1 Section 1.3

Question 2

A circular disk of radius 1 in the plane xy rolls without slipping along the x axis. The figure described by a point of the circumference of the disk is calIed a cycloid.

- Obtain a parametrized curve $\alpha : \mathbb{R} \to \mathbb{R}^2$ the trace of which is the cycloid, and determine its singular points.
- Compute the arc length of the cycloid corresponding to a complete rotation of the disk.

Solution:
Let us first parameterize the location of the centre of the circle. When it has rotated by θ, it will also have moved θ to the right. Hence, the position of the centre with respect to amount of rotation is $(\theta, 1)$.
Now consider the positional vector from the centre to the marked point on the circumference. At $\theta = 0$, this is at $(0, -1)$. Then, for general θ, this is at $(-\sin\theta, -\cos\theta)$. Summing this, it shows that the parameterization $\alpha(\theta) = (\theta - \sin\theta, 1 - \cos\theta)$.
We shall use the arc-length formula to yield

$$\begin{aligned}\int_0^{2\pi} |\nabla \cdot \alpha(x)| \mathrm{d}x &= \int_0^{2\pi} \sqrt{(1-\cos x)^2 + (\sin x)^2} \mathrm{d}x \\ &= \int_0^{2\pi} \sqrt{2 - 2\cos x} \mathrm{d}x \\ &= \left[-4\cos\frac{x}{2}\right]_{x=0}^{x=2\pi} \\ &= 8.\end{aligned}$$

Question 3

Question 4

Question 5

Let $\alpha : (-1, \infty) \to \mathbb{R}^2$ be given by

$$\alpha(t) = \left(\frac{3at}{1+t^3}, \frac{3at^2}{1+t^3}\right)$$

Solution:
(a) For $t = 0$, α is tangent to the x-axis. Computing the derivative, $\frac{\partial\alpha(t)}{\partial t} = \left(\frac{a(3-6t^3)}{(1+t^3)^2}, \frac{3at(2-t^3)}{(1+t^3)^2}\right)$. Thus, $\alpha(0) = (0,0)$ and $\frac{\partial\alpha(0)}{\partial t} = (3a, 0)$. Thus, it is tangent to the x-axis.
(b) As $t \to \infty$, $\alpha(t) = \frac{\partial\alpha(t)}{\partial t} = (0,0)$. We take limits, $\lim_{t\to\infty} \alpha(t) = \left(\lim_{t\to\infty} \frac{3at}{1+t^3}, \lim_{t\to\infty} \frac{3at^2}{1+t^3}\right) = (0,0)$. Similarly, $\lim_{t\to\infty} \frac{\partial\alpha(t)}{\partial t} = \left(\lim_{t\to\infty} \frac{a(3-6t^3)}{(1+t^3)^2}, \lim_{t\to\infty} \frac{3at(2-t^3)}{(1+t^3)^2}\right) = (0,0)$.

(c)Take the curve with the opposite orientation. Now, as $t \to -1$, the curve and its tangent approach the line $x + y + a = 0$.
Let us compute $\lim_{t\to -1} \frac{\alpha(t)_y}{\alpha(t)_x} = \lim_{t\to -1} \frac{1}{t} = -1$. Now, consider

$$\lim_{t\to -1} \alpha(t)_y - (-1)\alpha(t)_x = \lim_{t\to -1} \frac{3a(t+t^2)}{1+t^3} = -a.$$

Thus, the tangent approaches the line $y = (-1)x + (-a)$, or the line $x + y + a = 0$.

Question 10

2 Section 1.4

Question 10

The natural orientation of R^2 makes it possible to associate a sign to the area A of a parallelogram generated by two linearly independent vectors $u, v \in R^2$. To do this, let $\{e_i\}, i = 1, 2$, be the natural ordered basis of R^2, and write $u = u_1e_1 + u_2e_2, v = v_1e_1 + v_2e_2$. Observe the matrix relation

$$\begin{pmatrix} u \cdot u & u \cdot v \\ v \cdot u & v \cdot v \end{pmatrix} = \begin{pmatrix} u_1 & u_2 \\ v_1 & v_2 \end{pmatrix} \begin{pmatrix} u_1 & v_1 \\ u_2 & v_2 \end{pmatrix}$$

and conclude that

$$A^2 = \begin{vmatrix} u_1 & u_2 \\ v_1 & v_2 \end{vmatrix}^2.$$

Since the last determinant has the same sign as the basis $\{u, v\}$, we can say that A is positive or negative according to whether the orientation of $\{u, v\}$ is positive or negative. This is called the *oriented area* in R^2.

Solution:

$$\begin{aligned} A^2 &= (u \wedge v) \cdot (u \wedge v) \\ &= u \cdot (v \wedge (u \wedge v)) \\ &= u \cdot [(v \cdot v)u - (v \cdot u)v] \\ &= (u \cdot u)(v \cdot v) - (v \cdot u)(v \cdot u) \\ &= \begin{vmatrix} u \cdot u & u \cdot v \\ v \cdot u & v \cdot v \end{vmatrix} \\ &= \begin{vmatrix} u_1 & u_2 \\ v_1 & v_2 \end{vmatrix} \begin{vmatrix} u_1 & v_1 \\ u_2 & v_2 \end{vmatrix} \\ &= \begin{vmatrix} u_1 & u_2 \\ v_1 & v_2 \end{vmatrix}^2. \end{aligned}$$

Question 11

a. Show that the volume V of a parallelepiped generated by three linearly independent vectors $u, v, w \in R^3$ is given by $V = |(u \wedge v) \cdot w|$, and introduce an oriented volume in R^3.

b. Prove that

$$V^2 = \begin{vmatrix} u\cdot u & u\cdot v & u\cdot w \\ v\cdot u & v\cdot v & v\cdot w \\ w\cdot u & w\cdot v & w\cdot w \end{vmatrix}$$

Solution. (a) Let $n = \frac{u\wedge v}{||u\wedge v||}$ be the normal vector of the plane generated by u and v. Then

$$\begin{aligned} V &= (||u|| \times ||v|| \times |\sin(u,v)|) \times ||w|| \times |\cos(n,w)| \\ &= ||u\wedge v|| \times ||w|| \times |\cos(n,w)| \\ &= ||u\wedge v|| \times ||w|| \times |\cos(u\times v,w)| \\ &= |(u\wedge v)\cdot w| \end{aligned}$$

(b) We know that

$$\begin{aligned} |(u\wedge v)\cdot w| &= | \begin{pmatrix} u_2v_3 - v_2u_3 \\ u_3v_1 - v_3u_1 \\ u_1v_2 - v_1u_2 \end{pmatrix} \cdot w| \\ &= \begin{vmatrix} u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix} \\ &= \det(u,v,w). \end{aligned}$$

Hence,

$$\begin{aligned} V^2 &= \det(u,v,w)^2 \\ &= | \begin{pmatrix} u^T \\ v^T \\ w^T \end{pmatrix} \begin{pmatrix} u & v & w \end{pmatrix} | \\ &= \begin{vmatrix} u^Tu & u^Tv & u^Tw \\ v^Tu & v^Tv & v^Tw \\ w^Tu & w^Tv & w^Tw \end{vmatrix} \\ &= \begin{vmatrix} u\cdot u & u\cdot v & u\cdot w \\ v\cdot u & v\cdot v & v\cdot w \\ w\cdot u & w\cdot v & w\cdot w. \end{vmatrix} \end{aligned}$$

Question 12

Given the vectors $v \neq 0$ and w, show that there exists a vector u such that $u\wedge v = w$ if and only if v is perpendicular to w. Is this vector u uniquely determined? If not, what is the most general solution?

Solution: ($\Rightarrow$) By the properties of cross product, $u\wedge v = w$ implies that $v\cdot w = 0$.
($\Leftarrow$) If $v\cdot w = 0$, we have

$$(v\wedge w)\wedge v = (v\cdot v)w - (v\cdot w)v = ||v||^2 w.$$

Then $v \neq 0$ implies that $w = \frac{v\wedge w}{||v||^2} \wedge v$. Let $u = \frac{v\wedge w}{||v||^2}$ and we have $u\wedge v = w$.

Suppose there exist u' other than u such that $u' \times v = w$. Then

$$\begin{aligned}
&u \wedge v = u' \wedge v \\
\Rightarrow &(u' - u) \wedge v = 0 \\
\Rightarrow &u' - u = kv, \quad k \in R \\
\Rightarrow &u' = u + kv, \quad k \in R.
\end{aligned}$$

Therefore, the most general solution of $u \wedge v = w$ is

$$u = \frac{v \wedge w}{||v||^2} + kv, \quad k \in R.$$