# Tala Nemeh

# 101170694

# Department of Systems and Computer Engineering

Course: SYSC4906

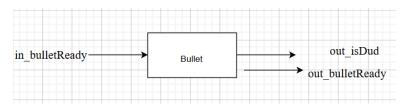
Assignment 1

#### **Introduction:**

This report presents the simulation and analysis of a discrete-event model developed using the DEVS (Discrete Event System Specification) formalism. The main objective of this assignment is to design, implement, and evaluate a simulation model that accurately represents the behavior of a system using the Cadmium DEVS simulation framework.

# **Devs Models Specifications:**

# **Bullet (Atomic Model):**



$$M_{Bullet} = \langle X, S, Y, \delta_{ext}, \delta_{int}, \lambda, ta \rangle$$

X: { in\_bulletReady }

S: { currentState  $\in$  { PASSIVE, ACTIVE }, bulletRdy  $\in$  {0, 1}, isDud  $\in$  {0, 1}

Y: { out\_isDud, out\_bulletReady }

 $\delta_{ext}$ : Processes the message from in\_bulletReady and determines the dud status randomly (95% chance of a good bullet). It then schedules an immediate internal transition ( $\sigma = 0$ ).

#### Pseudocode:

```
if (in_bulletReady not empty) then
   bulletRdy = last message from in_bulletReady
randVal = random value in [0,1]
if (randVal < 0.95) then
   isDud = 0  // bullet is good
else
   isDud = 1  // bullet is a dud
currentState = ACTIVE
σ = 0  // schedule immediate internal transition</pre>
```

 $\delta_{int}$ : Resets the model to a passive state by setting currentState to PASSIVE and  $\sigma$  to  $\infty$ 

```
currentState = PASSIVE
σ = ∞
```

λ: Outputs the dud status and the bullet-ready flag based on the current state.

#### Pseudocode:

```
send out_isDud = isDud
send out_bulletReady = bulletRdy
```

ta: Returns σ

# **Chamber (Atomic model):**

```
M_{Chamber} = \langle X, S, Y, \delta_{ext}, \delta_{int}, \lambda, ta \rangle
```

X: { in\_isDud, in\_bulletLoaded}

S: {currentState ∈ { passive, active },dudBullet, bulletIn}

Y:{out\_boltBack, out\_bulletFired, out\_casing}

 $\delta_{ext}$ : Processes incoming messages as follows:

#### Pseudocode:

```
if in_isDud has a message:
    dudBullet = message

if in_bulletLoaded has a message:
    bulletIn = message
    sigma = 5.0
```

 $\delta_{int}$ : On an internal event, the model resets:

#### Pseudocode:

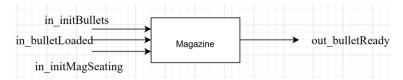
λ:

#### Pseudocode:

```
if dudBullet == 0 and bulletIn == 1:
    send out_boltBack message 1
    send out_bulletFired message 1
    send out_casing message 1
```

ta: Returns σ

# **Magazine**(Atomic model):



```
M_{\text{Magazine}} = \langle X, S, Y, \delta_{\text{ext}}, \delta_{\text{int}}, \lambda, ta \rangle
```

X: { in\_initBullets, in\_bulletLoaded, in\_initMagSeating }

S: {currentState ∈ { passive, active }, tempMsgVal, bulletsLeft, magSeating, bulletReady}

Y: { out\_bulletReady }

 $\delta_{ext}$ :

```
sigma = sigma - e
if in_initBullets has a message:
    tempMsgVal = message
if tempMsgVal >= 0 and tempMsgVal < 30
   bulletsLeft = tempMsgVal</pre>
else if in_initMagSeating has a message:
    tempMsgVal = message
magSeating = tempMsgVal
else if in_bulletLoaded has a message:
     tempMsgVal = message
     if tempMsgVal == 1:
         bulletsLeft = bulletsLeft - 1
if bulletsLeft >= 0:
     if magSeating == 1:
         bulletReady = 1
else:
    bulletReady = 0
currentState = active
sigma = 0.0
```

 $\delta_{int}$ :

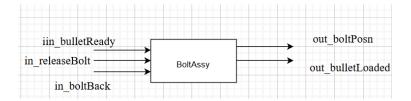
```
currentState = passive
sigma = infinity
```

λ:

```
send out_bulletReady message = bulletReady
```

ta: Returns σ

# **BoltAssy:**



```
M_{BoltAssy} = \langle X, S, Y, \delta_{ext}, \delta_{int}, \lambda, ta \rangle
```

X: { in\_bulletReady, in\_releaseBolt, in\_boltBack } (messages of type int)

S: { currentState  $\in$  { PASSIVE, ACTIVE }, boltFree  $\in$  {0,1}, readyBullet  $\in$  {0,1}, boltState  $\in$  {0 (forward), 1 (back), 2 (error)} }

Y: { out\_bulletLoaded, out\_boltPosn }

 $\delta_{\text{ext}}$ : Processes messages from in\_bulletReady, in\_releaseBolt, and in\_boltBack; schedules an immediate transition ( $\sigma = 0$ ) after updating boltState.

#### Pseudocode:

```
if in_bulletReady has a message:
    readyBullet = message

if in_releaseBolt has a message && message == 1 && boltState == 1:
    boltFree = 1

if in_boltBack has a message && message == 1 :
    if boltState equals 0 :
        boltState = 1
    else if boltState == 1:
        boltState == 0

if boltFree == 1 && boltState == 1:
    randVal = random value between 0 and 1
    if readyBullet == 1
    if randVal < 0.90:
        boltState = 0 // successful load
    else
        boltState = 2 // loading issue
    else
        boltState = 0 // no bullet ready

readyBullet = 0
    boltFree = 0
    currentState = active
    sigma = 0.0
```

 $\delta_{int}$ : Resets the model to a passive state (currentState = PASSIVE,  $\sigma = \infty$ ).

# Pseudocode:

```
currentState = PASSIVE \sigma = \infty
```

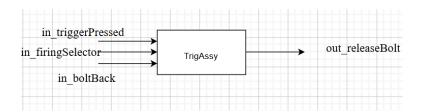
λ: Outputs bullet load status and bolt position based on the current boltState.

#### Pseudocode:

```
if (state.boltState == 0) then
    send out_bulletLoaded = 1
else if (state.boltState == 2) then
    send out_bulletLoaded = 0
send out_boltPosn = state.boltState
```

ta: Returns σ.

# **TrigAssy(Atomic model):**



TrigAssy =  $\langle X, S, Y, \delta_{ext}, \delta_{int}, \lambda, ta \rangle$ 

X:{ in\_triggerPressed, in\_firingSelector, in\_boltBack}

S: {currentState  $\in$  { passive, active }, triggerPull  $\in$  { 0, 1 }, firingSelector  $\in$  { 0, 1, 2 }}

Y: { out\_releaseBolt}

 $\delta$ \_ext:

 $\delta$ \_int: Resets the model to a passive state by setting currentState to PASSIVE and  $\sigma$  to  $\infty$ 

```
if firingSelector equals 1 and triggerPull equals 1 then
    triggerPull = 0
    currentState = passive
    sigma = infinity
```

```
λ:
```

```
if triggerPull does not equal 1 then
      if firingSelector equals 0 then
         send out_releaseBolt message 0
      else if firingSelector equals 1 ther
          send out_releaseBolt message 1
          if firingSelector equals 2 ther
ta: Returns \sigma.
MaggAssy(Coupled model):
MagAssy = \langle X, Y, \{M_i\}, EIC, EOC, IC \rangle
X:{in_initBullets, in_initMagSeating, in_bulletLoaded}
Y:{ out_bulletReady,out_isDud}
Submodels (\{M_i\}):
Magazine (an atomic DEVS model, as defined in Magazine.hpp)
Bullet (an atomic DEVS model, as defined in Bullet.hpp)
EIC: (
in initBullets → Magazine.in initBullets
in initMagSeating → Magazine.in initMagSeating
in bulletLoaded → Magazine.in bulletLoaded)
IC:
```

(Magazine.out bulletReady → Bullet.in bulletReady)

# EOC:

(Bullet.out bulletReady → out bulletReady Bullet.out isDud  $\rightarrow$  out isDud)

```
Rifle (Coupled model): Rifle = \langle X, Y, \{M_i\}, EIC \rangle
```

```
Rifle = \langle X, Y, \{M_i\}, EIC, EOC, IC \rangle
X: { in_triggerPressed, in_firingSelector, in_boltBack, in_magSeating, in_bulletLoaded }
Y: { out_releaseBolt }
Submodels ({M_i}):
  MagAssy (a coupled DEVS model, as defined in MagAssy.hpp)
  TrigAssy (an atomic DEVS model, as defined in TrigAssy.hpp)
  BoltAssy (an atomic DEVS model, as defined in BoltAssy.hpp)
  Chamber (an atomic DEVS model, as defined in Chamber.hpp)
EIC: (
  in triggerPressed → TrigAssy.in triggerPressed
  in firingSelector → TrigAssy.in firingSelector
  in boltBack → BoltAssy.in boltBack
  in magSeating → MagAssy.in initMagSeating
  in bulletLoaded → MagAssy.in bulletLoaded)
IC: (
  MagAssy.out bulletReady → BoltAssy.in bulletReady
  MagAssy.out isDud → Chamber.in isDud
  TrigAssy.out releaseBolt → BoltAssy.in releaseBolt
  BoltAssy.out bulletLoaded → Chamber.in bulletLoaded
  BoltAssy.out_bulletLoaded → MagAssy.in bulletLoaded
  Chamber.out boltBack → BoltAssy.in boltBack
  Chamber.out boltBack → TrigAssy.in boltBack)
EOC: (TrigAssy.out releaseBolt \rightarrow out releaseBolt)
```

#### **Test Scenarios and Results**

The testing phase was designed to evaluate the accuracy and efficiency of the developed DEVS models. The test scenarios were designed to assess the behavior of the system under different conditions, ensuring correct state transitions and input-output consistency. Each scenario was designed to validate individual atomic models before conducting system-wide integration tests.

#### **Atomic models tests:**

#### **Bullet Model:**

# **Bullet Queue Test**

**Objective:** To verify how the Bullet model handles a queue of bullets being ready sequentially without time gaps between signals, testing its capacity to handle rapid transitions.

#### Method:

- **Setup:** The generator will send a rapid sequence of bullet ready signals (in\_bulletReady = 1) in quick succession.
- **Expected Behavior:** The Bullet model should process each input without error, managing state transitions between ACTIVE and PASSIVE effectively.

# **Execution Steps:**

• Send multiple (bulletReady = 1) signals in rapid succession.

```
time; model id; model name; port name; data
0;1;bulletmodel;;{1, State: PASSIVE, bulletRdy: 0, isDud: 0}
0;2;genmodel;;{Messages Sent: 0, Sigma: 1}
[BulletQueueGenerator] Sending bulletReady: 1 (message #1)
1;1;bulletmodel;out isDud;0
1;1;bulletmodel;out bulletReady;0
1;1;bulletmodel;;{0, State: ACTIVE, bulletRdy: 1, isDud: 0}
1;2;genmodel;out bulletReady;1
1;2;genmodel;;{Messages Sent: 1, Sigma: 1}
1;1;bulletmodel;out_isDud;0
1;1;bulletmodel;out bulletReady;1
1;1;bulletmodel;;{inf, State: PASSIVE, bulletRdy: 1, isDud: 0}
[BulletQueueGenerator] Sending bulletReady: 1 (message #2)
2;1;bulletmodel;;{0, State: ACTIVE, bulletRdy: 1, isDud: 0}
2;2;genmodel;out bulletReady;1
2;2;genmodel;;{Messages Sent: 2, Sigma: 1}
2;1;bulletmodel;out isDud;0
2;1;bulletmodel;out bulletReady;1
2;1;bulletmodel;;{inf, State: PASSIVE, bulletRdy: 1, isDud: 0}
[BulletQueueGenerator] Sending bulletReady: 1 (message #3)
3;1;bulletmodel;;{0, State: ACTIVE, bulletRdy: 1, isDud: 0}
3;2;genmodel;out bulletReady;1
3;2;genmodel;;{Messages Sent: 3, Sigma: 1}
3;1;bulletmodel;out isDud;0
```

The Bullet model correctly responds to bullet readiness signals, processes inputs, and transitions between states as expected.

#### **State Transitions:**

The Bullet model starts in a PASSIVE state (bulletRdy = 0, isDud = 0).

Upon receiving a bulletReady = 1 message, it transitions to ACTIVE (bulletRdy = 1).

After processing the input, the model outputs out\_bulletReady = 1 and out\_isDud = 0, then returns to the PASSIVE state.

#### Bullet Readiness and Output:

Each bulletReady message is processed sequentially, and the model outputs a valid response.

The transitions occur without delay, confirming that the model correctly processes input signals and updates states.

#### Repeated Execution:

The log shows a consistent cycle where the model transitions from PASSIVE  $\rightarrow$  ACTIVE  $\rightarrow$  PASSIVE for each input signal.

This confirms that the Bullet model handles repeated inputs as expected.

# **Magazine Model:**

# **Magazine Rapid Re-Seating Test**

**Objective:** To verify the Magazine model's ability to handle frequent changes in seating status while correctly tracking bullet readiness and count.

#### **Method:**

• **Setup**: The generator rapidly toggles in\_initMagSeating between seated (1) and unseated (0), while occasionally sending in\_bulletLoaded = 1 signals.

# • Expected Behavior:

- o When seated and bullets remain, out\_bulletReady should be 1.
- o If unseated or out of bullets, out\_bulletReady should be 0.
- Bullet count decrements only when in\_bulletLoaded = 1 arrives while seated.

# • Execution Steps:

- o Rapidly switch in\_initMagSeating between 1 and 0.
- Send in\_bulletLoaded = 1 at intermittent intervals.
- Observe out\_bulletReady after each seating toggle and loading signal to confirm correct state transitions and bullet count management.

### • Results:

```
0;1;magazine;;{1}
};2;magGen;;{Messages Sent: 0, Sigma: 1, Toggle Seating: Yes, Send Load Signal: No}
MagazineQueueGenerator] Sending: in_initMagSeating = 1 (Message #1)
;1;magazine;out_bulletReady;0
 .2;magGen;out_magSeating;1
.2;magGen;;{Messages Sent: 1, Sigma: 1, Toggle Seating: No, Send Load Signal: No}
 ;1;magazine;out_bulletReady;1
;1;magazine;;{inf}
                   Generator] Sending: in_initMagSeating = 0 (Message #2)
;1;magazine;;{0}
 ;2;magGen;;(Messages Sent: 2, Sigma: 1, Toggle Seating: Yes, Send Load Signal: No);1;magazine;out_magbases Sent: 2, Sigma: 1, Toggle Seating: Yes, Send Load Signal: No);1;magazine;out_bulletReady;1
MagazineQueueGenerator] Sending: in_initMagSeating = 1 (Message #3)
 ;2;magGen;out_magSeating;1
;2;magGen;;{Messages Sent: 3, Sigma: 1, Toggle Seating: No, Send Load Signal: Yes}
;1;magazine;out_bulletReady;1
;2;magGen;out_magSeating;0
;2;magGen;out_bulletLoaded;1
;2;magGen;;{Messages Sent: 4, Sigma: 1, Toggle Seating: Yes, Send Load Signal: No}
;1;magazine;out_bulletReady;1
;
;;;magazine;;{inf}
MagazineQueueGenerator]    Sending: in_initMagSeating = 1 (Message #5)
iggazine;;(e);

j:j:magazine;;(e);

j:j:magazine;;(e);

j:j:magGen;;(Messages Sent: 5, Sigma: 1, Toggle Seating: No, Send Load Signal: No);

j:j:magazine;out_bulletReady;1
 1;magazine;;{inf}
 MagazineQueueGenerator]    Sending: in_initMagSeating = 0 (Message #6)
 ;1;magazine;;{0}
 ;2;magGen;;(Messages Sent: 6, Sigma: 1, Toggle Seating: Yes, Send Load Signal: Yes);1;magazine;out_bulletReady;1
[MagazineQueueGenerator]    Sending: in_initMagSeating = 1, in_bulletLoaded = 1 (Message #7)
 ;1;magazine;;{0}
 ;2;magGen;out_magSeating;1
;2;magGen;out_bulletLoaded;1
 ,2;magGen;;{Messages Sent: 7, Sigma: 1, Toggle Seating: No, Send Load Signal: No};1;magazine;out_bulletReady;1
MagazineOueueGenerator] Sending: in initMagSeating = 0 (Message #8)
 ;1;magazine;;{0}
 2;magGen;out_magSeating;0
2;magGen;;{Messages Sent: 8, Sigma: 1, Toggle Seating: Yes, Send Load Signal: No}
```

When seated, the Magazine correctly sets out bulletReady = 1.

When unseated, out\_bulletReady = 0, preventing bullets from being loaded.

Bullet load signals only affect the bullet count when the magazine is seated.

The Magazine model successfully responds to rapid seating changes while ensuring bullets are only loaded when seated, demonstrating correct state transitions and bullet management under stress conditions.

**Bolt Assembly** 

**Bolt Cycling and Release Test** 

**Objective:** To verify how the Bolt Assembly (BoltAssy) model handles rapid bolt movements, ensuring correct state transitions and bullet loading behavior under frequent activation.

#### **Method:**

• **Setup**: The generator rapidly toggles the bolt position (in\_boltBack) between pulled back (1) and forward (0), while occasionally sending in\_releaseBolt = 1 to simulate bolt release.

# • Expected Behavior:

- When bolt is back (1) and a bullet is ready, out\_bulletLoaded should be 1.
- When bolt is forward (0), out\_bulletLoaded should be 0, preventing bullet loading.
- The model should correctly track the bolt state and respond accurately to in releaseBolt.

# • Execution Steps

- o Toggle in\_boltBack between 1 and 0 to simulate rapid bolt movement.
- Send in\_releaseBolt = 1 intermittently to test proper interaction between bolt release and bullet loading.

#### • Results:

```
### Company of the Co
```

The model correctly updates out\_boltPosn based on in\_boltBack. out\_bulletLoaded is only triggered when the bolt is back and a bullet is available. out releaseBolt is correctly triggered when in releaseBolt = 1.

The BoltAssy model successfully tracks rapid bolt movements while ensuring bullets are only loaded under the correct conditions. The test confirms that frequent state transitions do not cause errors or inconsistencies.

# **Trigger Assembly**

### **Trigger Mode and Rapid Fire Test**

**Objective:** To verify how the Trigger Assembly (TrigAssy) model handles rapid trigger pulls (in\_triggerPressed = 1) and firing mode changes (in\_firingSelector), ensuring proper bolt release behavior.

#### Method:

- **Setup**: The generator will rapidly toggle the trigger state (in\_triggerPressed = 1 or 0) while intermittently changing the firing mode (in\_firingSelector = 0, 1, or 2).
- Expected Behavior:
  - o If the trigger is pulled (in\_triggerPressed = 1) in SAFE mode (0), no bolt release occurs.
  - o In SINGLE mode (1), one bolt release occurs per trigger pull.
  - o In AUTO mode (2), the trigger remains engaged, allowing continuous bolt releases.
  - The model should properly transition between states without missing trigger inputs.

# • Execution Steps:

- Toggle in\_triggerPressed between 1 and 0 to simulate rapid trigger pulls.
- Switch in\_firingSelector between 0 (safe), 1 (single), and 2 (auto) at various intervals.

#### • Results:

```
time;model_id;model_name;port_name;data
0;1;trigAssy;;{inf, 0}
0;2;trigGen;;{Messages Sent: 0, Sigma: 1, Toggle Trigger: Yes, Firing Mode: 1}
[TriggerQueueGenerator] Sending: in_triggerPressed = 1, in_firingSelector = 1 (Message #1)
1;1;trigAssy;;{0, 1}
1;2;trigGen;out_triggerPressed;1
1;2;trigGen;out_firingSelector;1
1;2;trigGen;;{Messages Sent: 1, Sigma: 1, Toggle Trigger: No, Firing Mode: 1}
1;1;trigAssy;out_releaseBolt;1
1;1;trigAssy;;{inf, 0}
[TriggerQueueGenerator] Sending: in_triggerPressed = 0, in_firingSelector = 1 (Message #2)
2;1;trigAssy;;{0, 1}
2;2;trigGen;out_triggerPressed;0
2;2;trigGen;out_firingSelector;1
2;2;trigGen;;{Messages Sent: 2, Sigma: 1, Toggle Trigger: Yes, Firing Mode: 1}
2;1;trigAssy;;{inf, 0}
[TriggerQueueGenerator] Sending: in_triggerPressed = 1, in_firingSelector = 1 (Message #3)
3;1;trigAssy;;{0, 1}
3;2;trigGen;out_triggerPressed;1
3;2;trigGen;out_firingSelector;1
3;2;trigGen;;{Messages Sent: 3, Sigma: 1, Toggle Trigger: No, Firing Mode: 2}
3;1;trigAssy;out_releaseBolt;1
3;1;trigAssy;;{inf, 0}
[TriggerQueueGenerator] Sending: in_triggerPressed = 0, in_firingSelector = 2 (Message #4)
4;1;trigAssy;;{0, 1}
4;2;trigGen;out_triggerPressed;0
4;2;trigGen;out_firingSelector;2
4;2;trigGen;;{Messages Sent: 4, Sigma: 1, Toggle Trigger: Yes, Firing Mode: 2}
4;1;trigAssy;;{inf, 0}
[TriggerQueueGenerator] Sending: in_triggerPressed = 1, in_firingSelector = 2 (Message #5)
5;1;trigAssy;;{0, 1}
5;2;trigGen;out_triggerPressed;1
5;2;trigGen;out_firingSelector;2
5;2;trigGen;;{Messages Sent: 5, Sigma: 1, Toggle Trigger: No, Firing Mode: 2}
5;1;trigAssy;;{inf, 0}
[TriggerQueueGenerator] Sending: in_triggerPressed = 0, in_firingSelector = 2 (Message #6)
6;1;trigAssy;;{0, 1}
6;2;trigGen;out_triggerPressed;0
6;2;trigGen;out_firingSelector;2
6;2;trigGen;;{Messages Sent: 6, Sigma: 1, Toggle Trigger: Yes, Firing Mode: 0}
6;1;trigAssy;;{inf, 0}
[TriggerQueueGenerator] Sending: in_triggerPressed = 1, in_firingSelector = 0 (Message #7)
7;1;trigAssy;;{0, 1}
7;2;trigGen;out_triggerPressed;1
7;2;trigGen;out_firingSelector;0
  ;2;trigGen;;{Messages Sent: 7, Sigma: 1, Toggle Trigger: No, Firing Mode:
```

SAFE mode (0) correctly prevents out\_releaseBolt.

SINGLE mode (1) allows one bolt release per trigger pull.

AUTO mode (2) correctly maintains firing when the trigger remains pressed.

The TrigAssy model correctly responds to rapid mode changes, ensuring that the bolt is released only under valid conditions.

# **Coupled Model**

# **Magazine Assembly Loading and Readiness Test**

#### **Objective**

To verify how the MagAssy model handles bullet loading (in\_bulletLoaded), magazine seating (in\_initMagSeating), and bullet readiness (out\_bulletReady), ensuring correct operation when interacting with the Bullet model.

#### Method

### • Setup:

- The generator alternates between seated (1) and unseated (0) magazine states.
- Sends bullet load requests (in\_bulletLoaded = 1) at different intervals.
- o Starts with a set number of bullets (in\_initBullets) to test bullet depletion.

# • Expected Behavior:

- o If magazine is seated and bullets remain, out\_bulletReady = 1.
- o If magazine is unseated, out\_bulletReady = 0, even if bullets remain.
- Each bullet load request (in\_bulletLoaded = 1) decreases the count and updates out\_bulletReady.
- Once bullets reach zero, out\_bulletReady should remain 0, preventing further bullet usage.

# • Execution Steps

- Initialize the system:
  - Set in\_initBullets = 10 (start with 10 bullets) and in\_initMagSeating = 1 (seated).
- Toggle magazine seating: Send seating/unseating signals  $(1 \rightarrow 0 \rightarrow 1)$  to check if out\_bulletReady updates correctly.
- Load bullets:
- Send in\_bulletLoaded = 1, ensuring bullet count decreases properly.

#### • Results:

```
time, model, Lidendel, Jemes, port, news, data

(a) Pagaziner; (1)

(a) Sabulat; (1), state: PASSINE, bulletby: 0, index: 0)

(b) Pagaziner; (1)

(b) Sabulat; (1), state: PASSINE, bulletby: 0, index: 0)

(b) Sapulat; (1), state: PASSINE, bulletby: 0, index: 0)

(b) Sapulat; (1)

(b) Sabulat; (1)

(c) Sabulat; (2)

(c) Sabulat; (2)

(c) Sabulat; (3)

(c) Sabulat; (4)

(d) Sabulat; (4)

(d
```

out\_bulletReady = 1 when the magazine is seated and bullets are available. out\_bulletReady = 0 when the magazine is unseated, even if bullets remain. Bullet count decreases correctly with in\_bulletLoaded = 1, ensuring proper tracking.

The MagAssy model correctly updates bullet availability based on magazine seating and bullet loading, preventing incorrect firings when unseated or empty.

# **System Test**

# **Test 1: Firing Mode and Trigger Test**

**Objective:** Test three scenarios to determine whether the full system functions correctly under different test cases:

Scenario 1 tests the basic trigger and firing mode change.

Scenario 2 examines how the system reacts to changes in magazine seating and bullet availability.

Scenario 3 tests the effect of bolt position toggling on the firing process.

```
### Spins (1) State: ATTUR, Dollfree: 8, readyBullet: 9, boltState: 9)
### Bajban (1) State: ATTUR, Dollfree: 8, readyBullet: 9, boltState: 9)
### Bajban (1) State: ATTUR, Dollfree: 8, readyBullet: 9, boltState: 9)
### Bajban (1) State: ATTUR, BoltFree: 8, sinud: 9)
### Bajban (1) State: ATTUR, BoltFree: 9, sinud: 9)
### Bajban (1) State: PASSIVE, Bolletin: 1)
### Bajban (1) Bajban
```

```
ecompore_DurietLoaded_11

Places_Types_ages Sent: 4, Sigma: 1, Test Phase: 1, Firing Mode: 0, Trigger Proc. (jiff, State: PASSIVE, boltFree: 0, ready@ullet: 1, boltState: 0)

out_releaseBolt(0)

(jiff: all.)
         Asjiffr, states
Trjout_releaseBolt;0
Trjiffr, 8)
Trjiffr, 8)
Magainspot_balletBeady;1
Magainspot_balletBeady;1
Magainspot_balletBeady;1
Mallett;16, States ACTMP, balletBdy; 1, isDad: 8)
(Mallett;16, States ACTMP, balletBn; 1)
Mayjifr, State: PASSIVE, boltFree: 0, readyBullet: 1, boltState: 8)
Trainer: isDad;8
Trainer: isDad;8
                  ullet;out_bulletReady;1
ullet;out_bulletReady;1
ullet;;;[inf, State: PASSIVE, bulletRdy: 1, isDud: 0}
A;;[inf, State: PASSIVE, boltFree: 0, ready@ullet: 1, boltState: 0}
                                                                            magSeating;1
:sages Sent: 5, Sigma: 1, Test Phase: 1, Firing Mode: 1, Trigger Pressed: Yes, Bolt Back: No, Mag Seated: Yes, Bullets N
                        spiding.do
spiding.out.sulletReady;1
spiding.out.sulletReady;1
spiding.out.sulletReady;1
spiding.out.sulletReady: 1, isDud: 0)
spiding.out.sulletReady: 1, isDud: 0)
spiding.out.sulletReady: 0, readyBullet: 1, boltState: 0)
larg.out.sindudg
larg.out.sindudg
                      Iletjout_isoud;0
Iletjout_bulletbeady;1
Iletj;{inf, State: PASSIVE, bulletRdy: 1, isDud: 0}
;;{inf, State: PASSIVE, bulletRdy: 0, ready@ullet: 1, boltState: 0}
           rildefinjunt medseting;;
rrildefinjunt (unbetroode);
rrild
_bulletReady;1
nf, State: PASSIVE, bulletRdy: 1, isDud: 0}
State: PASSIVE, boltFree: 0, readyBullet: 1, boltState: 0}
     Tajout releaseBolt;1
Tajidin 90
Magazine;out bulletReady;1
Magazine;out bulletReady;1
Magazine;(in)
Bullet;(g) States ACTUP, bulletBdy: 1, isbud: 0)
Chor;(5) (doublett 0, bulletBn: 1)
Bajidin State PASSIM, boltree: 0, readyBullet: 1, bultState: 0)
Bulletzeri sindun.
                                                out_bulletReady;1
;(inf, State: PASSIVE, bulletRdy: 1, isDud: 0}
f, State: PASSIVE, boltFree: 0, readyBullet: 1, boltState: 0}
                           Teden-jourt.magdsatings]
Indems; [Messages Sent: 9, Sigma: 1, Test Phase: 1, Firing Mode: 1, Trigger Pressed: Yes, Bolt Back: No, Mag Seated: Yes, Bullets Remaining: 10)
;[(Inf. 9)
;[(Inf
                                                  out_isloud;1

out_bulletReady;1
;{inf, State: PASSIVE, bulletRdy: 1, isDud: 1}

of, State: PASSIVE, boltFree: 0, readyBullet: 1, boltState: 0}
```

```
er;out_dulietxeady;1
et;;(inf, State: PASSIVE, bulletRdy: 1, isDud: 1}
;(inf, State: PASSIVE, boltFree: 0, readyBullet: 1, boltState: 0}
                    ritedem; (Menzages Sent: 10, Sigma: 1, Test Phase: 1, Firing Mode: 2, Trigger Pressed: No, Bolt Back: No, Mag Se
BA;;{inf, State: PASSIVE, boltfree: 0, readyBullet: 1, boltState: 0}
juBujiun, research;
4/TApuir, leasescolt;
4/TApuir, leasescolt;
4/TApuir, leasescolt;
5/TApuir, leasescolt;
5/
                                   rifinen out holtBack;D
rifinen out magiesting:
rifinen out magiesting:
rifinen;(Messages Sent: 11, Signa: 1, Test Phase: 1, Firing Mode: 2, Trigger Pressed: Yes, Bolt Back: No, Mag Seated: Yes, Bullets Re
Th;(Inf. 0)
                                gazine; yout_bulletReady;1
gazine; y(inf)
llet; (6, State: ACTIVE, bulletRdy: 1, isDud: 0)
br; (5) {doubullet: 0, bulletIn: 1}
;; (inf, State: PASSIVE, boltFree: 0, readyBullet: 1, boltState: 0}
lletror (field)
                 Ma;[cfm, Sater: MASIVM, bolf-re: 0, readybullet: 1, boltState: 0)
bullet;pcd_bullet:pod;
bullet;pcd_bullet:pod;
bullet;pcd_bullet:pod;
bullet;pcf, state: PASIVM, bulletRey: 1, isbud: 0)
fts;[cfm, State: NASIVM, bulletRey: 0, readybullet: 1, boltState: 0)
fts;[cfm, State: NASIVM, bulletRey: 0, readybullet: 1, boltState: 0)
fts;[cfm, State: NASIVM, bulletRey: 0, readybullet: 1, boltState: 0)
fts;[cfm, State: NASIVM, bulletRey: 0, readybullet: 1, boltState: 0)
fts;[cfm, State: NASIVM, bulletRey: 0, readybullet: 1, boltState: 0)
fts;[cfm, State: NASIVM, bulletRey: 0, readybullet: 1, boltState: 0)
fts;[cfm, State: NASIVM, bulletRey: 0, readybullet: 1, boltState: 0)
fts;[cfm, State: NASIVM, bulletRey: 0, readybullet: 1, boltState: 0)
fts;[cfm, State: NASIVM, bulletRey: 0, readybullet: 1, boltState: 0)
fts;[cfm, State: NASIVM, bulletRey: 0, readybullet: 1, boltState: 0)
fts;[cfm, State: NASIVM, bulletRey: 0, readybullet: 1, boltState: 0)
fts;[cfm, State: NASIVM, bulletRey: 0, readybullet: 1, boltState: 0)
fts;[cfm, State: NASIVM, bulletRey: 0, readybullet: 1, boltState: 0)
fts;[cfm, State: NASIVM, bulletRey: 0, readybullet: 1, boltState: 0)
fts;[cfm, State: NASIVM, bulletRey: 0, readybullet: 1, boltState: 0)
fts;[cfm, State: NASIVM, bulletRey: 0, readybullet: 1, boltState: 0)
fts;[cfm, State: NASIVM, bulletRey: 0, readybullet: 1, boltState: 0)
fts;[cfm, State: NASIVM, bulletRey: 0, readybullet: 1, boltState: 0)
fts;[cfm, State: NASIVM, bulletRey: 0, readybullet: 1, boltState: 0)
fts;[cfm, State: NASIVM, bulletRey: 0, readybullet: 1, boltState: 0, readybullet: 1, boltState: 0)
fts;[cfm, State: NASIVM, bulletRey: 0, readybullet: 1, boltState: 0, readybullet: 1, boltState: 0)
fts;[cfm, State: NASIVM, bulletRey: 0, readybullet: 1, boltState: 0, readybullet. 1,
           jrfflednjout_magkestigj;
jrfflednjout_magkestigj;
jrfflednjout_magkes Sent: 12, Signe: 1, Test Phase: 3, Firing Mode: 2, Trigger Pressed: No, Bolt Back: No, Pag Seated: Yes, Bullets Remaining: 18
BNG;[ufr, State: MCDNUM, bolt/free: 0, readybullet: 1, boltState: 0)
     (at;out_bulletReady;1
(et;;(inf, State: PASSIVE, bulletRdy: 1, isDud: 0)
((inf, State: PASSIVE, boltFree: 0, ready@ullet: 1, boltState: 0)
                                               nempunc_firingsisettin;2
dempunc_boltsexsp
dempuncspecting;1
demp(Messages Sent: 13, Signa: 1, Test Phase: 1, Firing Mode: 2, Trigger Pressed: Yes, Bolt Back: No, Mag Seated: Yes, Bullets Remaining: 10)
3nf, 0)
gidgastine.ord_bulletinedp;i
gidgastine.ord_bulletinedp;i
gidgastine.idoubletine.gidgastine.idoubletine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.gidgastine.g
        gjessensport,ersettanset]
15jfffdeng:(Bergange Sent: 14, Sigma: 1, Test Phase: 1, Firing Mode: 2, Trigger Pressed: No, Bolt Back: No, Mag Seated: Yes, Bullets Remaining: 10)
15B4j;(inf, State: PASSIVE, boltfree: 0, readybullet: 1, boltState: 0)
           physical state of the state of 
        /Pablisty.ort_industry
/Pablisty.ort_industry
/Pablisty.ort_industry
/Pablisty.ort_industry
/Pablisty.ifuf, States PASSIVE, bulletSdy: 1, isDud: 8)
/Shiji.ifuf, States PASSIVE, bulletSdy: 1, isDud: 8)
/Shiji.ort_industry
/Shiparine; (0, 1)
/Shiparine; (0, 1)
/Shiparine; (0, 1)
/Shiparine; (0, 1)
```

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8;rif1eGen;Out_magSeating;1
8;rif1eGen;(Messages Sent: 15, Sigma: 1, Test Phase: 1, Firing Mode: 0, Trigger Pressed: Yes, Bolt Back: No, Mag Seated: Yes, Bullets Remaining: 10)
1;74;(sin*, 0)
1;74;(sin*, 0)
1;74;(sin*, 0)
1;74;(sin*, 0)
1;74;(sin*, 0)
1;75;(sin*, 0)
1;75
                  | Bulletjout_Exhaup;1
| Bulletjout_bulletReady;1
| Bulletj;{inf, State: PASSIVE, bulletRdy: 1, isDud: 0}
| BA;;{inf, State: PASSIVE, boltFree: 0, readyBullet: 1, boltState: 0}
     Doliffict,)
magGesting;1
ssages Sent: 17, Signa: 1, Test Phase: 1, Firing Mode: 0, Trigger Pressed: Yes, Bolt Back: No, Mag Seated: Yes, Bullets Remaining: 10)
                  refision; out_magneting;
refision; (Newsgase Sent: 17, Sigma: 1, Test Phase: 1, Firing Mode: 0,
Th;;(inf, 0)
Magazina; out_bulletReady;1
Magazina; (Linf)
Sullet;(0; State: ACTIVE, bulletRey: 1, isDud: 0)
(Obr;(0) (dudBullet: 0, bulletIn: 1)
Ms;(inf, State: MSSIVE, bulletRey: 0, readyBullet: 1, bultState: 0)
(Bullet;out_inDud;0)
                  [Bulletjout_jubbe]@
Bulletjout_bubletkeedpi1
Bulletjout_bubletkeedpi1
Bubletjout_bubletkeedpi1
Bubletjout_bubletkeedpi1
Bubletjout_form.
Bubletjout_bubletkeedpi1
Bubletjout_bubletkeedpi1
Bubletjout_form.
B
  #3.38a;(aff, State: MSSSTE, boltfree: 0, readyBullet: 1, boltState: 0)
#5.37a;(aff, 2)
#5.47a;(aff, 0)
#5.47a;(aff, 0)
#5.47a;(aff, 0)
#5.47a;(aff, 0)
#5.75allet;(d) State: ACTIVE, bulletRey: 1, isDud: 0)
#5.75allet;(d) State: ACTIVE, bulletRey: 1, isDud: 0)
#5.75allet;(aff, State: MSSSTE, boltfree: 0, readyBullet: 1, boltState: 0)
#5.75allet;(out,Stabud: 0)
#5.75allet;(out,Stabud: 0)
#5.75allet;(out,Stabud: 0)
#5.75allet;(out,Stabud: 0)
#5.75allet;(out,State: MSSSTE, boltfree: 0, readyBullet: 1, boltState: 0)
#5.75allet;(aff, State: MSSSTE, boltfree: 0, readyBullet: 1, boltState: 0)
#5.75allet;(aff, State: MSSSTE, boltfree: 0, readyBullet: 1, boltState: 0)
#5.75allet;(aff, State: MSSSTE, boltfree: 0, readyBullet: 1, boltState: 0)
#5.75allet;(aff, State: MSSSTE, boltfree: 0, readyBullet: 1, boltState: 0)
#5.75allet;(aff, State: MSSSTE, boltfree: 0, readyBullet: 1, boltState: 0)
#5.75allet;(aff, State: MSSSTE, boltfree: 0, readyBullet: 1, boltState: 0)
#5.75allet;(aff, State: MSSTE, boltfree: 0, readyBullet: 1, boltState: 0)
#5.75allet;(aff, State: MSSTE, boltfree: 0, readyBullet: 1, boltState: 0)
#5.75allet;(aff, State: MSSTE, boltfree: 0, readyBullet: 1, boltState: 0)
#5.75allet;(aff, State: MSSTE, boltfree: 0, readyBullet: 1, boltState: 0)
#5.75allet;(aff, State: MSSTE, boltfree: 0, readyBullet: 1, boltState: 0)
#5.75allet;(aff, State: MSSTE, boltfree: 0, readyBullet: 1, boltState: 0)
#5.75allet;(aff, State: MSSTE, boltfree: 0, readyBullet: 1, boltState: 0)
#5.75allet;(aff, State: MSSTE, boltfree: 0, readyBullet: 1, boltState: 0)
#5.75allet;(aff, State: MSSTE, boltfree: 0, readyBullet: 1, boltState: 0)
#5.75allet;(aff, State: MSSTE, boltfree: 0, readyBullet: 1, boltState: 0)
#5.75allet;(aff, State: MSSTE, boltfree: 0, readyBullet: 1, boltState: 0)
#5.75allet;(aff, State: MSSTE, boltfree: 0, readyBullet: 1, boltState: 0)
#5.75allet;(aff, State: MSSTE, boltfree: 0, readyBullet: 1, boltState: 0)
#5.75allet;(aff, State: MSSTE, boltfree: 0, readyBullet: 1, boltState: 0)
#5.75allet;(aff, State: MSSTE, boltfree: 0, 
               ); rif186m; out_magsacting; 1; rif186m; out_magsacting; 10; rif186m; out_magsa
  printmonen; Dir. Firingselactor; 0
8; rifl@den; out_boltSack; 8
8; rifl@den; out_sugearing; 1
8; rifl@en; out_sugearing; 1
8; rifl@en; out_bullet.coded; 1
8; rifl@en; out_bullet.coded; 2
8; rifl@en; (Messages Sent: 26, Sigma: 1, Test Phase: 1, Firing Mode: 1, Trigger Pressed: No, Bolt Back: No, Mag Seated: Yes, Bullets Remaining: 10)
4; Th; out_releaseBolt; 0
4; Th; out_releaseBolt; 0
4; Th; out_releaseBolt; 0
  llet;out_bulletReady;1
llet;;{inf, State: PASSIVE, bulletRdy: 1, isDud: 0}
```

The output of the 3 scenarios is shown in the screenshots above. They Rifle model was tested using a generator to simulate the different scenarios. The logs confirm that the generator is successfully producing the specified scenarios (trigger toggles, magazine seating toggles, bolt toggles) and that the system's components respond as intended.

# Initial Messages and State:

The system starts in Test Phase 1, with the firing mode initially set to 0 (safe) and the trigger not pressed.

Messages are generated at regular intervals, causing transitions between PASSIVE and ACTIVE states.

#### Scenario 1 Behavior:

Every internal transition, the trigger press status toggles (on/off).

Every 5 messages, the firing mode cycles (safe  $\rightarrow$  single  $\rightarrow$  auto  $\rightarrow$  back to safe).

The log lines show where the firing mode changes and the trigger toggles accordingly.

### Scenario 2 Behavior:

After enough messages are sent in Scenario 1, the generator transitions to Scenario 2.

Here, the magazine seating state toggles every 6 messages, and whenever the magazine is seated and bullets remain, the trigger is pressed (leading to a fire action).

The logs show when the magazine is seated or unseated, and how the bullet count decrements when a shot is fired.

#### Scenario 3 Behavior:

Finally, the generator switches to scenario 3, where the bolt position toggles each time.

If the bolt is back and there are bullets left, the trigger is pressed and a bullet is consumed. Otherwise, the trigger is not pressed.

The logs show these toggles and how the system transitions accordingly, with bullets decreasing when the bolt is back and the trigger is fired.

The simulation ends once the maximum number of messages is reached or no bullets remain.

#### **Conclusion**

This report outlined the implementation, testing, and evaluation of a discrete-event simulation model using the DEVS formalism. Through systematic testing of atomic and coupled models, the simulation successfully demonstrated correct state transitions, input processing, and output generation. Overall, the simulation provided a realistic representation of the rifle system using Cadmium DEVS modeling, highlighting the effectiveness of discrete-event simulations for analyzing complex cyber-physical systems