### ECEn 671: Mathematics of Signals and Systems

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### Section 1

**Linear Operators** 

## **Linear Operators**

Recall from Chapter 3 the definition of a Linear operator:

#### Definition

Let  $\mathbb X$  and  $\mathbb Y$  be vector spaces, then  $\mathcal A:\mathbb X\to\mathbb Y$  is a linear operator if

$$\mathcal{A}[\alpha_1 x_1 + \alpha_2 x_2] = \alpha_1 \mathcal{A}[x_1] + \alpha_2 \mathcal{A}[x_2]$$

 $\forall x_1, x_2 \in \mathbb{X} \text{ and } \forall \alpha_1, \alpha_2 \in \mathbb{F}$ 

See chapter 2 notes (slides 79-83) for examples of linear operators.



## Norm of a Linear Operator

An important concept is the <u>norm</u> of an operator. There are several ways to define norms for operators. The most important is the "induced" or "subordinate" norm.

### Definition

Let  $\mathcal{A}: \mathbb{X} \to \mathbb{Y}$  then

$$\|\mathcal{A}\| = \sup_{x \neq 0} \frac{\|\mathcal{A}[x]\|_{\mathbb{Y}}}{\|x\|_{\mathbb{X}}}$$
$$= \sup_{\|x\|_{\mathbb{X}} = 1} \|\mathcal{A}[x]\|_{\mathbb{Y}}$$

Different norms on  $\mathcal A$  are defined by taking different norms in  $\mathbb X$  and  $\mathbb Y$ .

## Norm of a Linear Operator, Examples

### Example

Let  $\mathcal{A}:L_2 o L_2$  then

$$\begin{split} \|\mathcal{A}\|_{2} &= \sup_{x \neq 0} \frac{\|\mathcal{A}[x]\|_{L_{2}}}{\|x\|_{L_{2}}} \\ &= \sup_{\|x\|_{L_{2}} = 1} \|\mathcal{A}[x]\|_{L_{2}} \end{split}$$

### Example

Let  $\mathcal{A}: L_{\infty} \to L_{\infty}$  then

$$\begin{split} \|\mathcal{A}\|_{\infty} &= \sup_{\mathbf{x} \neq \mathbf{0}} \frac{\|\mathcal{A}[\mathbf{x}]\|_{L_{\infty}}}{\|\mathbf{x}\|_{L_{\infty}}} \\ &= \sup_{\|\mathbf{x}\|_{L_{\infty}} = 1} \|\mathcal{A}[\mathbf{x}]\|_{L_{\infty}} \end{split}$$

## Norm of a Linear Operator, Examples

### Example

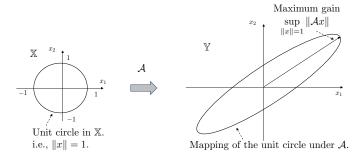
Let  $\mathcal{A}: \mathcal{L}_{p} 
ightarrow \mathcal{L}_{p}$  then

$$\|A\|_{p} = \sup_{x \neq 0} \frac{\|A[x]\|_{L_{p}}}{\|x\|_{L_{p}}}$$
$$= \sup_{\|x\|_{L_{p}}} \|A[x]\|_{L_{p}}$$

Why is it called the induced or subordinate norm? The norm on the operator is induced by the vector norm.

# Norm of a Linear Operator, Geometric Interpretation

$$||A|| = \sup_{||x||=1} ||Ax||$$



## Norm of a Linear Operator, System Interpretation

Given a linear system

$$u(t)$$
  $H(s)$   $y(t)$ 

The norm of the system H(s) is the maximum gain of the system.

### Norm of BIBO System

Let  $\mathcal{A}: L_{\infty} \to L_{\infty}$  be an LTI system that is BIBO stable with impulse response h(t), then

$$y(t) = \int_0^t h(t - \tau)u(\tau)d\tau$$
  
 $\stackrel{\triangle}{=} \mathcal{A}[u]$ 

Find  $\|A\|_{\infty}$ .

## Norm of BIBO System, cont

#### Lemma

$$\|\mathcal{A}\|_{\infty} = \|h\|_{L_1[0,\infty]}$$

$$\stackrel{\triangle}{=} \int_0^{\infty} |h(t)| dt$$

### Proof.

We need to prove two things

1. 
$$\|\mathcal{A}\|_{\infty} \leq \int_{0}^{\infty} |h(t)| dt$$

$$2. \int_0^\infty |h(t)| dt \le ||\mathcal{A}||_\infty$$





# Norm of BIBO System, Proof

#### Proof of 1.

$$\begin{split} \sup_{\|x\|_{\infty}=1} \|\mathcal{A}[u]\|_{\infty} &= \sup_{\|u\|_{\infty}=1} \left\| \int_{0}^{t} h(t-\tau)u(\tau)d\tau \right\|_{\infty} \\ &= \sup_{\|u\|_{\infty}=1} \left[ \sup_{t>0} \left| \int_{0}^{t} h(t-\tau)u(\tau)d\tau \right| \right] \\ &\leq \sup_{\|u\|_{\infty}=1} \left[ \sup_{t>0} \int_{0}^{t} |h(t-\tau)u(\tau)|d\tau \right] \\ &\leq \sup_{\|u\|_{\infty}=1} \left[ \|u\|_{\infty} \sup_{t>0} \int_{0}^{t} |h(t-\tau)|d\tau \right] \\ &\leq \int_{0}^{\infty} |h(\tau)|d\tau = \|h\|_{L_{1}[0,\infty]} \end{split}$$

# Norm of BIBO System, Proof

### Proof of 2.

Let 
$$\hat{u}_t(\tau) = \begin{cases} 1 & \text{if } h(t-\tau) \geq 0 \\ -1 & \text{otherwise} \end{cases}$$
.

Note that  $\|\hat{u}_t\|_{\infty}=1 \ \forall t>0$ , we have that

$$\int_0^t h(t- au)\hat{u}_t( au)d au = \int_0^t |h(t- au)|\,d au.$$

Therefore for this particular choice of  $\hat{u}_t$  we have that

$$\sup_{t>0} \left[ \int_0^t |h(t-\tau)| \, d\tau \right] = \left\| A \hat{u}_{\infty} \right\|_{\infty} = \int_0^\infty |h(\tau)| \, d\tau.$$

By definition of sup

$$\int_0^\infty |h(\tau)| d\tau = \|A\hat{u}_\infty\|_\infty \le \sup_{\|u\|=1} \|Au\|_\infty.$$

# Operator Norm: Proof Technique

The proof technique shown here is the general approach to show that the norm of an operator is some value.

Suppose that you would like to prove that

$$\|\mathcal{A}\| = M$$
.

You need to show two things

- 1.  $\|A\| \leq M$
- 2.  $M \le ||A||$ .

## Operator Norm: Proof Technique

To show (1) use triangle and other inequalities to show that

$$\|Ax\| \leq M \|x\|$$

which implies that

$$\sup_{\|x\|=1} \|\mathcal{A}x\| \leq \sup_{\|x\|=1} M \|x\| = M$$

To show (2), construct a specific  $\hat{x}$  such that

$$\|\hat{x}\| = 1$$
 and  $\|\mathcal{A}\hat{x}\| = M$ .

This implies that

$$M \leq \sup_{\|x\|=1} \|\mathcal{A}x\| = \|\mathcal{A}\|.$$



#### Lemma

For any induced operator norm,

$$\|\mathcal{A}x\| \leq \|\mathcal{A}\| \|x\|.$$

Proof.

$$\|\mathcal{A}\| = \sup_{x \neq 0} \frac{\|\mathcal{A}x\|}{\|x\|}.$$

Therefore for any  $x \neq 0$  we must have that

$$\|A\| \ge \frac{\|Ax\|}{\|x\|}$$
  
$$\Rightarrow \|Ax\| \le \|A\| \|x\|.$$



#### Lemma

All induced operator norms satisfy the "submultiplicative property," i.e.,

$$\|\mathcal{A}\mathcal{B}\| \le \|\mathcal{A}\| \|\mathcal{B}\|$$

Proof.

$$\begin{split} \|\mathcal{A}\mathcal{B}\| &= \sup_{\|x\|=1} \|\mathcal{A}\mathcal{B}x\| \\ &\leq \sup_{\|x\|=1} \|\mathcal{A}\| \|\mathcal{B}x\| \\ &\leq \sup_{\|x\|=1} \|\mathcal{A}\| \|\mathcal{B}\| \|x\| \\ &= \|\mathcal{A}\| \|\mathcal{B}\| \end{split}$$



#### Definition

An operator  $\mathcal{A}: \mathbb{X} \to \mathbb{Y}$  is bounded if  $\|\mathcal{A}\| < \infty$ 

#### **Definition**

The following three statements are equivalent

- 1.  $\mathcal{A}: \mathbb{X} \to \mathbb{Y}$  is continuous
- 2.  $x_n \to x^* \Rightarrow \mathcal{A}[x_n] \to \mathcal{A}[x^*]$  for all convergent sequences in  $\mathbb X$
- 3.  $\forall \epsilon > 0$ ,  $\exists \delta > 0$  such that

$$||x - y|| \le \delta \quad \Rightarrow \quad ||A[x] - A[y]|| < \epsilon \quad \forall x, y \in X$$

### Theorem (Moon Theorem 4.1)

A linear operator is bounded iff it is continuous.

### Proof.

(⇒) Suppose  $\|A\| = M < \infty$ , let  $\{x_n\}$  be any convergent sequence with limit  $x^* \in \mathbb{X}$ , then

$$\|Ax_{n} - Ax^{*}\| = \|A(x_{n} - x^{*})\| \le \|A\| \|x_{n} - x^{*}\|$$
$$= M \|x_{n} - x^{*}\| \to 0 \Rightarrow \|Ax_{n} - Ax^{*}\| \to 0.$$

Therefore A is continuous.

### Proof, cont

( $\Leftarrow$ ) Assume  $\mathcal A$  is continuous and let  $\epsilon=1$  and y=0 then  $\exists \delta$  such that  $\|x\| \leq \delta \Rightarrow \|\mathcal Ax\| < 1$ 

Now let  $0 \neq x \in \mathbb{X}$  be arbitrary, then

$$\left\| \frac{\delta x}{\|x\|} \right\| = \frac{\delta}{\|x\|} \|x\| = \delta \le \delta$$

implies that

$$\left\| \mathcal{A}\left(\frac{\delta x}{\|x\|}\right) \right\| = \frac{\delta}{\|x\|} \left\| \mathcal{A}x \right\| < 1$$

which implies that

$$\|\mathcal{A}x\| \le \frac{1}{\delta} \|x\|$$

Therefore A is bounded.



### Theorem (Moon Theorem 4.2)

Let  $\mathcal{A}: \mathbb{X} \to \mathbb{Y}$  be a linear operator. If  $\mathbb{X}$  is a finite dimensional Hilbert space, then  $\mathcal{A}$  is bounded.

### Proof.

Let  $\dim(\mathbb{X}) = n$  and let  $\{p_1, \dots p_n\}$  be an orthonormal basis for  $\mathbb{X}$ , then

$$x = \sum_{k=1}^{n} \langle x, p_k \rangle p_k$$

### Proof, cont.

Define  $D = \max\{\|\mathcal{A}p_1\|, \|\mathcal{A}p_2\|, \dots, \|\mathcal{A}p_n\|\}$  then

$$\|\mathcal{A}x\| = \left\| \mathcal{A} \left( \sum_{k=1}^{n} \langle x, p_{k} \rangle p_{k} \right) \right\|$$

$$\leq \sum_{k=1}^{n} |\langle x, p_{k} \rangle| \|\mathcal{A}p_{k}\|$$

$$\leq D \sum_{k=1}^{n} |\langle x, p_{k} \rangle|$$

$$\leq D \sum_{k=1}^{n} \|x\| \|p_{k}\| \qquad (Caucy - Schwartz)$$

$$= Dn \|x\|$$

Therefore A is bounded.