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Stochastic Variance-Reduced Policy Gradient

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Stochastic **V**ariance-**R**educed (**P**olicy) **G**radient

■ **SVRG** for Reinforcement Learning

- Motivation
- Challenges

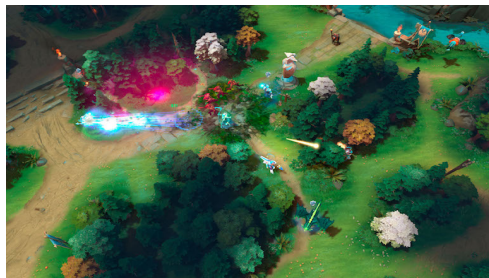
■ **SVRPG**

- Convergence Properties
- Heuristics
- Experiments

An effective **Reinforcement Learning (RL)** solution to **continuous** control problems:



Robotics (Heess et al., 2017)



Video games (OpenAI, 2018)

Mostly based on **Stochastic Gradient Ascent** (Robbins and Monro, 1951)

Plot: visualizing rates of convergence

Can we do something better?

A solution from **finite-sum optimization**:

$$\underbrace{\nabla J(\boldsymbol{\theta})}_{\text{SVRG estimator}} = \underbrace{\nabla J(\tilde{\boldsymbol{\theta}})}_{\text{FG in snapshot parameter}} + \underbrace{\nabla J(\boldsymbol{\theta})|_{\tau_i}}_{\text{SG in current parameter}} - \underbrace{\nabla J(\tilde{\boldsymbol{\theta}})|_{\tau_i}}_{\text{Correction term}}$$

- Unbiased
- Linear convergence
- More data-efficient than FG
- Easily applicable to **Supervised Learning (SL)**

Not trivial! There are three **challenges**:

- 1 **Non-concavity** of $J(\theta)$ (Allen-Zhu and Hazan, 2016; Reddi et al., 2016)
- 2 **Infinite dataset**: we would need *infinite samples* to compute FG (Harikandeh et al., 2015; Bietti and Mairal, 2017)
- 3 **Non-stationarity**: $\tau \sim p_{\theta}$ (new!)

RL so far: *policy evaluation* (Du et al., 2017) and *off-policy control* (Xu et al., 2017)

Our work: **on-policy control**

$$\underbrace{\nabla J(\boldsymbol{\theta})}_{\text{SVRPG estimator}} = \underbrace{\hat{\nabla}_N J(\tilde{\boldsymbol{\theta}})}_{\substack{\text{Large } N \\ \text{to approximate FG}}} + \underbrace{\hat{\nabla}_B J(\boldsymbol{\theta})}_{B \ll N} - \underbrace{\omega(\boldsymbol{\theta}, \tilde{\boldsymbol{\theta}}) \hat{\nabla}_B J(\tilde{\boldsymbol{\theta}})}_{\substack{\text{Importance weighting} \\ \text{for non-stationarity}}}$$

- Unbiased
- More data-efficient than FG

Convergence to **local** optimum:

$$\mathbb{E} \left[\|\nabla J(\boldsymbol{\theta})\|^2 \right] \leq \frac{J(\boldsymbol{\theta}^*) - J(\boldsymbol{\theta}_0)}{\psi T} + \underbrace{\frac{\zeta}{N}}_{\text{Infinite dataset}} + \underbrace{\frac{\xi}{B}}_{\text{Nonstationarity}}$$

■ Linear convergence + error

Meta-parameter selection

- Adaptive step size: two ADAM annealing schedules α_{FG} , α_{SG}
- Adaptive epoch size: take new snapshot when the effective step size becomes too small

$$\frac{\alpha_{SG}}{B} < \frac{\alpha_{FG}}{N} \implies \text{snapshot}$$

Thank you for your attention

Link/QR

Poster info

Contact information

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