

Retrace(λ)

Temporal Credit Assignment in Off-Policy Reinforcement Learning

Matteo Papini 28th November 2017 Before we start...

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Syllabus

- Introduction
- 2 Eligibility Traces
- 3 Off-policy Credit Assignment
- 4 Retrace(λ)
- 5 Experiments

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Reinforcement Learning

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Value Function

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Policy Iteration

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Temporal Difference Learning

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Value Function update at time t:

$$Q(s_t, a_t) \leftarrow Q(s_t, a_t) + \alpha \left[G_t - Q(s_t, a_t) \right]$$
$$\Delta Q(s_t, a_t) = \alpha \left[G_t - Q(s_t, a_t) \right]$$

Forward view: look one step forward to compute the target

$$G_t = r_{t+1} + \gamma \mathop{E}_{a \sim \pi} \left[Q(s_{t+1}, a) \right]$$

Backward view: wait one step to update $Q(s_t, a_t)$

$$\Delta Q(s_{t-1}, a_{t-1}) = \alpha \left[r_t + \gamma \mathop{E}_{a \sim \pi} \left[Q(s_t, a) \right] - Q(s_{t-1}, a_{t-1}) \right]$$

Temporal Credit Assignment Problem

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Look far (n steps) in the future:

$$G_t^{(n)} \doteq r_{t+1} + \gamma r_{t+2} + \dots + \gamma^{n-1} r_{t+n} + \gamma^n \mathop{E}_{a \sim \pi} [Q(s_{t+n}, a)]$$
$$= \sum_{k=1}^n \gamma^{k-1} r_{t+k} + \gamma^n \mathop{E}_{a \sim \pi} [Q(s_{t+n}, a)]$$

- lacksquare $G_t^{(1)}$ is a TD target
- lacksquare $G_t^{(T-t)}$ is a Monte Carlo target

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$$G_t^{\lambda} \doteq (1 - \lambda) \sum_{n=1}^{\infty} \lambda^{n-1} G_t^{(n)}$$

- $\lambda = 0$ gives $G_t^{(1)}$, the TD target
- $\lambda = 1$ gives $G_t^{(T-t)}$, the Monte Carlo target

$$G_t^{\lambda} \doteq (1 - \lambda) \sum_{n=1}^{T} \lambda^{n-1} G_t^{(n)}$$

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Backward View

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Video here

$$e(s, a) \leftarrow \gamma \lambda e(s, a) + \mathbb{1}\{s = s_t, a = a_t\}$$

$$\Delta Q(s, a) = \alpha e(s, a) (G_t^{(1)} - Q(s, a))$$

$$e \leftarrow \gamma \lambda e + \mathbb{1}_t$$
$$\Delta Q = \alpha e \delta_t$$

$$e \leftarrow (1 - \mathbb{1}_t)\gamma\lambda e + \mathbb{1}_t$$
$$\Delta Q = \alpha e \delta_t$$

Dutch Traces 17

$$e \leftarrow (1 - \frac{\alpha}{\alpha} \mathbb{1}_t) \gamma \lambda e + \mathbb{1}_t$$
$$\Delta Q = \alpha e \delta_t$$

General Traces

Update at time t:

$$\Delta Q = \alpha e_t \delta_t$$

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General Traces

Update at time t:

$$\Delta Q = \alpha \gamma^t \left(\prod_{s=1}^t c_s \right) \delta_t$$

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- Lorem ipsum dolor sit amet, consectetur adipiscing elit.
- Nulla id ex ornare, gravida nisi in, ornare risus.
 - 1. Aenean eu posuere purus.
 - 2. Etiam maximus convallis libero, ac venenatis nunc sagittis nec.
- Suspendisse orci ex, pharetra vitae aliquam ac, rutrum in dui.

Title B2

Theorem (Th. Name)

This is a theorem

- Property 1;
- Property 2.

Proof.

$$a + b = c \tag{1}$$

$$a = c - b \tag{2}$$

$$answer = 42 \tag{3}$$

Proof

Another proof style.

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Another proof style.



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Second column.

Third column.

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First column.

Second column.

Third column.

Appears with third column

First column.

Second column.

Third column.

Appears with third column

Image:



- Iorem
- 2 Ipsus
 - sub1
 - 2 sub3
 - 1 sub4
 - 2 sub5

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