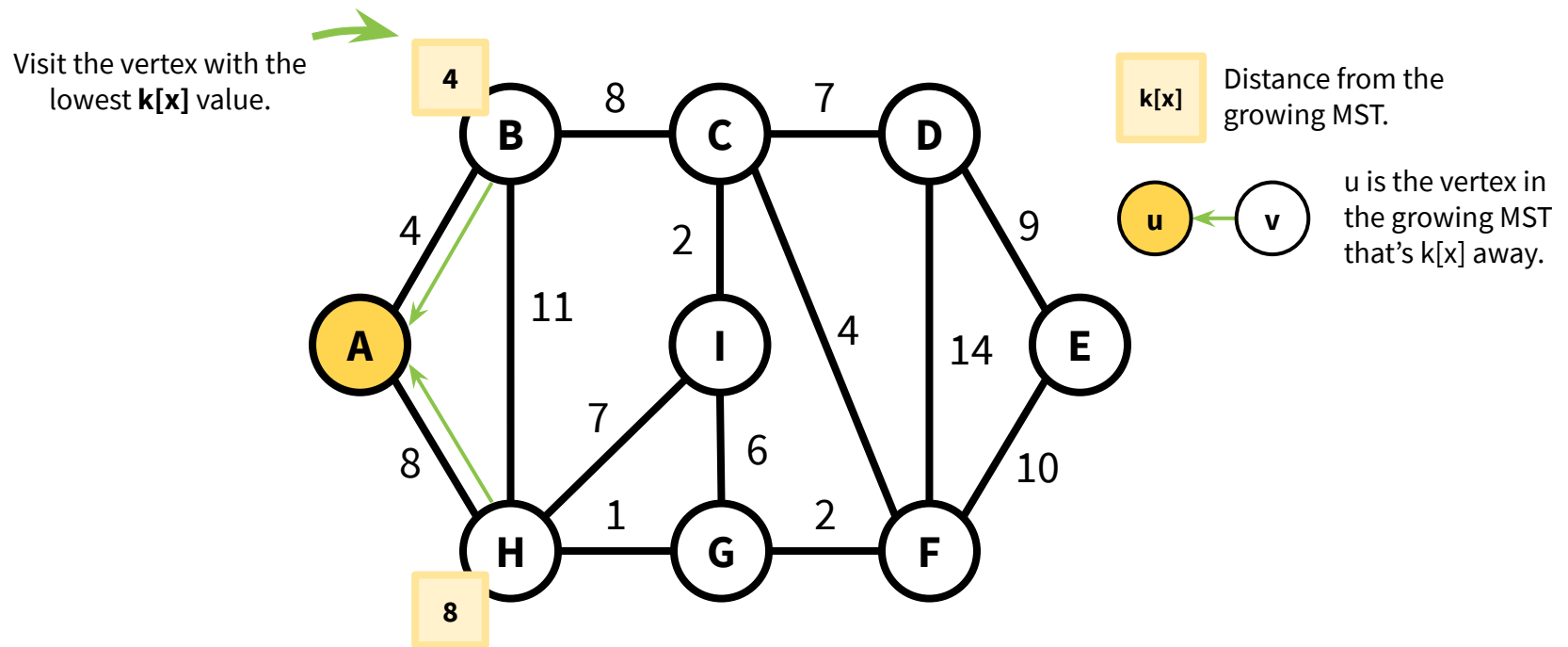
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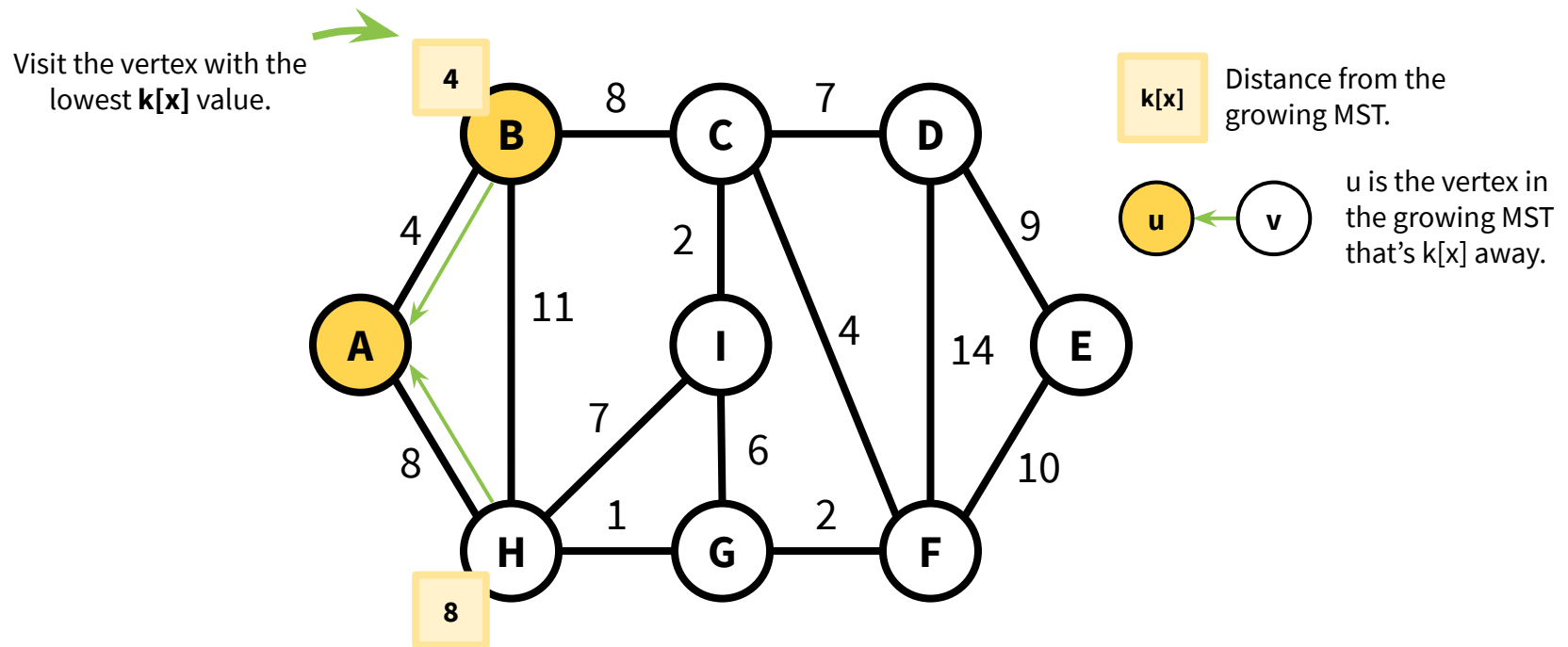
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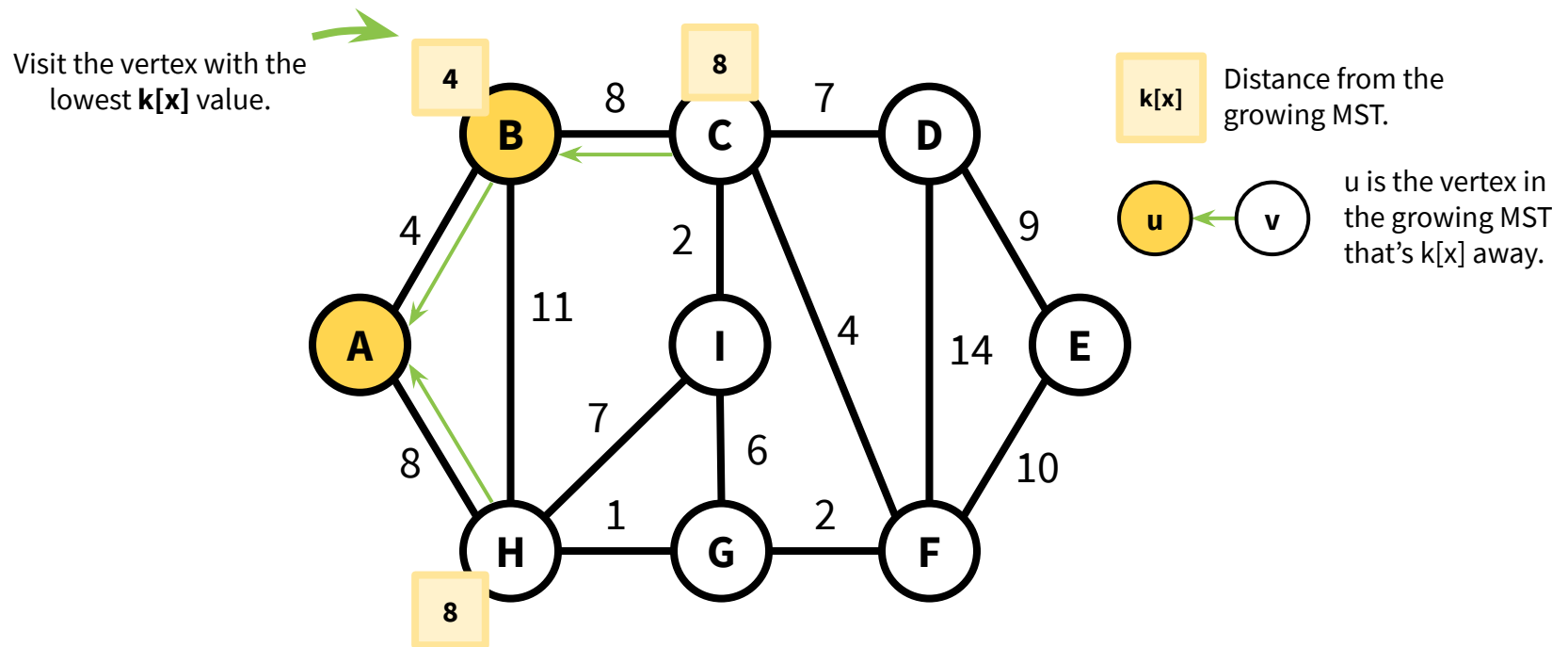
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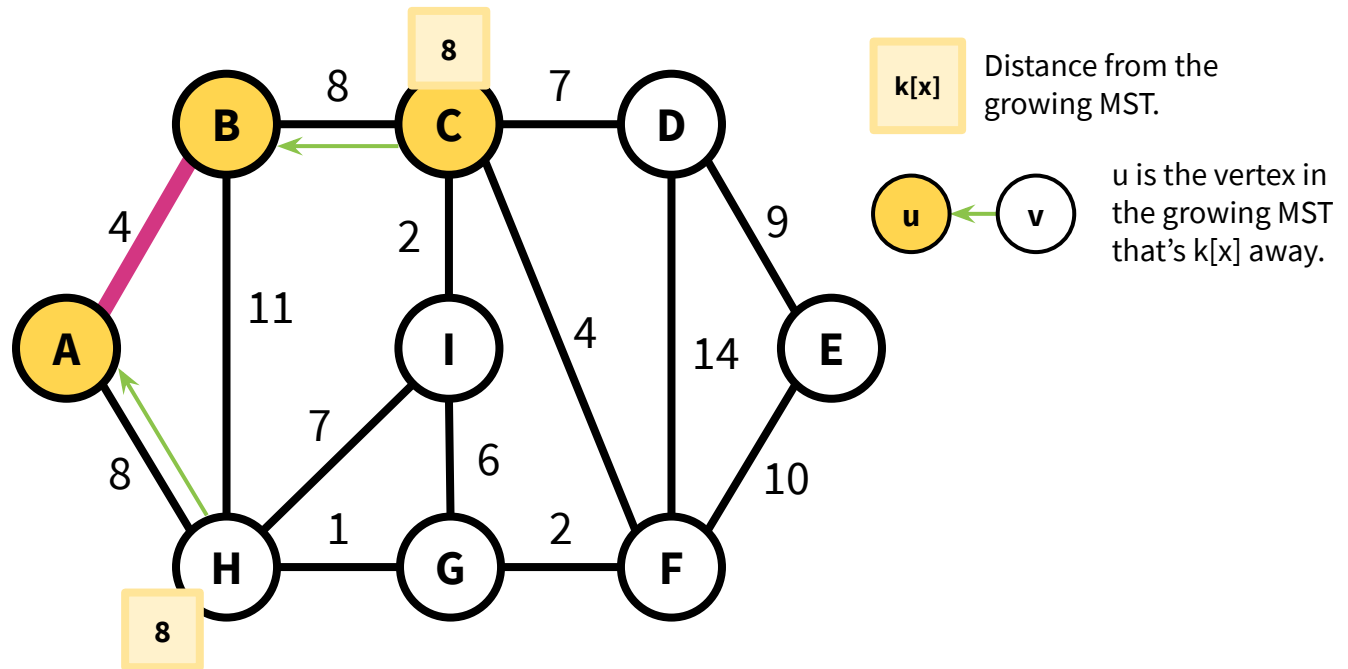
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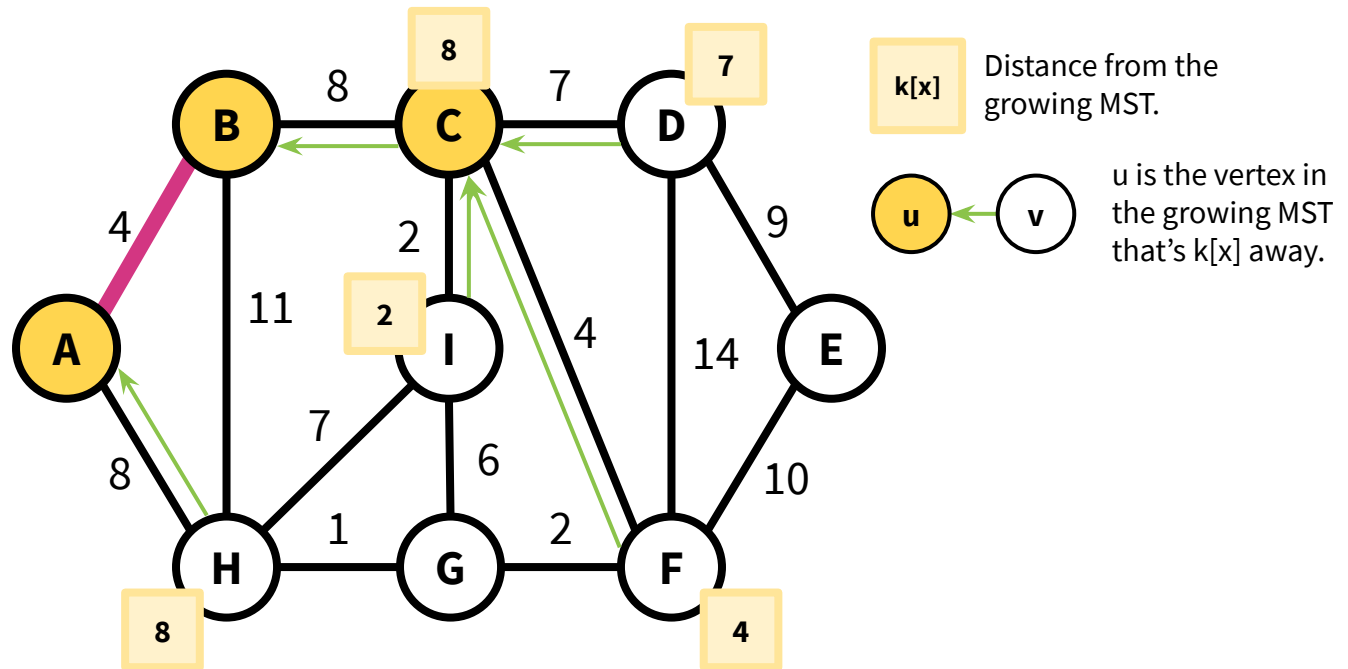
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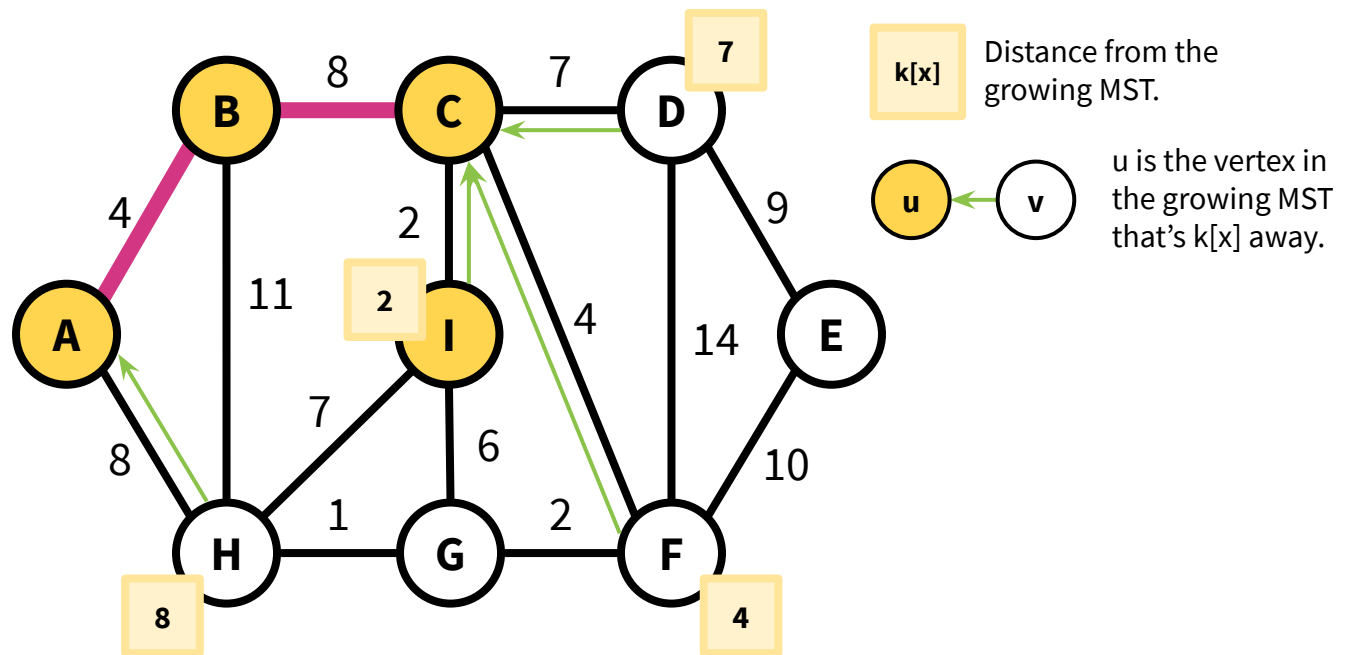
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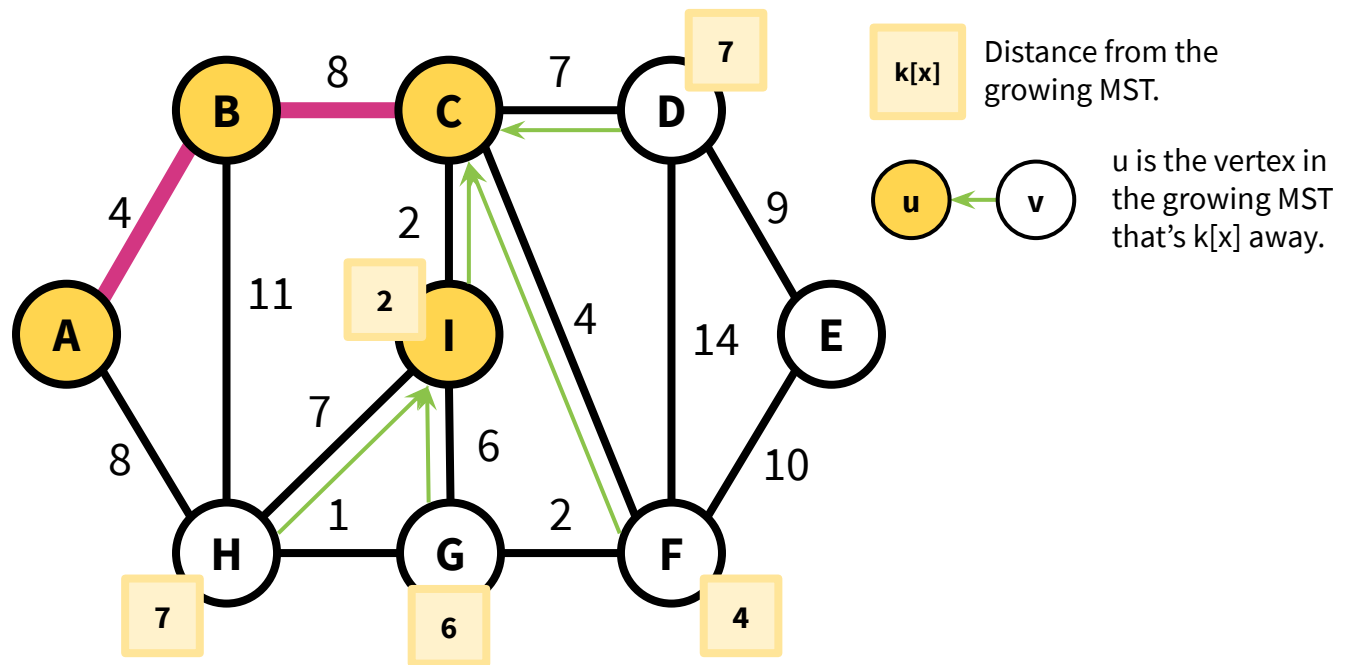
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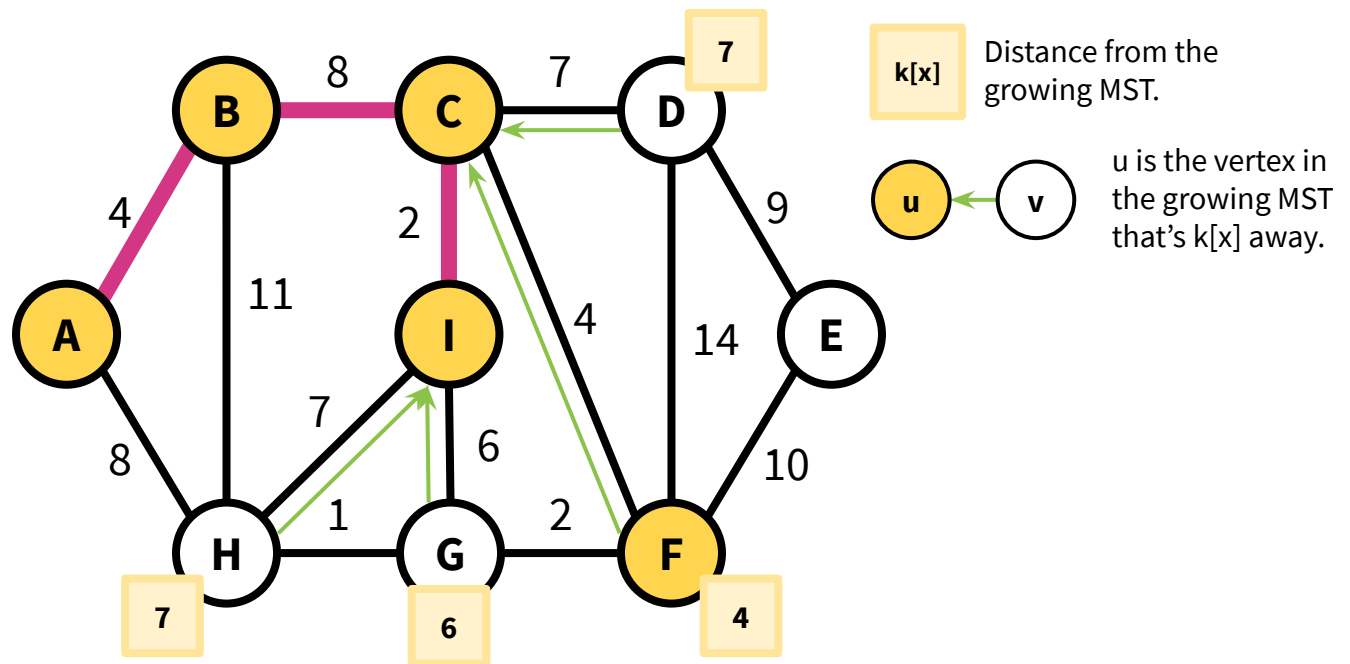
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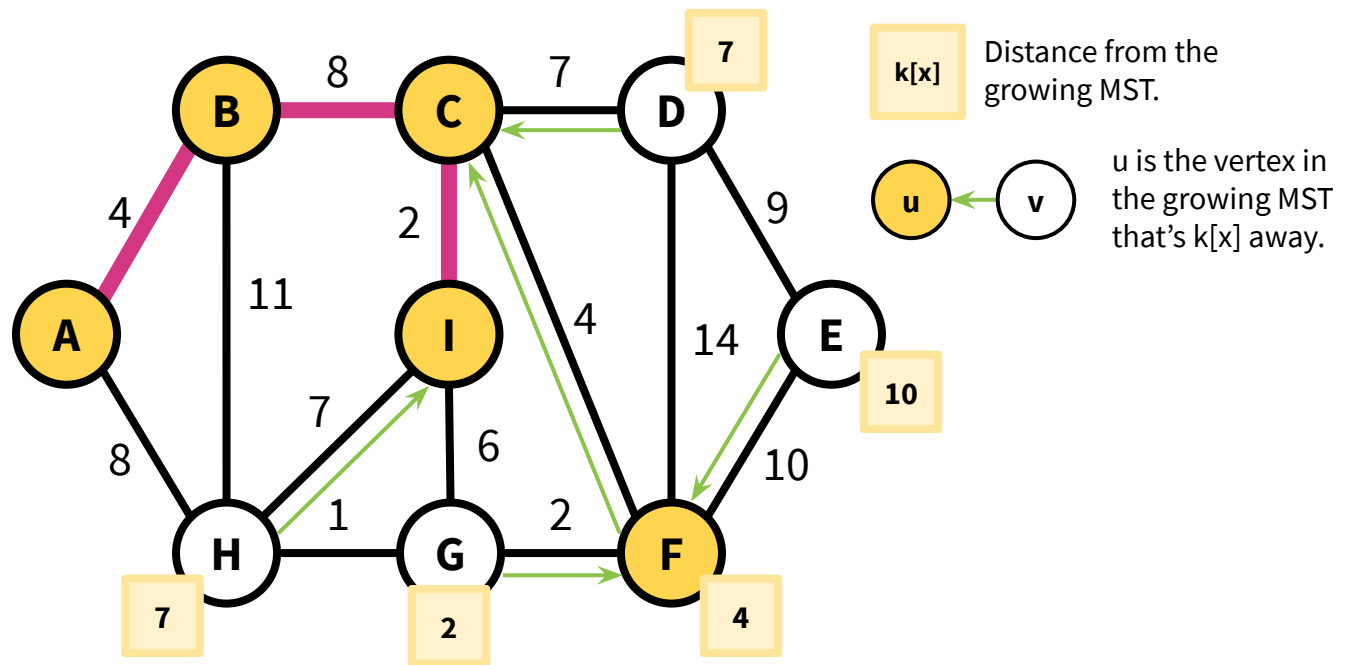
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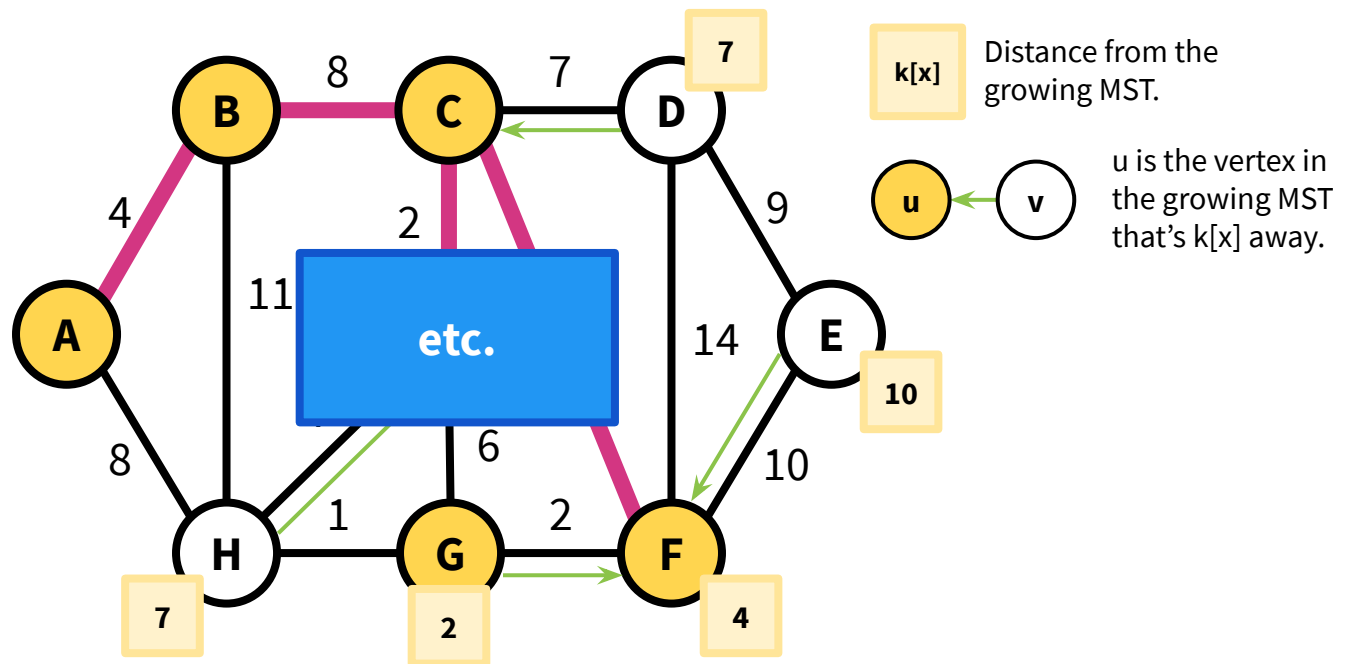
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# Prim's Algorithm

```
def prim(G):  
    s = random vertex in G  
    MST = {}  
    visited_vertices = {s}   
    update_info(G, s)  
    while |visited_vertices| < |V|:  
        (x, v) = lightest_edge(G, visited_vertices)  
        MST.add((x, v))  
        visited_vertices.add(v)  
        update_info(G, v)  
    return MST
```

Updates  
information about  
distance from the  
growing MST.

## Runtime:

$O(|E| \log(|V|))$   Using a red-black tree  
as a priority queue

$O(|E| + |V| \log(|V|))$   Using a fibonacci heap