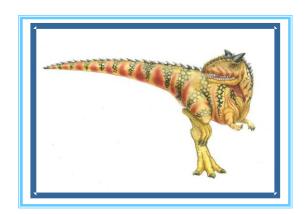
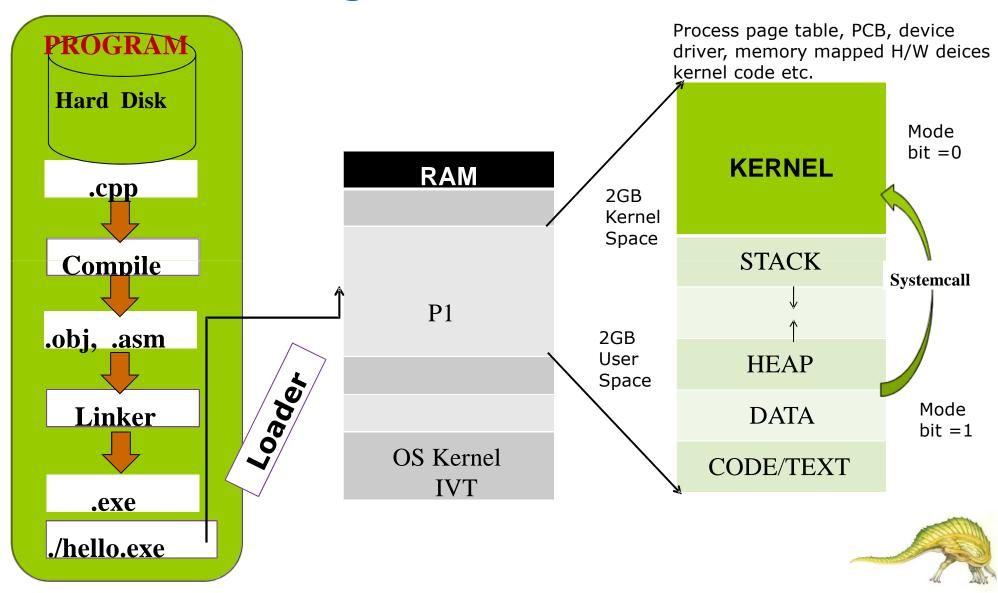
# Lecture 4, 5 Process Management





### **Program to Process**





When a program is loaded into memory, user space is organized into four regions of memory, called segments:

text segment, data segment, stack segment & heap segment

#### **Text segment (or code segment)**

where the compiled code of the program itself resides.

#### Data segment (Data & BSS)

data area contains

global or static or external variables that are initialized.

**BSS** contains

global or static or external variables that are uninitialized.

Pointer variable int \*arr; declared in global then in data else in stack

#### Heap segment

dynamically allocated variables are allocated in here.

it is managed by malloc and free.

#### Stack segment

- contains the program stack,
   a LIFO structure.
- •\$sp register point to the top of the stack.
- memory is allocated for automatic variables (local variables) within functions scope.





### The Process-Executable Program

- We write a program in e.g., Java.
- A compiler turns that program into an instruction list.
- The CPU interprets the instruction list (which is more a graph of basic blocks).

```
void X (int b) {
   if(b == 1) {
   ...
int main() {
   int a = 2;
   X(a);
}
```

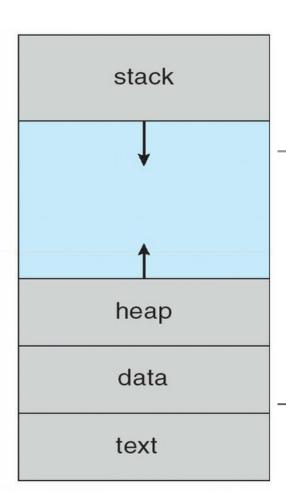
Program counter next instruction address



### **Process in Memory**

max

0



- Program to process.
- What you wrote

```
void X (int b) {
  if (b == 1) {
  ...
int main() {
  int a = 2;
  X(a);
}
```

What must the OS track for a process?

What is in memory.

```
main; a = 2
X; b = 2

Heap

void X (int b) {
   if (b == 1) {
    ...
   int main() {
      int a = 2;
      X(a);
   }

Code
```





### **Process Concept @ OS**

Textbook uses the terms job and process almost interchangeably.

A process is - Execution of an individual program.

#### Each time a process is created,

OS must create a complete independent address space (base, limit) (i.e., processes do not share their heap or stack data)

#### RAM

P1

P2

P3

## Represents by a Data Structure to OS Called Process Control Block- PCB





### **Process Control Block (PCB)**

OS maintains a process table to keep track of the active processes

#### Information for each process:

Program counter

Program id, user id, group id

Program status word

CPU register values

CPU Scheduling-process priority, pointer to scheduling queue

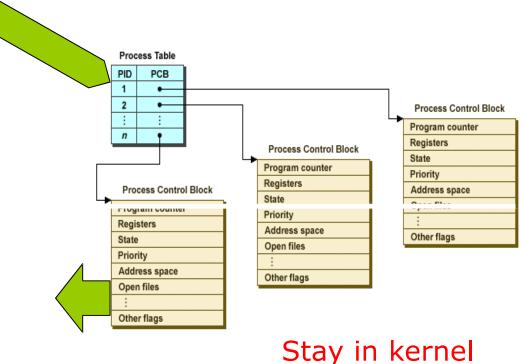
Memory maps-base/limit register, page table, segment table

Stack pointer

I/O status Information-allocated I/O devices, list of Open files

Accounting information, etc.-amount of CPU & real time used,

time limits, account numbers, job/process number



(Main Memory)

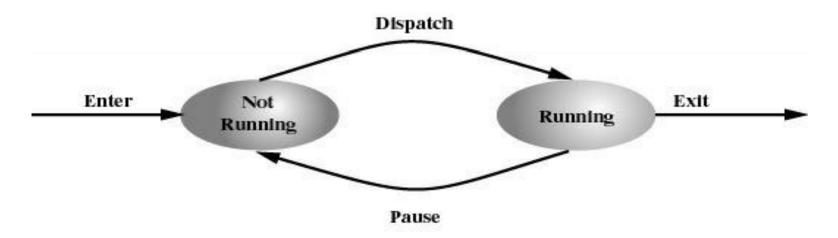


### **Two-State Process Model**

Process may be in one of two states

Running

Not-running

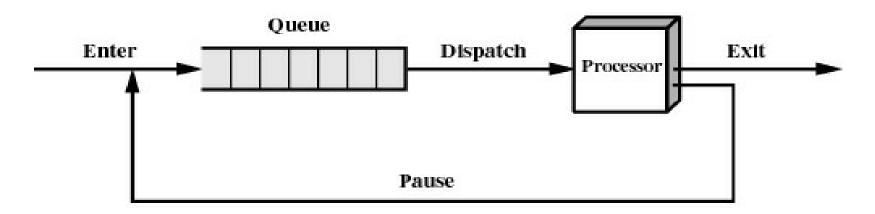


(a) State transition diagram



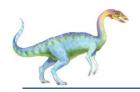


### **Not-Running Process in a Queue**



(b) Queuing diagram





### **Five States Process Model**

As a process executes, it changes *state* 

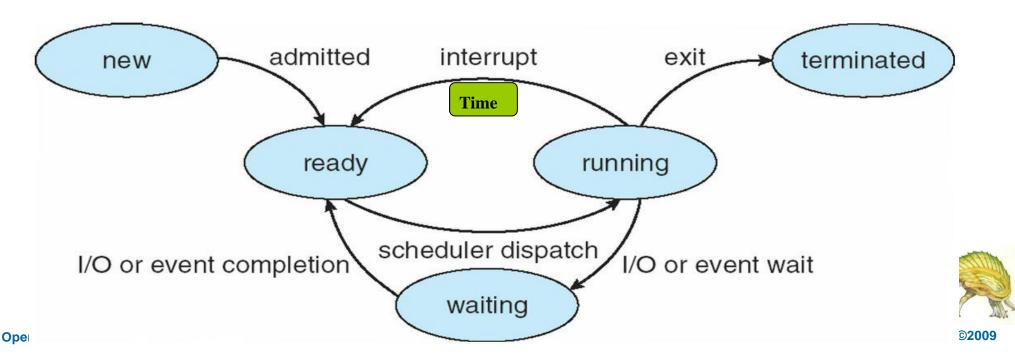
**new**: The process is being created

running: Instructions are being executed

waiting: The process is waiting for some event to occur

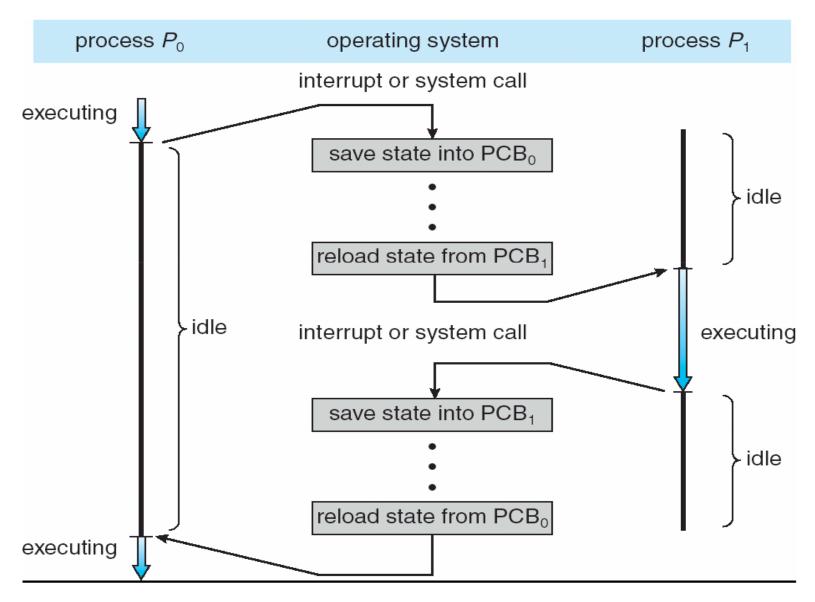
**ready**: The process is waiting to be assigned to a processor

terminated: The process has finished execution



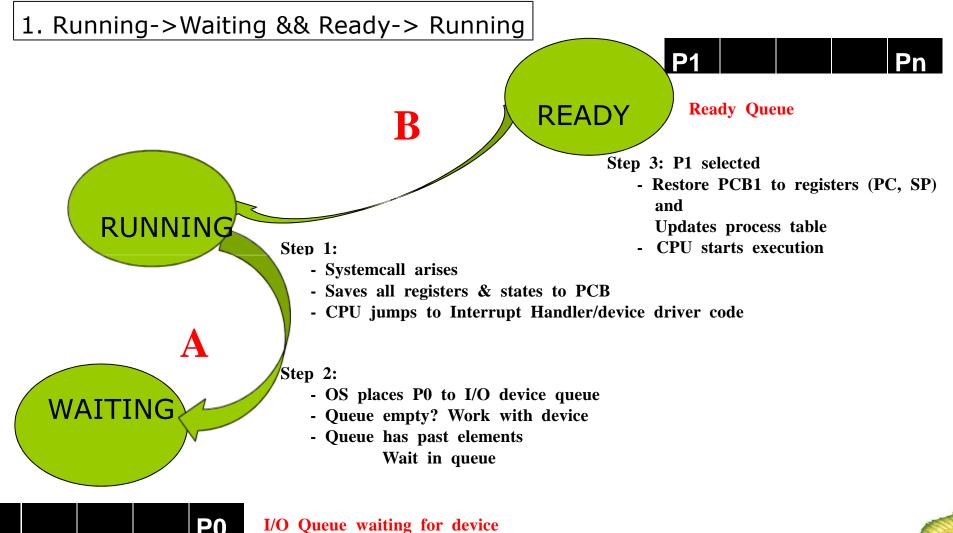


### **CPU Switch From Process to Process**



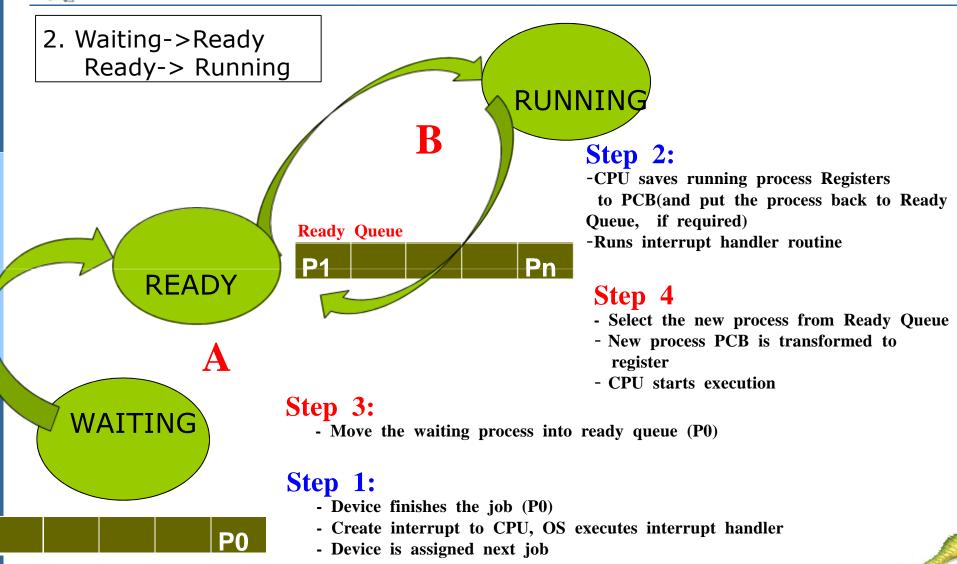


### **Context Switch**





### **Context Switch**



I/O Queue @ Device status table



### **Process Scheduling**

AIM: Maximize CPU use, quickly switch processes onto CPU for time sharing

**Process scheduler (is a process)** selects process among available for next execution on CPU

Maintains scheduling queues of processes

**Job queue** – set of all processes in the system (HD-Pool)

**Ready queue** – set of all processes residing in main memory, ready and waiting to execute

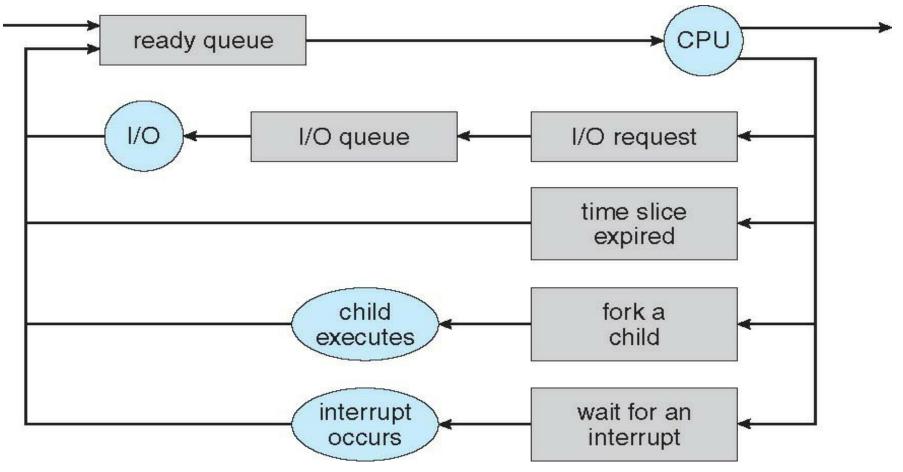
**Device queues** – set of processes waiting for an I/O device

Processes migrate among the various queues

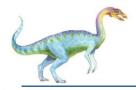




### Representation of Process Scheduling







#### Schedulers

Long-term scheduler/Job scheduler

which processes should be brought into the ready queue

invoked very infrequently (seconds, minutes) ⇒ (may be slow)

controls the degree of multiprogramming

Short-term scheduler/CPU scheduler

which process should be executed next and allocates CPU

invoked very frequently (milliseconds) ⇒

(must be fast)

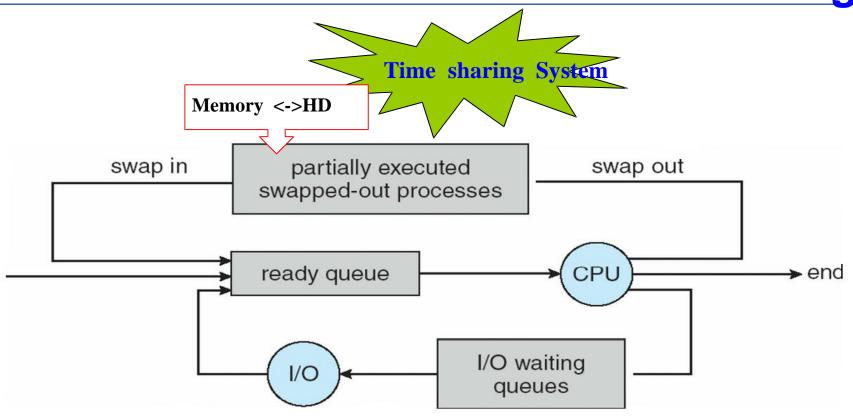
Balanced

I/O-bound process
CPU-bound process

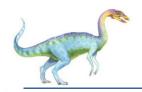




### Addition of Medium Term Scheduling







#### **Process Creation**

**Parent** process creates **children** processes, which, in turn create other processes, forming a tree of processes.

Process identifier (pid): process identified and managed.

#### Resource sharing

Parent and children share all resources

Children share subset of parent's resources

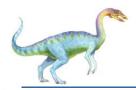
Parent and child share no resources

#### Execution

Parent and children execute concurrently

Parent waits until children terminate





#### Lecture Materials

Galvin 4.1-4.3

Galvin 13.4.1,13.4.2,13.4.3,13.4.4,13.5



### End of Lecture 4, 5

