A red FPV drone with a GoPro camera mounted on top, resting on a blue grid mat. The drone has four propellers and a black frame. The GoPro is mounted on a black bracket. The text "FPV Streaming Server with ffmpeg" is overlaid in white.

FPV Streaming Server with ffmpeg

Chan Shik Lim
chanshik@gmail.com

Introduction

- Chan Shik Lim (chanshik@gmail.com)
- Programmer @ NexCloud
- Go, Python
- System Programming
- Linux, Kubernetes, Prometheus
- **Hiring Programmer for
Kubernetes Operator &
Prometheus &
Monitoring System**



Agenda

- FPV
 - FPV System
 - FPV Channels and Frequency
- FPV Streaming System
 - Build ffmpeg on Windows
 - Incoming Stream Handler
 - WebSocket Handler
 - Client Handler
 - JSMPEG Video Canvas
- DEMO



FPV (First Person View)

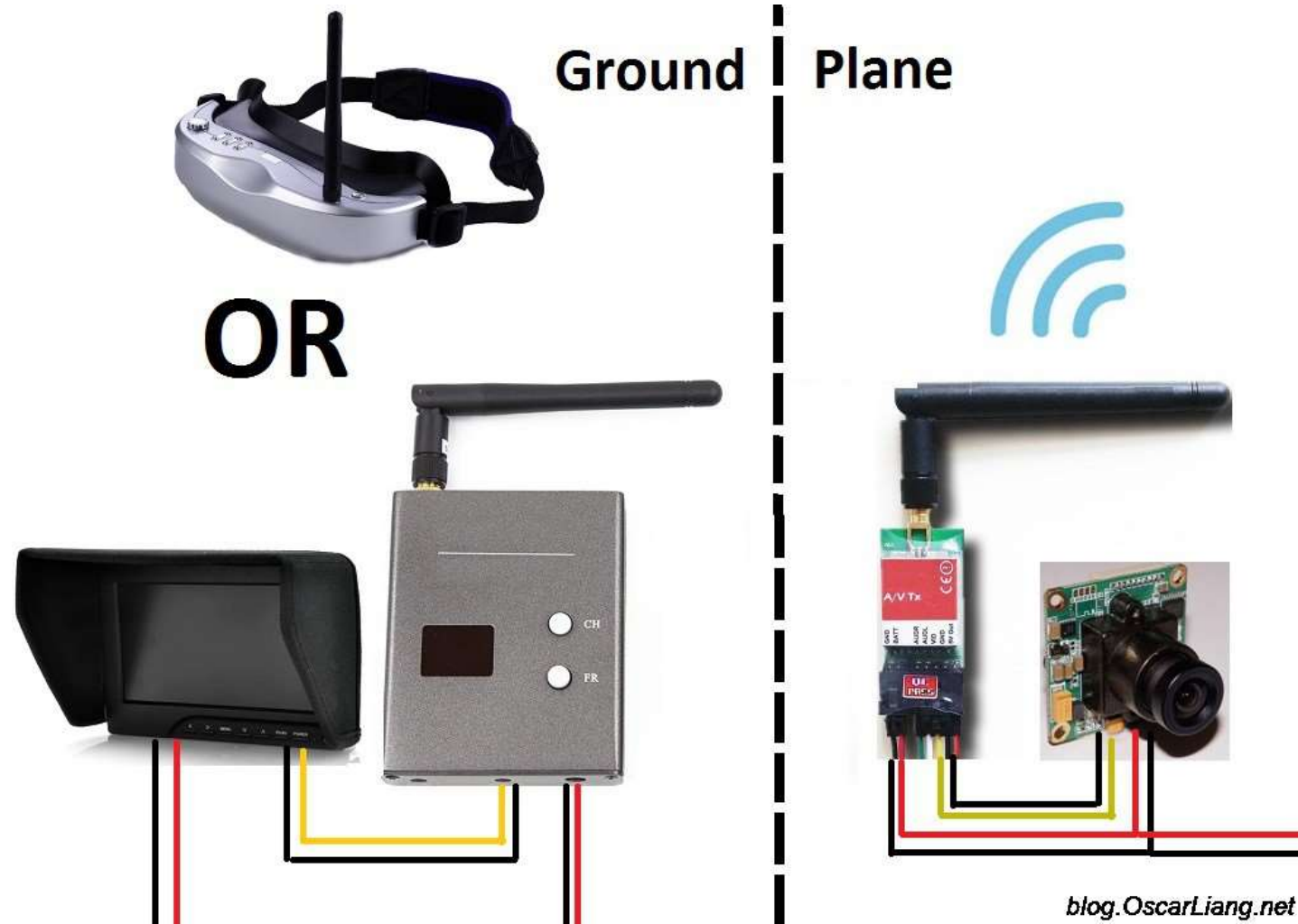


FPV Drone with ActionCam



FPV System

- FPV Camera
- Video Transmitter (VTX)
- Video Receiver (VRX)
- FPV Goggles or Monitor
- Antennas



5.8Ghz Channels and Frequency for FPV

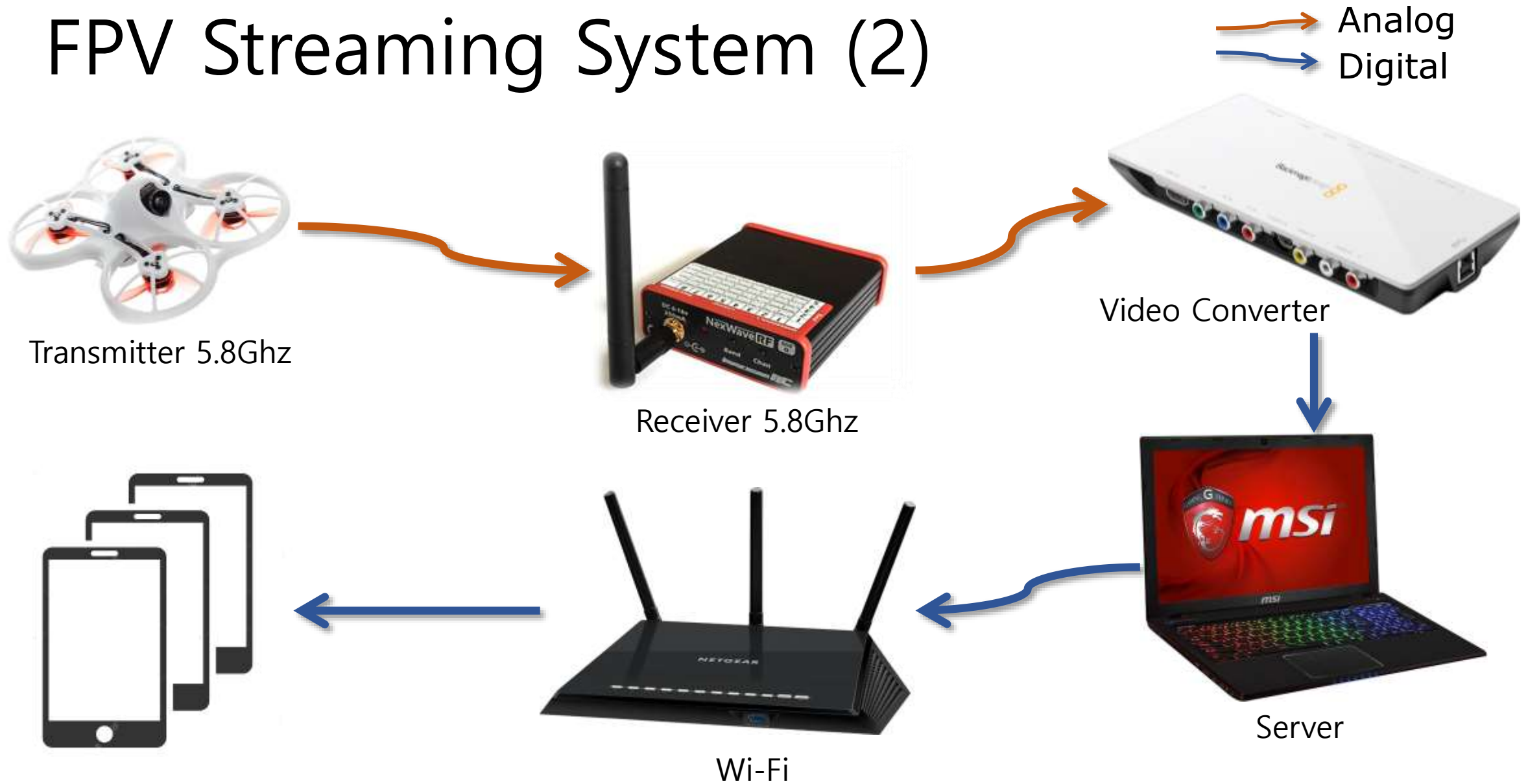
Band	CH 1	CH 2	CH 3	CH 4	CH 5	CH 6	CH 7	CH 8
A	5865	5845	5825	5805	5785	5765	5745	5725
B	5733	5752	5771	5790	5809	5828	5847	5866
E	5705	5685	5665	5645	5885	5905	5925	5945
F	5740	5760	5780	5800	5820	5840	5860	5880
C (Race)	5658	5695	5732	5769	5806	5843	5880	5917
D	5362	5399	5436	5473	5510	5547	5584	5621
U	5325	5348	5366	5384	5402	5420	5438	5456
O	5474	5492	5510	5528	5546	5564	5582	5600
L	5333	5373	5413	5453	5493	5533	5573	5613
H	5653	5693	5733	5773	5813	5853	5893	5933

FPV Streaming System (1)

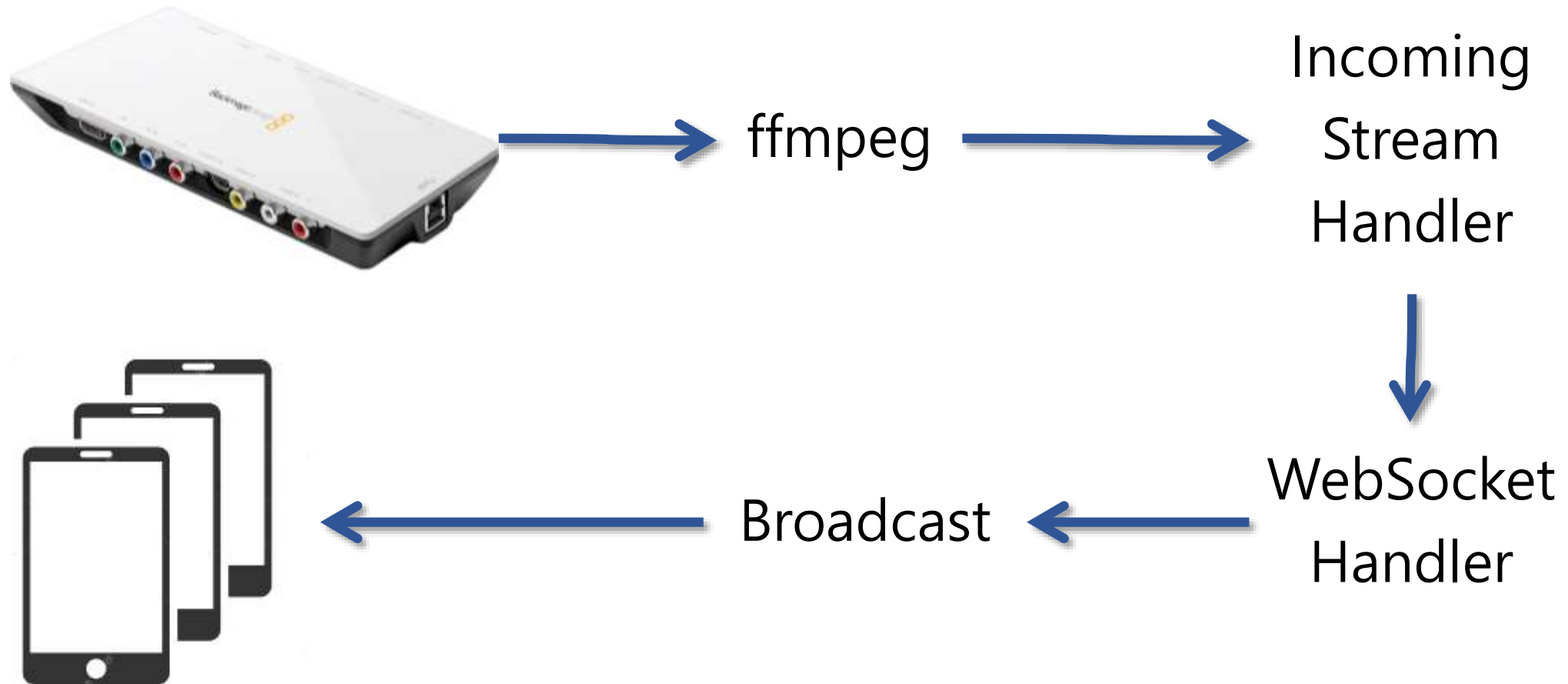
- Share video transmitted in the 5.8Ghz band
- Make it easy to see what the racer sees
- Use Wi-Fi to stop data consumption



FPV Streaming System (2)



FPV Streaming System (3)



Build ffmpeg on Windows

- Enable the Windows Subsystem for Linux optional component
- Go to the Windows Store app and search for Ubuntu and install it.

```
$ sudo apt-get update
```

```
$ sudo apt-get install subversion ragel curl texinfo g++ bison flex cvs yasm  
automake libtool autoconf gcc cmake git make pkg-config zlib1g-dev mercurial  
unzip pax nasm gperf autogen bzip2 autoconf-archive p7zip-full python3-  
distutils -y
```

```
$ mkdir ffmpeg
```

```
$ cd ffmpeg
```

```
ffmpeg $ git clone https://github.com/rdp/ffmpeg-windows-build-helpers.git
```

```
ffmpeg $ cd ffmpeg-windows-build-helpers
```

```
ffmpeg-windows-build-helpers $ sudo ./cross_compile_ffmpeg.sh --disable-  
nonfree=n
```


Incoming Stream Handler

- Handle POST request
- Receive video data from external device
- Transmit video data every 1024 bytes

```
for {  
    data, err := ioutil.ReadAll(io.LimitReader(r.Body, 1024))  
    if err != nil || len(data) == 0 {  
        break  
    }  
  
    s.clientManager.BroadcastData(&data)  
}
```

WebSocket Handler: ServeWS()

```
func (h *WebSocketHandler) ServeWS(w http.ResponseWriter, r *http.Request) {  
    if r.Method != "GET" {  
        http.Error(w, "Method not allowed", 405)  
        return  
    }  
  
    ws, err := h.upgrader.Upgrade(w, r, nil)  
    if err != nil {  
        log.Println(err)  
        return  
    }  
  
    log.Println("New client connected")  
    client := NewClient(ws, h.unregister)  
  
    h.register <- client  
  
    go client.Run()  
}
```

WebSocket Handler: Run()

```
for {
    select {
    case client := <-h.register:
        h.clients[client] = true
        log.Printf("New client registered. Total: %d\n", len(h.clients))
        break

    case client := <- h.unregister:
        _, ok := h.clients[client]
        if ok {
            delete(h.clients, client)
        }
        log.Printf("Client unregistered. Total: %d\n", len(h.clients))
        break
    }
}
```


Client Handler: ReadHandler()

```
func (c *Client) ReadHandler() {  
    defer func() {  
        c.unregisterChan <- c  
    }()  
  
    for {  
        msgType, msg, err := c.ws.ReadMessage()  
        if err != nil {  
            break  
        }  
  
        if msgType == websocket.CloseMessage {  
            break  
        }  
  
        log.Println("Received from client: " + string(msg))  
    }  
}
```

Client Handler: WriteHandler()

```
func (c *Client) WriteHandler() {  
    defer func() {  
        c.unregisterChan <- c  
    }()  
  
    for {  
        select {  
        case data, ok := <- c.sendChan:  
            if !ok {  
                log.Println("Client send failed")  
                c.ws.WriteMessage(websocket.CloseMessage, []byte{})  
                return  
            }  
  
            c.ws.WriteMessage(websocket.BinaryMessage, *data)  
        }  
    }  
}
```

Broadcast Video Stream

- IncomingStreamHandler call **WebSocketHandler.BroadcastData()**

```
func (h *WebSocketHandler) BroadcastData(data *[]byte) {  
    for client := range h.clients {  
        client.sendChan <- data  
    }  
}
```

- Client's WriteHandler

```
case data, ok := <- c.sendChan:  
    if !ok {  
        log.Println("Client send failed")  
        c.ws.WriteMessage(websocket.CloseMessage, []byte{})  
        return  
    }  
  
    c.ws.WriteMessage(websocket.BinaryMessage, *data)  
}
```


JSMpeg Video Canvas

```
<span>Video</span><br/>
<canvas id="videoCanvas" width="1024" height="576">
  <p>
    Please use a browser that supports the Canvas Element, like
    <a href="http://www.google.com/chrome">Chrome</a>,
    <a href="http://www.mozilla.com/firefox/">Firefox</a>,
    <a href="http://www.apple.com/safari/">Safari</a> or Internet Explorer 10
  </p>
</canvas>
<script type="text/javascript" src="/static/jsmpeg.min.js"></script>
<script type="text/javascript">
  var url = 'ws://' + document.location.hostname + ':8084/';
  var canvas = document.getElementById('videoCanvas');
  var player = new JSMpeg.Player(url, {canvas: canvas});
</script>
```

DEMO

- Setup FPV equipment
- **Run stream-server.go**

go run stream-server.go

- **Run ffmpeg**

ffmpeg.exe -f decklink -hwaccel cuvid -i "Intensity Shuttle" -c:v rawvideo -f mpegts -c:v mpeg1video -b:v 800k -r 60 http://localhost:8082/secret

- **Access <http://localhost:8080>**
- **Repo.: <https://github.com/chanshik/jsmpeg-stream-go>**

References

<https://github.com/chanshik/jsmpeg-stream-go>

<https://twitter.com/mrsteelefpv/status/858056393533923329>

<https://www.fatshark.com/product/hdo-fpv-goggles/>

<https://www.dji.com/kr/fpv>

<https://oscarliang.com/fpv-guide/>

<https://emaxmodel.com/tinyhawk.html>

<https://immersionrc.com/fpv-products/duo5800-5-8ghz-av-rx/>

<https://blackmagicdesign.com/products/intensity>



Thank you for listening
the presentation

Chan Shik Lim
chanshik@gmail.com