Distributed Systems COMP 212

Lecture 10

Othon Michail



Breadth-First Search and Construction of a BFS Tree

So Far

- Broadcast from a root u_0 given a spanning tree
- Broadcast without a spanning tree but again from a root u₀
- Leader election in special networks
- Leader election in general networks, knowing the diameter D

• Question: Can we still solve these without any assumptions but unique ids?

Broadcast without a given Spanning Tree

Problem:

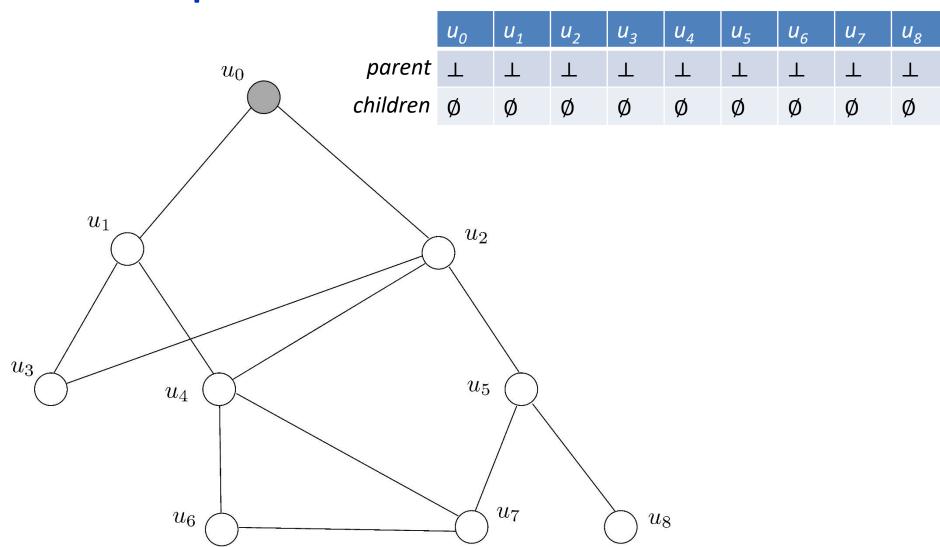
- u₀ has some information it wishes to send to all processors
 - e.g., a message $\langle M \rangle$
 - additionally all nodes must have terminated in the end
- No spanning tree of the network G is given in advance
- The algorithm should also output a constructed spanning tree of G

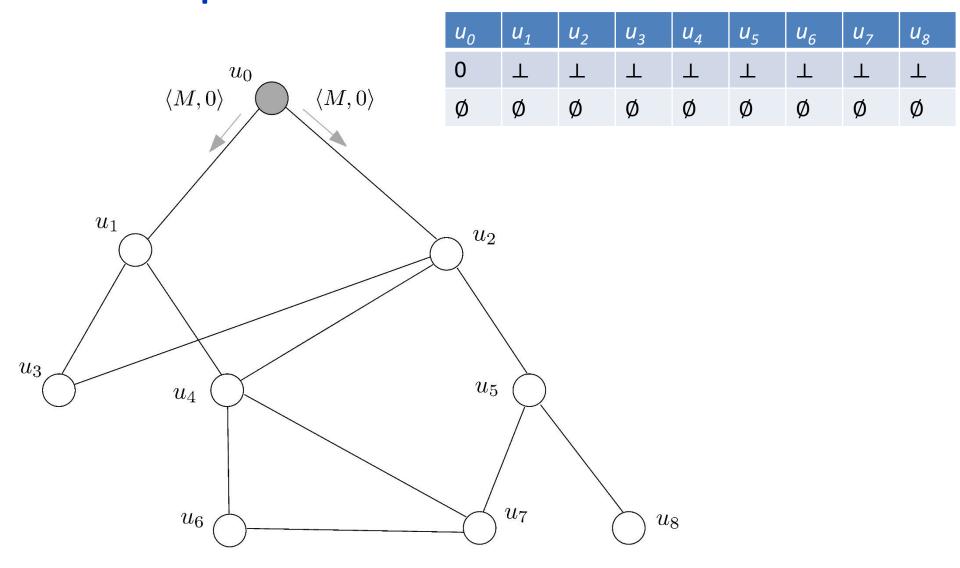
Solution: Informal description

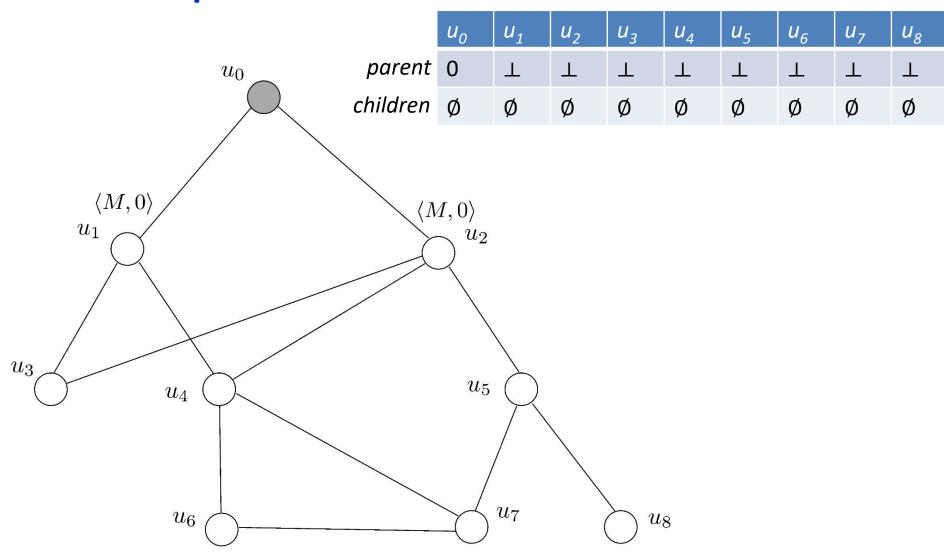
- All nodes awake initially
- If awake and have just received (M) from some neighbours,
 - Choose one of those neighbours as your parent and let him know
 - forward $\langle M \rangle$ to the rest of the neighbours
 - Wait for 1 round to collect children (if any) and then sleep
- If neighbours inform you that you are their parent,
 - add those processors to your children list
 - sleep
- If you are asleep, do nothing

Solution: Pseudocode

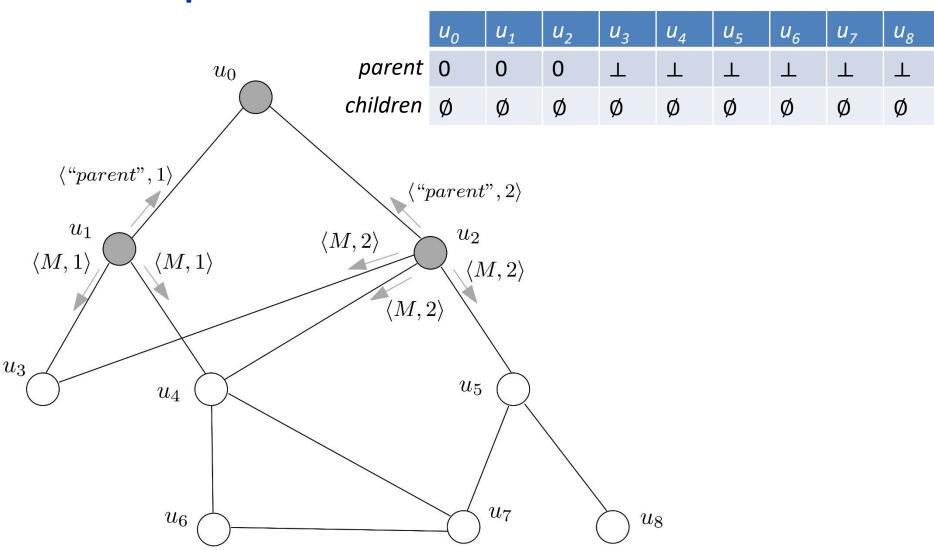
```
Algorithm Broadcast & Spanning tree construction
Code for processor u_i, i \in \{0, 1, ..., n - 1\}:
Initially parent = \perp and children = \emptyset
if u_i = u_0 and parent = \perp then
                                          // root has not yet sent (M)
  send (M) to all neighbours
  parent := u_i
upon receiving (M) from neighbours N:
  if parent = \bot then
                                            // u_i has not received (M) before
    parent := u_i \in N
                                            // select one arbitrarily as parent
    send ("parent") to u_i
    send \langle M \rangle to all neighbours except those in N
    wait for one round to collect children if any and then terminate
  else terminate
upon receiving ("parent") from neighbours N:
  add all u_i \in N to children
  terminate
```

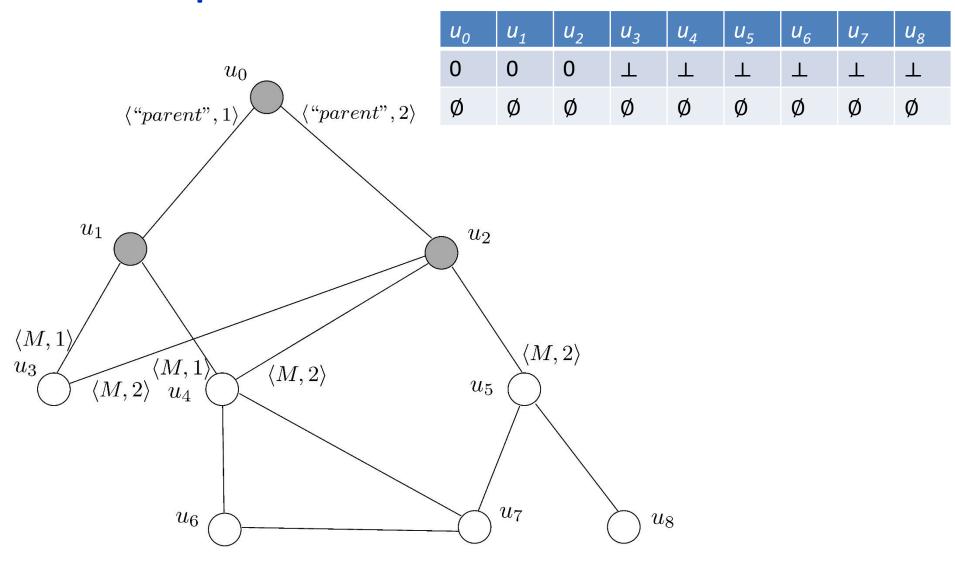




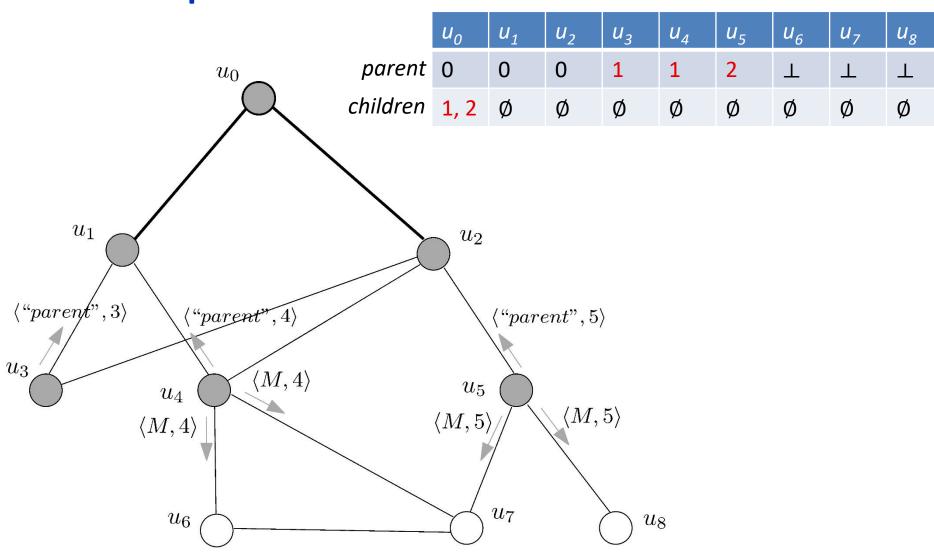


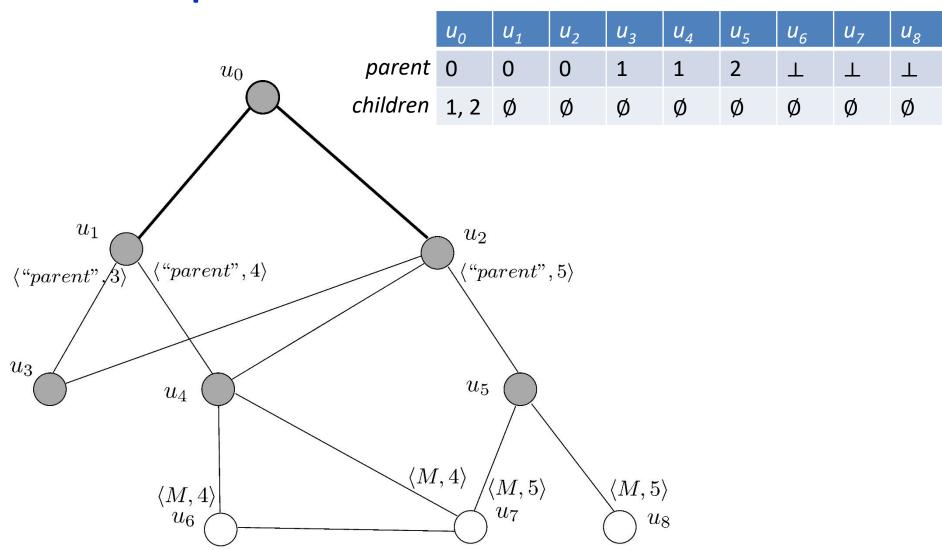
round = 2

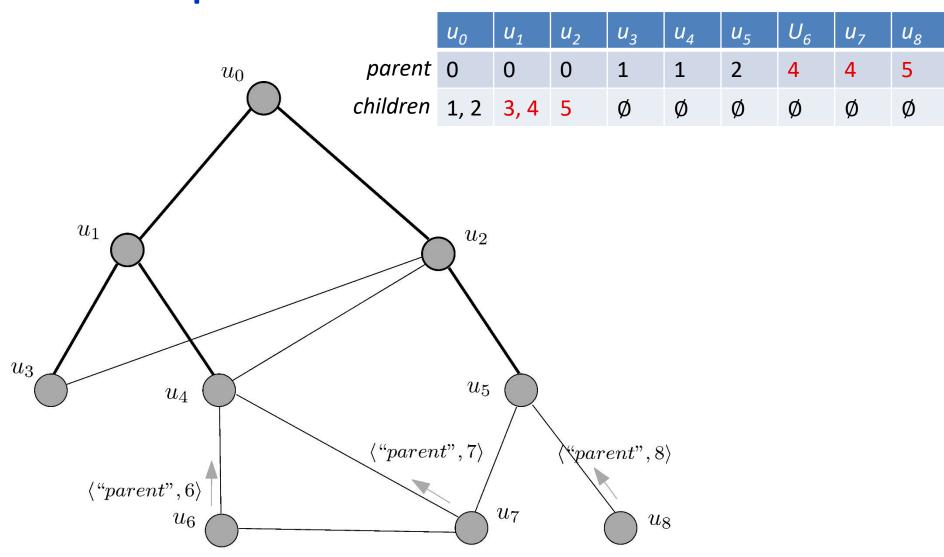




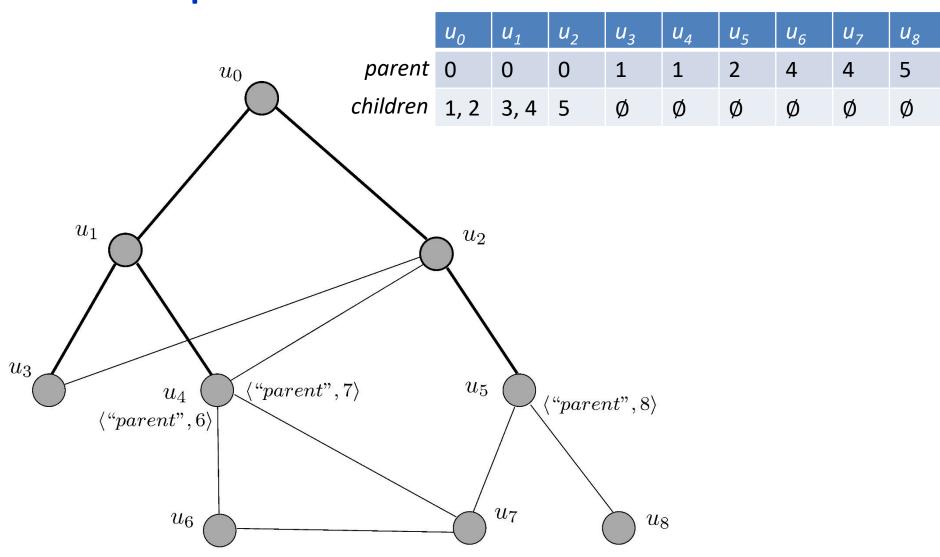
round = 2



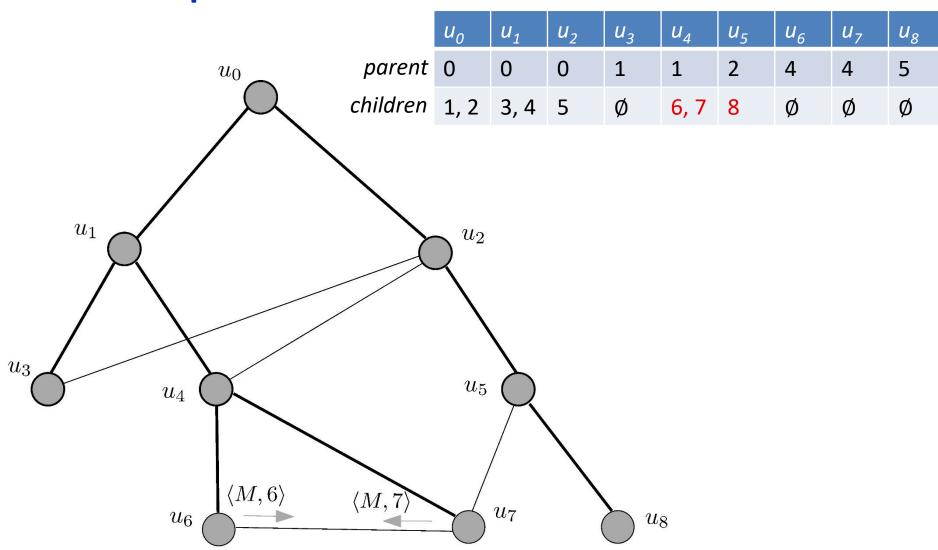




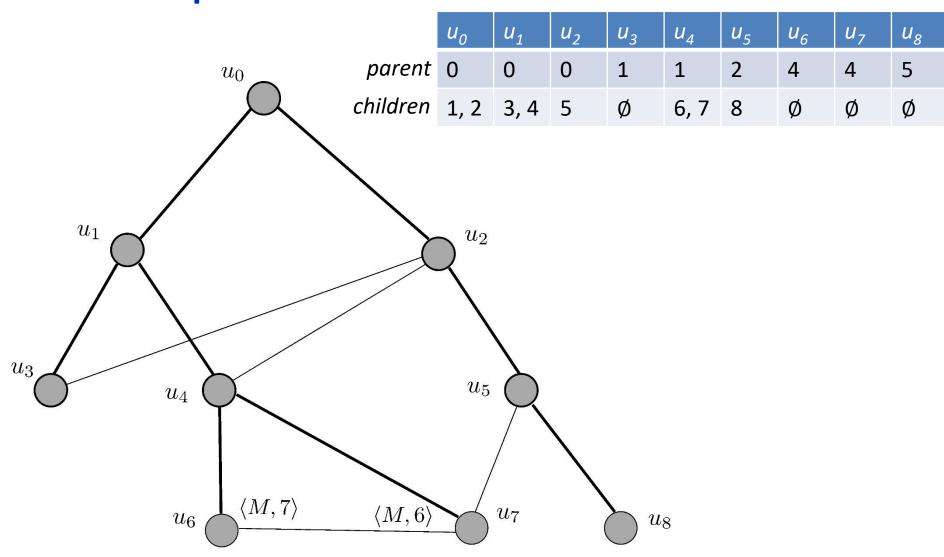
round = 4



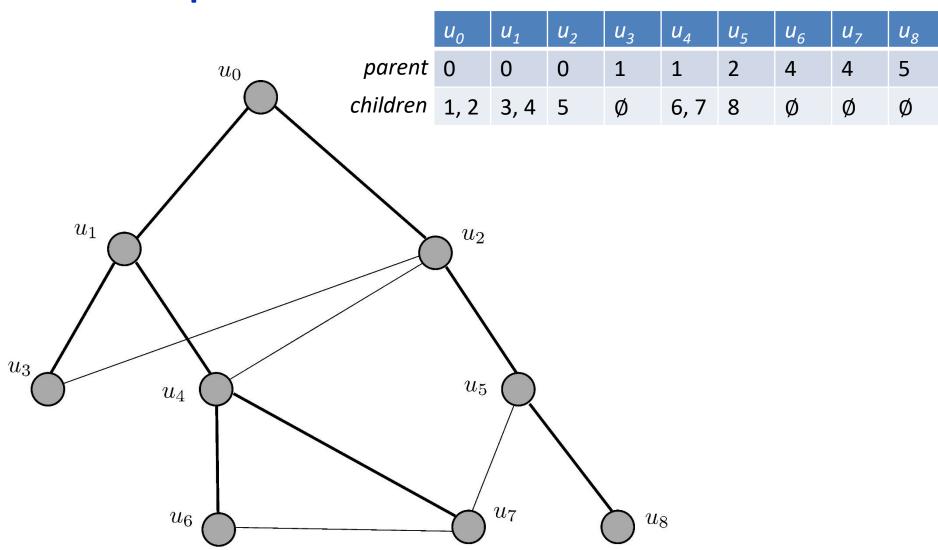
round = 4

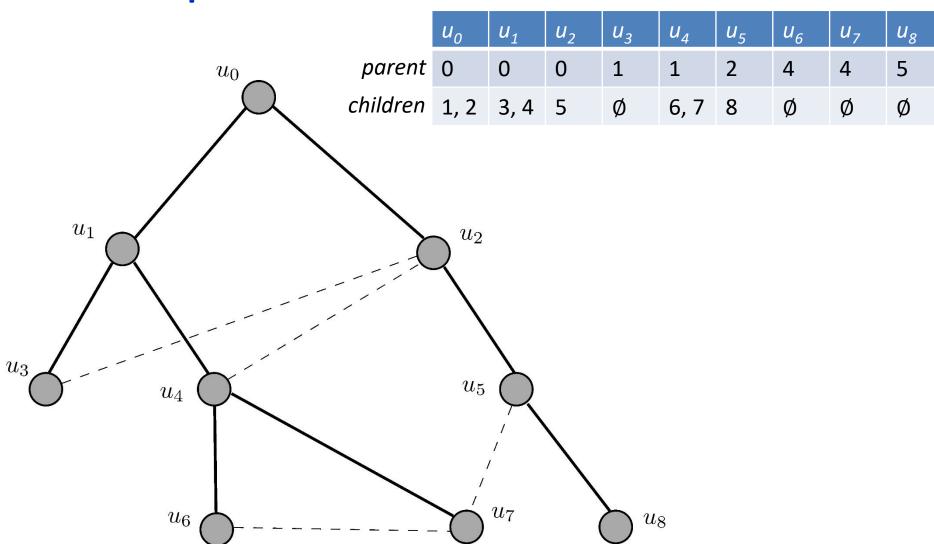


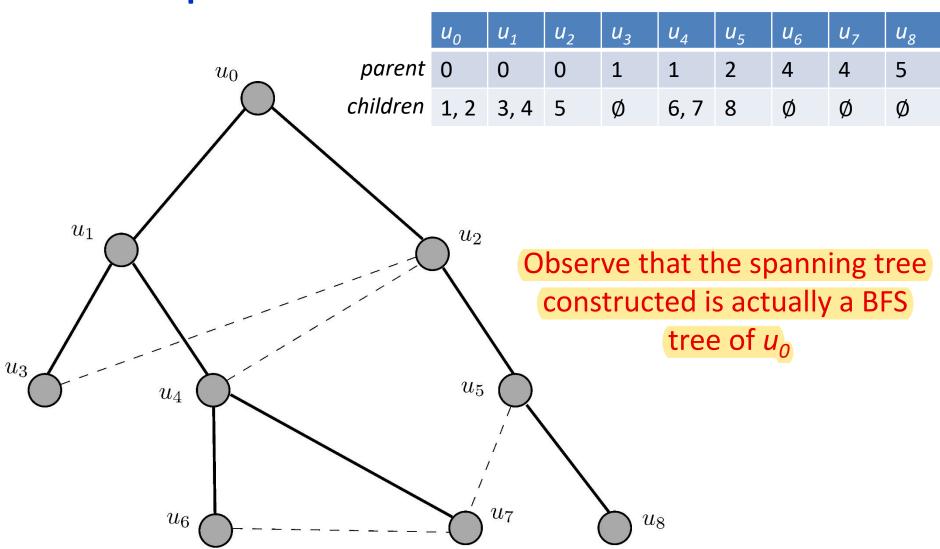
round = 5



round = 5







Beyond a Predetermined Root

- But the previous algorithm essentially requires a predetermined root u_0
 - $-u_0$ starts and ends the BFS/Broadcast
 - All other processors simply "follow" whenever they receive information that has originated at u_0
- But in a "truly" distributed system we may not have such a u_0
- Question: Can we drop this assumption?
- That is, can we construct a single BFS (spanning) tree, with a designated root despite the fact that initially no such root exists?

Beyond a Predetermined Root

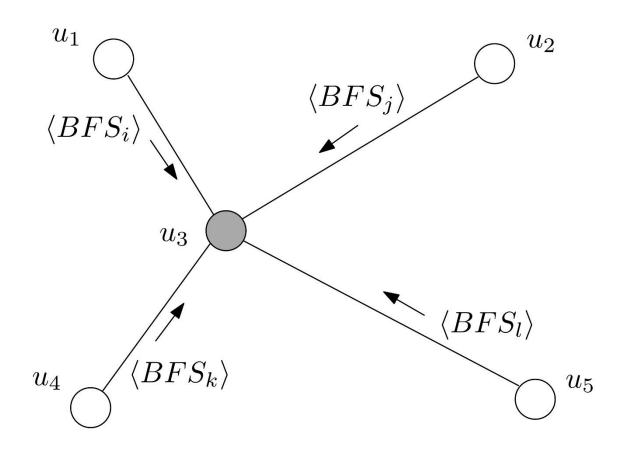
- Can we construct a single BFS (spanning) tree, with a designated root despite the fact that initially no such root exists?
- Yes we can!

All in Parallel

- Main idea: Each processor pretends to be the root and initiates its own BFS/broadcast
- So, initially n BFSs start in parallel
- To avoid "interference", each root broadcasts its unique id
- But how does an "internal" node of one or more BFSs (which btw is also the root of its own BFS) chooses what to store and forward?

All in Parallel

 But how does an "internal" node chooses what to store and forward?



Two Main Approaches

- Store and forward "everything"
- Store and forward only the BFS of the root with the maximum id (among those heard so far)

1. Everything

Main Idea:

- All nodes transmit initially their id to all their neighbours
- Every node u that receives a (rootID) message from neighbours v_i,
 - Sets one of those, call it v, as its parent in the T_{RootID} tree
 - Responds ("parent", rootID) to v
 - Forwards (rootID) to all its neighbours apart from v
- Upon receipt of ("parent", rootID) from neighbours
 - Add those neighbours to your children_{RootID} list

1. Everything

- Therefore, every processor
 - Is the root of its own tree
 - Will be a non-root node in n 1 other processors'
 trees
 - Has to also play the role of an internal or leaf node in
 n 1 other trees
- Does this by
 - maintaining for each such tree one parent variable (parent_{rootID}) and one children variable (children_{rootID})
 - forwarding in every round all information that needs to be forwarded for every such tree (all in parallel)

2. Maximum Prevails

Main Idea:

- A node always maintains and forwards the information related to a single tree
 - despite the fact that many such trees are trying to evolve in parallel
 - the tree of the root with the maximum id from those heard so far is preferred

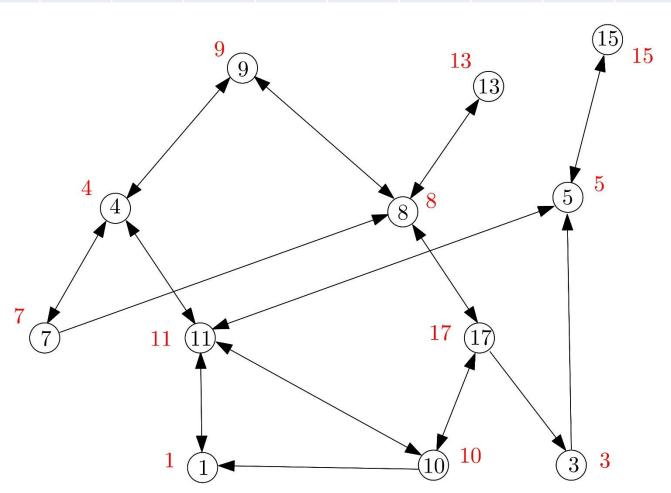
Pseudocode

upon receiving ("parent") from neighbours N:

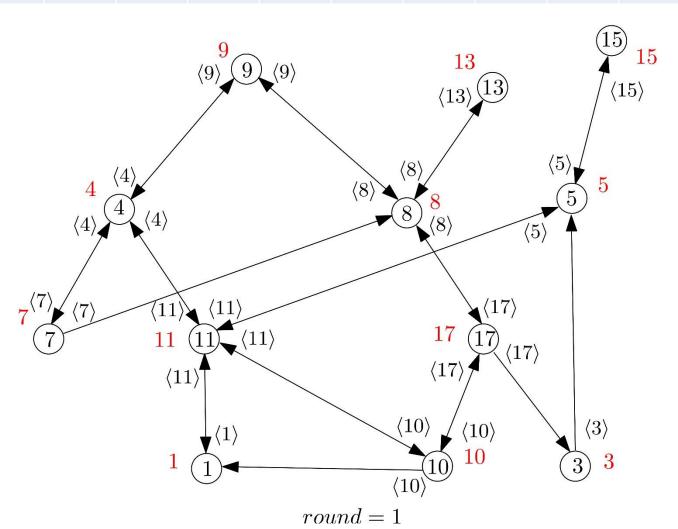
add all $u_i \in N$ to *children*

```
Algorithm MaxBFS
Code for processor u_i, i \in \{0, 1, ..., n - 1\}:
Initially parent = \perp, children = \emptyset, maxRoot := myID, root := true
if round = 1 then // all trees start
  send \langle myID \rangle to all neighbours
  parent := myID
upon receiving \langle rootID_i \rangle from neighbours N:
  if maxRoot < max<sub>i</sub>{rootID<sub>i</sub>} then
                                                        // u_i hears of a new prevailing root
     if root := true then root := false
     maxRoot := max_i \{rootID_i\}
     parent := u \in N where u just sent \max_{i} \{rootID_{i}\} // select one of those that sent
     children := Ø // get rid of previous children
                                                                  // the max, arbitrarily as parent
     send \langle"parent"\rangle to u
     send (maxRoot) to all neighbours except those from which you just received it
   else do nothing
```

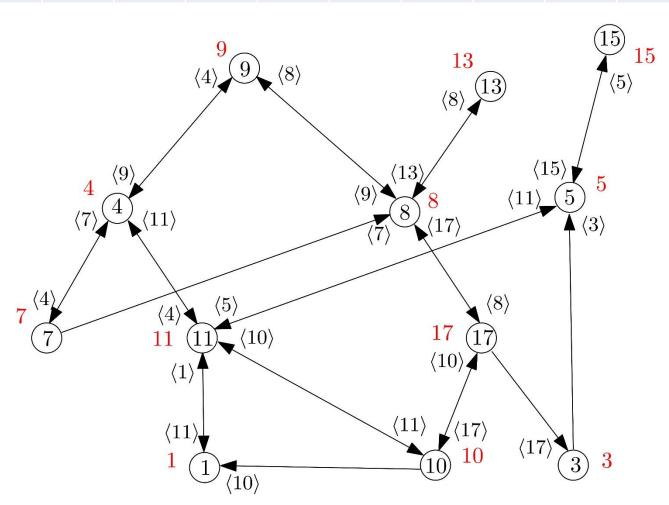
1	3	4	5	7	8	9	10	11	13	15	17
Τ	Τ	Τ	Τ	Т	Т	Τ	Τ	Τ	Τ	土	工
Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø



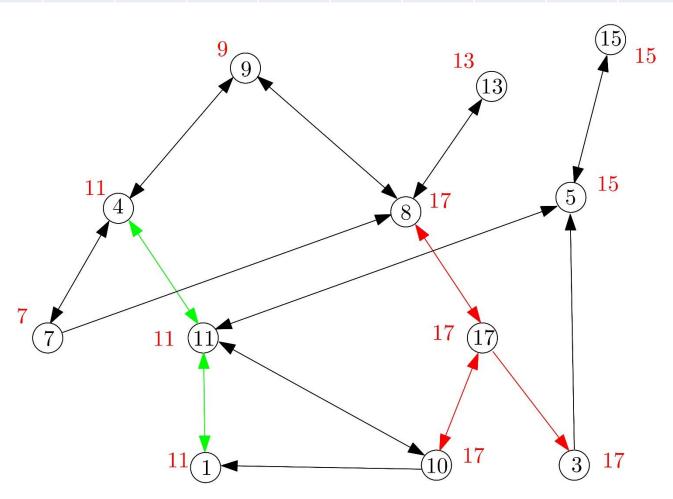
1	3	4	5	7	8	9	10	11	13	15	17
1	3	4	5	7	8	9	10	11	13	15	17
Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø



1	3	4	5	7	8	9	10	11	13	15	17
1	3	4	5	7	8	9	10	11	13	15	17
Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø

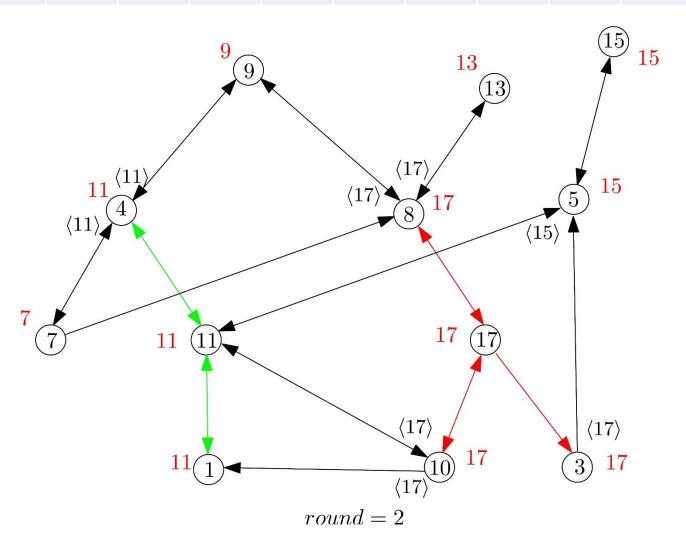


1	3	4	5	7	8	9	10	11	13	15	17
11	17	11	15	7	17	9	17	11	13	15	17
Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø

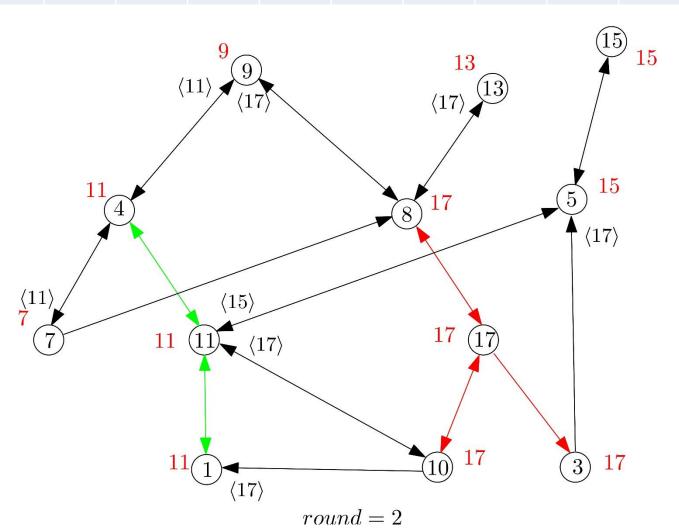


parent children

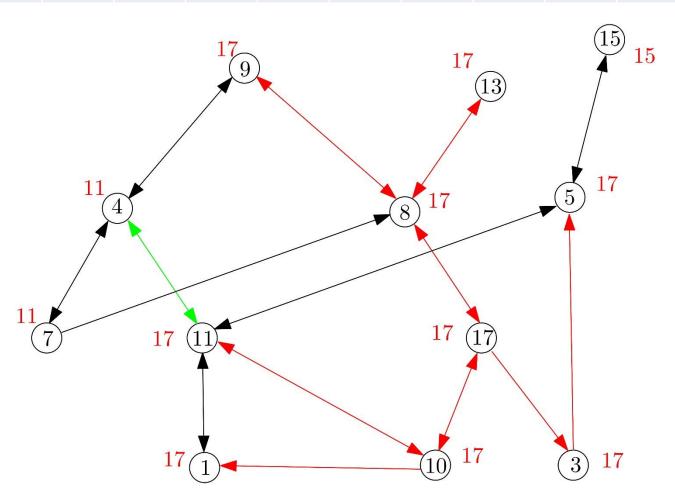
	1	3	4	5	7	8	9	10	11	13	15	17
	11	17	11	15	7	17	9	17	11	13	15	17
1	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø



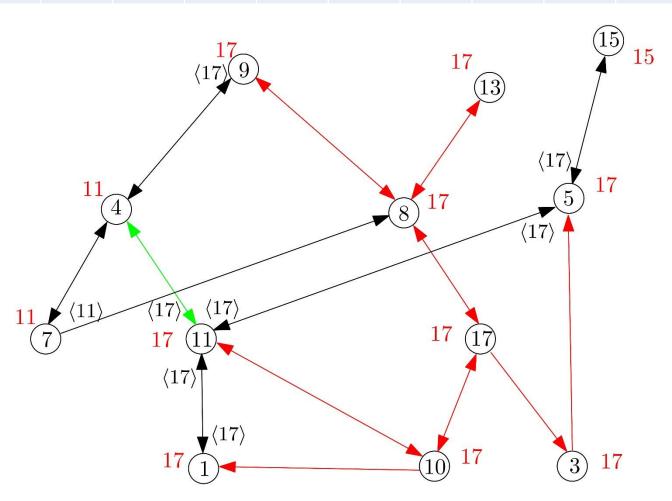
1	3	4	5	7	8	9	10	11	13	15	17
11	17	11	15	7	17	9	17	11	13	15	17
Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø



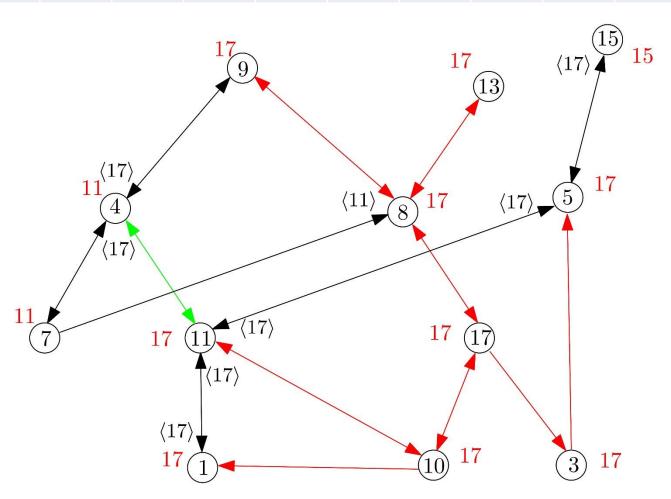
1	3	4	5	7	8	9	10	11	13	15	17
10	17	11	3	7	17	8	17	10	8	15	17
Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	5	3,8,10



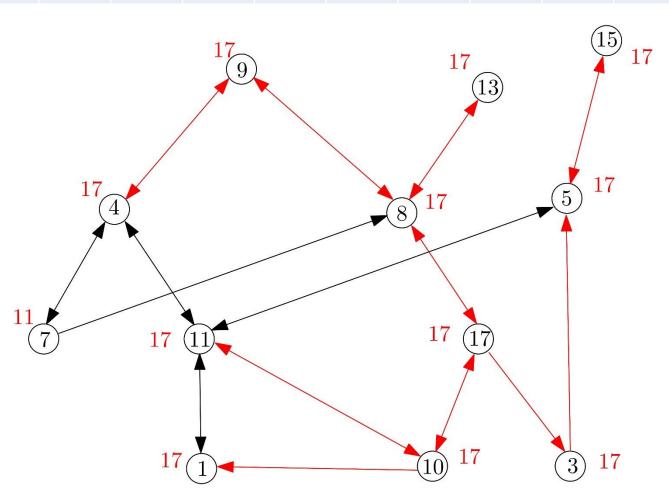
1	3	4	5	7	8	9	10	11	13	15	17
10	17	11	3	7	17	8	17	10	8	15	17
Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	5	3,8,10



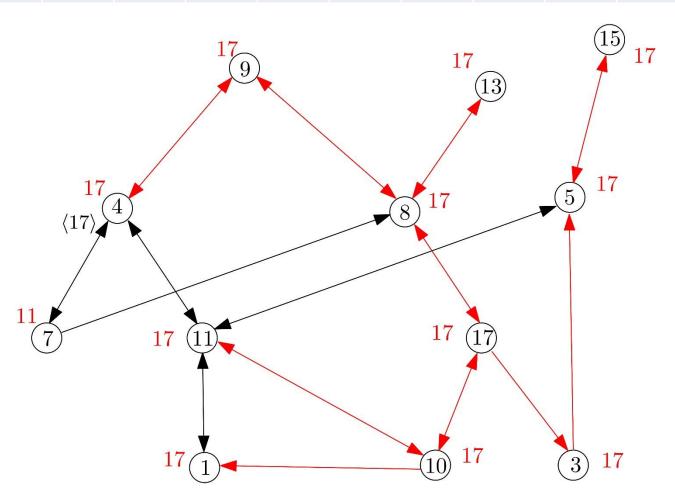
1	3	4	5	7	8	9	10	11	13	15	17
10	17	11	3	7	17	8	17	10	8	15	17
Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	Ø	5	3,8,10



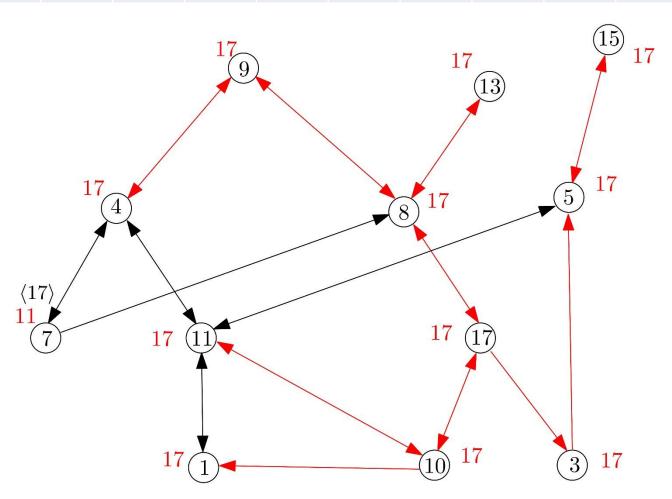
1	3	4	5	7	8	9	10	11	13	15	17
10	17	9	3	7	17	8	17	10	8	5	17
Ø	5	Ø	Ø	Ø	9,13	Ø	1,11	Ø	Ø	Ø	3,8,10



1	3	4	5	7	8	9	10	11	13	15	17
10	17	9	3	7	17	8	17	10	8	5	17
Ø	5	Ø	Ø	Ø	9,13	Ø	1,11	Ø	Ø	Ø	3,8,10

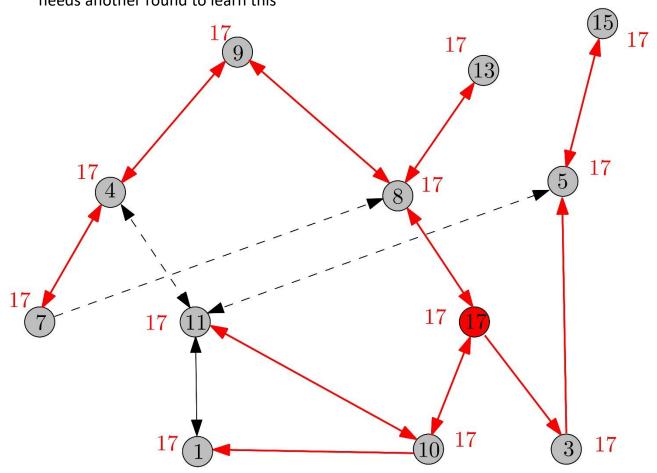


1	3	4	5	7	8	9	10	11	13	15	17
10	17	9	3	7	17	8	17	10	8	5	17
Ø	5	Ø	Ø	Ø	9,13	Ø	1,11	Ø	Ø	Ø	3,8,10



1	3	4	5	7	8	9	10	11	13	15	17
10	17	9	3	4	17	8	17	10	8	5	17
Ø	5	7 *	15	Ø	9,13	4	1,11	Ø	Ø	Ø	3,8,10

^{*} needs another round to learn this



Applications (assuming bidirectional networks)

Broadcast

- We pay the tree construction once
- Then, we can keep using it for broadcast that assumes a given spanning tree and a root
- Global computation
 - The root can collect all information contained in other processors
 - Convergecast towards the root
 - Once the root has this, can compute any function on those values, e.g., find max, min, average, ...
 - Can then broadcast the result to all processors

Applications

Leader Election

- So far, were assuming some additional knowledge (e.g., diameter D)
- The algorithm we described elects a unique leader without knowing n or D
- It is the root whose tree prevails
- How can we make it aware that it has been elected and allow it to terminate? (simpler to answer if we keep all trees in parallel)

Computing the Diameter

- Again, more straightforward if we keep all trees
- Every root initiates a procedure with which shall estimate the depth d_i of its own BFS tree
- Then a convergecast of the d_i s of all other processors can allow a processor to compute $D := \max\{d_i\}$ which is the diameter
- All processors do the same in parallel, therefore all learn the diameter

Summary

- Broadcast can be solved
 - given a root and a spanning tree
 - given a root only and constructing a BFS tree
- Leader election can be solved
 - special networks (e.g., rings)
 - general networks by assuming knowledge of the network diameter D
 - if we knew only n instead?
- Fortunately, both problems can be solved in general networks without any of these assumptions (only unique ids)
 - Parallel broadcasts (BFS trees) of all processors
 - Keep all and decide at the end
 - Maintain and forward only the maximum heard so far