



SST

# Introduction to the SysML v2 Language

## *Textual Notation*

This is a training presentation on the evolving SysML v2 language as it is being developed by the SysML v2 Submission Team (SST).

It is updated as appropriate for each release of the  
SysML v2 Pilot Implementation.

Release: 2022-02

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# Changes in this Release

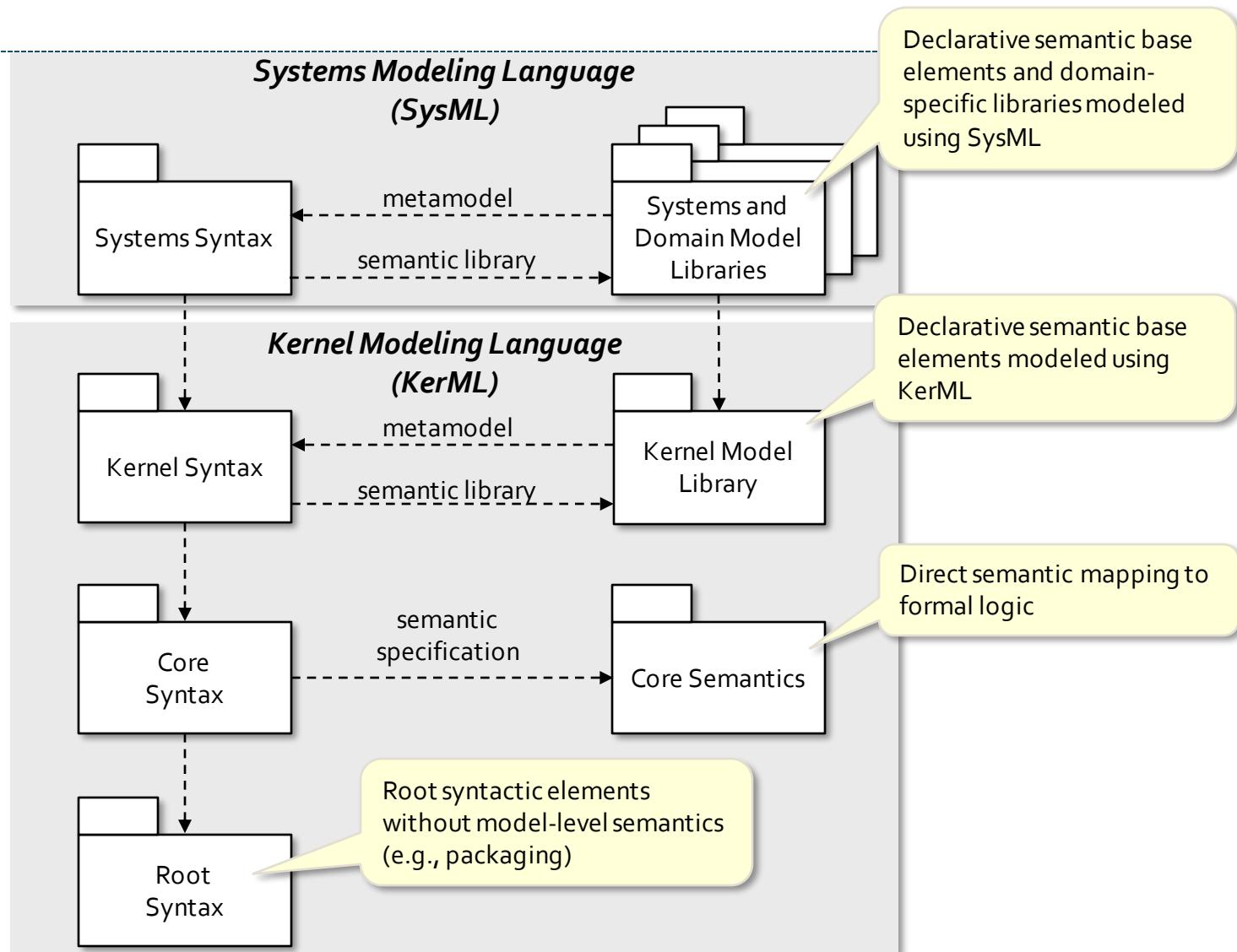
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- Removed remaining SysML v1.6 connector examples.
- Updated shorthand notation for select expressions.
- Kernel Library:
  - Moved sum and product functions from DataFunctions to NumericalFunctions
  - Added Collections, VectorValues, ComplexFunctions, CollectionFunctions, VectorFunctions and TrigFunctions.
  - Revised mathematical function names to be consistently lower-case-initial.
- Quantities and Units Library:
  - Updated UnitsAndScales and VectorCalculations.
- Added the Geometry Library.

*To find slides that have changed recently, search for  
Last changed: 2022-02  
(and similarly for earlier releases).*

# SysML v2 Language Architecture

SST



- Root – Root syntactic elements
  - Element, AnnotatingElement, Comment, TextualRepresentation, Namespace
  - Relationship, Ownership, Annotation, Documentation, Membership, Import
- Core – Fundamental semantic concepts – Formal declarative semantics
  - Type, Classifier, Feature, Multiplicity
  - FeatureMembership, EndFeatureMembership, Generalization, Superclassing, Subsetting, Redefinition, FeatureTyping, Conjugation, TypeFeaturing
- Kernel – Foundation for building modeling languages – Semantic kernel library
  - Class, DataType, Behavior, Function, Step, Expression, AnnotatingFeature, Package
  - Association, Interaction, Connector, BindingConnector, Succession, ItemFlow, SuccessionItemFlow
- Systems – Modeling language for systems engineering – Domain libraries
  - AttributeDefinition, EnumerationDefinition, OccurrenceDefinition, ItemDefinition, PartDefinition, PortDefinition, ActionDefinition, StateDefinition, ConstraintDefinition, RequirementDefinition, ConcernDefinition, CalculationDefinition, CaseDefinition, AnalysisCaseDefinition, VerificationCaseDefinition, UseCaseDefinition, ViewDefinition, ViewpointDefinition, RenderingDefinition
  - ReferenceUsage, AttributeUsage, EnumerationUsage, OccurrenceUsage, ItemUsage, PartUsage, PortUsage, ActionUsage, StateUsage, ConstraintUsage, RequirementUsage, ConcernUsage, CalculationUsage, CaseUsage, AnalysisCaseUsage, VerificationCaseUsage, UseCaseUsage, ViewUsage, ViewpointUsage, RenderingUsage
  - ConnectionDefinition, ConnectionUsage, InterfaceUsage, InterfaceDefinition, AllocationDefinition, AllocationUsage, BindingConnectionAsUsage, SuccessionAsUsage, FlowConnectionUsage, SuccessionFlowConnectionUsage, Dependency

# Packages – Members

A *package* acts as a *namespace* for its members and a *container* for its owned members.

ⓘ A name with spaces or other special characters is surrounded in single quotes.

The *owned members* of a package are elements directly contained in the package.

```
package 'Package Example' {
    import ISO::TorqueValue;
    import ScalarValues::*;

    part def Automobile;

    alias Car for Automobile;
    alias Torque for ISO::TorqueValue;
}
```

An *import* adds either a single member or all the members of an *imported* package to the *importing* package.

A package can introduce *aliases* for its owned members or for individual members of other packages.

ⓘ A qualified name is a package name (which may itself be qualified) followed by the name of one of its members, separated by :: .

# Packages – Visibility

All members from a public import are visible (*re-exported*) from the importing package. Members from a private import are not.

A *private* member is not visible outside the package (but it is visible to subpackages).

Members are *public* by default but can also be marked public explicitly.

```
package 'Package Example' {  
    public import ISO::TorqueValue;  
    private import ScalarValues::*;

    private part def Automobile;

    public alias Car for Automobile;
    alias Torque for ISO::TorqueValue;
}
```

# Comments

A comment begins with `/*` and ends with `*/`.

A comment can optionally be named.

A comment that begins with `/**` annotates the following element.

A note begins with `//` and extends to the end of the line.  
(A multiline note begins with `/**` and ends with `*/`.)

```
package 'Comment Example' {
    /* This is documentary comment, part of the model,
     * annotating (by default) it's owning package. */

    comment Comment1 /* This is a named comment. */

    comment about Automobile
        /* This is an unnamed documentary comment,
         * annotating an explicitly specified element.
        */

    part def Automobile;

    /**
     * This is a documentary comment, annotating the
     * following element.
     */
    alias Car for Automobile;

    // This is a note. It is in the text, but not part
    // of the model.
    alias Torque for ISO::TorqueValue;
}
```

What the comment annotates can be explicitly specified (it is the owning namespace by default).

*Documentation* is a special kind of comment that is directly owned by the element it documents.

Because it is not a member, a documentation comment cannot be named.

Alias and import elements cannot have documentation comments.

```
package 'Documentation Example' {
    doc /* This is documentation of the owning
          * package.
          */

    part def Automobile {
        doc /* This is documentation of Automobile. */
    }

    alias Car for Automobile;
    alias Torque for ISO::TorqueValue;
}
```

# Part and Attribute Definitions

A *part definition* is a definition of a class of systems or parts of systems, which are mutable and exist in space and time.

An *attribute definition* is a definition of attributive data that can be used to describe systems or parts.

- ➊ Definitions and usages are also namespaces that allow **import**.

```
part def Vehicle {  
    attribute mass : ScalarValues::Real;  
  
    part eng : Engine;  
  
    ref part driver : Person;  
}  
  
attribute def VehicleStatus  
    import ScalarValues::*;  
  
    attribute gearSetting : Integer;  
    attribute acceleratorPosition : Real;  
}  
  
part def Engine;  
part def Person;
```

An *attribute usage* of an *attribute definition*, used here as a feature of the part definition.

A *part usage* is a *composite* feature that is the usage of a part definition.

A *reference part usage* is a *referential* feature that is the usage of a part definition.

An attribute definition may not have part usages.

# Generalization/Specialization

An *abstract* definition is one whose instances must be members of some specialization.

```
abstract part def Vehicle;

part def HumanDrivenVehicle specializes Vehicle {
    ref part driver : Person;
}

part def PoweredVehicle :> Vehicle {
    part eng : Engine;
}

part def HumanDrivenPoweredVehicle :>
    HumanDrivenVehicle, PoweredVehicle;

part def Engine;
part def Person;
```

A *specialized* definition defines a subset of the classification of its generalization.

The `:>` symbol is equivalent to the `specializes` keyword.

A specialization can define additional features.

A definition can have multiple generalizations, *inheriting* the features of all general definitions.

# Subsetting

```
part def Vehicle {  
    part parts : VehiclePart[*];  
  
    part eng : Engine subsets parts;  
    part trans : Transmission subsets parts;  
    part wheels : Wheel[4] :> parts;  
}  
  
abstract part def VehiclePart;  
part def Engine :> VehiclePart;  
part def Transmission :> VehiclePart;  
part def Wheel :> VehiclePart;
```

*Subsetting asserts that, in any common context, the values of one feature are a subset of the values of another feature.*

Subsetting is a kind of generalization between features.

# Redefinition

There is shorthand notation for redefining a feature with the same name.

```
part def Vehicle {  
    part eng : Engine;  
}  
part def SmallVehicle :> Vehicle {  
    part smallEng : SmallEngine redefines eng;  
}  
part def BigVehicle :> Vehicle {  
    part bigEng : BigEngine :>> eng;  
}  
  
part def Engine {  
    part cyl : Cylinder[4..6];  
}  
part def SmallEngine :> Engine {  
    part redefines cyl[4];  
}  
part def BigEngine :> Engine {  
    part redefines cyl[6];  
}  
  
part def Cylinder;
```

A specialized definition can *redefine* a feature that would otherwise be inherited, to change its name and/or specialize its type.

The `:>` symbol is equivalent to the `redefines` keyword.

A feature can also specify *multiplicity*.

ⓘ The default multiplicity for parts is `1..1`.

Redefinition can be used to constrain the multiplicity of a feature.

# Enumeration Definitions (1)

An *enumeration definition* is a kind of attribute definition that defines a set of *enumerated values*.

```
enum def TrafficLightColor {  
    enum green;  
    enum yellow;  
    enum red;  
}  
  
part def TrafficLight {  
    attribute currentColor : TrafficLightColor;  
}  
  
part def TrafficLightGo specializes TrafficLight {  
    attribute redefines currentColor = TrafficLightColor::green;  
}
```

The values of an attribute usage defined by an enumeration definition are limited to the defined set of enumerated values.

This shows an attribute being *bound* to a specific value (more on binding later).

# Enumeration Definitions (2)

The `enum` keyword is optional when declaring enumerated values.

```
attribute def ClassificationLevel {  
    attribute code : String;  
    attribute color : TrafficLightColor;  
}  
  
enum def ClassificationKind specializes ClassificationLevel {  
    unclassified {  
        :>> code = "uncl";  
        :>> color = TrafficLightColor::green;  
    }  
    confidential {  
        :>> code = "conf";  
        :>> color = TrafficLightColor::yellow;  
    }  
    secret {  
        :>> code = "secr";  
        :>> color = TrafficLightColor::red;  
    }  
}  
  
enum def GradePoints :> Real {  
    A = 4.0;  
    B = 3.0;  
    C = 2.0;  
    D = 1.0;  
    F = 0.0;  
}
```

An enumeration definition can contain nothing but declarations of its enumerated values. However, it can specialize a regular attribute definition and inherit nested features.

⚠ An enumeration definition cannot specialize another enumeration definition.

The nested features can then be bound to specific values in each of the enumerated values.

Enumerated values can also be bound directly to specific values of a specialized attribute definition or data type.

Parts can be specified outside the context of a specific part definition.

```
// Definitions
part def Vehicle {
    part eng : Engine;
}
part def Engine {
    part cyl : Cylinder[4..6];
}
part def Cylinder;

// Usages
part smallVehicle : Vehicle {
    part redefines eng {
        part redefines cyl[4];
    }
}
part bigVehicle : Vehicle {
    part redefines eng {
        part redefines cyl[6];
    }
}
```

The **defined by** relationship is a kind of generalization.

Parts inherit properties from their definitions and can redefine them, to any level of nesting.

# Parts (2)

```
// Definitions
part def Vehicle;
part def Engine;
part def Cylinder;

// Usages
part vehicle : Vehicle {
    part eng : Engine {
        part cyl : Cylinder[4..6];
    }
}
part smallVehicle :> vehicle {
    part redefines eng {
        part redefines cyl[4];
    }
}
part bigVehicle :> vehicle {
    part redefines eng {
        part redefines cyl[6];
    }
}
```

Composite structure can be specified entirely on parts.

A part can specialize another part.

An *item definition* defines a class of things that exist in space and time but are not necessarily considered "parts" of a system being modeled.

① All parts can be treated as items, but not all items are parts. The design of a system determines what should be modeled as its "parts".

```
item def Fuel;  
item def Person;  
  
part def Vehicle {  
    attribute mass : Real;  
  
    ref item driver : Person;  
  
    part fuelTank {  
        item fuel: Fuel;  
    }  
}
```

① The default multiplicity for attributes and items is also [1..1](#).

A system model may reference discrete items that interact with or pass through the system.

① An item is continuous if any portion of it in space is the same kind of thing. A portion of fuel is still fuel. A portion of a person is generally no longer a person.

Items may also model continuous materials that are stored in and/or flow between parts of a system.

# Connections (1)

A *connection definition* is a part definition whose usages are *connections* between its ends.

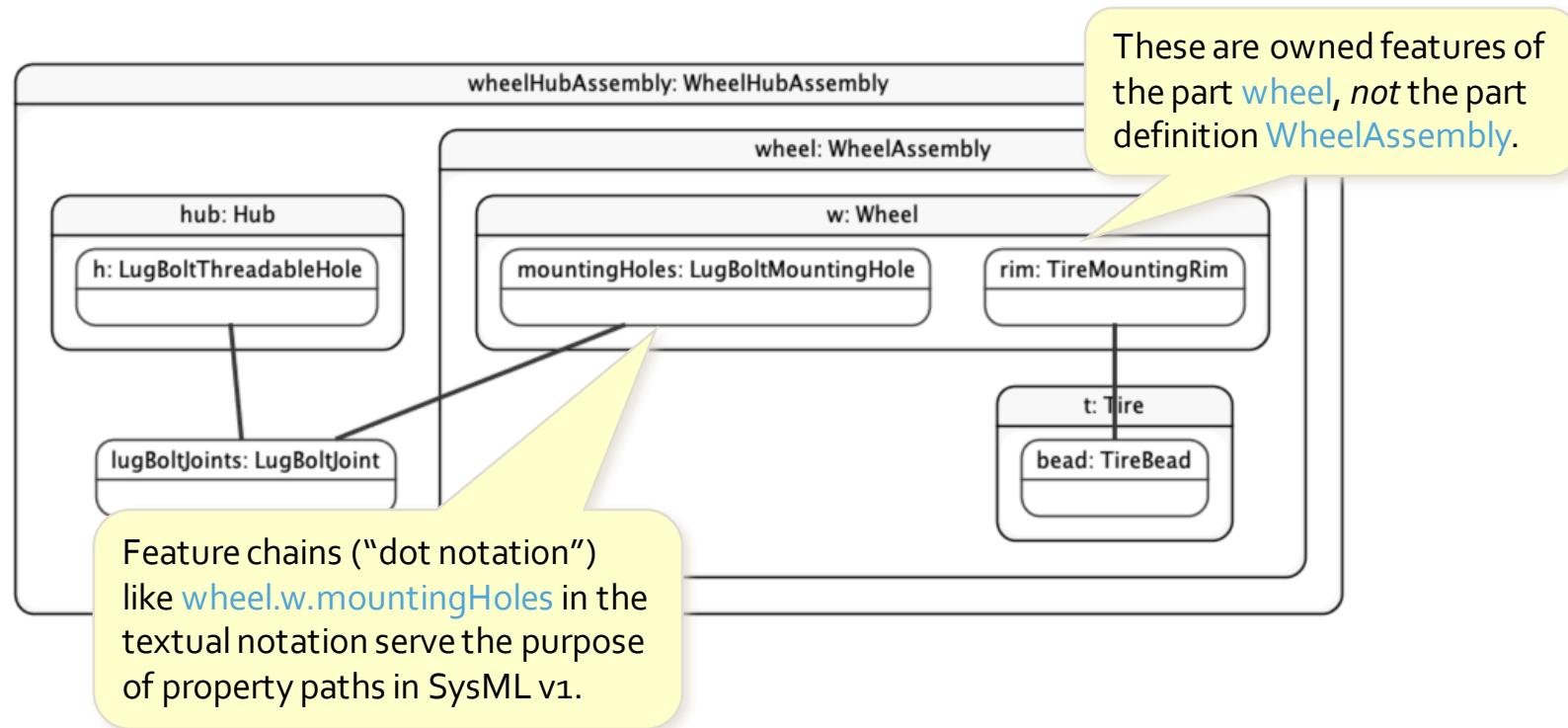
A *connection* is a usage of a connection definition, which connects two other features.

If a connection definition is not specified, a generic connection definition (called **Connection**) is used.

```
connection def PressureSeat {  
    end : TireBead[1];  
    end : TireMountingRim[1];  
}  
  
part wheelHubAssembly : WheelHubAssembly {  
  
    part wheel : WheelAssembly[1] {  
        part t : Tire[1] {  
            part bead : TireBead[2];  
        }  
        part w: Wheel[1] {  
            part rim : TireMountingRim[2];  
            part mountingHoles : LugBoltMountingHole[5];  
        }  
        connection : PressureSeat connect t.bead to w.rim;  
    }  
  
    part lugBoltJoints : LugBoltJoint[0..5];  
    part hub : Hub[1] {  
        part h : LugBoltThreadableHole[5];  
    }  
    connect lugBoltJoints[0..1]  
        to mountingHole :> wheel.w.mountingHoles[1];  
    connect lugBoltJoints[0..1]  
        to threadedHole :> hub.h[1];  
}
```

“Dot” notation is used to specify paths to nested features to be connected.

# Connections (2)



# Ports

A *port definition* defines features that can be made available via ports. (Replaces interface blocks in SysML v1).

- ① Directed features are always referential, so it is not necessary to explicitly use the `ref` keyword.

A *port* is a connection point through which a part definition makes some of its features available in a limited way. (Like a proxy port in SysML v1.)

```
port def FuelOutPort {  
    attribute temperature : Temp;  
    out item fuelSupply : Fuel;  
    in item fuelReturn : Fuel;  
}  
  
port def FuelInPort {  
    attribute temperature : Temp;  
    in item fuelSupply : Fuel;  
    out item fuelReturn : Fuel;  
}  
  
part def FuelTankAssembly {  
    port fuelTankPort : FuelOutPort;  
}  
  
part def Engine {  
    port engineFuelPort : FuelInPort;  
}
```

Ports may have attribute and reference features. A feature with a direction (`in`, `out` or `inout`) is a *directed feature*.

Two ports are *compatible* for connection if they have directed features that match with inverse directions.

# Port Conjugation

Every port definition has an implicit *conjugate* port definition that reverses input and output features. It has the name of the original definition with `~` prepended (e.g., `'~FuelPort'`).

```
port def FuelPort {  
    attribute temperature : Temp;  
    out item fuelSupply : Fuel;  
    in item fuelReturn : Fuel;  
}  
  
part def FuelTankAssembly {  
    port fuelTankPort : FuelPort;  
}  
  
part def Engine {  
    port engineFuelPort : ~FuelPort;  
}
```

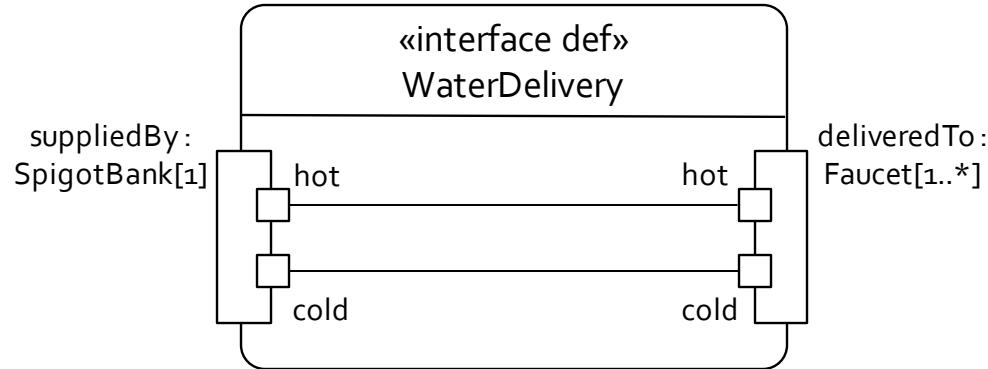
Using a `~` symbol on the port type is a short had for using the conjugate port definition (e.g., `FuelPort:'~FuelPort'`).

An *interface definition* is a connection definition whose ends are ports.

```
interface def FuelInterface {  
    end supplierPort : FuelOutPort;  
    end consumerPort : FuelInPort;  
}  
  
part vehicle : Vehicle {  
    part tankAssy : FuelTankAssembly;  
    part eng : Engine;  
  
    interface : FuelInterface connect  
        supplierPort :> tankAssy.fuelTankPort to  
        consumerPort :> eng.engineFuelPort;  
}
```

An *interface usage* is a connection usage defined by an interface definition, connecting two compatible ports.

# Interface Decomposition



```
interface def WaterDelivery {  
    end suppliedBy : SpigotBank[1] {  
        port hot : Spigot;  
        port cold : Spigot;  
    }  
    end deliveredTo : Faucet[1..*] {  
        port hot : FaucetInlet;  
        port cold : FaucetInlet;  
    }  
  
    connect suppliedBy.hot to deliveredTo.hot;  
    connect suppliedBy.cold to deliveredTo.cold;  
}
```

Connection ends have multiplicities corresponding to navigating across the connection...

...but they can be interconnected like participant properties.

# Binding Connection (1)

```
part tank : FuelTankAssembly {  
    port redefines fuelTankPort {  
        out item redefines fuelSupply;  
        in item redefines fuelReturn;  
    }  
  
    bind fuelTankPort.fuelSupply = pump.pumpOut;  
    bind fuelTankPort.fuelReturn = tank.fuelIn;  
  
part pump : FuelPump {  
    out item pumpOut : Fuel;  
    in item pumpIn : Fuel;  
}  
part tank : FuelTank {  
    out item fuelOut : Fuel;  
    in item fuelIn : Fuel;  
}  
}
```

A *binding connection* is a connection that asserts the *equivalence* of the connected features (i.e., they have equal values in the same context).

Usages on parts can also have direction (and are automatically referential).

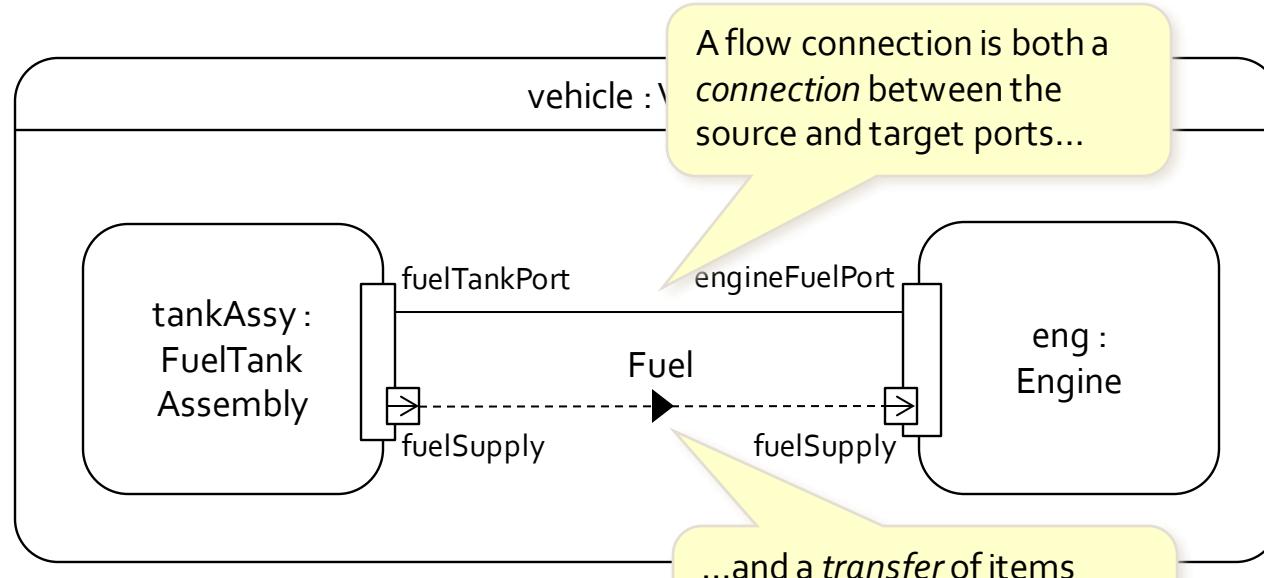
# Binding Connections (2)

```
part tank : FuelTankAssembly {  
    port redefines fuelTankPort {  
        out item redefines fuelOut : Fuel;  
        in item redefines fuelIn : Fuel = fuelTankPort.fuelSupply;  
    }  
  
    part pump : FuelPump {  
        out item pumpOut : Fuel = fuelTankPort.fuelSupply;  
        in item pumpIn : Fuel;  
    }  
    part tank : FuelTank {  
        out item fuelOut : Fuel;  
        in item fuelIn : Fuel = fuelTankPort.fuelReturn;  
    }  
}
```

This shorthand notation combines the definition of a feature with a binding connection.

⚠ This is not the same as an initial or default value, like in UML.

# Flow Connections



- ① A flow connection is *streaming* if the transfer is ongoing between the source and target, as opposed to happening once after the source generates its output and before the target consumes its input.

A *flow connection* is a transfer of something from an output of a source port to an input of a target port.

- ① Specifying the item type (e.g., “*of Fuel*”) is optional.

```
part vehicle : Vehicle {  
    part tankAssy : FuelTankAssembly;  
    part eng : Engine;  
  
    flow of Fuel  
        from tankAssy.fuelTankPort.fuelSupply  
        to eng.engineFuelPort.fuelSupply;  
  
    flow of Fuel  
        from eng.engineFuelPort.fuelReturn  
        to tankAssy.fuelTankPort.fuelReturn;  
}
```

```
interface def FuelInterface {  
    end supplierPort : FuelOutPort;  
    end consumerPort : FuelInPort;  
  
    flow supplierPort.fuelSupply to consumerPort.fuelSupply;  
    flow consumerPort.fuelReturn to supplierPort.fuelReturn;  
}  
  
part vehicle : Vehicle {  
    part tankAssy : FuelTankAssembly;  
    part eng : Engine;  
  
    interface : FuelInterface connect  
        supplierPort :> tankAssy.fuelTankPort to  
        consumerPort :> eng.engineFuelPort;  
}
```

Flow connections can be defined within an interface definition.

The flows are established when the interface is used.

# Action Definition

An *action definition* is a definition of some action to be performed.

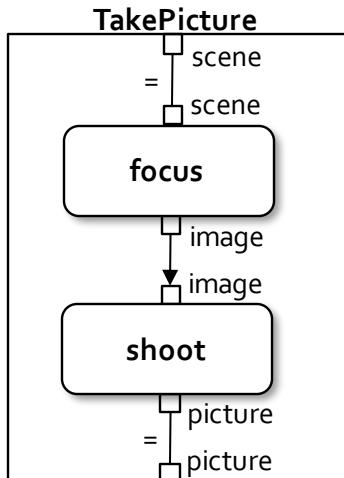
Action definitions may have **in**, **out** and **inout** parameters (the default is **in**).

```
action def Focus(in scene : Scene, out image : Image);
action def Shoot(in image : Image, out picture : Picture);
```

```
action def TakePicture
    (in scene : Scene,
     out picture : Picture) {
bind focus.scene = scene;
```

```
action focus : Focus (in scene, out image);
flow focus.image to shoot.image;
```

```
action shoot : Shoot (in image, out picture);
bind shoot.picture = picture;
```



An *action* is a usage of an action definition performed in a specific context.

A flow connection can be used to transfer items between actions.

An action has parameters corresponding to its action definition.

# Action Succession (1)

```

action def Focus(in scene : Scene, out image : Image);
action def Shoot(in image : Image, out picture : Picture);

action def TakePicture {
    in item scene : Scene;
    out item picture : Picture;

    bind focus.scene = scene;

    action focus : Focus (in scene, out image);

    flow focus.image to shoot.image;
    first focus then shoot;

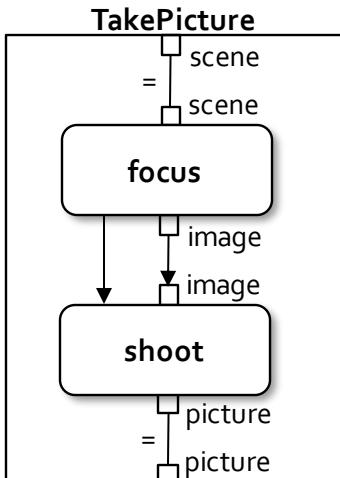
    action shoot : Shoot (in image, out picture);

    bind shoot.picture = picture;
}

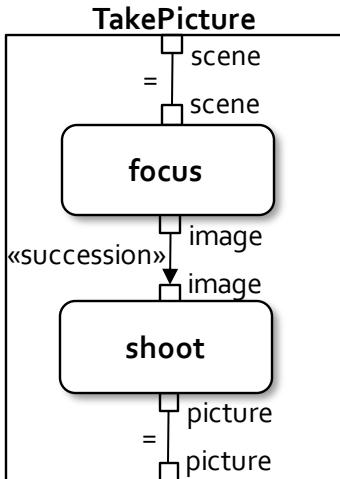
```

Parameters can also be declared in the action body, similarly to directed features.

A succession asserts that the first action must complete before the second can begin.



# Action Succession (2)



```

action def Focus(in scene : Scene, out image : Image);
action def Shoot(in image : Image, out picture : Picture);

action def TakePicture {
    in item scene : Scene;
    out item picture : Picture;

    bind focus.scene = scene;

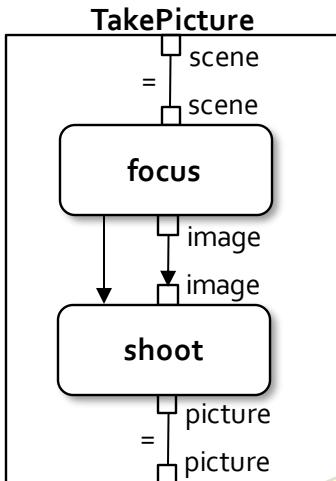
    action focus : Focus (in scene, out image)
        succession flow focus.image to shoot.image;

        action shoot : Shoot (in image, out picture);
        bind shoot.picture = picture;
    }
}

```

A *succession flow* requires the first action to finish producing its output before the second can begin consuming it.

# Action Notation Shorthands



This is a shorthand for a succession between the lexically previous action and this action.

```
action def Focus(in scene : Scene, out image : Image);  
action def Shoot(in image : Image, out picture : Picture);
```

```
action def TakePicture {  
    in item scene : Scene;  
    out item picture : Picture
```

This is the same shorthand for binding used previously.

```
    action focus : Focus {  
        in item scene = TakePicture::scene;  
        out item image;  
    }
```

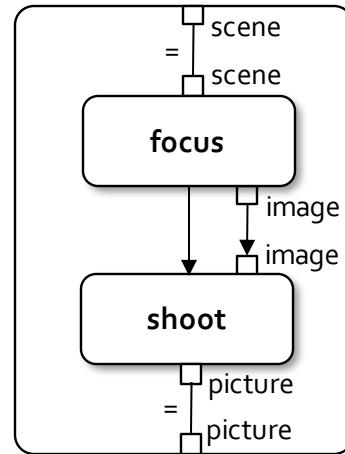
This is a shorthand for a flow connection *into* the parameter.

```
    then action shoot : Shoot {  
        in item image flow from focus.image;  
        out item picture = TakePicture::picture;  
    }
```

This qualified name refers to the picture parameter of **TakePicture**, rather than the parameter of **shoot** with the same name.

# Action Decomposition

takePicture : TakePicture



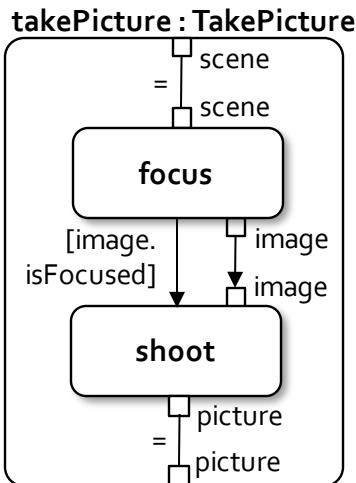
```
action def Focus(in scene : Scene, out image : Image);  
action def Shoot(in image : Image, out picture : Picture);  
action def TakePicture(in scene : Scene, out picture : Picture);  
  
action takePicture : TakePicture {  
    in item scene;  
    out item picture;  
  
    action focus : Focus {  
        in item scene = takePicture::scene;  
        out item image;  
    }  
  
    then action shoot : Shoot {  
        in item image flow from focus.image;  
        out item picture = takePicture::picture;  
    }  
}
```

An action can also be directly decomposed into other actions.

**takePicture** is a usage, so dot notation could be used here, but it is unnecessary because **picture** is in an outer scope, not nested.

# Conditional Succession (1)

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```

action takePicture : TakePicture {
    in item scene;
    out item picture;

    action focus : Focus {
        in item scene = takePicture
        out item image;
    }

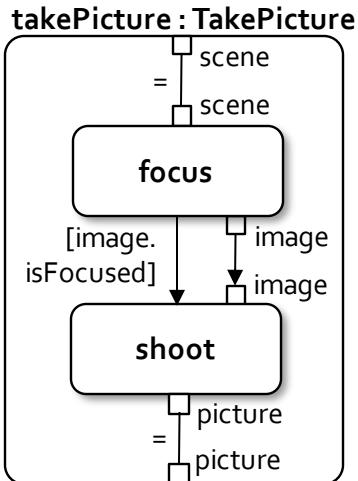
    first focus
        if focus.image.isFocused then shoot;

    action shoot : Shoot {
        in item image flow from focus.image;
        out item picture = takePicture::picture;
    }
}
  
```

A *conditional succession* asserts that the second action must follow the first only if a *guard* condition is true. If the guard is false, succession is not possible.

⚠ Note that, currently, the target action must be explicitly named (no shorthand).

# Conditional Succession (2)



```
action takePicture : TakePicture {
    in item scene;
    out item picture;

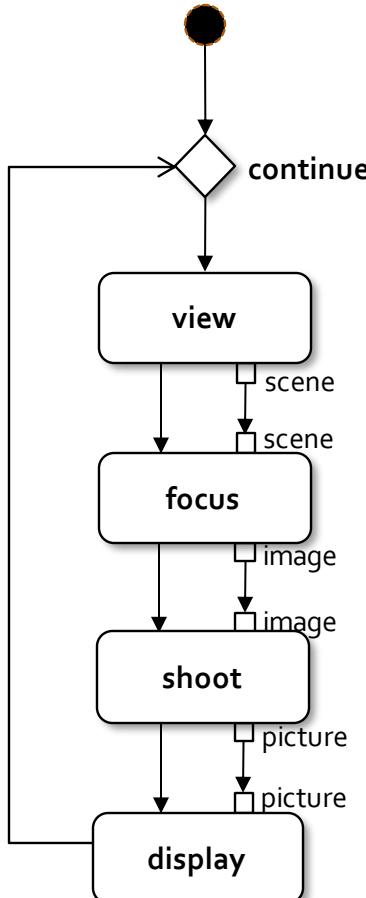
    action focus : Focus {
        in item scene = takePicture::scene;
        out item This is a shorthand for a conditional succession
    } following the lexically previous action.

    if focus.image.isFocused then shoot;

    action shoot : Shoot {
        in item image flow from focus.image;
        out item picture = takePicture::picture;
    }
}
```

# Merge Nodes

References the start of the action as the source of the initial succession.

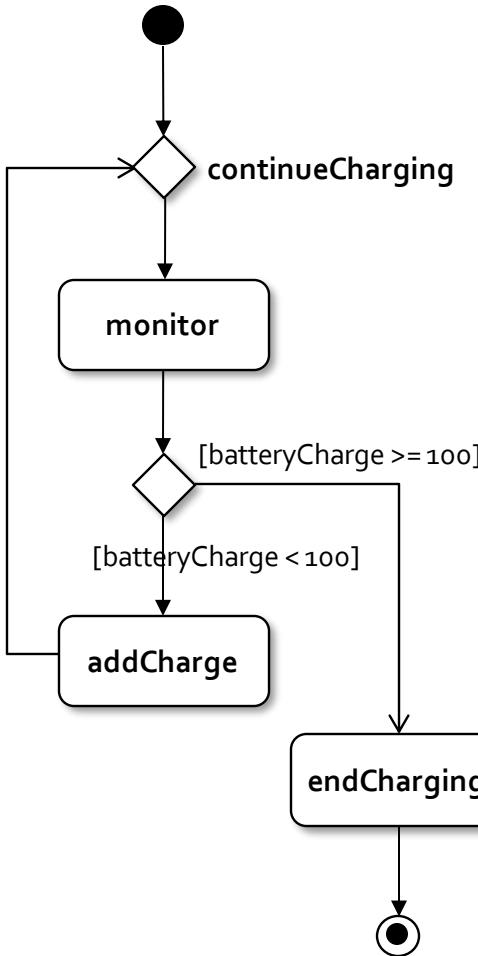


```

action takePicture : TakePicture {
    first start;
    then merge continue;
    then action trigger { out item scene; }
    then action focus : Focus {
        in item scene flow from trigger.scene;
        out item image;
    }
    then action shoot : Shoot {
        in image flow from focus.image;
        out picture;
    }
    then action display {
        in picture flow from shoot.picture;
    }
    then continue;
}
  
```

A merge node waits for exactly one predecessor to happen before continuing.

# Decision Nodes



```

action def ChargeBattery {
  first start;

  then merge continueCharging;
  then action monitor : MonitorBattery {
    out batteryCharge : Real;
  }

  then decide;
    if monitor.batteryCharge < 100 then addCharge;
    if monitor.batteryCharge >= 100 then endCharging;

  action addCharge : AddCharge {
    in charge = monitor.batteryCharge;
  }
  then continueCharging;

  action endCharging : EndCharging {
    in charge = monitor.batteryCharge;
  }

  then done;
}
  
```

A decision node (`decide` keyword) chooses *exactly one successor* to happen after it.

A decision node is typically followed by one or more conditional successions (the last “`if...then`” can be replaced by “`else`”).

References the end of the action as the target of a succession.

# Control Structures

A *loop action* repeatedly performs a *body action*.

- ❶ Control-structure actions provide a structured alternative to control nodes for conditionals and looping.

```
action def ChargeBattery {  
    loop action charging {  
        action monitor : MonitorBattery {  
            out charge;  
        }  
  
        then if monitor.charge < 100 {  
            action addCharge : AddCharge {  
                in charge = monitor.charge;  
            }  
        }  
    } until charging.monitor.charge >= 100;  
  
    then action endCharging : EndCharging;  
    then done;  
}
```

An *if action* performs its body if a Boolean condition is true. (It can also have an *else part*, which is performed if the condition is false.)

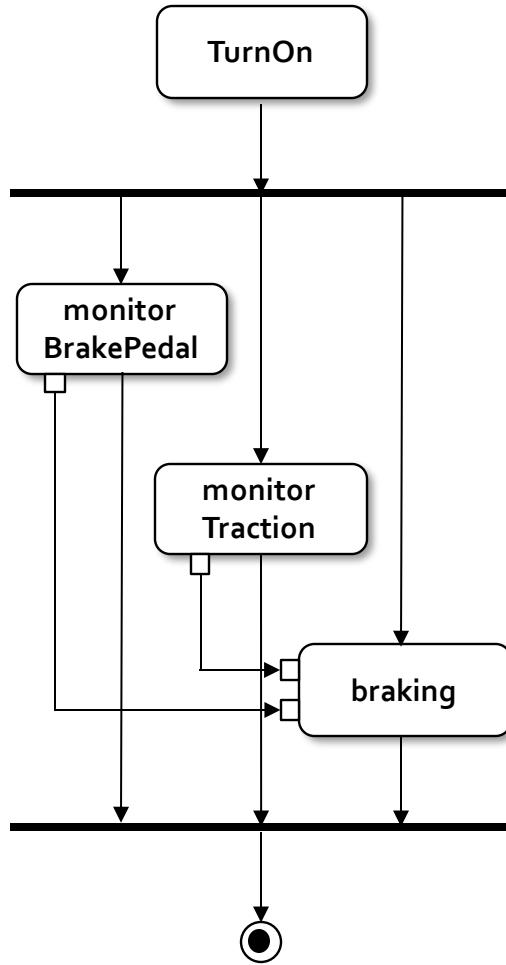
*until* introduces a Boolean condition that terminates the loop when it is true.

- ❶ A loop action can also begin with *while* (instead of *loop*), introducing a Boolean condition that terminates the loop when it is false.

This is the *body action*, which is given the name *charging*. (The default name is *body*.)

⚠ *if* used in this way represents an action, *not* a succession.

# Fork and Join Nodes



```

action def Brake {
  action TurnOn;
  then fork;
  then monitorBrakePedal;
  then monitorTraction;
  then braking;
}

action monitorBrakePedal : MonitorBrakePedal {
  out brakePressure; }
then joinNode;

action monitorTraction : MonitorTraction {
  out modulationFrequency; }
then joinNode;

action braking : Braking {
  in brakePressure flow from
    monitorBrakePedal.brakePressure;
  in modulationFrequency flow from
    monitorTraction.modulationFrequency; }
then joinNode;

join joinNode;
then done;
}
  
```

A **fork** node enables *all* its successors to happen after it.

The source for *all* these successions is the **fork** node.

A **join** node waits for *all* its predecessors to happen before continuing.

# Performed Actions

`perform` identifies the owner as the performer of an action.

This shorthand simply identifies the performed action owned elsewhere without renaming it locally.

```
part camera : Camera {  
  
    perform action takePhoto[*] ordered  
        :> takePicture;  
  
    part f : AutoFocus {  
        perform takePhoto.focus;  
    }  
  
    part i : Imager {  
        perform takePhoto.shoot;  
    }  
}
```

# Assignment Actions

A *for loop action* repeatedly performs its body, setting a *loop variable* to successive values from the result of a *sequence expression*.

An action may also be performed by another action (similar to a "call").

An *assignment action* sets the value of a feature to the result of an expression at the time of performance of the assignment.

```
action def ComputeMotion {
    in attribute powerProfile :> ISQ::power[*];
    in attribute vehicleMass :> ISQ::mass;
    in attribute initialPosition :> ISQ::length;
    in attribute initialSpeed :> ISQ::speed;
    in attribute deltaT :> ISQ::time;
    out attribute positions :> ISQ::length[*] := ( );
}

private attribute position := initialPosition;
private attribute speed := initialSpeed;

for i in 1..powerProfile->size()-1 {
    perform action dynamics : StraightLineDynamics {
        in power = powerProfile[i];
        in mass = vehicleMass;
        in delta_t = deltaT;
        in x_in = position; in v_in = speed;
        out x_out; out v_out;
    }
    then assign position := dynamics.x_out;
    then assign speed := dynamics.v_out;
    then assign positions :=
        positions->including(position);
}
```

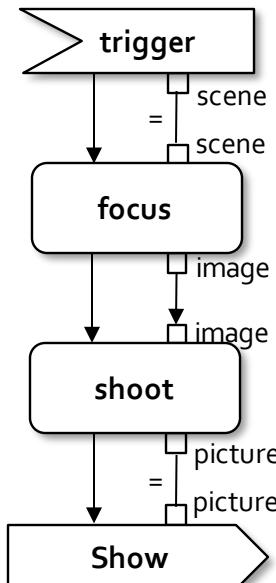
Using `:=` instead of `=` here indicates an *initial value*, instead of a binding.

This evaluates to the *i*'th value of the `powerProfile`.

ⓘ The functions `size` and `including` come from the `SequenceFunctions` library package.

# Asynchronous Messaging

An *accept action* receives an incoming asynchronous transfer any kind of values.



A *send action* is an outgoing transfer of values to a specific target.

This is the *name* of the action.

This is a declaration of what is being received, which can be anything.

```

action takePicture : TakePicture {
    action trigger accept scene : Scene;
    then action focus : Focus {
        in item scene = trigger.scene;
        out item image;
    }
    then action shoot : Shoot {
        in item image flow from focus.image;
        out item picture;
    }
    then send Show(shoot.picture) to screen;
}
  
```

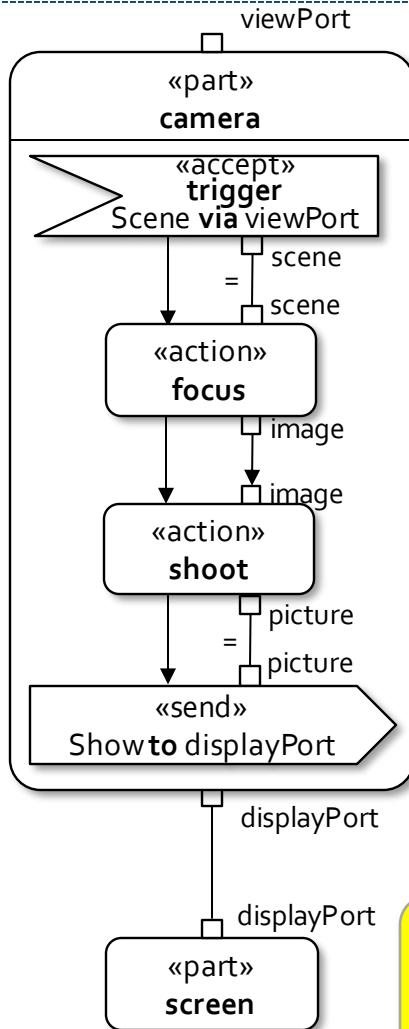
This is an *expression* evaluating to the value to be sent.

**i** The notation “*Show(...)*” means to create an instance of the definition *Show* with the given value for its nested attribute.

This is also an expression, evaluating to the target (in this case just a feature reference).

# Asynchronous Messaging through Ports

SST



```

part camera : Camera {
  port viewPort;
  port displayPort;

  perform action takePicture : TakePicture {
    action trigger accept scene : Scene via viewPort;

    then action focus : Focus {
      in item scene = trigger.scene;
      out item image;
    }

    then action shoot : Shoot {
      in item image flow from focus.image;
      out item picture;
    }

    then send Show(shoot.picture) to displayPort;
  }
}
  
```

An accept action can be *via* a specific port, meaning that the transfer is expected to be received on that port.

⚠ An asynchronous transfer can propagate over a connection, but that is not currently modeled as a flow.

A send action can target a specific port, meaning that the transfer is sent out over that port.

# Opaque Actions

An "opaque" action definition or usage can be specified using a *textual representation* annotation in a language other than SysML.

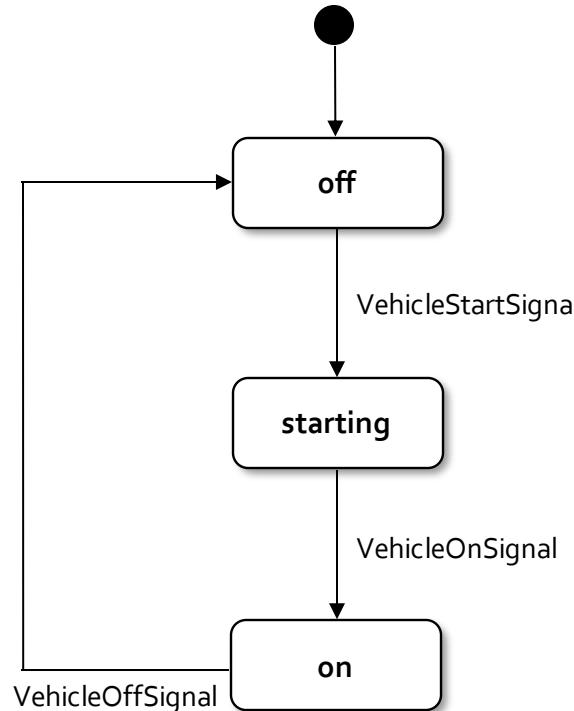
```
action def UpdateSensors (in sensors : Sensor[*]) {  
    language "Alf"  
    /*  
     * for (sensor in sensors) {  
     *     if (sensor.ready) {  
     *         Update(sensor);  
     *     }  
     * }  
     */  
}
```

The textual representation body is written using comment syntax. The `/*`, `*/` and leading `*` symbols are *not* included in the body text. Note that support for referencing SysML elements from the body text is tool-specific.

- ⓘ A textual representation annotation can actually be used with any kind of element, not just actions. OMG-standard languages a tool may support include "OCL" (Object Constraint Language) and "Alf" (Action Language for fUML). A tool can also provide support for other languages (e.g., "JavaScript" or "Modelica").

# State Definitions (1)

A state definition is like a state machine in UML and SysML v1. It defines a behavioral state that can be exhibited by a system.



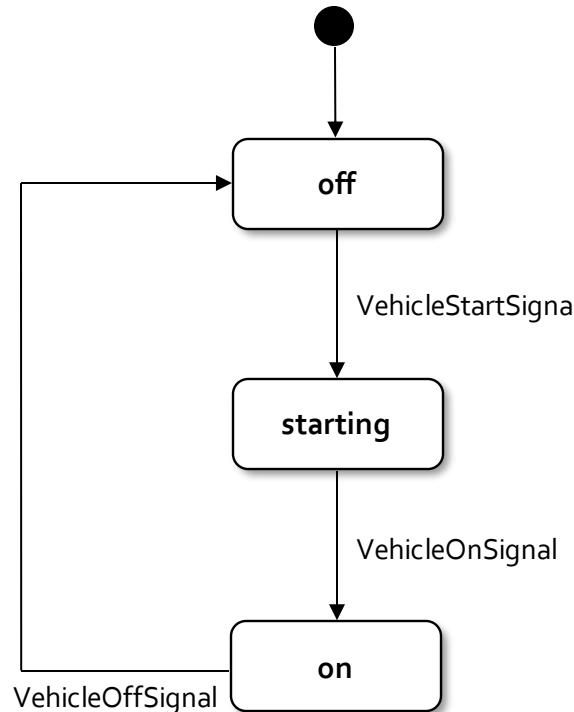
```
state def VehicleStates {  
    entry; then off;  
  
    state off;  
  
    transition off_to_starting  
        first off  
        accept VehicleStartSignal  
        then starting;  
  
    state starting;  
  
    transition starting_to_on  
        first starting  
        accept VehicleOnSignal  
        then on;  
  
    state on;  
  
    transition on_to_off  
        first on  
        accept VehicleOffSignal  
        then off;  
}
```

This indicates the the initial state after entry is "off".

A state definition can specify a set of discrete nested states.

States are connected by transitions that fire on acceptance of item transfers (like accept actions).

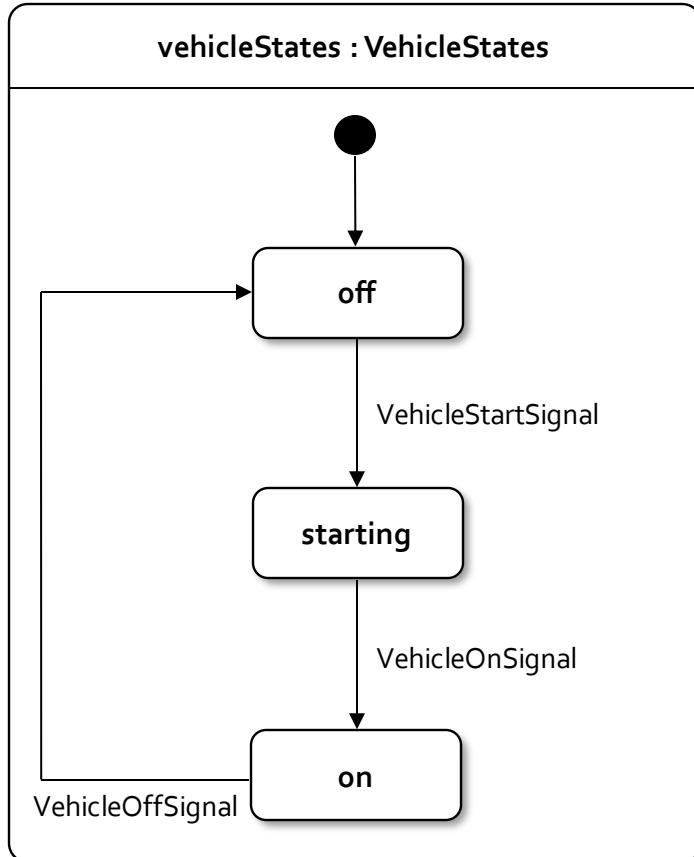
# State Definitions (2)



```
state def VehicleStates {  
    entry; then off;  
  
    state off;  
    accept VehicleStartSignal  
        then starting;  
  
    state starting;  
    accept VehicleOnSignal  
        then on;  
  
    state on;  
    accept VehicleOffSignal  
        then off;  
}
```

This is a shorthand for a transition whose source is the lexically previous state.

# State Decomposition



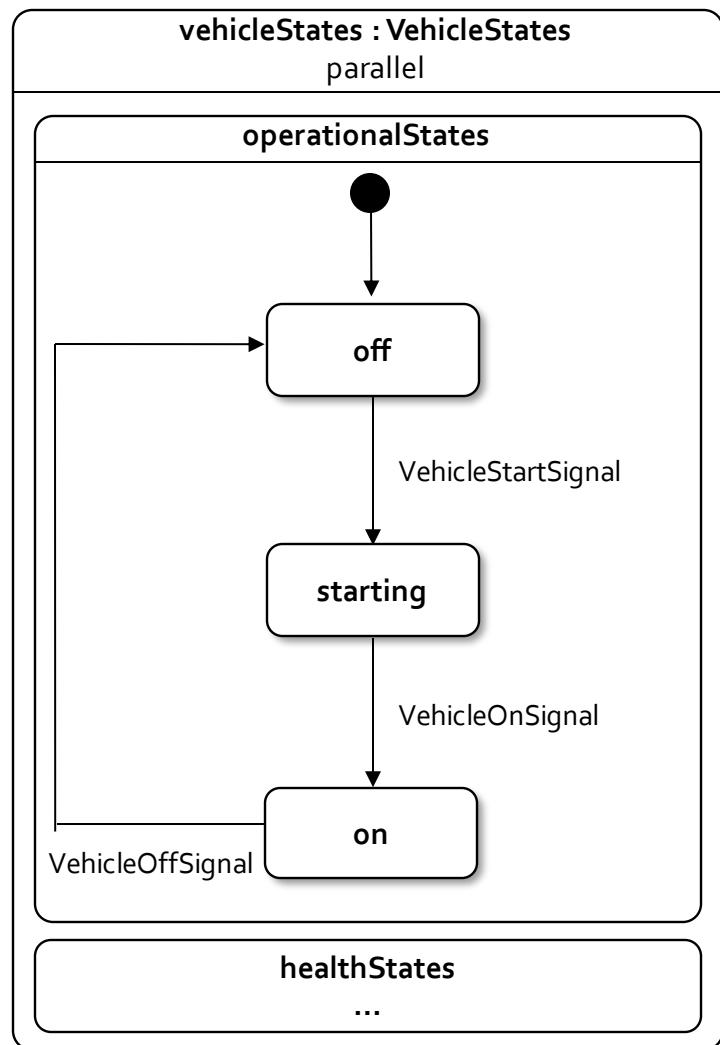
```
state def VehicleStates;  
  
state vehicleStates : VehicleStates {  
    entry; then off;  
  
    state off;  
    accept VehicleStartSignal  
    then starting;  
  
    state starting;  
    accept VehicleOnSignal  
    then on;  
  
    state on;  
    accept VehicleOffSignal  
    then off;  
}
```

A state can be explicitly declared to be a usage of a state definition.

A state can also be directly decomposed into other states.

- ⓘ This is just a part structure as before, only typed by state definitions instead of blocks.

# Concurrent States

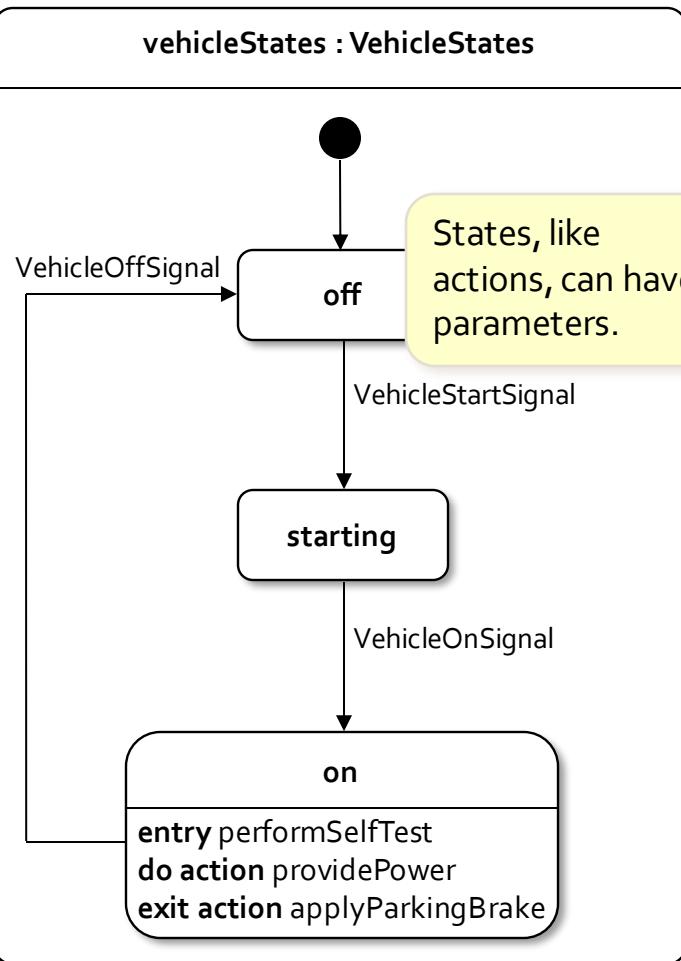


A *parallel state* is one whose nested states are concurrent.

```
state def VehicleStates;  
  
state vehicleStates : VehicleStates parallel {  
  
    state operationalStates {  
        entry; then off;  
  
        state off;  
        accept VehicleStartSignal  
            then starting;  
  
        state starting;  
        accept VehicleOnSignal  
            then on;  
  
        state on;  
        accept VehicleOffSignal  
            then off;  
    }  
  
    state healthStates {  
        ...  
    }  
}
```

⚠ Transitions are not allowed between concurrent states.

# State Entry, Do and Exit Actions



```
action performSelfTest(vehicle : Vehicle);

state def VehicleStates(operatingVehicle : Vehicle);

state vehicleStates : VehicleStates {
    in operatingVehicle : Vehicle;

    entry; then off;
    state off;
    accept VehicleStartSignal
        then starting;
    state starting;
    accept VehicleOnSignal
        then on;
    state on {
        entry performSelfTest
            (in vehicle = operatingVehicle);
        do action providePower { ... }
        exit action applyParkingBrake { ... }
    }
    accept VehicleOffSignal
        then off;
}
```

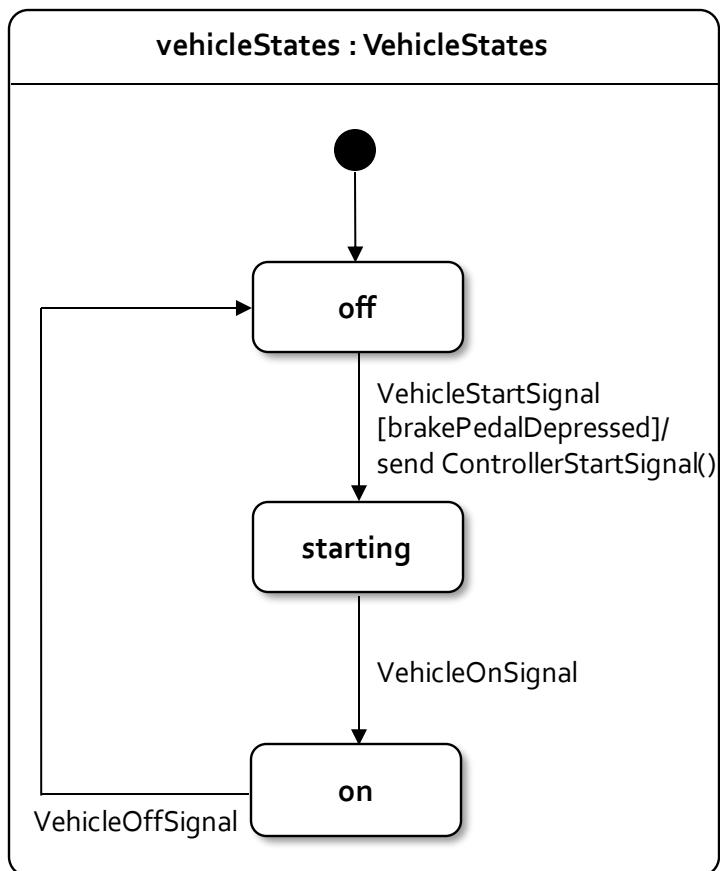
❶ An *entry action* is performed on entry to a state, a *do action* while in it, and an *exit action* on exit from it.

A state **entry**, **do** or **exit** can reference an action defined elsewhere...

... or the action can be defined within the state.

# Transition Guards and Effect Actions

SST



```

action performSelfTest(vehicle : Vehicle);

state def VehicleStates (
  operatingVehicle : Vehicle,
  controller : VehicleController);

state vehicleStates : VehicleStates {
  in operatingVehicle : Vehicle;
  in controller : VehicleController;

  entry; then off;

  state off;
  accept VehicleStartSignal
    if operatingVehicle.brakePedalDepressed
      do send ControllerStartSignal() to controller
    then starting;

  state starting;
  accept VehicleOnSignal
    then on;

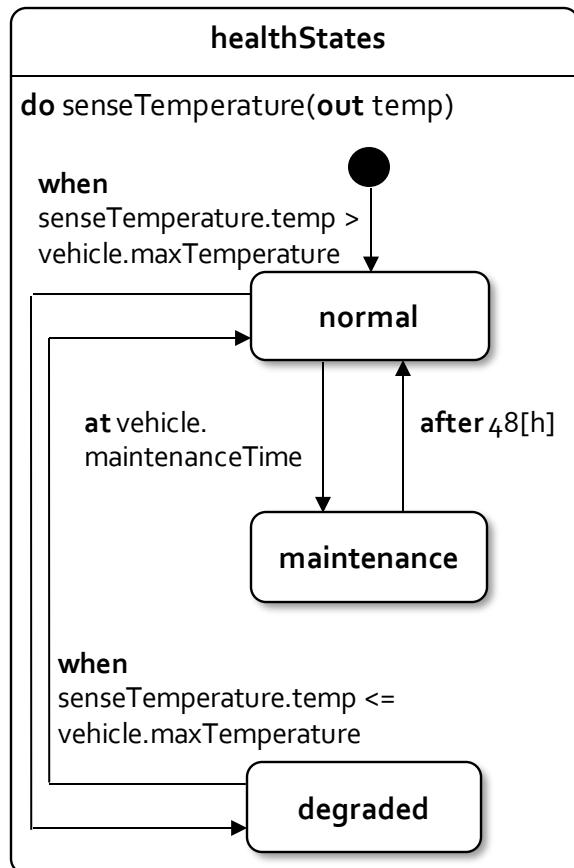
  state on { ... }
  accept VehicleOffSignal
    then off;
}
  
```

A *guard* is a condition that must be true for a transition to fire.

An *effect action* is performed when a transition fires, before entry to the target state.

# Change and Time Triggers

- Change and time triggers can also be used in accept actions.



```

action senseTemperature (out temp : TemperatureValue);

state healthStates {
    in vehicle : Vehicle;
    in controller : VehicleController;
}

entry; then normal;
do senseTemperature (out temp);

state normal;
accept at vehicle.maintenanceTime
then maintenance;
accept when senseTemperature.temp > vehicle.maxTemperature
do send OverTemp() to controller
then degraded;

state maintenance {
entry assign vehicle.maintenanceTime :=
vehicle.maintenanceTime + vehicle.maintenanceInterval;
}
accept after 48 [h]
then normal;

state degraded;
accept when senseTemperature.temp <= vehicle.maxTemperature
then normal;
}

```

An *absolute time trigger* fires at a given instant of time.

A *change trigger* fires when a given Boolean expression becomes true.

⚠ Time instant quantities are defined in the **Time package**, *not* the **ISO package**.

A *relative time trigger* fires after a given time duration.

# Exhibited States

**exhibit** identifies the part that is exhibiting states that are defined elsewhere.

```
part vehicle : Vehicle {  
  
    part vehicleController : VehicleController;  
  
    exhibit vehicleStates {  
        in operatingVehicle = vehicle;  
        in controller = vehicleController;  
    }  
}
```

Parameters for a state usage can be bound in the same way as parameters of an action usage.

# Occurrences, Time Slices and Snapshots (1) SST

① An occurrence is something that happens over time.  
Items and parts are structural occurrences. Actions are behavioral occurrences. Attributes are *not* occurrences.

A *time slice* represents a portion of the *lifetime* of an occurrence over some period of time.

A *snapshot* represents an occurrence at a specific point in time (a time slice with zero duration).

```
attribute def Date;  
  
item def Person;  
  
part def Vehicle {  
    timeslice assembly;  
  
    first assembly then delivery;  
  
    snapshot delivery;  
  
    first delivery then ownership;  
  
    timeslice ownership[0..*] ordered;  
  
    snapshot junked = done;  
}
```

A *succession* asserts that the first occurrence ends before the second can begin.

① Timeslices and snapshots are *suboccurrences*.

done is the name of the *end-of-life snapshot* of any occurrence.

# Occurrences, Time Slices and Snapshots (2) SST

```
part def Vehicle {  
    ...  
  
    snapshot delivery {  
        attribute deliveryDate : Date;  
    }  
  
    then timeslice ownership[0..*] ordered {  
        snapshot sale = start;  
  
        ref item owner : Person[1];  
  
        timeslice driven[0..*] {  
            ref item driver : Person[1];  
        }  
    }  
  
    snapshot junked = done;  
}
```

This is a shorthand for a succession after the lexically previous occurrence.

Time slices and snapshots can have nested time slices, snapshots and other features applicable during their occurrence.

*start* is the name of the *start-of-life snapshot* of any occurrence.

One occurrence references another during the same time period in the other reference's lifetime.

# Event Occurrences

An *event occurrence* is a reference to something that happens during the lifetime of another occurrence.

Event occurrences can be sequenced as usual using succession.

```
part driver : Driver {  
    event occurrence setSpeedSent;  
}  
  
part vehicle : Vehicle {  
    part cruiseController : CruiseController {  
        event occurrence setSpeedReceived;  
        then event occurrence sensedSpeedReceived;  
        then event occurrence fuelCommandSent;  
    }  
  
    part speedometer : Speedometer {  
        event occurrence sensedSpeedSent;  
    }  
  
    part engine : Engine {  
        event occurrence fuelCommandReceived;  
    }  
}
```

# Messages (1)

An *occurrence definition* defines a class of occurrences, without committing to whether they are structural or behavioral.

A *message* asserts that there is a *transfer* of some payload of a certain type from one occurrence to another (specifying the payload type is optional).

Messages can be explicitly ordered. Otherwise, they are only partially ordered by the time-ordering of their respective sources and targets.

```
occurrence def CruiseControlInteraction {
    ref part :>> driver;
    ref part :>> vehicle;

    message setSpeedMessage of SetSpeed
        from driver.setSpeedSent
        to vehicle.cruiseController.setSpeedReceived;

    message sensedSpeedMessage of SensedSpeed
        from vehicle.speedometer.sensedSpeedSent
        to vehicle.cruiseController.sensedSpeedReceived;

    message fuelCommandMessage of FuelCommand
        from vehicle.cruiseController.fuelCommandSent
        to vehicle.engine.fuelCommandReceived;

    first setSpeedMessage then sensedSpeedMessage;
}
```

# Messages (2)

An event can also be specified by reference to an identified occurrence (such as the source or target of a message).

Each message has a **source** and **target**, even if it is not explicitly identified in the message declaration.

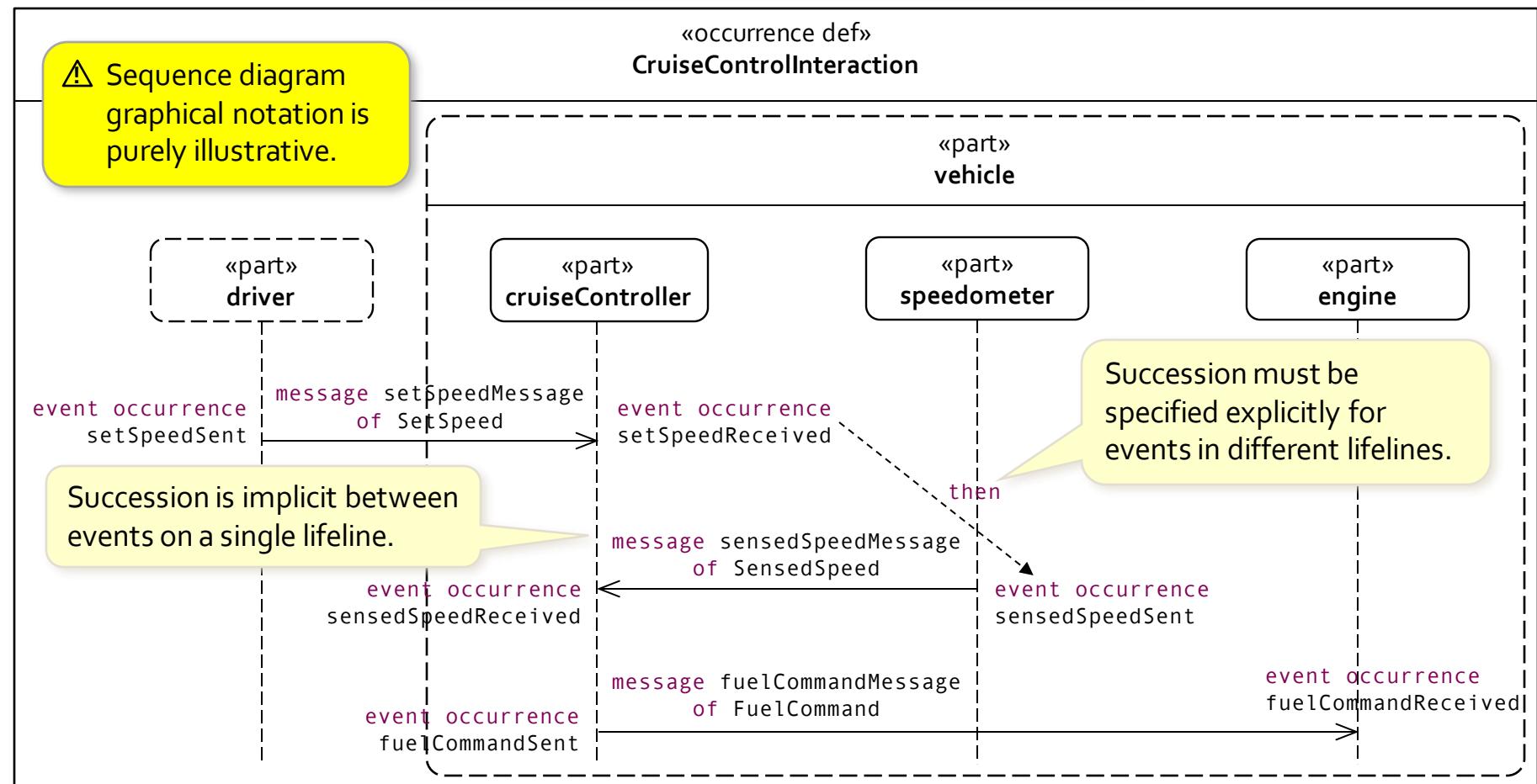
```
occurrence def CruiseControlInteraction {
    ref part driver : Driver {
        event setSpeedMessage::source;
    }

    ref part vehicle : Vehicle {
        part cruiseController : CruiseController {
            event setSpeedMessage::target;
            then event sensedSpeedMessage::target;
            then event fuelCommandMessage::source;
        }
        part speedometer : Speedometer {
            event sensedSpeedMessage::source;
        }
        part engine : Engine {
            event fuelCommandMessage::target;
        }
    }

    message setSpeedMessage of SetSpeed;
    then message sensedSpeedMessage of SensedSpeed;
    message fuelCommandMessage of FuelCommand;
}
```

# Interactions

- ① Event occurrences and messages can be used together to specify an *interaction* between parts without committing to *how* the interaction happens.



# Interaction Realization by Actions (1)

SST

In this model, event occurrences are realized by nested send and accept actions.

```
part driver_a : Driver {
    perform action driverBehavior {
        send SetSpeed() to vehicle_a;
    }
}

part vehicle_a : Vehicle {
    part cruiseController_a : CruiseController {
        perform action controllerBehavior {
            accept SetSpeed via vehicle_a;
            then accept SensedSpeed via cruiseController_a;
            then send FuelCommand() to engine_a;
        }
    }
}

part speedometer_a : Speedometer {
    perform action speedometerBehavior {
        send SensedSpeed() to cruiseController_a;
    }
}

part engine_a : Engine {
    perform action engineBehavior {
        accept FuelCommand via engine_a;
    }
}
```

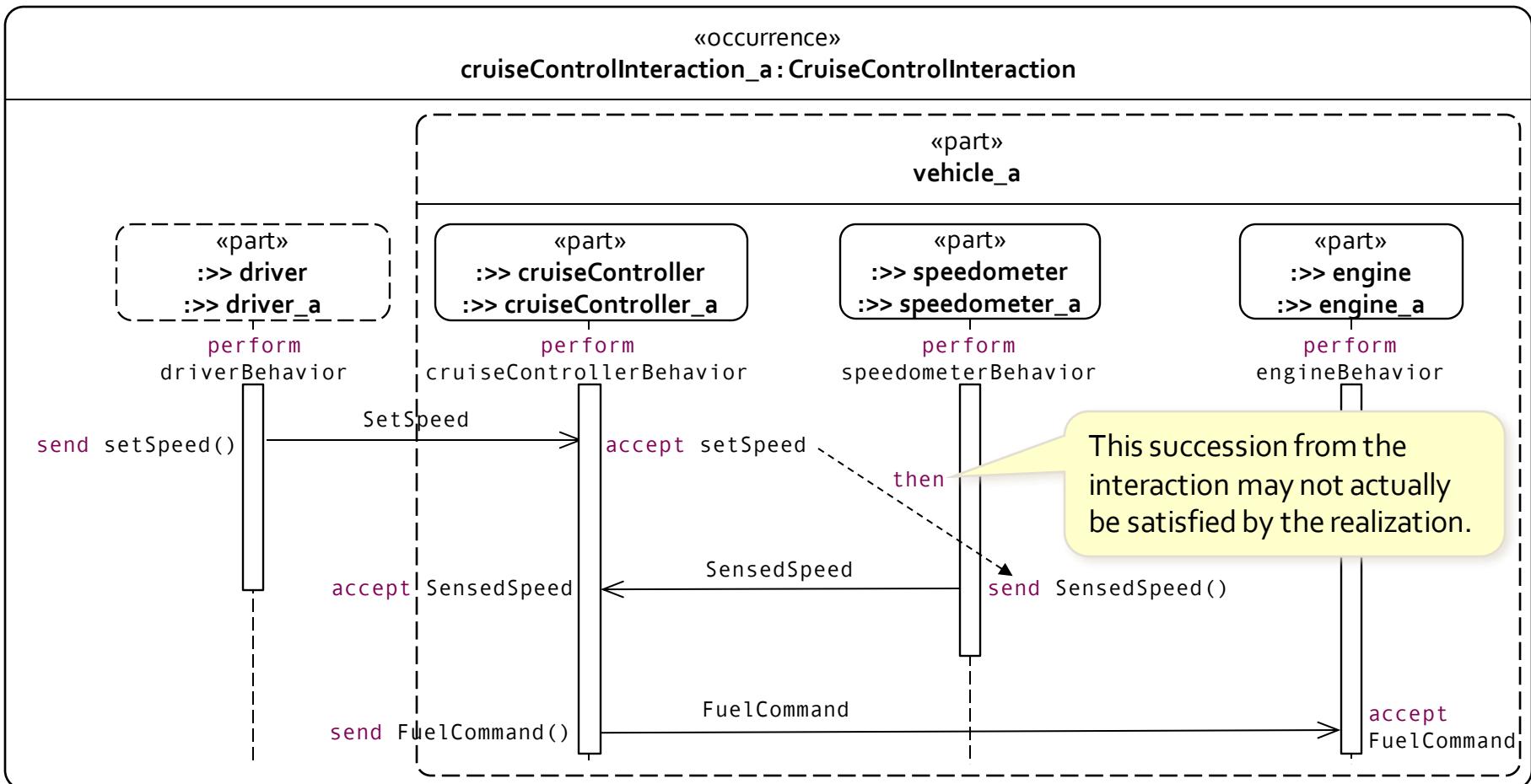
Messages are realized by the implicit transfers between send actions and corresponding accept actions.

① An interaction can be *realized* by many different models. A valid realization must have suboccurrences that can be identified with all the events and messages in the interaction.

① In more realistic cases, a realizing model will have more extensive behavior, only a subset of which will conform to any one interaction model.

# Interaction Realization by Actions (2)

SST



# Interaction Realization by Flows (1)

In this model, event occurrences are realized by values leaving from and arriving at ports.

Messages are realized by explicit flows between features of ports.

```
part driver_b : Driver {
    port setSpeedPort {
        out setSpeed : SetSpeed;
    }
}

interface driver_b.setSpeedPort to vehicle_b.setSpeedPort {
    flow of SetSpeed from driver_b.setSpeedPort.setSpeed
        to vehicle_b.setSpeedPort.setSpeed;
}

part vehicle_b : Vehicle {
    port setSpeedPort {
        in setSpeed : SetSpeed;
    }
}

part cruiseController_b : CruiseController {
    port setSpeedPort {
        in setSpeed : SetSpeed = vehicle_b.setSpeedPort.setSpeed;
    }
    port sensedSpeedPort {
        in sensedSpeed : SensedSpeed;
    }
    ...
}

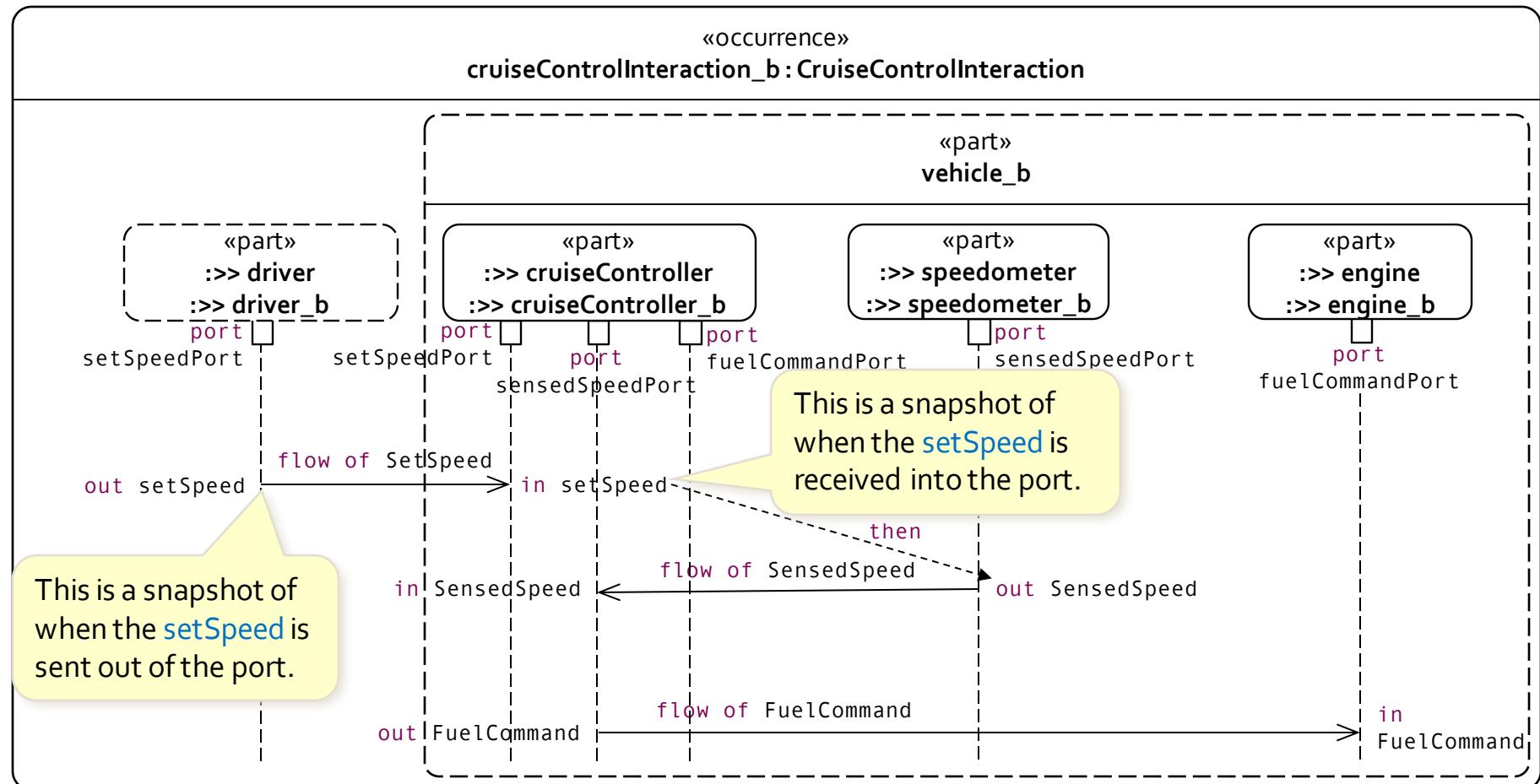
flow of SensedSpeed from speedometer_b.sensedSpeedPort.sensedSpeed
    to cruiseController_b.sensedSpeedPort.sensedSpeed;

part speedometer_b : Speedometer {
    port sensedSpeedPort {
        out sensedSpeed : SensedSpeed;
    }
}
...
```

❶ Ports are also suboccurrences of the parts that contain them.

# Interaction Realization by Flows (2)

SST



# Individuals and Snapshots (1)

An *individual definition* is an occurrence definition (of any kind) restricted to model a single individual and how it changes over its lifetime.

As occurrences, individuals can have snapshots that describe them at a single instant of time.

This is a compact notation for showing redefinition of an attribute usage.

An individual definition will often specialize a definition of the general class of things the individual is one of.

```
individual item def PhysicalContext;
individual part def Vehicle_1 :> Vehicle;

individual item context : PhysicalContext {

snapshot part vehicle_1_t0 : Vehicle_1
    :>> mass = 2000.0;
    :>> status {
        :>> gearSetting = 0;
        :>> acceleratorPosition = 0.0;
    }
}
```

An *individual usage* represents an individual during some portion of its lifetime.

An attribute does not have snapshots, but it can be asserted to have a specific value in a certain snapshot.

# Individuals and Snapshots (2)

```
individual item context : PhysicalContext {  
  
    snapshot part vehicle_1_t0 : Vehicle_1 {  
        :>> mass = 2000.0;  
        :>> status {  
            :>> gearSetting = 0;  
            :>> acceleratorPosition = 0.0;  
        }  
    }  
  
    snapshot part vehicle_1_t1 : Vehicle_1 {  
        :>> mass = 1500.0;  
        :>> status {  
            :>> gearSetting = 2;  
            :>> acceleratorPosition = 0.5;  
        }  
    }  
  
    first vehicle_1_t0 then vehicle_1_t1;  
}
```

As usual, succession asserts that the first snapshot occurs before the second in time, in some context.

The values of the attributes of an individual can change over time.

```
individual part def Vehicle_1 :> Vehicle {  
    part leftFrontWheel : Wheel;  
    part rightFrontWheel : Wheel;  
}  
  
individual part def Wheel_1 :> Wheel;  
  
individual part vehicle_1 : Vehicle_1 {  
  
    snapshot part vehicle_1_t0 {  
        snapshot leftFrontWheel_t0 : Wheel_1 :>> leftFrontWheel;  
    }  
  
    then snapshot part vehicle_1_t1 {  
        snapshot rightFrontWheel_t1 : Wheel_1 :>> rightFrontWheel;  
    }  
}
```

By default, these are snapshots of the containing individual.

During the first snapshot of [Vehicle\\_1](#), [Wheel\\_1](#) has the role of the [leftFrontWheel](#).

During a later snapshot, the *same* [Wheel\\_1](#) has the role of the [rightFrontWheel](#).

# Individuals and Time Slices

A time slice represents an individual over some period of time (that this is a time slice of a part is implicit).

`start` and `done` are snapshots at the beginning and end of the time slice.

Succession asserts that the first time slice must complete before the second can begin.

```
individual item def Alice :> Person;
individual item def Bob :> Person;

individual part : Vehicle_1 {

    timeslice aliceDriving {
        ref individual item :>> driver : Alice;

        snapshot :>> start {
            :>> mass = 2000.0;
        }

        snapshot :>> done {
            :>> mass = 1500.0;
        }
    }

    then timeslice bobDriving {
        ref individual item :>> driver : Bob;
    }
}
```

During this time slice of `Vehicle_1`, the `Alice` has the role of the `driver`.

During a later time slice of `Vehicle_1`, `Bob` has the role of the `driver`.

# Expressions and Feature Values

```
package MassRollup1 {  
    import ScalarFunctions::*;

    part def MassedThing {  
        attribute simplMass :> ISQ::mass;  
        attribute totalMass :> ISQ::mass;  
    }

    part simpleThing : MassedThing {  
        attribute :>> totalMass = simpleMass;  
    }

    part compositeThing : MassedThing {  
        part subcomponents: MassedThing[*];  
        attribute :>> totalMass =  
            simpleMass + sum(subcomponents.totalMass);  
    }
}
```

An *expression* in general is a computation expressed using a typical mathematical operator notation.

ISQ::mass is a standard quantity kind from the *International System of Quantities* library model.

A *feature value* is a shorthand for binding a feature to the result of an expression (here simply the value of another feature).

The dot notation can be used as an expression to read the values of a feature. Here, the **totalMass** is collected for each of the subcomponents.

# Car Mass Rollup Example (1)

```
import ScalarValues::*;
import MassRollup1::*;

part def CarPart :> MassedThing {
    attribute serialNumber : String;
}

part car: CarPart :> compositeThing {
    attribute vin :>> serialNumber;
    part carParts : CarPart[*] :>> subcomponents;
    part engine :> simpleThing, carParts { ... }
    part transmission :> simpleThing, carParts { ... }
}

// Example usage
import SI::kg;
part c :> car {
    attribute :>> simpleMass = 1000[kg];
    part :>> engine {
        attribute :>> simpleMass = 100[kg];
    }
    part attribute transmission {
        attribute :>> simpleMass = 50[kg];
    }
}

// c.totalMass --> 1150.0[kg]
```

This is an expression for a quantity with a specific numeric value and unit. Note that units are identified on the quantity *value*, *not* the type.

The **totalMass** of **c** can be computed using the feature value expressions from **simpleThing** and **compositeThing**.

# Default Values

```
package MassRollup2 {  
    import ScalarFunctions::*;

    part def MassedThing {  
        attribute simpleMass :> ISQ::mass;  
        attribute totalMass :> ISQ::mass default simpleMass;  
    }

    part compositeThing : MassedThing {  
        part subcomponents: MassedThing[*];  
        attribute :>> totalMass default mass + sum(subcomponents.totalMass);  
    }

    part filteredMassThing :> compositeThing {  
        attribute minMass : ISQ::mass;  
        attribute :>> totalMass =  
            sum(subcomponents.totalMass.?{in p:>ISQ::mass; p >= minMass});  
    }
}
```

A *default value* is feature value that applies *unless* explicitly overridden.

A default value can be overridden when the feature is redefined, with a default or bound value.

Once bound, the value of the feature is *fixed* as the result of the value expression.

A dot can be followed by a *select* expression in order to filter a collection of values.

# Car Mass Rollup Example (2)

```
import ScalarValues::*;
import MassRollup2::*;

part def CarPart :> MassedThing {
    attribute serialNumber : String;
}

part car: CarPart :> compositeThing {
    attribute vin :>> serialNumber;
    part carParts : CarPart[*] :>> subcomponents;
    part engine :> carParts { ... }
    part transmission :> carParts { ... }
}

// Example usage
import SI::kg;
part c :> car {
    attribute :>> simpleMass = 1000[kg];
    part :>> engine {
        attribute :>> simpleMass = 100[kg];
    }
    part attribute transmission {
        attribute :>> simpleMass = 50[kg];
    }
}
// c.totalMass --> 1150.0[kg]
```

The default of `totalMass` to `simpleMass` is inherited.

The default for `totalMass` is overridden as specified in `compositeThing`.

The `totalMass` default is *not* overridden for the nested `carParts`.

When computing the `totalMass` of `c`, `c.engine` and `c.transmission`, the relevant defaults are used.

# Calculation Definitions

A *calculation definition* is a reusable, parameterized expression.

```
calc def Power (  
    whlpwr : PowerValue,  
    Cd : Real,  
    Cf : Real,  
    tm : MassValue,  
    v : SpeedValue ) : PowerValue {
```

*Calculation parameters* are similar to the parameters on actions.

A calculation has a single *return result*.

```
    attribute drag = Cd * v;  
    attribute friction = Cf * tm *
```

The calculation can include the computation of intermediate values.

```
    whlpwr - drag - friction  
}
```

The calculation *result expression* must conform to the return type.

```
calc def Acceleration (tp: PowerValue, tm : MassValue, v: SpeedValue) : AccelerationValue {  
    tp / (tm * v)  
}
```

⚠ There is no semicolon at the end of a result expression.

```
calc def Velocity (dt : TimeValue, v0 : SpeedValue, a : AccelValue) : SpeedValue  
= v0 + a * dt;
```

```
calc def Position (dt : TimeValue, x0 : LengthValue, v : SpeedValue) : LengthValue  
= x0 + v * dt;
```

If there are no intermediate computations, a shortened form can be used.

# Calculation Usages (1)

```
part def VehicleDynamics {  
    attribute C_d : Real;  
    attribute C_f : Real;  
    attribute wheelPower : PowerValue;  
    attribute mass : MassValue;  
  
    action straightLineDynamics(  
        in delta_t : TimeValue,  
        in v_in : SpeedValue, in x_in : LengthValue,  
        out v_out : SpeedValue, out x_out : LengthValue) {  
  
        calc acc : Acceleration (  
            tp = Power(wheelPower, C_d, C_f, mass, v_in) ,  
            tm = mass,  
            v = v_in  
        ) return a;  
  
        calc vel : Velocity (  
            dt = delta_t,  
            v0 = v_in,  
            a = acc.a  
        ) return v = v_out;  
  
        calc pos : Position (  
            dt = delta_t,  
            x0 = x_in,  
            v = vel.v  
        ) return x = x_out;  
    }  
}
```

Values are bound to the parameters of *calculation usages* (similar to action parameters).

- ➊ Note that the return result is *outside* the parentheses. The `return` keyword is optional.

A calculation definition can also be *invoked* as an expression, with input values given as arguments, evaluating to the result of the calculation.

Calculation results can be referenced by name and/or bound (like action output parameters).

# Calculation Usages (2)

```
attribute def DynamicState {  
    attribute v: SpeedValue;  
    attribute x: LengthValue;  
}  
  
part def VehicleDynamics {  
    attribute C_d : Real;  
    attribute C_f : Real;  
    attribute wheelPower : PowerValue;  
    attribute mass : MassValue;  
  
    calc updateState  
        (delta_t : TimeValue, currState : DynamicState) {  
  
        attribute totalPower : PowerValue =  
            Power(wheelPower, C_d, C_f, mass, currState.v);  
  
        return attribute newState : DynamicState {  
            :>> v = Velocity(delta_t, currState.v, Acceleration(totalPower, mass, currState.v));  
            :>> x = Position(delta_t, currState.x, currState.v);  
        }  
    }  
}
```

A calculation can be specified without an explicit calculation definition.

Calculations can also handle structured values.

This is a declaration of the result *parameter* of the calculation, with bound subattributes.

# Constraint Definitions (1)

⚠ There is no semicolon at the end of a constraint expression.

A *constraint* is the usage of a constraint definition, which may be true or false in a given context.

ⓘ A constraint may be *violated* (false) without making the model inconsistent.

```
import ISQ::*;
import SI::*;
import ScalarFunctions::*;

constraint def MassConstraint (
    partMasses : MassValue[0..*],
    massLimit : MassValue) {
    sum(partMasses) <= massLimit
}

part def Vehicle {
    constraint massConstraint : MassConstraint (
        partMasses = (chassisMass, engine.mass, transmission.mass),
        massLimit = 2500[kg]);
    attribute chassisMass : MassValue;
}

part engine : Engine {
    attribute mass : MassValue;
}

part transmission : Engine {
    attribute mass : MassValue;
}
```

A *constraint definition* is a reusable, parameterized Boolean expression.

*Constraint parameters* are similar to the parameters on actions.

The *constraint expression* can be any Boolean expression using the constraint parameters.

Values are bound to constraint parameters (similarly to actions).

# Constraint Definitions (2)

```
import ISQ::*;
import SI::*;
import ScalarFunctions::*;

constraint def MassConstraint {
    attribute partMasses : MassValue[0..*];
    attribute massLimit : MassValue;

    sum(partMasses) <= massLimit
}

part def Vehicle {
    constraint massConstraint : MassConstraint {
        redefines partMasses = (chassisMass, engine.mass, transmission.mass);
        redefines massLimit = 2500[kg];
    }

    attribute chassisMass : MassValue;
}

part engine : Engine {
    attribute mass : MassValue;
}

part transmission : Engine {
    attribute mass : MassValue;
}
```

Alternatively, constraint parameters may be modeled as attribute or reference features.

The constraint parameter properties are then redefined in order to be bound.

# Constraint Assertions (1)

```
import ISQ::*;

import SI::*;
import ScalarFunctions::*;

constraint def MassConstraint (
    partMasses : MassValue[0..*],
    massLimit : MassValue) {

    sum(partMasses) <= massLimit
}

part def Vehicle {
    assert constraint massConstraint : MassConstraint (
        partMasses = (chassisMass, engine.mass, transmission.mass),
        massLimit = 2500[kg]);

    attribute chassisMass : MassValue;

    part engine : Engine {
        attribute mass : MassValue;
    }

    part transmission : Engine {
        attribute mass : MassValue;
    }
}
```

A *constraint assertion* asserts that a constraint *must* be true.

ⓘ If an assertion is violated, then the model is *inconsistent*.

# Constraint Assertions (2)

The constraint expression can also be defined on a *usage* of a constraint def.

```
constraint def MassConstraint (
    partMasses : MassValue[0..*],
    massLimit : MassValue);

constraint massConstraint : MassConstraint (
    partMasses : MassValue[0..*],
    massLimit : MassValue) {
    sum(partMasses) <= massLimit
}

part def Vehicle {
    assert massConstraint (
        partMasses = (chassisMass, engine.mass, transmission.mass),
        massLimit = 2500[kg]);

    attribute chassisMass : MassValue;

    attribute engine : Engine {
        value mass : MassValue;
    }

    attribute transmission : Engine {
        value mass : MassValue;
    }
}
```

A named constraint can be asserted in multiple contexts.

# Derivation Constraints

```
part vehicle1 : Vehicle {  
    attribute totalMass : MassValue;  
    assert constraint {totalMass == chassisMass + engine.mass + transmission.mass}  
}  
  
part vehicle2 : Vehicle {  
    attribute totalMass : MassValue = chassisMass + engine.mass + transmission.mass;  
}  
  
constraint def AveragedDynamics (  
    mass: MassValue,  
    initialSpeed : SpeedValue,  
    finalSpeed : SpeedValue,  
    deltaT : TimeValue,  
    force : ForceValue ) {  
  
    force * deltaT == mass * (finalSpeed - initialSpeed) &  
    mass > 0[kg]  
}
```

In UML and SysML v1, constraints are often used to define *derived values*.

In SysML v2 this can usually be done more directly using a binding.

⚠ Be careful about the difference between `==`, which is the Boolean-valued equality operator, and `=`, which denotes binding.

However, constraints allow for more general equalities and inequalities than direct derivation.

# Analytical Constraints

```
constraint def StraightLineDynamicsEquations(
    p : PowerValue, m : MassValue, dt : TimeValue,
    x_i : LengthValue, v_i : SpeedValue,
    x_f : LengthValue, v_f : SpeedValue,
    a : AccelerationValue
) {
    attribute v_avg : SpeedValue = (v_i + v_f)/2;

    a == Acceleration(p, m, v_avg) &
    v_f == Velocity(dt, v_i, a) &
    x_f == Position(dt, x_i, v_avg)
}
```

```
action def StraightLineDynamics (
    in power : PowerValue, in mass : MassValue, in delta_t : TimeValue,
    in x_in : LengthValue, in v_in : SpeedValue,
    out x_out : LengthValue, out v_out : SpeedValue,
    out a_out : AccelerationValue
) {
    assert constraint dynamics : StraightLineDynamicsEquations (
        p = power, m = mass, dt = delta_t,
        x_i = x_in, v_i = v_in,
        x_f = x_out, v_f = v_out,
        a = a_out
    );
}
```

This constraint definition provides a reusable specification of a system of (coupled) equations.

ⓘ Note the use of the calculation definitions defined earlier.

An action definition is inherently "causal" in the sense that outputs are determined in terms of inputs.

ⓘ This specifies that the action outputs must be solved for analytically given the action inputs, consistent with the asserted constraint.

A constraint is inherently "acausal" – it is simply true or false for given values of its parameters.

# Time Constraints

```
state healthStates {  
    in vehicle : Vehicle;  
  
    entry; then normal;  
  
    state normal;  
    accept at vehicle.maintenanceTime  
        then maintenance;  
  
    state maintenance {  
        assert constraint { TimeOf(maintenance) > vehicle.maintenanceTime }  
        assert constraint { TimeOf(maintenance) - TimeOf(normal.done) < 2 [s] }  
    }  
    entry assign vehicle.maintenanceTime :=  
        vehicle.maintenanceTime + vehicle.maintenanceInterval;  
    }  
    accept MaintenanceDone  
        then normal;  
  
    constraint { DurationOf(maintenance) <= 48 [h] }  
}
```

ⓘ TimeOf and DurationOf are from the Time package in the Quantities and Units Domain Library.

TimeOf returns the time of the start of an occurrence (in this example, a state performance).

DurationOf returns the time duration of an occurrence (the difference between its start and done times).

# Requirement Definitions (1)

A *requirement definition* is a special kind of constraint definition.

A textual statement of the requirement can be given as a documentation comment in the requirement definition body.

```
requirement def MassLimitationRequirement {  
    doc /* The actual mass shall be less than or equal  
        * to the required mass. */  
  
    attribute massActual : MassValue;  
    attribute massReqd : MassValue;  
  
    require constraint { massActual <= massReqd }  
}
```

Like a constraint definition, a requirement definition can be parameterized using features.

The requirement can be formalized by giving one or more component *required constraints*.

# Requirement Definitions (2)

```
part def Vehicle {  
    attribute dryMass: MassValue;  
    attribute fuelMass: MassValue;  
    attribute fuelFullMass: MassValue;  
    ...  
}  
  
requirement def <'1'> VehicleMassLimitationRequirement :> MassLimitationRequirement {  
    doc /* The total mass of a vehicle shall be less than or equal to the required mass. */  
    subject vehicle : Vehicle;  
    attribute redefines massActual = vehicle.dryMass + vehicle.fuelMass;  
    assume constraint { vehicle.fuelMass > 0[kg] }  
}
```

A requirement definition may have a modeler specified *human id*, which is an alternate name for it.

ⓘ Actually, any identifiable element can have a human id, not just requirements.

A requirement definition is always about some *subject*, which may be implicit or specified explicitly.

Features of the subject can be used in the requirement definition.

A requirement definition may also specify one or more *assumptions*.

# Requirement Definitions (3)

The subject of a requirement definition can have any kind of definition.

```
port def ClutchPort;
action def GenerateTorque;

requirement def <'2'> DrivePowerInterfaceRequirement {
    doc /* The engine shall transfer its generated torque to the transmission
        * via the clutch interface. */
    subject clutchPort: ClutchPort;
}

requirement def <'3'> TorqueGenerationRequirement {
    doc /* The engine shall generate torque as a function of RPM as shown in Table 1. */
    subject generateTorque: GenerateTorque;
}
```

# Requirement Usages

A requirement may optionally have its own human id.

A *requirement* is the usage of a requirement definition.

```
requirement <'1.1'> fullVehicleMassLimit : VehicleMassLimitationRequirement {
    subject vehicle : Vehicle;
    attribute :>> massReqd = 2000[kg];

    assume constraint {
        doc /* Fuel tank is full.*/
        vehicle.fuelMass == vehicle.fuelFullMass
    }
}

requirement <'1.2'> emptyVehicleMassLimit : VehicleMassLimitationRequirement {
    subject vehicle : Vehicle;
    attribute :>> massReqd = 1500[kg];

    assume constraint {
        doc /* Fuel tank is empty.*/
        vehicle.fuelMass == 0[kg]
    }
}
```

A requirement will often bind requirement definition parameters to specific values.

# Requirement Groups

A requirement may also be used to group other requirements.

Requirements can be grouped by reference...

...or by composition.

- ① Grouped requirements are treated as required constraints of the group.

```
requirement vehicleSpecification {
    doc /* Overall vehicle requirements group */
    subject vehicle : Vehicle;

    require fullVehicleMassLimit;
    require emptyVehicleMassLimit;
}

part def Engine {
    port clutchPort: ClutchPort;
    perform action generateTorque: GenerateTorque;
}

requirement engineSpecification {
    doc /* Engine power requirements group */
    subject engine : Engine;

    requirement drivePowerInterface : DrivePowerInterfaceRequirement {
        subject clutchPort = engine.clutchPort;
    }

    requirement torqueGeneration : TorqueGenerationRequirement {
        subject generateTorque = engine.generateTorque;
    }
}
```

By default, the subject of grouped requirements is assumed to be the same as that of the group.

The subject of a grouped requirement can also be bound explicitly.

# Requirement Satisfaction

```
part vehicle_c1 : Vehicle {  
    part engine_v1: Engine { ... }  
    ...  
}  
  
part 'Vehicle c1 Design Context' {  
    ref vehicle_design :> vehicle_c1;  
  
    satisfy vehicleSpecification by vehicle_design;  
    satisfy engineSpecification by vehicle_design.engine_v1;  
}
```

A *requirement satisfaction* asserts that a given requirement is satisfied when its subject parameter is bound to a specific thing.

- ① Formally, a requirement is *satisfied* for a subject if, when all its assumed constraints are true, then all its required constraints are true.

# Analysis Case Definitions (1)

An *analysis case definition* defines the computation of the result of analyzing some *subject*, meeting an *objective*.

```
analysis def FuelEconomyAnalysis {  
    subject vehicle : Vehicle;  
    return fuelEconomyResult : DistancePerVolumeValue;  
  
    objective fuelEconomyAnalysisObjective {  
        doc /*  
         * The objective of this analysis is to determine whether the  
         * subject vehicle can satisfy the fuel economy requirement.  
         */  
  
        assume constraint {  
            vehicle.wheelDiameter == 33['in'] and  
            vehicle.driveTrainEfficiency == 0.4  
        }  
  
        require constraint {  
            fuelEconomyResult > 30[mi / gallon]  
        }  
    }  
    ...  
}
```

The subject may be specified similarly to the subject of a requirement definition.

The analysis result is declared as a return result (as for a calculation definition).

The objective of this analysis is to determine whether the subject vehicle can satisfy the fuel economy requirement.

The analysis objective is specified as a requirement, allowing both assumed and required constraints.

The objective is a requirement on the result of the analysis case.

# Analysis Case Definitions (2)

The steps of an analysis case are actions that, together, compute the analysis result.

The second step computes the fuel economy result, given the power profile determined in the first step.

```
analysis def FuelEconomyAnalysis {
    subject vehicle : Vehicle;
    return fuelEconomyResult : Distance
    ...
    in attribute scenario[*] {
        time : TimeValue;
        position : LengthValue;
        velocity : SpeedValue;
    }
    action solveForPower {
        out power: PowerValue[*];
        out acceleration: AccelerationValue[*];
        assert constraint {
            (1..size(scenario)-1)->forAll {in i : Positive;
                StraightLineDynamicsEquations (
                    power[i], vehicle.mass,
                    scenario.time[i+1] - scenario.time[i],
                    scenario.position[i], scenario.velocity[i],
                    scenario.position[i+1], scenario.velocity[i+1],
                    acceleration[i+1]))
        }
    }
    then action solveForFuelEconomy {
        in power : PowerValue[*] = solveForPower.power;
        out fuelEconomy : DistancePerVolumeValue = fuelEconomyResult;
        ...
    }
}
```

Additional parameters can be specified in the case body.

The first step solves for the engine power needed for a given position/velocity scenario.

```
part vehicleFuelEconomyAnalysisContext {  
  
    requirement vehicleFuelEconomyRequirements{subject vehicle : Vehicle; ... }  
  
    attribute cityScenario :> FuelEconomyAnalysis::scenario = { ... };  
    attribute highwayScenario :> FuelEconomyAnalysis::scenario = { ... };  
  
    analysis cityAnalysis : FuelEconomyAnalysis {  
        subject vehicle = vehicle_c1;  
        in scenario = cityScenario;  
    }  
  
    analysis highwayAnalysis : FuelEconomyAnalysis {  
        subject vehicle = vehicle_c1;  
        in scenario = highwayScenario;  
    }  
  
    part vehicle_c1 : Vehicle {  
        ...  
        attribute :>> fuelEconomy_city = cityAnalysis.fuelEconomyResult;  
        attribute :>> fuelEconomy_highway = highwayAnalysis.fuelEconomyResult;  
    }  
  
    satisfy vehicleFuelEconomyRequirements by vehicle_c1;  
}
```

The previously defined analysis is carried out for a specific vehicle configuration for two different scenarios.

The subject and parameters are automatically redefined, so redefinition does not need to be specified explicitly.

If the vehicle fuel economy is set to the results of the analysis, then this configuration is asserted to satisfy the desired fuel economy requirements.

# Trade-off Study Analysis

The [TradeStudy](#) analysis definition from the [TradeStudies](#) domain library model provides a general framework for defining basic trade study analyses.

```
analysis engineTradeStudy : TradeStudies::TradeStudy {  
    subject : Engine = (engine4cyl, engine6cyl);  
    objective : MaximizeObjective;  
  
    calc :>> evaluationFunction {  
        in part engine :>> alternative : Engine;  
        calc powerRollup: PowerRollup (engine)  
            return power : ISQ::PowerValue;  
        calc massRollup: MassRollup (engine)  
            return mass : ISQ::MassValue;  
        calc efficiencyRollup: EfficiencyRollup (engine)  
            return efficiency : Real;  
        calc costRollup: CostRollup (engine)  
            return cost : Real;  
        return :>> result : Real = EngineEvaluation(  
            powerRollup.power, massRollup.mass,  
            efficiencyRollup.efficiency, costRollup.cost  
        );  
    }  
  
    return part :>> selectedAlternative : Engine;  
}
```

ⓘ A trade-off study is an analysis with the objective of selecting the optimum alternative from a given set based on an evaluation of each alternative.

Bind the analysis subject to the set of study alternatives. Select either [MaximizeObjective](#) or [MinimizeObjective](#).

Redefine the [evaluationFunction](#) calculation to provide an evaluation of *each one* of the alternatives.

The result of the analysis will be the alternative with either the maximum or minimum evaluated value.

# Verification Case Definitions (1)

```
requirement vehicleMassRequirement {  
    subject vehicle : Vehicle;  
    in massActual :> ISQ::mass = vehicle.mass;  
    doc /* The vehicle mass shall be less  
        * than or equal to 2500 kg. */  
    require constraint {  
        massActual <= 2500[SI::kg] }  
}  
  
verification def VehicleMassTest {  
    import Verifications::*;  
  
    subject testVehicle : Vehicle;  
  
    objective vehicleMassVerificationObjective {  
        verify vehicleMassRequirement;  
    }  
  
    return verdict : VerdictKind;  
}
```

Parameterizing the requirement allows it to be checked against a measured `massActual`, while asserting that this must be equal to the `vehicle.mass`.

A *verification case definition* defines a process for verifying whether a *subject* satisfies one or more requirements.

The subject may be specified similarly to the subject of a requirement or analysis case.

The requirements to be verified are declared in the verification case objective. The subject of the verification case is automatically bound to the subject of the verified requirements.

A verification case always returns a verdict of type `VerdictKind`. (The default name is `verdict`, but a different name can be used if desired.)

ⓘ `VerdictKind` is an *enumeration* with allowed values `pass`, `fail`, `inconclusive` and `error`.

# Verification Case Definitions (2)

The *steps* of a verification case are actions that, together, determine the verdict.

**PassIf** is a utility function that returns a **pass** or **fail** verdict depending on whether its argument is true or false.

ⓘ The use of named argument notation here is optional.

```
verification def VehicleMassTest {
    import Verifications::*;

    subject testVehicle : Vehicle;
    objective vehicleMassVerificationObjective {
        verify vehicleMassRequirement;
    }

    action collectData {
        in part testVehicle : Vehicle = VehicleMassTest::testVehicle;
        out massMeasured :> ISQ::mass;
    }
    action processData {
        in massMeasured :> ISQ::mass = collectData.massMeasured;
        out massProcessed :> ISQ::mass;
    }
    action evaluateData {
        in massProcessed :> ISQ::mass = processData.massProcessed;
        out verdict : VerdictKind =
            PassIf(vehicleMassRequirement(
                vehicle = testVehicle,
                massActual = massProcessed));
    }

    return verdict : VerdictKind = evaluateData.verdict;
}
```

This is a *check* of whether the requirement is satisfied for the given parameter values.

# Verification Case Usages (1)

This is a *verification case usage* in which the subject has been restricted to a specific test configuration.

A verification case can be performed as an action by a verification system.

Parts of the verification system can perform steps in the overall verification process.

```
part vehicleTestConfig : Vehicle { ... }

verification vehicleMassTest : VehicleMassTest {
    subject testVehicle :> vehicleTestConfig;
}

part massVerificationSystem : MassVerificationSystem {
    perform vehicleMassTest;

    part scale : Scale {
        perform vehicleMassTest::collectData {
            in part :>> testVehicle;

            bind measurement = testVehicle.mass;
            out :>> massMeasured = measurement;
        }
    }
}
```

In reality, this would be some more involved process to determine the measured mass.

# Verification Case Usages (2)

Individuals can be used to model the carrying out of actual tests.

⚠ The keyword `action` is required here to permit the local redefinition.

```
individual def TestSystem :> MassVerificationSystem;
individual def TestVehicle1 :> Vehicle;
individual def TestVehicle2 :> Vehicle;

individual testSystem : TestSystem :> massVerificationSystem {

    timeslice test1 {
        perform action :>> vehicleMassTest {
            individual :>> testVehicle : TestVehicle1 {
                :>> mass = 2500[SI::kg];
            }
        }
    }
}

then timeslice test2 {
    perform action :>> vehicleMassTest {
        individual :>> testVehicle : TestVehicle2 {
            :>> mass = 3000[SI::kg];
        }
    }
}
```

The test on the individual `TestVehicle1` should pass.

The test on the individual `TestVehicle2` should fail.

# Use Case Definition

An *actor* is a parameter of the use case representing a role played by entity external to the subject.

The *objective* of the use case is for the subject to provide a result of value to one or more of the actors.

① Actors may also be specified for other kinds of cases and for requirements.

A *use case definition* defines a required interaction between its *subject* and certain external *actors*.

```
use case def 'Provide Transportation' {
    subject vehicle : Vehicle;
    actor driver : Person;
    actor passengers : Person[0..4];
    actor environment : Environment;
    objective {
        doc /* Transport driver and passengers from
             * starting location to ending location.
             */
    }
}

use case def 'Enter Vehicle' {
    subject vehicle : Vehicle;
    actor driver : Person;
    actor passengers : Person[0..4];
}

use case def 'Exit Vehicle' {
    subject vehicle : Vehicle;
    actor driver : Person;
    actor passengers : Person[0..4];
}
```

⚠ Actors are (referential) part usages and so must have part definitions.

# Use Case Usage

The required behavior of a use case can be specified as for an action.

A use case can define sub-use cases within its behavior.

A use case can *include* the performance of a use case defined elsewhere (similar to performing an action).

⚠ The traditional use case “extend” relationship is not supported yet.

A use case can also be specified without an explicit use case definition.

```
use case 'provide transportation' : 'Provide Transportation' {
    first start;
    then include use case 'enter vehicle' : 'Enter Vehicle' {
        actor :>> driver = 'provide transportation'::driver;
        actor :>> passengers = 'provide transportation'::passengers;
    }
    then use case 'drive vehicle' {
        actor driver = 'provide transportation'::driver;
        actor environment = 'provide transportation'::environment;
        include 'add fuel'[0...*] {
            actor :>> fueler = driver;
        }
    }
    then include use case 'exit vehicle' : 'Exit Vehicle' {
        actor :>> driver = 'provide transportation'::driver;
        actor :>> passengers = 'provide transportation'::passengers;
    }
    then done;
}

use case 'add fuel' {
    subject vehicle : Vehicle;
    actor fueler : Person;
    actor 'fuel station' : 'Fuel Station';
}
```

The subject of a nested use case is implicitly the same as its containing use case, but actors need to be explicitly bound.

# Variation Definitions

Any kind of definition can be marked as a *variation*, expressing variability within a product line model.

A variation defines one or more *variant* usages, which represent the allowed choices for that variation.

```
attribute def Diameter :> Real;

part def Cylinder {
    attribute diameter : Diameter[1];
}

part def Engine {
    part cylinder : Cylinder[2..*];
}
part '4cylEngine' : Engine {
    part redefines cylinder[4];
}
part '6cylEngine' : Engine {
    part redefines cylinder[6];
}

// Variability model

variation attribute def DiameterChoices :> Diameter {
    variant attribute diameterSmall = 70[mm];
    variant attribute diameterLarge = 100[mm];
}
variation part def EngineChoices :> Engine {
    variant '4cylEngine';
    variant '6cylEngine';
}
```

A variation definition will typically specialize a definition from a design model, representing the type of thing being varied. The variants must then be valid usages of this type.

Variants can also be declared by reference to usages defined elsewhere.

# Variation Usages

Any kind of usage can also be a variation, defining allowable variants without a separate variation definition.

A variation definition can be used like any other definition, but valid values of the usage are restricted to the allowed variants of the variation.

```
abstract part vehicleFamily : Vehicle {
    part engine : EngineChoices[1];
    variation part transmission : Transmission[1] {
        variant manualTransmission;
        variant automaticTransmission;
    }
    assert constraint {
        (engine == engine::'4cylEngine' and
         transmission == transmission::manualTransmission) xor
        (engine == engine::'6cylEngine' and
         transmission == transmission::automaticTransmission)
    }
}
```

A constraint can be used to model restrictions across the choices that can be made.

- ① The operator `xor` means "exclusive or". So, this constraint means "choose either a `4cylEngine` and a `manualTransmission`, or a `6cylEngine` and an `automaticTransmission`".

An element from a variability model with variation usages can be *configured* by specializing it and making selections for each of the variations.

A selection is made for a variation by binding one of the allowed variants to the variation usage.

```
part vehicle4Cyl :> vehicleFamily {  
    part redefines engine = engine::'4cylEngine';  
    part redefines transmission = transmission::manualTransmission;  
}  
  
part vehicle6Cyl :> vehicleFamily {  
    part redefines engine = engine::'6cylEngine';  
    part redefines transmission = transmission::manualTransmission;  
}
```

Choosing a `manualTransmission` with a `6cylEngine` is not allowed by the constraint asserted on `vehicleFamily`, so this model of `vehicle6Cyl` is invalid.

# Dependencies

```
package 'Dependency Example' {
    part 'System Assembly' {
        part 'Computer Subsystem' {
            ...
        }
        part 'Storage Subsystem' {
            ...
        }
    }
    package 'Software Design' {
        item def MessageSchema {
            ...
        }
        item def DataSchema {
            ...
        }
    }
}

dependency from 'System Assembly'::'Computer Subsystem' to 'Software Design';

dependency Schemata
    from 'System Assembly'::'Storage Subsystem'
    to 'Software Design'::MessageSchema, 'Software Design'::DataSchema;
}
```

❶ A dependency is a relationship that indicates that one or more client elements require one or more supplier elements for their complete specification. A dependency is entirely a model-level relationship, without instance-level semantics.

A dependency can be between any kinds of elements, generally meaning that a change to a supplier may necessitate a change to the client element.

A dependency can have multiple clients and/or suppliers.

# Allocation

```
package LogicalModel {  
    ...  
    part torqueGenerator : TorqueGenerator {  
        perform generateTorque;  
    }  
}  
  
package PhysicalModel {  
    import LogicalModel::*;

    ...
    part powerTrain : PowerTrain {  
        part engine : Engine {  
            perform generateTorque;  
        }  
    }  
  
    allocate torqueGenerator to powerTrain {  
        allocate torqueGenerator.generateTorque  
            to powerTrain.engine.generateTorque;  
    }  
}
```

An *allocation* specifies that some or all of the responsibility for realizing the intent of the source is allocated to the target.

- ➊ Allocations define traceable links across the various structures and hierarchies of a system model, perhaps as a precursor to more rigorous specifications and implementations.

An allocation can be refined using nested allocations that give a finer-grained decomposition of the containing allocation mapping.

# Allocation Definition

⚠ Unlike SysML v1, an allocation in SysML v2 is *not* a dependency but, rather, an instantiable connection across model features.

An *allocation definition* defines a class of allocations between features of specific types.

An *allocation usage* must allocate features that conform to the types of the ends of its allocation definition.

```
package LogicalModel {  
    ...  
    part def LogicalElement;  
    part def TorqueGenerator > LogicalElement;  
  
    part torqueGenerator : TorqueGenerator { ... }  
}  
  
package PhysicalModel {  
    import LogicalModel::*;  
    ...  
    part def PhysicalElement;  
    part def PowerTrain > PhysicalElement;  
  
    part powerTrain : PowerTrain { ... }  
}  
  
allocation def LogicalToPhysical {  
    end logical : LogicalElement;  
    end physical : PhysicalElement;  
}  
  
allocation torqueGenAlloc : LogicalToPhysical  
    allocate torqueGenerator to powerTrain { ... }  
}
```

# Metadata (1)

- ① Metadata is additional data that can be used to annotate the elements of a model.

Metadata can be defined using regular attribute definitions.

A specific type of metadata can then be applied as an annotation to one or more model elements.

```
part vehicle {  
    part interior {  
        part alarm;  
        part seatBelt[2];  
        part frontSeat[2];  
        part driverAirBag;  
    }  
    part bodyAssy {  
        part body;  
        part bumper;  
        part keylessEntry;  
    }  
  
    attribute def SafetyFeature;  
    attribute def SecurityFeature;  
  
    metadata SafetyFeature about  
        vehicle::interior::seatBelt,  
        vehicle::interior::driverAirBag,  
        vehicle::bodyAssy::bumper;  
  
    metadata SecurityFeature about  
        vehicle::interior::alarm,  
        vehicle::bodyAssy::keylessEntry;
```

- ① At its simplest, a metadata annotation can be used to simply "tag" certain elements, so that they can, e.g., be grouped by tooling.

# Metadata (2)

```
package AnalysisTooling {  
    private import ScalarValues::*;  
    attribute def ToolExecution {  
        attribute toolName : String;  
        attribute uri : String;  
    }  
    attribute def ToolVariable {  
        attribute name : String;  
    }  
}
```

❶ The `AnalysisTooling` package is part of the `Analysis` domain library.

```
action computeDynamics {  
    import AnalysisTooling::*;  
  
    metadata ToolExecution {  
        toolName = "ModelCenter";  
        uri = "aserv://localhost/Vehicle/Equation1";  
    }  
  
    in dt : ISQ::TimeValue  {@ToolVariable {name = "deltaT";}}  
    in a : ISQ:: AccelerationValue  {@ToolVariable {name = "mass";}}  
    in v_in : ISQ:: VelocityValue  {@ToolVariable {name = "v0";}}  
    in x_in : ISQ:: LengthValue {@ToolVariable {name = "x0";}}  
  
    out v_out : ISQ:: VelocityValue {@ToolVariable {name = "v";}}  
    out x_out : ISQ:: LengthValue  {@ToolVariable {name = "x";}}  
}
```

If the metadata definition has nested features, these must be bound to values in the metadata annotation.

A metadata annotation contained in the body of a namespace (package, definition or usage) is, by default, about that namespace.

The `@` symbol is equivalent to the `metadata` keyword.

# Element Import Filtering (1)

```
attribute def Safety {  
    attribute isMandatory : Boolean;  
}  
  
part vehicle {  
    part interior {  
        part alarm;  
        part seatBelt[2] {  
            @Safety{isMandatory = true;}  
        }  
        part frontSeat[2];  
        part driverAirBag {  
            @Safety{isMandatory = false;}  
        }  
    }  
    part bodyAssy {  
        part body;  
        part bumper {  
            @Safety{isMandatory = true;}  
        }  
        part keylessEntry;  
    }  
    part wheelAssy {  
        part wheel[2];  
        part antilockBrakes[2] {  
            @Safety{isMandatory = false;}  
        }  
    }  
}
```

⚠ Currently, a metadata annotation must be owned by the annotated element to be accessed in a filter condition.

```
package 'Safety Features' {  
    import vehicle::**;  
    filter @Safety;  
}  
  
package 'Mandatory Safety Features' {  
    import vehicle::**;  
    filter @Safety and Safety::isMandatory;  
}
```

A recursive import (using `**`) imports members of a namespace *and*, recursively, members of any nested namespaces.

A **filter** is a Boolean condition that must be true for an element to actually be imported into a package. In this context, `@` is a shorthand for checking if an element has the given metadata annotation.

# Element Import Filtering (2)

```
attribute def Safety {  
    attribute isMandatory : Boolean;  
}  
  
part vehicle {  
    part interior {  
        part alarm;  
        part seatBelt[2] {  
            @Safety{isMandatory = true;} }  
        part frontSeat[2];  
        part driverAirBag {  
            @Safety{isMandatory = false;} }  
    }  
    part bodyAssy {  
        part body;  
        part bumper {  
            @Safety{isMandatory = true;} }  
        part keylessEntry;  
    }  
    part wheelAssy {  
        part wheel[2];  
        part antilockBrakes[2] {  
            @Safety{isMandatory = false;} }  
    }  
}
```

ⓘ The `filter` keyword is only allowed in a package, but a filtered import can be used anywhere an import is allowed.

Filter conditions can also be combined with the import itself.

```
package 'Safety Features' {  
    import vehicle::**[@Safety];  
}  
  
package 'Mandatory Safety Features' {  
    > import vehicle::**  
        [@Safety and Safety::isMandatory];  
}
```

⚠ A filter condition expression must be model-level evaluable. It can reference only literals and metadata annotations and attributes, connected using basic arithmetic, comparison and Boolean operators.

```
part def 'Systems Engineer';
part def 'IV&V';

concern 'system breakdown' {
    doc /*
        * To ensure that a system covers all its required capabilities,
        * it is necessary to understand how it is broken down into
        * subsystems and components that provide those capabilities.
    */
    stakeholder se: 'systems engineer';
    stakeholder ivv: 'IV&V';
}

concern modularity {
    doc /*
        * There should be well defined interfaces between the parts of
        * a system that allow each part to be understood individually,
        * as well as being part of the whole system.
    */
    stakeholder 'systems engineer';
}
```

A *concern* is a specific topic that one or more stakeholders desire to be addressed.

A *stakeholder* is a person, organization or other entity with concerns to be addressed.

ⓘ Stakeholders may be specified for any kind of requirement, not just concerns.

A *viewpoint* is a requirement to present information from a model in a view that addresses certain stakeholder concerns.

```
viewpoint 'system structure perspective' {
    frame 'system breakdown';
    frame modularity;

    require constraint {
        doc /*
            * A system structure view shall show the hierarchical
            * part decomposition of a system, starting with a
            * specified root part.
        */
    }
}
```

A viewpoint *frames* the concerns that will be addressed by a view that satisfies the viewpoint.

- ① Any requirement may be modeled as framing relevant stakeholder concerns, not just viewpoints.

# Views (1)

A view definition can filter the elements to be included in the views it specifies.

```
view def 'Part Structure View' {
    satisfy 'system structure perspective';

    filter @SysML::PartUsage;
}

view 'vehicle structure view' :
    'Part Structure View' {
    expose vehicle::**;
    render asTreeDiagram;
}
```

A view usage specifies a certain view conforming to a view definition.

- ① The view rendering can also be given in the view definition, in which case it will be the same for all usages of that definition. But only view usages can expose elements to be viewed.

A view *definition* specifies how information can be extracted from a model in order to satisfy one or more viewpoints.

The [SysML](#) library package models the SysML abstract syntax, which can be used to filter on specific kinds of model elements.

A view usage *exposes* the model elements to be included in the view, which are filtered as specified in the view definition.

A view usage specifies how the view is to be *rendered* as a physical artifact.

# Views (2)

Specialized kinds of renderings can be defined in a user model.

- ① The Views library package includes four basic kinds of rendering: `asTreeDiagram`, `asInterconnectionDiagram`, `asTextualNotation` and `asElementTable`.

```
rendering asTextualNotationTable :> asElementTable {
    view :>> columnView[1] {
        render asTextualNotation;
    }
}

view 'vehicle tabular views' {
    view 'safety features view' : 'Part Structure View' {
        expose vehicle:**[@Safety];
        render asElementTable;
    }

    view 'non-safety features view' : 'Part Structure View' {
        expose vehicle:**[not (@Safety)];
        render asElementTable;
    }
}
```

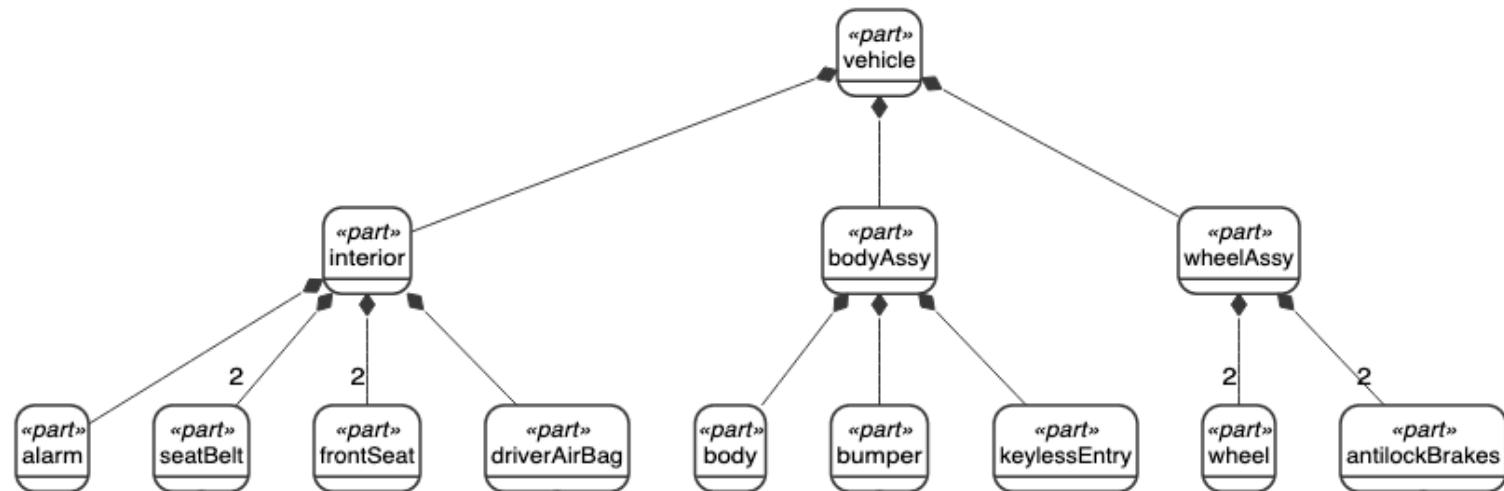
Views can have subviews.

⚠ A more comprehensive rendering library model is planned for future release.

Views can specify additional filtering conditions on an `expose`, using the same notation as for an `import`.

# Example View Rendering

```
view 'vehicle structure view' {
    expose vehicle::**[@SysML::PartUsage];
    render asTreeDiagram;
}
```



# **Kernel Model Library (selected models)**

```
package ScalarValues {
    private import Base::*;

    abstract datatype ScalarValue specializes Value;
    datatype Boolean specializes ScalarValue;
    datatype String specializes ScalarValue;
    abstract datatype NumericalValue specializes ScalarValue;

    abstract datatype Number specializes NumericalValue;
    datatype Complex specializes Number;
    datatype Real specializes Complex;
    datatype Rational specializes Real;
    datatype Integer specializes Rational;
    datatype Natural specializes Integer;
    datatype Positive specializes Natural;
}
```

```
package Collections {  
    ...  
    abstract datatype Collection {  
        feature elements[0..*] nonunique;  
    }  
    abstract datatype OrderedCollection :> Collection {  
        feature :>> elements[0..*] ordered nonunique;  
    }  
    abstract datatype UniqueCollection :> Collection {  
        feature :>> elements[0..*];  
    }  
  
    datatype Array :> OrderedCollection {  
        feature dimensions: Positive[0..*] ordered nonunique;  
        feature rank: Natural[1] = size(dimensions);  
        feature flattenedSize: Positive[1] = dimensions->reduce '*' ?? 1;  
        inv { flattenedSize == size(elements) }  
    }  
  
    datatype Bag :> Collection;  
    datatype Set :> UniqueCollection;  
    datatype OrderedSet :> OrderedCollection, UniqueCollection {  
        feature :>> elements[0..*] ordered;  
    }  
    datatype List :> OrderedCollection;  
    ...  
}
```

# Collections (2)

```
package Collections {  
    ...  
  
    datatype KeyValuePair {  
        feature key: Anything[0..*] ordered nonunique;  
        feature val: Anything[0..*] ordered nonunique;  
    }  
  
    datatype Map :> Collection {  
        feature :>> elements: KeyValuePair[0..*];  
    }  
  
    datatype OrderedMap :> Map {  
        feature :>> elements: KeyValuePair[0..*] ordered;  
    }  
}
```



# Vector Values

SST

```
package VectorValues {
    private import ScalarValues::NumericalValue;
    private import ScalarValues::Real;
    private import Collections::Array;

    abstract datatype VectorValue;

    datatype NumericalVectorValue :> VectorValue, Array {
        feature dimension[0..1] :>> dimensions;
        feature :>> elements : NumericalValue;
    }

    datatype CartesianVectorValue :> NumericalVectorValue {
        feature :>> elements : Real;
    }

    datatype ThreeVectorValue :> NumericalVectorValue {
        feature :>> dimension = 3;
    }

    datatype CartesianThreeVectorValue :> CartesianVectorValue, ThreeVectorValue;
}
```



# Base Functions

SST

```
package BaseFunctions {
    private import Base::Anything;
    private import ScalarValues::*;

    abstract function '=='(x: Anything[0..1], y: Anything[0..1]): Boolean[1];
    function '!='(x: Anything[0..1], y: Anything[0..1]): Boolean[1] {
        !(x == y)
    }

    function ToString(x: Anything[0..1]): String[1];

    ...
}
```

# Data Functions

```

package DataFunctions {
    private import Base::NumericalValue;
    private import ScalarValues::Boolean;

    abstract function '+'(x: NumericalValue[1], y: NumericalValue[0..1]): ;
    abstract function '-'(x: NumericalValue[1], y: NumericalValue[0..1]): NumericalValue[1];
    abstract function '*'(x: NumericalValue[1], y: NumericalValue[1]): NumericalValue[1];
    abstract function '/'(x: NumericalValue[1], y: NumericalValue[1]): NumericalValue[1];
    abstract function '**'(x: NumericalValue[1], y: NumericalValue[1]): NumericalValue[1];
    abstract function '^'(x: NumericalValue[1], y: NumericalValue[1]): NumericalValue[1];
    abstract function '%' (x: NumericalValue[1], y: NumericalValue[1]): NumericalValue[1];
    abstract function '!'(x: NumericalValue[1]): NumericalValue[1];
    abstract function 'not'(x: NumericalValue[1]): NumericalValue[1];
    abstract function '~'(x: NumericalValue[1]): NumericalValue[1];
    abstract function '|'(x: NumericalValue[1], y: NumericalValue[1]): NumericalValue[1];
    abstract function '^^(x: NumericalValue[1], y: NumericalValue[1]): NumericalValue[1];
    abstract function 'xor'(x: NumericalValue[1], y: NumericalValue[1]): NumericalValue[1];
    abstract function '&'(x: NumericalValue[1], y: NumericalValue[1]): NumericalValue[1];
    abstract function '<'(x: NumericalValue[1], y: NumericalValue[1]): Boolean[1];
    abstract function '>'(x: NumericalValue[1], y: NumericalValue[1]): Boolean[1];
    abstract function '<='(x: NumericalValue[1], y: NumericalValue[1]): Boolean[1];
    abstract function '>='(x: NumericalValue[1], y: NumericalValue[1]): Boolean[1];
    abstract function max(x: NumericalValue[1], y: NumericalValue[1]): NumericalValue[1];
    abstract function min(x: NumericalValue[1], y: NumericalValue[1]): NumericalValue[1];
    abstract function '...' (lower:NumericalValue[1],upper:NumericalValue[1]):
        NumericalValue[0..*] ordered;
}

```

① **ScalarFunctions** package is similar but specialized for **ScalarValue**.



# Boolean Functions

SST

```
package BooleanFunctions {  
    import ScalarValues::*;

    function '!' specializes ScalarFunctions:'!'(x: Boolean): Boolean;
    function 'not' specializes ScalarFunctions:'not'(x: Boolean): Boolean;

    function '|' specializes ScalarFunctions:'|'(x: Boolean, y: Boolean): Boolean;
    function '^'^ specializes ScalarFunctions:'^'^'(x: Boolean, y: Boolean):
        Boolean;
    function 'xor' specializes ScalarFunctions:'^'^'(x: Boolean, y: Boolean):
        Boolean;
    function '&' specializes ScalarFunctions:'&'(x: Boolean, y: Boolean): Boolean;

    function '==' specializes BaseFunctions:'=='(x: Boolean, y: Boolean): Boolean;
    function '!=' specializes BaseFunctions:'!='(x: Boolean, y: Boolean): Boolean;

    function ToString specializes BaseFunctions::ToString (x: Boolean): String;
    function ToBoolean(x: String): Boolean;
}
```

# String Functions

```
package StringFunctions {  
    import ScalarValues::*;

    function '+' specializes ScalarFunctions::'+'(x: String, y:String): String;

    function Size(x: String): Natural;
    function Substring(x: String, lower: Integer, upper: Integer): String;

    function '<' specializes ScalarFunctions::'<'(x: String, y: String): Boolean;
    function '>' specializes ScalarFunctions::'>'(x: String, y: String): Boolean;
    function '<=' specializes ScalarFunctions::'<='(x: String, y: String): Boolean;
    function '>=' specializes ScalarFunctions::'>='(x: String, y: String): Boolean;

    function '=' specializes BaseFunctions::'=='(x: String, y: String): Boolean;
    function '!=' specializes BaseFunctions::'!='(x: String, y: String): Boolean;
    function ToString specializes BaseFunctions::ToString(x: String): String;
}
```

```
package RealFunctions {
    import ScalarValues::*;

    abstract function '+'(x: NumericalValue[1], y: NumericalValue[0..1]): NumericalValue[1];
    abstract function '-'(x: NumericalValue[1], y: NumericalValue[0..1]): NumericalValue[1];
    abstract function '*'(x: NumericalValue[1], y: NumericalValue[1]): NumericalValue[1];
    abstract function '/'(x: NumericalValue[1], y: NumericalValue[1]): NumericalValue[1];
    abstract function '**'(x: NumericalValue[1], y: NumericalValue[1]): NumericalValue[1];
    abstract function '^'(x: NumericalValue[1], y: NumericalValue[1]): NumericalValue[1];
    abstract function '%'(x: NumericalValue[1], y: NumericalValue[1]): NumericalValue[1];

    abstract function '<'(x: NumericalValue[1], y: NumericalValue[1]): Boolean[1];
    abstract function '>'(x: NumericalValue[1], y: NumericalValue[1]): Boolean[1];
    abstract function '<='(x: NumericalValue[1], y: NumericalValue[1]): Boolean[1];
    abstract function '>='(x: NumericalValue[1], y: NumericalValue[1]): Boolean[1];

    abstract function max(x: NumericalValue[1], y: NumericalValue[1]): NumericalValue[1];
    abstract function min(x: NumericalValue[1], y: NumericalValue[1]): NumericalValue[1];

    abstract function sum(collection: NumericalValue[0..*] ordered): NumericalValue[1];
    abstract function product(collection: NumericalValue[0..*] ordered): NumericalValue[1];
}
```

```
package ComplexFunctions {
    import ScalarValues::*;

    feature i: Complex[1] = rect(0.0, 1.0);

    function rect(re: Real[1], im: Real[1]): Complex[1];
    function polar(abs: Real[1], arg: Real[1]): Complex[1];
    function re(x: Complex[1]): Real[1];
    function im(x: Complex[1]): Real[1];

    function abs specializes NumericalFunctions::abs (x: Complex[1]): Real[1];
    function arg(x: Complex[1]): Real[1];
    function '+' specializes NumericalFunctions::'+' (x: Complex[1], y: Complex[0..1]): Complex[1];
    function '-' specializes NumericalFunctions::'-' (x: Complex[1], y: Complex[0..1]): Complex[1];
    function '*' specializes NumericalFunctions::'*' (x: Complex[1], y: Complex[1]): Complex[1];
    function '/' specializes NumericalFunctions::'/' (x: Complex[1], y: Complex[1]): Complex[1];
    function '**' specializes NumericalFunctions::'**' (x: Complex[1], y: Complex[1]): Complex[1];
    function '^' specializes NumericalFunctions::'^' (x: Complex[1], y: Complex[1]): Complex[1];
    function '==' specializes DataFunctions::'==' (x: Complex[0..1], y: Complex[0..1]): Boolean[1];

    function ToString specializes BaseFunctions::ToString (x: Complex[1]): String[1];
    function ToComplex(x: String[1]): Complex[1];

    function sum specializes NumericalFunctions::sum (collection: Complex[0..*]): Complex[1];
    function product specializes NumericalFunctions::product (collection: Complex[0..*]): Complex[1];
}
```

```

package RealFunctions {
    import ScalarValues::*;

    function abs specializes ComplexFunctions::abs (x: Real[1]): Real[1];
    function '+' specializes ComplexFunctions::'+' (x: Real[1], y: Real[0..1]): Real[1];
    function '-' specializes ComplexFunctions::'-' (x: Real[1], y: Real[0..1]): Real[1];
    function '*' specializes ComplexFunctions::'*' (x: Real[1], y: Real[1]): Real[1];
    function '/' specializes ComplexFunctions::'/' (x: Real[1], y: Real[1]): Real[1];
    function '**' specializes ComplexFunctions::'**' (x: Real[1], y: Real[1]): Real[1];
    function '^' specializes ComplexFunctions::'^' (x: Real[1], y: Real[1]): Real[1];
    function '<' specializes ComplexFunctions::'<' (x: Real[1], y: Real[1]): Boolean[1];
    function '>' specializes ComplexFunctions::'>' (x: Real[1], y: Real[1]): Boolean[1];
    function '<=' specializes ComplexFunctions::'<=' (x: Real[1], y: Real[1]): Boolean[1];
    function '>=' specializes ComplexFunctions::'>=' (x: Real[1], y: Real[1]): Boolean[1];
    function max specializes ComplexFunctions::max (x: Real[1], y: Real[1]): Real[1];
    function min specializes ComplexFunctions::min (x: Real[1], y: Real[1]): Real[1];
    function '==' specializes ComplexFunctions::'==' (x: Real[1], y: Real[1]): Boolean[1];

    function sqrt(x: Real[1]): Real[1];
    function floor(x: Real[1]): Integer[1];
    function round(x: Real[1]): Integer[1];

    function ToString specializes ComplexFunctions::ToString (x: Real[1]): String[1];
    function ToInteger(x: Real[1]): Integer;
    function ToRational(x: Real[1]): Rational;
    function ToReal(x: String[1]): Real;
    function ToComplex(x: Real[1]): Complex;

    function sum specializes ComplexFunctions::sum (collection: Real[0..*]): Real[1];
    function product specializes ComplexFunctions::product (collection: Real[0..*]): Real[1];
}

}

```



# Rational Functions

SST

```
package RationalFunctions {
    import ScalarValues::*;

    function rat(numer: Integer[1], denum: Integer[1]): Rational[1];
    function numer(rat: Rational[1]): Integer[1];
    function denom(rat: Rational[1]): Integer[1];

    function abs specializes RealFunctions::abs (x: Rational[1]): Rational[1];
    function '+' specializes RealFunctions::'+' (x: Rational[1], y: Rational[0..1]): Rational[1];
    function '-' specializes RealFunctions::'-' (x: Rational[1], y: Rational[0..1]): Rational[1];
    function '*' specializes RealFunctions::'*' (x: Rational[1], y: Rational[1]): Rational[1];
    function '/' specializes RealFunctions::'/' (x: Rational[1], y: Rational[1]): Rational[1];
    function '**' specializes RealFunctions::'**' (x: Rational[1], y: Rational[1]): Rational[1];
    function '^' specializes RealFunctions::'^' (x: Rational[1], y: Rational[1]): Rational[1];
    function '<' specializes RealFunctions::'<' (x: Rational[1], y: Rational[1]): Boolean[1];
    function '>' specializes RealFunctions::'>' (x: Rational[1], y: Rational[1]): Boolean[1];
    function '<=' specializes RealFunctions::'<=' (x: Rational[1], y: Rational[1]): Boolean[1];
    function '>=' specializes RealFunctions::'>=' (x: Rational[1], y: Rational[1]): Boolean[1];
    function max specializes RealFunctions::max (x: Rational[1], y: Rational[1]): Rational[1];
    function min specializes RealFunctions::min (x: Rational[1], y: Rational[1]): Rational[1];
    function '==' specializes RealFunctions::'==' (x: Rational[1], y: Rational[1]): Boolean[1];

    function gcd(x: Rational[1], y: Rational[1]): Integer[1];
    function floor(x: Rational[1]): Integer[1];
    function round(x: Rational[1]): Integer[1];

    function ToString specializes RealFunctions::ToString (x: Rational[1]): String[1];
    function ToInteger(x: Rational[1]): Integer[1];
    function ToRational(x: String[1]): Rational[1];

    function sum specializes RealFunctions::sum(collection: Rational[0..*]): Rational[1];
    function product specializes RealFunctions::product(collection: Rational[0..*]): Rational[1];
}
```

```

package IntegerFunctions {
    import ScalarValues::*;

    function abs specializes RationalFunctions::abs (x: Integer[1]): Natural[1];
    function '+' specializes RationalFunctions::'+' (x: Integer[1], y: Integer[0..1]): Integer[1];
    function '-' specializes RationalFunctions::'-' (x: Integer[1], y: Integer[0..1]): Integer[1];
    function '*' specializes RationalFunctions::'*' (x: Integer[1], y: Integer[1]): Integer[1];
    function '/' specializes RationalFunctions::'/' (x: Integer[1], y: Integer[1]): Rational[1];
    function '**' specializes RationalFunctions::'**' (x: Integer[1], y: Natural[1]): Integer[1];
    function '^' specializes RationalFunctions::'^' (x: Integer[1], y: Natural[1]): Integer[1];
    function '%' specializes RationalFunctions::'%' (x: Integer[1], y: Integer[1]): Integer[1];

    function '<' specializes RationalFunctions::'<' (x: Integer[1], y: Integer[1]): Boolean[1];
    function '>' specializes RationalFunctions::'>' (x: Integer[1], y: Integer[1]): Boolean[1];
    function '<=' specializes RationalFunctions::'<=' (x: Integer[1], y: Integer[1]): Boolean[1];
    function '>=' specializes RationalFunctions::'>=' (x: Integer[1], y: Integer[1]): Boolean[1];

    function max specializes RationalFunctions::max (x: Integer[1], y: Integer[1]): Integer[1];
    function min specializes RationalFunctions::min (x: Integer[1], y: Integer[1]): Integer[1];

    function '==' specializes DataFunctions::'==' (x: Integer[1], y: Integer[1]): Boolean[1];
    function '..' specializes ScalarFunctions::'..' (lower: Integer[1], upper: Integer[1]): Integer[0..*];

    function ToString specializes BaseFunctions::ToString (x: Integer[1]): String[1];
    function ToNatural(x: Integer[1]): Natural[1];
    function ToInteger(x: String[1]): Integer[1];

    function sum specializes RationalFunctions::sum (collection: Integer[0..*]): Integer[1];
    function product specializes RationalFunctions::product (collection: Integer[0..*]): Integer[1];
}

}

```



# Natural Functions

SST

```
package NaturalFunctions {
    import ScalarValues::*;

    function '+' specializes IntegerFunctions::'+' (x: Natural[1], y: Natural[0..1]): Natural[1];
    function '*' specializes IntegerFunctions::'*' (x: Natural[1], y: Natural[1]): Natural[1];
    function '/' specializes IntegerFunctions::'/' (x: Natural[1], y: Natural[1]): Natural[1];
    function '%' specializes IntegerFunctions::'%' (x: Natural[1], y: Natural[1]): Natural[1];

    function '<' specializes IntegerFunctions::'<' (x: Natural[1], y: Natural[1]): Boolean[1];
    function '>' specializes IntegerFunctions::'>' (x: Natural[1], y: Natural[1]): Boolean[1];
    function '<=' specializes IntegerFunctions::'<=' (x: Natural[1], y: Natural[1]): Boolean[1];
    function '>=' specializes IntegerFunctions::'>=' (x: Natural[1], y: Natural[1]): Boolean[1];

    function max specializes IntegerFunctions::max (x: Natural[1], y: Natural[1]): Natural[1];
    function min specializes IntegerFunctions::min (x: Natural[1], y: Natural[1]): Natural[1];

    function '==' specializes IntegerFunctions::'==' (x: Natural[1], y: Natural[1]): Boolean[1];

    function ToString specializes IntegerFunctions::ToString (x: Natural[1]): String[1];
    function ToNatural(x: String[1]): Natural[1];
}
```

```
package TrigFunctions {
    import ScalarValues::Real;

    feature pi : Real;
    inv piPrecision {
        RealFunctions::round(pi * 1E20) == 314159265358979323846.0
    }

    function deg(theta_rad : Real);
    function rad(theta_deg : Real);

    datatype UnitBoundedReal :> Real;

    function sin(theta : Real) : UnitBoundedReal;
    function cos(theta : Real) : UnitBoundedReal;
    function tan(theta : Real) : Real;
    function cot(theta : Real) : Real;
    function arcsin(x : UnitBoundedReal) : Real;
    function arccos(x : UnitBoundedReal) : Real;
    function arctan(x : Real) : Real;
}
```



# Sequence Functions

SST

```
package SequenceFunctions {  
    private import Base::Anything;  
    private import ScalarValues::*;  
  
    function equals  
        (x: Anything[0..*] ordered nonunique,  
         y: Anything[0..*] ordered nonunique): Boolean[1];  
    function size(seq: Anything[0..*] ordered nonunique): Natural[1];  
    function isEmpty(seq: Anything[0..*] ordered nonunique): Boolean[1];  
    function notEmpty(seq: Anything[0..*] ordered nonunique): Boolean[1];  
    function includes(  
        seq: Anything[0..*] ordered nonunique,  
        value: Anything[1]): Boolean[1];  
    function excludes(  
        seq: Anything[0..*] ordered nonunique,  
        value: Anything[1]): Boolean[1];  
  
    function head(seq: Anything[0..*] ordered nonunique): Anything[0..1];  
    function tail(seq: Anything[0..*] ordered nonunique):  
        Anything[0..*] ordered nonunique;  
    function last(seq: Anything[0..*]): Anything[0..1];  
    ...  
}
```



# Collection Functions

SST

```
package CollectionFunctions {  
    ...  
    import Collections::*;  
  
    function '==' specializes BaseFunctions::'=='  
        (col1: Collection[0..1], col2: Collection[0..1]): Boolean[1];  
    function size (col: Collection[1]): Natural[1];  
    function isEmpty (col: Collection[1]): Boolean[1];  
    function notEmpty (col: Collection[1]): Boolean[1];  
    function contains(col: Collection[1], values: Anything[*]): Boolean[1];  
    function containsAll(coll1: Collection[1], col2: Collection[2]): Boolean[1];  
    function head(col: OrderedCollection[1]): Anything[0..1];  
    function tail(col: OrderedCollection[1]): Anything[0..*] ordered nonunique;  
    function last(col: OrderedCollection[1]): Anything[0..1];  
  
    function '[' specializes BaseFunctions::'['  
        (col: OrderedCollection[1], index: Positive[1]): Anything[0..1];  
    function 'array[' specializes '['  
        (arr: Array[1], indexes: Positive[n] ordered nonunique): Anything[0..1] {  
            private feature n : Natural[1] = arr.rank;  
            ...  
        }  
    }
```

# Vector Functions (1)

```
package VectorFunctions {  
    ...  
    import VectorValues::*;  
  
    abstract function isZeroVector(v: VectorValue[1]): Boolean[1];  
    abstract function '+' specializes DataFunctions:: '+'  
        (v: VectorValue[1], w: VectorValue[0..1]) u: VectorValue[1];  
    abstract function '-' specializes DataFunctions:: '-'  
        (v: VectorValue[1], w: VectorValue[0..1]) u: VectorValue[1];  
  
    function VectorOf(components: NumericalValue[1..*] ordered nonunique):  
        NumericalVectorValue[1];  
  
    abstract function scalarVectorMult specializes DataFunctions:: '*'  
        (x: NumericalValue[1], v: NumericalVectorValue[1]) w: NumericalVectorValue[1];  
    alias '*' for scalarVectorMult;  
    abstract function vectorScalarMult specializes DataFunctions:: '*'  
        (v: NumericalVectorValue[1], x: NumericalValue[1]): NumericalVectorValue[1];  
    abstract function vectorScalarDiv specializes DataFunctions:: '/'  
        (v: NumericalVectorValue[1], x: NumericalValue[1]): NumericalVectorValue[1];  
    abstract function inner specializes DataFunctions:: '*'  
        (v: NumericalVectorValue[1], w: NumericalVectorValue[1]) x: NumericalValue[1];  
    abstract function norm(v: NumericalVectorValue[1]) l : NumericalValue[1];  
    abstract function angle(v: NumericalVectorValue[1], w: NumericalVectorValue[1])  
        theta: NumericalValue[1];  
    ...  
}
```

# Vector Functions (2)

```

package VectorFunctions {
    ...

    function CartesianVectorOf(components : Real[*]) : CartesianVectorValue;
    function CartesianThreeVectorOf specializes CartesianVectorOf
        (components: Real[*]): CartesianThreeVectorValue;

    function isCartesianZeroVector specializes isZeroVector (v: CartesianVectorValue) :
        Boolean[1];

    function 'cartesian+' specializes '+'
        (v: CartesianVectorValue[1], w: CartesianVectorValue[0..1]): CartesianVectorValue[1];
    function 'cartesian-' specializes '-'
        (v: CartesianVectorValue[1], w: CartesianVectorValue[0..1]): CartesianVectorValue[1];
    function cartesianScalarVectorMult specializes scalarVectorMult
        (x: Real[1], v: CartesianVectorValue[1]): CartesianVectorValue[1];
    function cartesianVectorScalarMult specializes vectorScalarMult
        (v: CartesianVectorValue[1], x: Real[1]): CartesianVectorValue[1];
    function cartesianInner specializes inner
        (v: CartesianVectorValue[1], w : CartesianVectorValue[1]): Real[1];
    function cartesianNorm specializes norm
        (v: CartesianVectorValue[1]) : NumericalValue[1];
    function cartesianAngle specializes angle
        (v: CartesianVectorValue[1], w: CartesianVectorValue[1]): Real[1];

    function sum(coll: CartesianThreeVectorValue): CartesianThreeVectorValue;
}

```

# Control Functions

```
package ControlFunctions {
    private import Base::Anything;
    private import ScalarValues::ScalarValue;

    abstract function '?'(test: Boolean[1], expr thenValue[0..1], expr elseValue[0..1]):
        Anything[0..*] ordered nonunique;
    abstract function '??'(firstValue: Anything[0..*], expr secondValue[0..1]):
        Anything[0..*] ordered nonunique;
    abstract function '&&'(firstValue: Boolean[1], expr secondValue[0..1]): Boolean[1];
    function 'and'(firstValue: Boolean[1], expr secondValue[0..1]): Boolean[1];
    abstract function '||'(firstValue: Boolean[1], expr secondValue[0..1]): Boolean[1];
    function 'or'(firstValue: Boolean[1], expr secondValue[0..1]): Boolean[1];
    abstract function '>='(firstValue: Boolean[1], expr secondValue[0..1]): Boolean[1];
    function 'implies'(firstValue: Boolean[1], expr secondValue[0..1]): Boolean[1];

    abstract function collect(collection: Anything[0..*] ordered nonunique):
        Anything[0..*] ordered nonunique {
        in expr mapper[0..*] (argument: Anything[1]): Anything[0..*] ordered nonunique;
    }
    abstract function select(collection: Anything[0..*] ordered nonunique):
        Anything[0..*] ordered nonunique {
        in expr selector[0..*] (argument: Anything[1]): Boolean[1];
    }
    abstract function reject(collection: Anything[0..*] ordered nonunique):
        Anything[0..*] ordered nonunique {
        in expr rejector[0..*] (argument: Anything[1]): Boolean[1];
    }

    ...
}
```

# Metadata Domain Library

# Risk Metadata

```
package RiskMetadata {
    import ScalarValues::Real;
    attribute def Level :> Real {
        private attribute level : Level :>> self;
        assert constraint { level >= 0.0 && level <= 1.0 }
    }
    enum def LevelEnum :> Level {
        low = 0.25;
        medium = 0.50;
        high = 0.75;
    }
    attribute def RiskLevel {
        attribute probability : Level;
        attribute impact : Level [0..1];
    }
    enum def RiskLevelEnum :> RiskLevel {
        low = RiskLevel(probability = LevelEnum::L);
        medium = RiskLevel(probability = LevelEnum::M);
        high = RiskLevel(probability = LevelEnum::H);
    }
    attribute def Risk {
        attribute totalRisk : RiskLevel [0..1];
        attribute technicalRisk : RiskLevel [0..1];
        attribute scheduleRisk : RiskLevel [0..1];
        attribute costRisk : RiskLevel [0..1];
    }
}
```

General risk level in terms of probability and impact.

Standard low, medium and high risk levels.

To be used to annotate model elements as to their risk level in typical risk areas.

# Modeling Metadata

```
package ModelingMetadata {  
    private import Base::Anything;  
    private import ScalarValues::String;  
    private import RiskMetadata::Risk;  
  
    enum def StatusKind {  
        open;  
        tbd; // To be determined  
        tbr; // To be resolved  
        tbc; // To be confirmed  
        done;  
        closed;  
    }  
    attribute def StatusInfo {  
        attribute originator : String [0..1];  
        attribute owner : String [0..1];  
        attribute status : StatusKind;  
        attribute risk : Risk [0..1];  
    }  
    attribute def Rationale {  
        attribute text : String;  
        ref explanation : Anything [0..1];  
    }  
    attribute def Issue {  
        attribute text : String;  
    }  
}
```

To be used to annotate model elements with status information.

To be used to give a rationale for a model element.

Generic issue annotation.

This is an optional reference to a feature that further explains this rationale (e.g., a trade study analysis).

# Analysis Domain Library

# Trade Studies

```
package TradeStudies {  
    import Base::Anything;  
    import ScalarValues::*;  
    import ScalarFunctions::*;  
    abstract calc def EvaluationFunction(alternative) result : ScalarValue[1];  
    abstract requirement def TradeStudyObjective {  
        subject selectedAlternative : Anything;  
        in ref alternatives : Anything[1..*];  
        in calc fn : EvaluationFunction;  
        out attribute best : ScalarValue;  
        require constraint { fn(selectedAlternative) == best }  
    }  
    requirement def MinimizeObjective :> TradeStudyObjective {  
        out attribute :>> best = alternatives->minimize {in x; fn(x)},  
    }  
    requirement def MaximizeObjective :> TradeStudyObjective {  
        out attribute :>> best = alternatives->maximize {in x; fn(x)};  
    }  
    abstract analysis def TradeStudy {  
        subject studyAlternatives : Anything[1..*];  
        abstract calc evaluationFunction : EvaluationFunction;  
        objective tradeStudyObjective : TradeStudyObjective {  
            in ref :>> alternatives = studyAlternatives;  
            in calc :>> fn = evaluationFunction;  
        }  
        return ref selectedAlternative =  
            studyAlternatives->selectOne {in ref a; tradeStudyObjective(a)};  
    }  
}
```

An **EvaluationFunction** is a calculation that evaluates a **TradeStudy** alternative.

A **TradeStudyObjective** is the base definition for the objective of a **TradeStudy**, requiring the **selectedAlternative** to have best evaluation according to a given **EvaluationFunction**.

A **TradeStudy** is an analysis case whose subject is a set of alternatives and whose result is a selection of one of those alternatives, based on a given **EvaluationFunction** such that it satisfies the objective of the **TradeStudy**.

# Analysis Tooling Annotations

```
package AnalysisTooling {  
    private import ScalarValues::*;

    attribute def ToolExecution {
        attribute toolName : String;
        attribute uri : String;
    }

    attribute def ToolVariable {
        attribute name : String;
    }
}
```

ToolExecution metadata identifies an external analysis tool to be used to implement the annotated action.

ToolVariable metadata is used in the context of an action that has been annotated with ToolExecution metadata. It is used to annotate a parameter or other feature of the action with the name of the variable in the tool that is to correspond to the annotated feature.

# State Space Representation (1)

```
package StateSpaceRepresentation {  
    import ISQ::DurationValue;  
    import Quantities::VectorQuantityValue;  
    import VectorCalculations::*;

    abstract attribute def StateSpace :> VectorQuantityValue;
    abstract attribute def Input :> VectorQuantityValue;
    abstract attribute def Output :> VectorQuantityValue;
    abstract calc def GetNextState  
        (input: Input, stateSpace: StateSpace, timeStep: DurationValue): StateSpace;
    abstract calc def GetOutput(input: Input, stateSpace: StateSpace): Output;
    abstract action def StateSpaceEventDef;
    action def ZeroCrossingEventDef :> StateSpaceEventDef;
    item def StateSpaceItem;

    abstract action def StateSpaceDynamics {  
        in attribute input: Input;  
        abstract calc getNextState: GetNextState;  
        abstract calc getOutput: GetOutput;  
        attribute stateSpace: StateSpace;  
        out attribute output: Output = getOutput(input, stateSpace);  
    }
    abstract attribute def StateDerivative :> VectorQuantityValue { ... }
    abstract calc def GetDerivative(input: Input, stateSpace: StateSpace): StateDerivative;
    abstract calc def Integrate (getDerivative: GetDerivative, input: Input,
        initialState: StateSpace, timeInterval: DurationValue) result: StateSpace;
    ...
}
```

**StateSpaceDynamics** is the simplest form of state space representation, and **getNextState** directly computes the **stateSpace** of the next timestep.

# State Space Representation (2)

`ContinuousStateSpaceDynamics` represents continuous behavior. The `derivative` needs to return a time derivative of `stateSpace`, i.e.  $dx/dt$ .

```
...  
  
abstract action def ContinuousStateSpaceDynamics :> StateSpaceDynamics {  
    abstract calc getDerivative: GetDerivative;  
    calc :>> getNextState: GetNextState {  
        calc integrate: Integrate(  
            derivative = ContinuousStateSpaceDynamics::getDerivative,  
            input = GetNextState::input,  
            initialState = GetNextState::stateSpace,  
            timeInterval = GetNextState::timeStep  
        ) return resultState = result;  
    }  
    event occurrence zeroCrossingEvents[0..*] : ZeroCr  
}  
  
abstract calc def GetDifference(input: Input, stateSpace: StateSpace) : StateSpace {  
  
abstract action def DiscreteStateSpaceDynamics :> StateSpaceDynamics {  
    abstract calc getDifference: GetDifference;  
    calc :>> getNextState: GetNextState {  
        attribute diff: StateSpace = getDifference(input, stateSpace);  
        stateSpace + diff  
    }  
}
```

`DiscreteStateSpaceDynamics` represents discrete behavior. `getDifference` returns the difference of the `stateSpace` for each timestep.

# Sampled Functions

**SampleFunction** is a variable-size, ordered collection of **SamplePair** elements representing a discretely sampled mathematical function.

**Domain** and **Range** return all the domain values and range values of a sampled function.

**Sample** a calculation on given domain values to create a **SampledFunction**.

**Interpolate** a **SampledFunction** to compute a result for a given domain value.

```
package SampledFunctions {  
    ...  
  
    attribute def SamplePair :> KeyValuePair {  
        attribute domainValue :>> key;  
        attribute rangeValue :>> val;  
    }  
  
    attribute def SampledFunction :> OrderedMap {  
        attribute samples: SamplePair[0..*] ordered :>> elements;  
        assert constraint { ... }  
    }  
  
    calc def Domain(fn : SampledFunction) : Anything[0..*]  
        = fn.samples.domainValue;  
    calc def Range(fn : SampledFunction) : Anything[0..*]  
        = fn.samples.rangeValue;  
  
    calc def Sample  
        (in calc calculation (x), in attribute domainValues [0..*])  
        return sampling { ... }  
  
    calc def Interpolate  
        (attribute fn : SampledFunction, attribute value)  
        return attribute result;  
    calc interpolateLinear : Interpolate { ... }  
}
```

**SamplePair** is a key-value pair of a domain-value and a range-value, used as a sample element in **SampledFunction**.

The function is constrained to be strictly increasing or strictly decreasing.

# **Quantities and Units Domain Library (selected models)**

# Quantities

```
package Quantities {
```

```
    abstract attribute def TensorQuantityValue :> Collections::Array {
```

```
        attribute num : ScalarValues::Number[1..*] ordered nonunique :>> elements;
```

```
        attribute mRef : UnitsAndScales::TensorMeasurementReference;
```

```
        attribute :>> dimensions = mRef::dimensions;
```

```
    }
```

```
    abstract attribute def VectorQuantityValue :> TensorQuantityValue {
```

```
        attribute :>> mRef : UnitsAndScales::VectorMeasurementReference;
```

```
}
```

```
    abstract attribute def ScalarQuantityValue :> ScalarQuantityValue {
```

```
        attribute :>> mRef : UnitsAndScales::ScalarMeasurementReference;
```

```
}
```

```
    abstract attribute tensorQuantities: TensorQuantityValue[*]
```

```
    abstract attribute vectorQuantities: VectorQuantityValue[*]
```

```
    abstract attribute scalarQuantities: ScalarQuantityValue[*]
```

```
    alias TensorQuantityValue as QuantityValue;
```

```
    alias tensorQuantities as quantity;
```

```
    ...
```

A *tensor quantity value* represents the value of the most general kind of quantity, a *tensor*.

The numeric value of the tensor is given as an array of numbers.

The value of a tensor quantity is relative to a multi-dimensional *tensor measurement reference*.

A *vector* is a tensor with a single dimension.

A *scalar* is a vector with a single element. Its measurement reference may be a *measurement unit* if the scale is a *ratio scale*.

A *quantity* is a usage of a quantity value to represent a feature of something.

# Measurement References

A *tensor measurement reference* is defined as an array of *scalar measurement references*, one for each element of the tensor.

```
package UnitsAndScales {
    attribute def TensorMeasurementReference :> Collections::Array {
        attribute mrefs : ScalarMeasurementReference[1..*] :>> elements;
        ...
    }
    alias TensorMeasurementReference as MeasurementReference;

    attribute def VectorMeasurementReference
        :> TensorMeasurementReference {
        attribute :>> dimensions[0..1];
        ...
    }

    attribute def ScalarMeasurementReference
        :> VectorMeasurementReference {
        attribute :>> dimensions = ();
        ...
    }
    ...
}
```

A *measurement unit* is a measurement scale defined as a sequence of unit power factors.

A *simple unit* is a measurement unit with no power factor dependencies on other units.

A *derived unit* is any unit that is not simple.

A *unit powerfactor* is a representation of a reference unit raised to an exponent.

```
package UnitsAndScales {  
    ...  
  
    abstract attribute def MeasurementUnit  
        :> ScalarMeasurementReference {  
            attribute unitPowerFactor : UnitPowerFactor[1..*] ordered;  
            attribute unitConversion : UnitConversion[0..1];  
        }  
  
    abstract attribute def SimpleUnit :> MeasurementUnit {  
        attribute redefines unitPowerFactor[1] {  
            attribute redefines unit = SimpleUnit::self;  
            attribute redefines exponent = 1;  
        }  
    }  
  
    abstract attribute def DerivedUnit :> MeasurementUnit;  
  
    attribute def UnitPowerFactor {  
        attribute unit : MeasurementUnit;  
        attribute exponent : ScalarValues::Real;  
    }  
    ...  
}
```

```
package ISQ {  
    import ISQBase::*;

    import ISQSpaceTime::*;
    ...
}
```

```
package ISQBase {
```

```
    attribute def LengthUnit :> SimpleUnit {...}
```

```
    attribute def LengthValue :> ScalarQuantityValue {  
        attribute redefines num : ScalarValues::Real;  
        attribute redefines mRef : LengthUnit;  
    }
```

```
    attribute length: LengthValue :> quantity;
```

```
    ...
```

```
package ISQSpaceTime {  
    import ISQBase::*;

    ...
}
```

A *length unit* is a simple unit.

A *length value* is a quantity value with a real magnitude and a length-unit scale.

A *length* is a quantity with a length value.

The *International System of Quantities* defines seven abstract units (length, mass, time, electric current, temperature, amount of substance, luminous intensity) and many other units derived from those.

The ISO standard (ISO 80000) is divided into several parts. For example, Part 3 defines units related to space and time.

# International System of Units / Système International (SI)

The *International System of Units* defines base units for the seven abstract ISQ unit types.

```
package SI {  
    import ISQ::*;

    import SIPrefixes::*;

    attribute <g> gram : MassUnit;  
  
    attribute <m> metre : LengthUnit;  
    attribute <kg> kilogram : MassUnit {  
        attribute redefines unitConversion : ConversionByPrefix {  
            attribute redefines prefix = kilo;  
            attribute redefines referenceUnit = g  
        }  
    }  
    attribute <s> second : TimeUnit;  
    attribute <A> ampere : ElectricCurrentUnit;  
    attribute <K> kelvin : ThermodynamicTemperatureUnit;  
    attribute <mol> mole : AmountOfSubstanceUnit;  
    attribute <cd> candela : LuminousIntensityUnit;  
    ...  
  
    attribute <N> newton : ForceUnit = kg * m / s ^ 2;
```

Each unit declaration includes the full unit name and its abbreviation as an identifier.

A unit can be defined using prefix-based conversion from a reference unit.

A derived unit can be defined from an arithmetic expression of other units.

```
package USCustomaryUnits {  
    import ISQ::*;

    private import SI::*;

    attribute <ft> foot : LengthUnit {  
        attribute redefines unitConversion : ConversionByConvention {  
            attribute redefines referenceUnit = m,  
            attribute redefines conversionFactor = 3048/10000;  
        }  
    }  
    ...  
    attribute <mi> mile : LengthUnit {  
        attribute redefines unitConversion : ConversionByConvention {  
            attribute redefines referenceUnit = ft,  
            attribute redefines conversionFactor = 5280;  
        }  
    }  
    ...  
    attribute <'mi/hr'> 'mile per hour' : SpeedUnit = mi / hr;  
    alias mph for 'mi/hr';  
    ...  
}
```

*US customary units* are defined by conversion from SI units.

An alias for mile per hour.

```
package VectorCalculations {  
    private import ScalarValues::Boolean;  
    private import ScalarValues::Number;  
    private import Quantities::VectorQuantityValue;  
  
    calc def '+' specializes VectorFunctions::'+'  
        (: VectorQuantityValue, : VectorQuantityValue): VectorQuantityValue;  
    calc def '-' specializes VectorFunctions::'-'  
        (: VectorQuantityValue, : VectorQuantityValue): VectorQuantityValue;  
  
    calc def scalarVectorMult specializes VectorFunctions:: scalarVectorMult  
        (: Number, : VectorQuantityValue): VectorQuantityValue;  
    calc def vectorScalarMult specializes VectorFunctions:: vectorScalarMult  
        (: VectorQuantityValue, : Number): VectorQuantityValue;  
    calc def vectorScalarDiv specializes RealFunctions::'*'  
        (: VectorQuantityValue, : Number): VectorQuantityValue;  
    calc def inner specializes VectorFunctions::inner  
        (: VectorQuantityValue, : VectorQuantityValue): Number;  
  
    alias scalarVectorMult as '*';  
  
    calc def norm specializes VectorFunctions::norm (: VectorQuantityValue): Number;  
    calc def angle specializes VectorFunctions::angle  
        (: VectorQuantityValue, : VectorQuantityValue): Number;  
}
```

# Time (1)

**Clocks** is a Kernel Library model of the semantics of clocks.

A clock provides the current time as a quantity that advances monotonically over the lifetime of the clock.

**TimeOf** returns the time instant of the start of an occurrence relative to a given clock.

**DurationOf** returns the duration of a given occurrence relative to a given clock (the time of its end snapshot minus the time of its start snapshot).

```
package Time {  
  
    readonly part defaultClock : Clock[1] =  
        Clocks::defaultClock;  
  
    part def Clock :> Clocks::Clock {  
        attribute :>> currentTime : TimeInstantValue;  
    }  
  
    calc def TimeOf :> Clocks::TimeOf {  
        in o : Occurrence[1];  
        in clock : Clock[1] default defaultClock;  
        return timeInstant : TimeInstantValue[1];  
    }  
  
    calc def DurationOf :> Clocks::DurationOf {  
        in o : Occurrence[1];  
        in clock : Clock[1] default defaultClock;  
        return duration : DurationValue;  
    }  
}
```

The default clock used for change and time triggers.

## Time (2)

Generic time scale to express a time instant.

Captures the specification of the time instant with value zero, also known as the (reference) epoch.

```
attribute def TimeScale :> IntervalScale {  
    attribute :>> unit: DurationUnit[1];  
    attribute definitionalEpoch: DefinitionalQuantityValue[1];  
    attribute :>> definitionalQuantityValues = definitionalEpoch;  
}  
  
attribute def TimeInstantValue :> ScalarQuantityValue {  
    attribute :>> num: Real[1];  
    attribute :>> mRef: TimeScale[1];  
}  
attribute timeInstant: TimeInstantValue :> scalarQuantities;  
  
abstract attribute def DateTime :> TimeInstantValue;  
abstract attribute def Date :> TimeInstantValue;  
abstract attribute def TimeOfDay :> TimeInstantValue;  
  
attribute UTC: TimeScale {  
    attribute :>> longName = "Coordinated Universal Time";  
    attribute :>> unit = SI::s;  
    attribute :>> definitionalEpoch: DefinitionalQuantityValue {  
        :>> num = 0;  
        :>> definition = "UTC epoch at 1 January 1958 at 0 hour 0 minute 0 second";  
    }  
}  
attribute def UtcTimeInstantValue :> DateTime { :>> mRef = UTC; }  
attribute utcTimeInstant: UtcTimeInstantValue;
```

Representation of a time instant quantity.

Generic representation of a time instant as a calendar date and time of day.

Representation of the Coordinated Universal Time (UTC) time scale.

# Time (3)

```
attribute def Iso8601DateTimeEncoding :> String;  
  
attribute def Iso8601DateTime :> UtcTimeInstantValue {  
    attribute :>> num = getElapsedUtcTime(val);  
    attribute val: Iso8601DateTimeEncoding;  
    private calc getElapsedUtcTime(iso8601DateTime: Iso8601Da  
}  
  
attribute def Iso8601DateTimeStructure :> UtcTimeInstantValue {  
    attribute :>> num = getElapsedUtcTime(year, month, day, hour, minute, second,  
        microsecond, hourOffset, minuteOffset);  
    attribute :>> mRef = UTC;  
    attribute year: Integer;  
    attribute month: Natural;  
    attribute day: Natural;  
    attribute hour: Natural;  
    attribute minute: Natural;  
    attribute second: Natural;  
    attribute microsecond: Natural;  
    attribute hourOffset: Integer;  
    attribute minuteOffset: Integer;  
    private calc getElapsedUtcTime(year: Integer, month: Natural, day: Natural,  
        hour: Natural, minute: Natural, second: Natural, microsecond: Natural,  
        hourOffset: Integer, minuteOffset: Integer) : Real;  
}  
...  
}
```

Representation of an ISO 8601-1 date and time in extended string format.

Representation of an ISO 8601 date and time with explicit date and time component attributes.

# Geometry Library

# Spatial Items (1)

```
package SpatialItems {  
    ...  
    item def SpatialItem :> SpatialFrame {  
        item :>> self : SpatialItem;  
  
        item localClock : Clock[1] default Time::defaultClock;  
        attribute coordinateFrame : VectorMeasurementReference[1]  
            default Cartesian3dSpatialCoordinateSystem();  
  
        item originPoint : Point :> spaceShots;  
    }  
  
    item def CompoundSpatialItem :> SpatialItem {  
        item componentItems : SpatialItem[0..*] ordered :> subitems {  
            item nestedLocalClock :>> localClock default localClock;  
            attribute nestedBasisDirections : VectorQuantityValue[3];  
            attribute nestedOrigin : VectorQuantityValue[0..1];  
            attribute nestedCoordinateFrame :>> coordinateFrame {  
                attribute :>> placement[1] { ... }  
            }  
        }  
        attribute componentUnion[1] :> unionsOf {  
            item :>> elements = componentItems;  
        }  
    }  
    ...  
}
```

A *spatial item* is an Item with a three-dimensional spatial extent that also acts as a spatial frame of reference.

A spatial item has local time and space references used within it.

A *compound spatial item* is a spatial item that is a (spatial) union of a collection of component spatial items.

# Spatial Items (1)

```

package SpatialItems {
    ...
    calc def PositionOf :> SpatialFrames::PositionOf {
        in point : Point[1];
        in timeInstant : TimeInstantValue[1];
        in enclosingItem :>> 'frame' : SpatialItem[1];
        in clock : Clock[1] default enclosingItem.localClock;
        return positionVector : VectorQuantityValue[1];
    }
    calc def CurrentPositionOf :> SpatialFrames::CurrentPositionOf {
        in point : Point[1];
        in enclosingItem :>> 'frame' : SpatialItem[1];
        in clock : Clock[1] default enclosingItem.localClock;
        return positionVector : VectorQuantityValue[1];
    }
    calc def DisplacementOf :> SpatialFrames::DisplacementOf {
        in point1 : Point[1];
        in point2 : Point[1];
        in timeInstant : TimeInstantValue[1];
        in spacialItem :>> 'frame' : SpatialItem[1];
        in clock : Clock[1] default spacialItem.localClock;
        return displacementVector : VectorQuantityValue[1];
    }
    calc def CurrentDisplacementOf :> SpatialFrames::CurrentDisplacementOf {
        in point1 : Point[1];
        in point2 : Point[1];
        in spacialItem :>> 'frame' : SpatialItem[1];
        in clock : Clock[1] default spacialItem.localClock;
        return displacementVector : VectorQuantityValue[1];
    }
}

```

The position of points in space can be determined relative to the space and time references of a spatial item.

The position of a point can move over time, with its "current" position being relative to the clock reference of the spatial item.

# Shape Items (1)

```
package ShapeItems {  
    ...  
    item def Line :> Curve {  
        attribute :>> length;  
        attribute :>> outerSpaceDimension = 1;  
    }  
    item def PlanarSurface :> Surface {  
        attribute :>> area;  
        attribute :>> outerSpaceDimension = 2;  
    }  
  
    abstract item def Shell :> Item, StructuredSpaceObject, Surface;  
    abstract item def Path :> Item, StructuredSpaceObject, Curve;  
  
    item def Circle :> Path {  
        attribute radius :>> radius;  
        ...  
    }  
    item def Disc :> Shell {  
        attribute radius :>> radius;  
        item :>> shape : Circle [1] {  
            attribute :>> radius = Disc::radius;  
        }  
        ...  
    }  
    ...  
}
```

The ShapeItems package provides a model of items that represent basic geometric shapes.

# Shape Items (2)

```
package ShapeItems {  
    ...  
  
    item def Sphere :> Shell {  
        attribute :>> radius;  
        ...  
    }  
    item def Cone :> Shell {  
        attribute baseRadius :> radius;  
        attribute apexRadius :> radius default 0 [m];  
        attribute :>> height;  
        attribute isTruncated : Boolean [1] = (apexRadius > 0);  
        ...  
    }  
    item def Cylinder :> Cone {  
        attribute :>> radius = baseRadius;  
        attribute :>> baseRadius = apexRadius;  
        ...  
    }  
    item def Cuboid :> Shell {  
        attribute :>> length;  
        attribute :>> width;  
        attribute :>> height;  
        ...  
    }  
    alias Box for Cuboid;  
}
```