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| **VCC**  **F\_TRIG**  **F\_ECHO**  **GND** | **VCC**  **L\_TRIG**  **L\_ECHO**  **GND** | **VCC**  **R\_TRIG**  **R\_ECHO**  **GND** | **VCC**  **F\_TRIG**  **F\_ECHO**  **GND** | **VCC**  **L\_TRIG**  **L\_ECHO**  **GND** | **VCC**  **R\_TRIG**  **R\_ECHO**  **GND** | **STATE(NC)**  **RXD**  **TXD**  **GND**  **VCC**  **EN(NC)** | **EN(NC)**  **VCC GND TXD**  **RXD**  **STATE(NC)** | **L\_ECHO**  **L\_TRIG**  **R\_ECHO**  **R\_TRIG** | **R\_PWM**  **L\_PWM**  **L\_DIR1**  **L\_DIR2** | **GND**  **VCC**  **R\_DIR1**  **R\_DIR2** | **GND**  **VCC**  **L\_COLL** | **GND**  **VCC**  **L\_COLL** | **R\_COLL**  **VCC**  **GND** | **R\_COLL**  **VCC**  **GND** | **RIGHT**  **MOTOR** | **LEFT**  **MOTOR** | **RIGHT**  **MOTOR** | **LEFT**  **MOTOR** |