

ECEn 671: Mathematics of Signals and Systems

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Section 1

Levenberg-Marquardt Optimization

Nonlinear Least Squares

The downside of GN is that the matrix $J^\top(x)J(x)$ may be ill-conditions at some states x .

For the general nonlinear least squares problem, we have

$$\frac{\partial \frac{1}{2} \mathbf{r}^\top(x) \mathbf{r}(x)}{\partial x} = \frac{\partial \mathbf{r}^\top}{\partial x}(x) \mathbf{r}(x) = \mathbf{J}^\top(x) \mathbf{r}(x).$$

Therefore we have

Gradient Descent $x^{[k+1]} = x^{[k]} - \alpha \mathbf{J}^\top(x^{[k]}) \mathbf{r}(x^{[k]})$

Gauss-Newton $x^{[k+1]} = x^{[k]} - \left(\mathbf{J}^\top(x^{[k]}) \mathbf{J}(x^{[k]}) \right)^{-1} \mathbf{J}^\top(x^{[k]}) \mathbf{r}(x^{[k]}).$

Note that there is no inverse for Gradient Descent, but it may converge slowly, even for linear residuals.

Nonlinear Least Squares

The Levenberg-Marquardt (LM) iteration is a combination of gradient descent and Gauss-Newton:

$$\mathbf{x}^{[k+1]} = \mathbf{x}^{[k]} - \left(\lambda \mathbf{I} + \mathbf{J}^\top(\mathbf{x}^{[k]}) \mathbf{J}(\mathbf{x}^{[k]}) \right)^{-1} \mathbf{J}^\top(\mathbf{x}^{[k]}) \mathbf{r}(\mathbf{x}^{[k]}),$$

where $\lambda = 1/\alpha$.

Note that $\lambda \mathbf{I} + \mathbf{J}^\top \mathbf{J}$ is guaranteed to be full rank and well conditioned for large λ .

Standard practice:

- ▶ For the first iteration make λ large (e.g., $\approx 10^4$)
- ▶ If squared error decreases, decrease λ for next iteration (e.g., by half).
- ▶ If squared error increases, increase λ for next iteration (e.g., by 2x).

Weighted Nonlinear Least Squares

If $W = W^T > 0$ is a weighting matrix, then

$$\min_{x \in \mathbb{R}^n} \frac{1}{2} \mathbf{r}^T(x) W \mathbf{r}(x).$$

results in

$$(\text{GD}) \quad x^{[k+1]} = x^{[k]} - \lambda^{-1} \mathbf{J}^T W \mathbf{r}|_{x^{[k]}}$$

$$(\text{GN}) \quad x^{[k+1]} = x^{[k]} - \left(\mathbf{J}^T W \mathbf{J} \right)^{-1} \mathbf{J}^T W \mathbf{r}|_{x^{[k]}}$$

$$(\text{LM}) \quad x^{[k+1]} = x^{[k]} - \left(\lambda I + \mathbf{J}^T W \mathbf{J} \right)^{-1} \mathbf{J}^T W \mathbf{r}|_{x^{[k]}}.$$