#### **PART 10: Introduction to Feedback**

### **Summary**

- We have developed a device electrical 'model' (hybrid-pi)
- Used this to analyse amplifier configurations: CE, CC, CB, CE-ED, Diff. Amp
- Looked at dc biasing techniques for IC based circuits current mirrors, current sources
- Analysed the frequency response of amplifiers using equivalent circuits
  - $_{\text{-}}$   $f_{\text{T}}$
  - $A_V(f)$
  - High-bandwidth configurations: CB, Cascode
- Field effect transistors can use similar approaches but the model is different!
- Step response of an amplifier (time response)

#### Second half is concerned with **FEEDBACK**

- What is negative feedback?
  - o What happens when it is applied to an amplifier: (Also covered in Control Systems!)

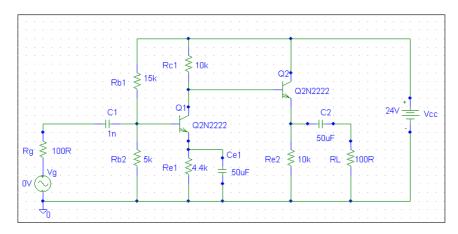
Q: Why is NF important?

A: Because transistors are such 'poor' components'

- what does poor mean??

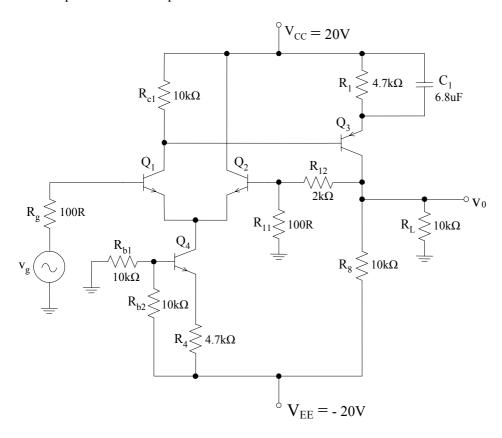
## Negative Feedback allows us to build precision amplifiers using cheap components

An example of a poor amplifier is shown below. Note the forward signal path. The results in the table indicate unacceptable performance if the circuit parameters are changed  $(\beta, R_L, R_g)$ .



| Circuit Parameters |                                  | Initial | β       | β      | $\mathbf{R}_{\mathrm{L}}$ up | R <sub>g</sub> up |
|--------------------|----------------------------------|---------|---------|--------|------------------------------|-------------------|
|                    |                                  | Values  | doubled | halved |                              |                   |
|                    | $\beta_1$                        | 100     | 200     | 50     | 100                          | 100               |
|                    | $\beta_2$                        | 100     | 200     | 50     | 100                          | 100               |
|                    | $R_{L}$                          | 100     | 100     | 100    | 1k                           | 100               |
|                    | $R_g$                            | 100     | 100     | 100    | 100                          | 1k                |
| Results            | $A_{v} = v_{o}/v_{g}$            | - 161   | - 214   | -106   | -312                         | -105              |
|                    | %<br>change<br>in A <sub>v</sub> | -       | +33%    | -34%   | +94%                         | -35%              |

An example of a better amplifier is shown below.



Note again the forward signal path and FEEDBACK path via feedback resistors  $R_{fl}$ ,  $R_{f2}$ . (Don't worry about the details of the circuit operation at the moment – we will look at this later – just note the improvement in performance...).

|                           | Initial<br>Value | β x2   | β /2   | Altered<br>Values | $R_{g}$ |        | Altered<br>Values | $R_{\rm L}$ |        |
|---------------------------|------------------|--------|--------|-------------------|---------|--------|-------------------|-------------|--------|
| 0                         |                  | 200    | 50     |                   | 100     | 100    |                   | 100         | 100    |
| $\beta_1$                 | 100              | 200    | 50     | 100               | 100     | 100    | 100               | 100         | 100    |
| $oldsymbol{eta_2}$        | 100              | 200    | 50     | 100               | 100     | 100    | 100               | 100         | 100    |
| $\beta_3$                 | 100              | 200    | 50     | 100               | 100     | 100    | 100               | 100         | 100    |
| $R_{g}$                   | 100              | 100    | 100    | 1k                | 10k     | 100k   | 100               | 100         | 100    |
| $R_{\rm L}$               | 10k              | 10k    | 10k    | 10k               | 10k     | 10k    | 100M              | 1k          | 100    |
| $\mathbf{A}_{\mathbf{V}}$ | 20.81            | 20.90  | 20.63  | 20.78             | 20.44   | 15.74  | 20.84             | 20.57       | 18.41  |
| %                         | -                | +0.43% | -0.86% | -0.14%            | -1.78%  | -24.4% | +0.14%            | -1.15%      | -11.5% |
| change                    |                  |        |        |                   |         |        |                   |             |        |

As you can see, changing the  $\beta$  values has now, little effect on the gain and as long as the source,  $R_g$  doesn't get too big (larger than 10k), or the load,  $R_L$  too small, then the gain is nearly constant at 20.8 ( $\pm 2\%$  say). Note that this is quite a small gain however, compared to the previous example. This is the **trade-off** we have made – better **stability** has been achieved at the expense of gain.

BUT, changing the feedback resistors  $R_{\rm fl}$ ,  $R_{\rm f2}$  DOES alter the gain.

**Conclusion:** using negative feedback makes gain more stable to changes of components in the FORWARD signal path and allows us to set gain to any required value (within reason!) by altering components in the FEEDBACK path.

### **Advantages of Negative Feedback**

- 1. Negative feedback reduces the <u>sensitivity</u> of the gain on parameters of amplifier such as transistor current gain.
- 2. Negative feedback allows us to set gain to any value we want.
- 3. Negative feedback increases the <u>bandwidth</u> of the amplifier.
- 4. Negative feedback reduces <u>distortion</u>
- 5. Negative feedback allows us to adjust the <u>input</u> and <u>output</u> impedances of an amplifier.

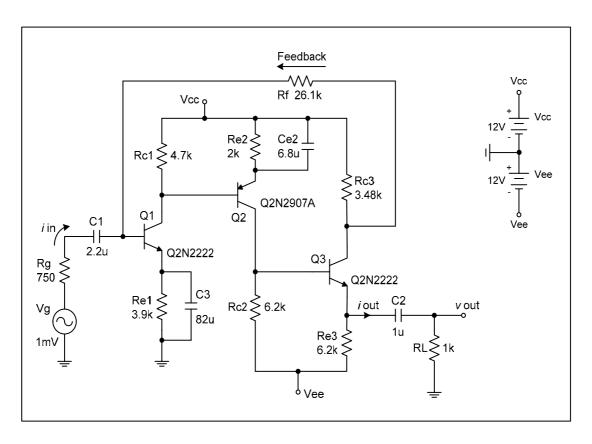
BUT these advantages do not come FREE!

## **Disadvantages of Negative Feedback**

- 1. Negative feedback <u>always</u> reduces the gain of an amplifier.
- 2. Over certain frequency ranges, it can be that negative feedback changes from <u>negative</u> to <u>Positive</u> with catastrophic results. Positive feedback <u>increases</u> gain of the amplifier may be converted to an <u>oscillator</u> no longer any use as an amplifier

Part 11: Introduction to Feedback - II

2<sup>nd</sup> example of an Amplifier with feedback – consider the circuit below.



Another Example: Current Amp

|                            | Initial Values | $\beta s$ doubled | Changing $R_g$ |      |      | Changing $R_L$ |      |          |
|----------------------------|----------------|-------------------|----------------|------|------|----------------|------|----------|
| $\beta_1$                  | 100            | 200               | 11             | 100  | 100  | 100            | 100  | 100      |
| $B_2$                      | 100            | 200               | 100            | 100  | 100  | 100            | 100  | 100      |
| $B_3$                      | 100            | 200               | 100            | 100  | 100  | 100            | 100  | 100      |
| $R_g$                      | 750            | 750               | 1k             | 2k   | 10k  | 750            | 750  | 750      |
| $R_{\scriptscriptstyle L}$ | 1k             | 1k                | 1k             | 1k   | 1k   | 100            | 6.2k | $\infty$ |
| $A_{v} = v_{o} / v_{in}$   | 9.85           | 9.81              | 7.39           | 3.69 | 0.74 | 1.1            | 35.4 | 70.6     |

Results for  $A_V = \frac{v_O}{v_{in}}$  are <u>poor</u> compared with example in previous lecture (part 10).

## What has gone wrong?!

Consider a <u>different</u> type of gain – the <u>current gain</u> of the amplifier defined as  $A_i = \frac{i_0}{i_m}$ 

| $A_i = i_o / i_{in}$ | 8.58 | 8.54 | 8.58 | 8.58 | 8.58 | 8.58 | 8.58 | 8.57 |
|----------------------|------|------|------|------|------|------|------|------|

The results show that for this type of gain, the stability to changes in parameters is good.

Q: what makes this amplifier keep  $A_i$  stable while in previous circuit  $A_V = \frac{v_O}{v_{in}}$  = was kept stable??

Answer is basically the <u>way</u> in which feedback is applied! To answer the question properly we must look at:

#### Different types of amplifier

1) Voltage Amp 
$$A_{v} = \frac{v_{o}}{v_{in}}$$

2. Current Amp 
$$A := \frac{i_o}{i_g}$$

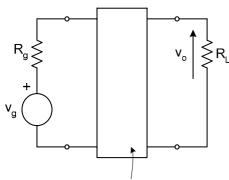
3. Transresistance Amp 
$$A_r = \frac{v_o}{i_g}$$
 (Measured in ohms)

4. Transconductance Amp 
$$A_g = \frac{i_o}{v_{in}}$$
 (Measured in Siemens)

Feedback can only stabilise one of these gains.

## **Ideal Amplifiers**

What makes these amplifiers different? When is it possible to describe an amplifier as a voltage amplifier rather than say a current amplifier?



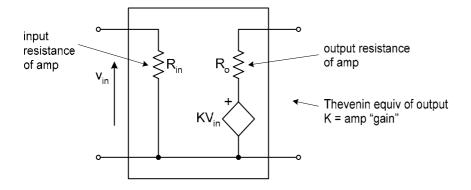
This is supposed to be a voltage amp

This is supposed to be a voltage amp but how do I tell? What we expect from a good voltage amplifier is that the overall voltage gain  $\frac{v_o}{v_g}$  from source to load should not vary

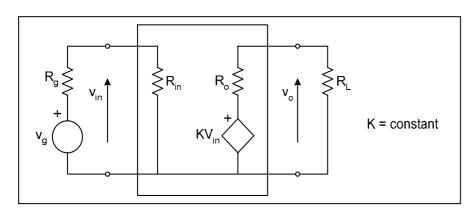
too much with changes in  $R_g$  and  $R_L$  - ideally not at all. So experimentally we could change  $R_g$  and  $R_L$  and see if voltage gain remains const. – if it does we have a good voltage amplifier

# Q: What makes a good voltage amplifier?

Ans: An amplifier will be a good voltage amplifier if its equivalent circuit looks like the model below, with  $R_{in}$  BIG and  $R_{o}$  SMALL.



### **Proof:**



$$v_{o} = \frac{R_{L}}{R_{o} + R_{L}} K v_{in}$$

$$v_{in} = \frac{R_{in}}{R_{in} + R_{g}} v_{g}$$

$$\therefore \frac{v_{o}}{v_{g}} = A_{v} = \frac{R_{L}}{R_{o} + R_{L}} K \frac{R_{in}}{R_{in} + R_{g}}$$

$$\rightarrow K \text{ if } R_{o} \text{ is small and } R_{in} \text{ is BIG}$$

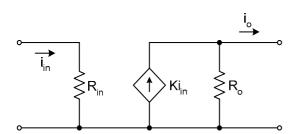
So  $A_{\nu}$  doesn't depend on  $R_{g}$  and  $R_{L}$  as required.

**Conclusion:** Ideal voltage Amp has  $R_{in} = \infty$ , and  $R_o = 0$ .

### **Current amps**

How do we recognise? -  $\frac{i_o}{i_{in}}$  should NOT change with changes in  $R_g$  and  $R_L$ 

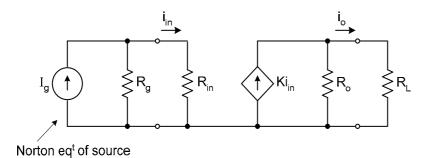
Equivalent circuit:



Note we use Norton equivalent now since dealing with currents.

To make a good current amp:  $R_{in}$  should be **small** and  $R_o$  should be **big** 

Let's look at the model:



$$i_o + \frac{R_o}{R_o + R_L} K i_{in} ; \quad i_{in} = \frac{R_g}{R_g + R_{in}} i_g$$

$$\therefore i_o = \frac{R_o}{R_o + R_L} K \frac{R_g}{R_g + R_{in}} i_g$$

$$\therefore \text{ current gain } \frac{i_o}{i_g} = \frac{R_o}{R_o + R_L} \quad K \quad \frac{R_g}{R_g + R_{in}} \quad \rightarrow \quad K$$

$$\text{If } R_{in} = 0 \text{ and } R_o = \infty$$

### Homework

Can  $\underline{you}$  generate the equivalent circuits for a good transresistance amplifier and a good transconductance amplifier? What values should  $R_{in}$  and  $R_{out}$  have  $\underline{ideally?}$