1 Section 1.7

Question 6

Let $\alpha(s), s \in [0, l]$ be a closed convex plane curve positively oriented. The curve

$$\beta(s) = \alpha(s) - rn(s)$$

where r is a positive constant and n is a normal vector, is called a *parallel* curve to α (textbook figure is wrong, curve needs to be convex). Show that

(a) Length of $\beta = \text{length of } \alpha + 2\pi r$.

Solution. WLOG assume α is parametrised by arc length, since α is a plane curve the torsion is zero, so n' = -kt.

$$\beta'(s) = \alpha'(s) - rn'(s)$$

$$= \alpha'(s) - r(-k(s)t(s))$$

$$= (1 + rk(s))t(s)$$

now as α is a simple closed curve with positive orientation, the rotation index is 1 and $\int_0^l k(s) ds = 2\pi$, so

length of
$$\beta = \int_0^l |\beta'(s)| ds$$

= $\int_0^l 1 + rk(s) ds$
= $l + 2\pi r$.

(b) $A(\beta) = A(\alpha) + rl + \pi r^2$. Solution. For each $t \in [0, r]$ let

$$\beta_t(s) = \alpha(s) - tn(s)$$

which is a curve that is also parallel to α and lies between α and β . Then we have the expression

$$A(\beta) - A(\alpha) = \int_0^r \text{length of } \beta_t \, dt$$
$$= \int_0^r l + 2\pi t \, dt$$
$$= rl + \pi r^2$$

as required.

(c) $k_{\beta}(s) = k_{\alpha}(s)/(1 + rk_{\alpha}(s))$ (question typo'd). Solution. We re-parametrise β by arc length. Let

$$t(s) = \int_0^s |\beta'(u)| \ du$$

and we have $\frac{ds}{dt} = \frac{1}{\beta'(s)}$. Define $\hat{\beta}$ such that $\hat{\beta}(t(s)) = \beta(s)$, then

$$\hat{\beta}''(l) = \frac{\alpha''(s)}{|\beta'(s)|}$$

taking lengths we have

$$|\hat{\beta}''(l)| = k_{\beta}(s) = \frac{k_{\alpha}(s)}{1 + rk_{\alpha}(s)}.$$

Question 7

Let $\alpha : \mathbb{R} \to \mathbb{R}^2$ be a plane curve defined in the entire real line \mathbb{R} . Assume that α does not pass through the origin O = (0,0) and that both limits

$$\lim_{t \to -\infty} |\alpha(t)| = \lim_{t \to \infty} |\alpha(t)| = \infty.$$

- (a) Prove that there exists a point t_0 such that $|\alpha(t_0)| \leq |\alpha(t)|$ for all $t \in \mathbb{R}$.
- (b) Show, by an example, that the assertion in part a is false if one does not assume that both $\lim_{t\to-\infty} |\alpha(t)| = \infty$ and $\lim_{t\to\infty} |\alpha(t)| = \infty$. Solution.
- (a) Consider $f: \mathbb{R} \to \mathbb{R}$ sending t to $|\alpha(t)|$. Pick an arbitrary $t_1 \in \mathbb{R}$. We can find a, b such that for all $t < a, f(t) > f(t_1)$ and for all t > b, we have $f(t) > f(t_1)$. Then, we can consider the restriction $f|_{[a,b]}$ to the compact interval [a,b]. By the Extreme Value Theorem, we have that this takes a minimum on [a,b], say at t_0 . Then this t_0 satisfy the required properties as for $t \in [a,b]$, $|\alpha(t_0)| \le |\alpha(t_1)|$, and for $t \notin [a,b]$, $|\alpha(t)| > |\alpha(t_1)| \ge |\alpha(t_0)|$.
- (b) Consider $f(t) = (e^t, 0)$. Then, $\inf_t |\alpha(t)| = 0$, but this is non-zero for all t.

Question 8

(a) Let $\alpha(s)$, $s \in [0, l]$, be a plane simple closed curve. Assume that the curvature k(s) satisfies $0 < k(s) \le c$ where c is a constant (thus, α is less curved than a circle of radius 1/c). Prove that

length of
$$\alpha \ge \frac{2\pi}{c}$$
.

Solution. We have a simple closed curve so we know that

$$\int_0^l k(s) \ ds = 2\pi$$

substituting the bounds $0 < k(s) \le c$ we have

$$2\pi \le cl \implies l \ge \frac{2\pi}{c}$$
.

(b) In part (a) replace the assumption of being simple by " α has rotation index N." Prove that

length of
$$\alpha \geq \frac{2\pi N}{c}$$
.

Solution. Similarly, as rotation index is N,

$$\int_0^l k(s) \ ds = 2\pi N$$

similarly substitute the bounds and we have

$$l \ge \frac{2\pi N}{c}$$
.

Question 9

We here define the notion of being "inside" a simple closed curve.

Definition 1.1. A point p is inside a simple closed curve C if there exists a ray from p that intersects exactly one point in C, say q, such that $q \neq p$. Moreover, the tangent line at q is not parallel to the ray from p to q.

Theorem 1.2. A set $K \subseteq \mathbb{R}^2$ is convex if for any two points $p, q \in K$, the segment of straight line \overline{pq} is contained in K.

Let C be a simple closed curve and K be the points on or inside C. Then if C is convex so is K.

Proof. For each point $c \in C$, let U_c be the closed half-plane, with the tangent line through c being the boundary and $C \subseteq U_c$. By convexity, we have $K \subseteq U = \cap_{c \in C} U_c$. As the intersection of two convex sets is convex, and half-planes are convex, it remains to show that $U \subseteq K$.

Consider a point $p \in \mathbb{R}^2 \setminus K$. As C is compact, we can pick $q \in C$ such that d(p,q) is minimized. Then, the tangent line at q must be perpendicular to the ray from p to q. Suppose then that $p \in U_q$. Then the ray can not intersect another point of C, as C cannot intersect the line segment \overline{pq} as q is the closest point to p on C, and C cannot intersect the ray after q, as all of C lies in U_q . By our definition, this implies that p is inside the curve, which is a contradiction.

2 Section 2.2

Question 4

Let $f(x, y, z) = z^2$. Prove that 0 is not a regular value off and yet that $f^{-1}(0)$ is a regular surface.

Solution. Note that

$$df = (f_x, f_y, f_z) = (0, 0, 2z),$$

which is not surjective only when z = 0. Hence, (0,0,0) is a critical point and thus f(0,0,0) = 0 is not a regular value.

However,

$$f^{-1}(0) = \{(x, y, z) \in \mathbb{R}^3 | z^2 = 0\}$$
$$= \{(x, y, 0) | x, y \in \mathbb{R}\}$$
$$= \mathbb{R}^2 \times \{0\}.$$

Hence, $f^{-1}(0)$ is homeomorphic to \mathbb{R}^2 and therefore is regular.

Question 5

Let $P=\{(x,y,z)\in\mathbb{R}^3|x=y\}$ (a plane) and let $x:U\subset\mathbb{R}^2\to\mathbb{R}^3$ be given by

$$x(u,v) = (u+v, u+v, uv),$$

where $U = \{(u, v) \in \mathbb{R}^2 | u > v\}$. Clearly, $x(U) \subset P$. Is x a parametrization of P?

Solution. Yes, x is a parametrization. Clearly, x is differentiable in U with

$$dx(u,v) = \begin{pmatrix} 1 & 1 \\ 1 & 1 \\ u & v \end{pmatrix}.$$

Note that for $(u, v) \in U$, we have u > v. Then

$$\left| \begin{array}{cc} 1 & 1 \\ u & v \end{array} \right| = v - u \neq 0.$$

This implies dx(u,v) is injective for all $(u,v) \in U$. Now let (a,a,b) be any point in x(U). Then

$$u + v = a, uv = b$$

$$\Rightarrow u(a - u) = b$$

$$\Rightarrow (u - \frac{a}{2})^2 = \frac{a^2}{4} - b.$$

Notice that here one must have $\frac{a^2}{4} - b \ge 0$ as the equations $\begin{cases} u + v = a \\ uv = b \end{cases}$ should have real solutions for $(a, a, b) \in x(U)$. Then given u > v, we have

$$u = \frac{a}{2} + \sqrt{\frac{a^2}{4} - b}$$
$$v = \frac{a}{2} - \sqrt{\frac{a^2}{4} - b}.$$

These are the unique (u, v) solving x(u, v) = (a, b), which shows x is injective. Hence, by Prop. 4, x^{-1} must be continuous and we can conclude that x is indeed a parametrization.

Question 6

Give another proof of Prop. 1 by applying Prop. 2 to h(x, y, z) = f(x, y) - z.

Solution. Since f is differentiable in U, for any point in $U \times \mathbb{R}$, we have

$$\mathrm{d}h = (f_x, f_y, -1),$$

which is always surjective regardless of the value of f_x , f_y . Hence, any $z_0 \in f(U)$ with $f(x_0, y_0) = z_0$, we have

$$h(x_0, y_0, z_0) = f(x_0, y_0) - z_0 = 0,$$

being a regular value. This implies that

$$h^{-1}(0) = \{(x, y, z) \in U \times \mathbb{R} | h(x, y, z) = 0\}$$
$$= \{(x, y, z) \in U \times \mathbb{R} | f(x, y) = z\}$$
$$= \{(x, y, f(x, y)) | (x, y) \in U\}$$

is a regular surface.