1 Section 2.3

Question 1

Let $S^2 = \{(x, y, z) \in \mathbb{R}^3 : x^2 + y^2 + z^2 = 1\}$ be the unit sphere and let $A : S^2 \to S^2$ be the (antipodal) map A(x, y, z) = (-x, -y, -z). Prove that A is a diffeomorphism.

Solution. Let $U = \{(x, y, \sqrt{1 - x^2 - y^2}) : x^2 + y^2 < 1\}$. Then we have

$$\begin{split} A(U) &= \{ -(x,y,\sqrt{1-x^2-y^2}) : x^2+y^2 < 1 \} \\ &= \{ (x,y,-\sqrt{1-x^2-y^2}) : x^2+y^2 < 1 \}. \end{split}$$

Let $\phi(u,v)=(u,v,\sqrt{1-u^2-v^2})$ be a parametrization for U and $\psi(u,v)=(u,v,-\sqrt{1-u^2-v^2})$ a parametrization for A(U). Then

$$\psi^{-1} \circ A \circ \phi(u, v) = \psi^{-1}(A(\phi(u, v)))$$

$$= \psi^{-1}(A((u, v, \sqrt{1 - u^2 - v^2})))$$

$$= \psi^{-1}((-u, -v, -\sqrt{1 - u^2 - v^2}))$$

$$= -(u, v).$$

Therefore, $\psi^{-1} \circ A \circ \phi$ is a differentiable function from $U \to A(U)$. This shows that A is a diffeomorphism.

Question 3

Show that the paraboloid $z = x^2 + y^2$ is diffeomorphic to the plane.

Solution. Luckily, we can pick one local chart each to cover the paraboloid U and the plane V. For the paraboloid, we can have (U, f^{-1}) where $f: (x, y) \to (x, y, x^2 + y^2)$ and for the plane, we can choose our local chart to be (V, g^{-1}) where to be $g: (x, y) \to (x, y)$.

Let us now define the diffeomorphism $\pi: U \to V$. Let $\pi(a,b,c) = (a,b)$. Then, $g^{-1} \circ \pi \circ f = \mathrm{id}_{\mathbb{R}^2}$. Thus, π is smooth. Then, π^{-1} is well-defined as it is bijective as a function of sets. π^{-1} is smooth as $f^{-1} \circ \pi^{-1} \circ g = \mathrm{Id}_{\mathbb{R}^2}$. Thus, π is a diffeomorphism.

Question 5

Let $S \subset R^3$ be a regular surface, and let $d: S \to R$ be given by $d(p) = |p - p_0|$, where $p \in S, p \in R^3, p_0 \notin S$; that is, d is the distance from p to a fixed point p_0 , not in S. Prove that d is differentiable.

Solution. We select $p \in S$, a open neighborhood U of p and a parametrization $x : V \to U$, where $V \subset \mathbb{R}^2$ and $x(u_0, v_0) = p$. Let $p_0 = (p_1, p_2, p_3)$. Let $f(p) = (d(p, p_0))^2$ Then

$$f \circ \underline{x}(u,v) = (x_1(u,v) - p_1)^2 + (x_2(u,v) - p_2)^2 + (x_3(u,v) - p_3)^2$$

Since $x_i(u, v)$ are all smooth functions, $f \circ \bar{x}$ should also be smooth. Since $p_0 \notin S$, we have $f \circ \bar{x}(S) \in (0, \infty)$. Note that $g(x) = \sqrt{x}$ is smooth on $(0, \infty)$. Therefore, $\sqrt{f \circ \bar{x}} = d \circ \bar{x}$ is also smooth. This shows that d is differentiable.

Question 7

Definition 1.1. A manifold is a second-countable Hausdorff topological space M such that for any point $m \in M$, there exists an open set N containing m such that N is homeomorphic to a subspace of \mathbb{R}^k for some fixed $k \in \mathbb{Z}_{\geq 0}$.

A **chart** is a pair (U, ϕ) such that U is an open subset of M and $\phi : U \to \mathbb{R}^k$ is a homeomorphism. Then, an **atlas** is a set of charts such that for every point, there exists a chart (A, α) such that A contains the point.

A differentiable manifold is a manifold with an atlas with the property that for any two charts (A, α) and (B, β) in the atlas, if $A \cap B$ is nonempty, $\beta \circ \alpha^{-1}$ is a differentiable map when restricted such that the image of α^{-1} is $A \cap B$.

Remark 1.2. A surface is a manifold, as it is by definition Hausdorff and second countable as a subspace of \mathbb{R}^3 , and locally is isomorphic to \mathbb{R}^2 as per the definition of surface. A regular surface implies that we have a atlas with compatible differentiable structure.

Theorem 1.3. Diffeomorphism is an isomorphism in the category of Differentiable Manifolds.

Proof. We need to show reflexivity, symmetric and transititive. Let (M, \mathscr{A}) and (N, \mathscr{B}) be two manifolds where \mathscr{A}, \mathscr{B} are maximal atlas. Let $f: M \to N$ be a diffeomorphism.

- (Reflexive) The diffeomorphism has the property that $x \in \mathcal{B}$ if and only if $x \circ f \in \mathcal{A}$, and f is bijective (as sets). Thus, $y \in \mathcal{A}$ implies, $y \circ f^{-1} \circ f \in \mathcal{A}$, implying $y \circ f^{-1} \in \mathcal{B}$. As the implication are reversible, this shows that f^{-1} is also a diffeomorphism.
- (Symmetric) Consider the identity map on M. This has the property that $x \in \mathscr{A}$ if and only if $x \circ \mathrm{Id}_M \in A$.
- (Transitivity) Let (K, \mathcal{C}) be a manifold where \mathcal{C} is a maximal atlas, and g be a diffeomorphism from N to K. Then, $x \in \mathcal{C}$ if and only if $x \circ g \in \mathcal{B}$ if and only if $x \circ g \circ f \in \mathcal{A}$. As the composition of bijective functions is bijective, $(g \circ f)$ is a diffeomorphism.

Question 9

(a). Define the notion of differentiable function on a regular curve. What does one need to prove for the definition to make sense?

Solution. Let $f: C \to \mathbb{R}$ be defined on a regular curve S. Then f is differentiable at $p \in C$ if, for some parametrization $\alpha: I \to C$ with $p \in \alpha(I) \subset C$ where I is an interval, the composition $f \circ \alpha: I \to \mathbb{R}$ is differentiable at $\alpha^{-1}(p)$. f is differentiable in C if it is differentiable at all points $p \in C$.

For the definition to make sense, one has to prove that the definition given does not depend on the choice of parametrization. One needs to prove a statement analogous to proposition 1, that is given two parametrizations of C both containing a neighbourhood of p, the change of parameters between those is a diffeomorphism.

2 Section 2.4

Question 15

Show that if all normals to a connected surface pass through a fixed point, the surface is contained in a sphere.

Solution. Let p_0 be such a fixed point. Then for any $p = \underline{x}(u, v) \in S$, $p - p_0$ is normal to the tangent plane in p. That is

$$\underline{x}_u \cdot (p - p_0) = \underline{x}_v \cdot (p - p_0) = 0.$$

Then for the function $h(u,v) = (\underline{x}(u,v) - p_0) \cdot (\underline{x}(u,v) - p_0)$, we have

$$h_u = 2x_u \cdot (x - p_0) = 0$$

$$h_v = 2\underline{x}_v \cdot (\underline{x} - p_0) = 0.$$

This shows that h is constant for any connected component of S. However, since S is connected, h should be constant on S, which implies that $S \subset p \in \mathbb{R}^3 : ||p - p_0|| = K$ for some K > 0.

Question 17

Two regular surfaces S_1 and S_2 intersect transversally if whenever $p \in S_1 \cap S_2$, then $T_p(S_1) \neq T_p(S_2)$. Prove that if S_1 intersects S_2 transversally, then a connected component of $S_1 \cap S_2$ is a regular curve.

Proof. Observe in \mathbb{R}^3 , if $T_p(S_1) \neq T_p(S_2)$, then $\dim_{\mathbb{R}}(T_p(S_1) \cap T_p(S_2)) = 1$.

It suffices to show that $S_1 \cap S_2$ is a locally a curve. This can be seen as we pick $v \in T_p(S_1) \cap T_p(S_2)$. Then we have a curve $c:[0,1] \to S_1$ with initial conditions c(0) = p, c'(0) = v. Similarly, we have a curve $d:[0,1] \to S_2$ mutatis mutandis. As they share initial conditions, they are locally equal at p, and thus the intersection is locally a curve.

Question 19

Let $S \in \mathbb{R}^3$ be a regular surface and $P \in \mathbb{R}^3$ be a plane. If all points of S are on the same side of P, prove that P is tangent to S at all points of $P \cap S$.

Proof. Let $p \in P$ and n_P be a unit normal of the plane P, then consider

$$h(r) = (r - p) \cdot n_P$$

one can compute that $dh_r = n_P$ for all $r \in \mathbb{R}^3$.

Without loss of generality assume that for all $s \in S$, $h(s) \ge 0$, so the surface lies on the "positive" side of the plane. If $\gamma(u)$ is a regular path in S, then

$$(h \circ \gamma)'(u) = (\nabla h) \cdot \gamma'(u) = n_P \cdot \gamma'(u).$$

Now if $s \in P \cap S$, then h(s) = 0, and if γ is a path that goes through s such that $\gamma(u_0) = s$, then we know that $(h \circ \gamma)(u) \ge (h \circ \gamma)(u_0)$ and by extreme value theorem we have

$$(h \circ \gamma)'(u_0) = 0 = \gamma'(u_0) \cdot n_P.$$

Since the path γ chosen was arbitrary, it means that the entire tangent plane of s is normal to n_P at s, which means that its tangent plane is P.

Question 21

Let $f: S \to R$ be a differentiable function on a connected regular surface S. Assume that $df_p = 0$ for all $p \in S$. Prove that f is constant on S.

Proof. Suppose for a contradiction that f is non-constant, let $f(s_1) = y_1$ and $f(s_2) = y_2$ where $s_1 \neq s_2$ and $y_1 \neq y_2$. Since S is connected, consider a regular path γ from s_1 to s_2 , let $\gamma(a) = s_1$ and $\gamma(b) = s_2$. By chain rule

$$(f \circ \gamma)'(x) = df_{\gamma(x)} \cdot \gamma'(x) = 0$$

from single variable calculus we have $f \circ \gamma$ is a constant function, but $(f \circ \gamma)(s_1) = y_1 \neq y_2 = (f \circ \gamma)(s_2)$.

Question 23

Let $U = \{(x, y, z) \in \mathbb{R}^3 \mid z = -1\}$ be identified with the complex plane \mathbb{C} , by sending $(x, y, z) \in U$ to x + iy. Let $P(x) = \sum_{k=0}^n a_k x^{n-k} \in \mathbb{C}[x]$ be of degree n. Denote π to be the stereographic projection of $S^2 = \{(x, y, z) \in \mathbb{R}^3 \mid x^2 + y^2 + z^2 = 1\}$ from the north pole (0, 0, 1) onto U. Prove that the map $F: S^2 \to S^2$ given by

$$F(p) = \pi^{-1} \circ P \circ \pi(p) \text{ for } p \notin U \setminus \{(0, 0, 1)\}$$

$$F((0, 0, 1)) = (0, 0, 1)$$

has finitely many critical points.

Proof. Recall that $\pi(x,y,z) = \left(\frac{2x}{1-z},\frac{2y}{1-z},-1\right) \subseteq U$. Thus π is a diffeomorphism between $U \setminus \{(0,0,1)\}$ and \mathbb{R}^2 . Thus, it suffices to show that $\hat{P}: \mathbb{R}^2 \to \mathbb{R}^2$ sending (x,y) to $(\operatorname{Re}P(x+iy),\operatorname{Im}P(x+iy))$ has finitely many critical points. (We can ignore the north pole, as it doesn't contain infinitely many distinct points). To see this, we require $\frac{\partial \operatorname{Re}P(x+iy)}{\partial x} = \frac{\partial \operatorname{Im}P(x+iy)}{\partial y} = \frac{\partial \operatorname{Im}P(x+iy)}{\partial x} = \frac{\partial \operatorname{Im}P(x+iy)}{\partial y} = 0$. By Complex Analysis, this implies that $\frac{\mathrm{d}P(z)}{\mathrm{d}z} = 0$, but that can only occurs finitely many times as P is a polynomial.

Question 25

Prove that if two regular curves C_1 and C_2 of a regular surface S are tangent at a point $p \in S$, and if $\varphi: S \to S$ is a diffeomorphism, then $\varphi(C_1)$ and $\varphi(C_2)$ are regular curves which are tangent at $\varphi(p)$.

Solution. Let U be a neighborhood of p with parametrization $\underline{x}(u,v)$. Let $\alpha_1(t)$ and $\alpha_2(t)$ be such that $\underline{x} \circ \alpha_1$ and $\underline{x} \circ \alpha_2$ are regular parametrizations of C_1 and C_2 with $\underline{x} \circ \alpha_1(0) = \underline{x} \circ \alpha_2(0) = p$. Then that C_1 and C_2 are tangent at p implies that

$$\alpha_1'(0) = \alpha_2'(0).$$

Now let V be a neighborhood of $\varphi(p)$ with parametrization y(w,z) and $\psi=(\psi_1,\psi_2)=y^{-1}\circ\varphi\circ x$. Let $\beta_1(t)$ and $\beta_2(t)$ be such that $y\circ\beta_1$ and $y\circ\beta_2$ are regular parametrizations of $\varphi(C_1)$ and $\varphi(C_2)$ with $y\circ\beta_1(0)=y\circ\beta_2(0)=\varphi(p)$. Than

$$\beta_1'(0) = \left(\frac{\partial \psi_1}{\partial u}(\alpha_1(0))\alpha_{1u}'(0) + \frac{\partial \psi_1}{\partial v}(\alpha_1(0))\alpha_{1v}'(0), \frac{\partial \psi_2}{\partial u}(\alpha_1(0))\alpha_{1u}'(0) + \frac{\partial \psi_2}{\partial v}(\alpha_1(0))\alpha_{1v}'(0)\right)$$

$$= \left(\frac{\partial \psi_1}{\partial u}(\alpha_1(0)) - \frac{\partial \psi_1}{\partial v}(\alpha_1(0))\right)\alpha_1'(0)$$

$$= J_{\psi}(\alpha_1(0))\alpha_1'(0).$$

Likewise, we have

$$\beta_2'(0) = J_{\psi}(\alpha_2(0))\alpha_2'(0).$$

However, since $\alpha_1(0) = \alpha_2(0) = \bar{x}^{-1}(p)$ and $\alpha_1'(0) = \alpha_2'(0)$, we have $\beta_1'(0) = \beta_2'(0)$. This implies that $\varphi(C_1)$ and $\varphi(C_2)$ is tangent at $\varphi(p)$.