# RateOfClimb.m user guide

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#### 1 Introduction

#### Rate of climb

The rate of climb is calculated as:

$$P_{avai} - (P_{request})_{FF} = T_{TPP} \cdot V_r sin\gamma_r = T_{TPP} \cdot V_c \qquad (1.1)$$

Where TPP is for tip path plane and FF is for forward flight.

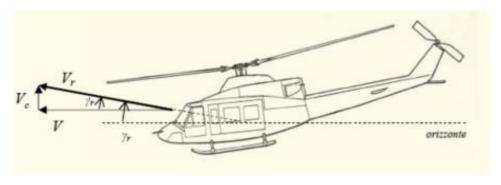


Figura 1.1: Triangle of speeds of a generic helicopter [1].

### 2 Inputs and outputs

#### 2.1 Inputs

The function has the following inputs:

helicopter weigth  $(W_{t0})$ , Total Required Power (Ptot\_req), Available Power (Pavai), Asymptotic Current Speed  $(V_{inf})$ .

#### 2.2 Outputs

The function has the following outputs:

Rate Of Climb (RC), Fastest Climb Speed (Vy), Maximum Rate Of Climb (RC\_rapid), Steepest Climb Speed (Vx), Angle of Maximum Rate Of Climb (gamma\_ripid).

### **3** Function description

This function calculates:

- rate of climb;
- the fastest climb speed (Vy), at which we have the maximum rate of climb (RC\_rapid);
- the steepest climb (Vx), at which we have the maximum climbing angle (gamma\_ripid)

at different altitudes and weights.

```
function [RC,...
          Vy, RC_rapid,...
          Vx, gamma ripid] = RateOfClimb(Wto, Ptot req, Pavai, Vinf)
    RC = (Pavai - Ptot req)./Wto; % (Pavai-Ptot req) is Power in excess
    for i=1:length(RC)
        if RC(i)<0
            RC(i) = 0;
                        % If RC<0 we don't have the Required Power to climb
        end
    end
    for i=1:length(Vinf)
       if (RC(i) == max(RC))
           Vy = Vinf(i); % Vy is the fastest climb speed,
% at which we have the maximum rate of climb
           RC rapid = RC(i);
       end
       if (RC(i)/Vinf(i) == max(RC./Vinf))
           Vx = Vinf(i);
                                       % Vx is the steepest climb, at which
                                        %we have the maximum climbing angle
           RC ripid = RC(i);
           gamma_ripid = asin(RC_ripid/Vx)*180/pi;
       end
    end
end
```

#### 4 Test Case

A test case was performed.

```
mu viscoso = mu0*(Temp/T0)^1.5*(T0+110)/(Temp+110); % Sutherlan's law
                                         % tail rotor
  % 2) main rotor
             = 4;
                                          N rc
             = 8.18;
                                                  = 1.7;
                                          R rc
                                                                   % [m]
    R rp
             = pi*R_rp^2;
                                                  = pi*R rc^2; % [m^2]
    A rp
                                         A rc
             = 0.53;
    С
                                         c rc
                                                  = 0.2;
                                                                    % [m]
    sigma_rp = 0.082;
                                          \overline{\text{sigma}} rc = 0.188;
    Vtip = 220.98;
                                          Vtip rc = 208.79;
    Omega_rp = Vtip/R_rp;
                                          Omega_rc = Vtip_rc/R_rc;
            = Omega_rp/(2*pi);
                                                  = Omega_rc/(2*pi);
                                         n_rc
                                            % [m]
                            br = 10.73;
    theta1 rp = -18;
                                           thetal rc = -17;
          = 10;
= linspace(0.05,R_rp,Num); r_rc = linspace(0.05,R_rc,Num);
    Nıım
    r rp
    r adim rp = r rp/R rp;
                                           r adim rc = r rc./R rc;
  Cd rc=0.01;
  Cd rp=0.01;
 k = 1.15;
num = 120;
Vinf = linspace(0,120,num);
P aus = 25000; % [W]
P ausil = P aus*ones(1,length(Vinf));
\overline{\text{eta}} rc = \overline{1.03};
%available power
v h = linspace(0, 1800, length(Vinf));
[~, ~, ~, rho_sl] = atmosisa(0);
for j = 1:length(v_h)
  [a,b,c,density] = atmosisa(v h(j));
 v_Pavailable(j) = Pd_sl*density/rho_sl;
end
figure
plot(v_h,v_Pavailable, 'k');
xlabel('h [m]'); ylabel('P a v a i [W]'); title('Avaiable Power at different h');
grid on;
v \text{ WTO} = [0.75*\text{Wto}, 0.90*\text{Wto}, \text{Wto}];
h = [0, 1000, 1800];
v input=[R rp,A rp,sigma rp, Omega rp, Cd rp,...
       R_rc, A_rc, sigma_rc, Omega_rc, Cd_rc,...
         br, k, P_aus, eta_rc, Pd_sl];
for i = 1:length(h)
for j = 1:length(v WTO)
    [Pind_B, Pparas_rp,Pfus,Ptot_rp,...
Pind_rc, Pparassita_rc, Ptot_rc,Ptot_request(j,:),Pdisp,...
     V NE, V BE, V BR] = PowerInForwardFlight main tail rotor(h(i), Vinf,
v WTO(j), v input);
    Pavaiable(j,:) = Pdisp*ones(1,length(Vinf));
    plot(Vinf,Pind_B,'k-.',Vinf,Pparas_rp,'k--',Vinf,Pfus,'k:',Vinf,Ptot_rp,'k-
', Vinf, Pavaiable (j,:), '.-k');
   hold on;
```

```
xlabel('V \propto [m/s]'); ylabel('P [W]'); title('Required Power of the main rotor in
 forward flight!);
                 subtitle(['altitude h = ',num2str(h(i)), 'm']);
                legend('P i n d','P p a r','P f u s o l a g e','P t o t','P a v a i');
                grid on
                figure
                plot(Vinf, Pparassita rc, 'k-.', Vinf, Pind rc, 'k--', Vinf, Ptot rc, 'k-');
                title('Powers of the tail rotor'); xlabel('V ~ [m/s]'); ylabel('P [W]');
                subtitle(['altitude h = ',num2str(h(i)), 'm']);
                legend('P p a r', 'P i n d', 'P t o t');
                    grid on;
                    figure
                    plot(Vinf, Ptot rp, 'k-.', Vinf, Ptot rc, 'k--
 ', Vinf, P_ausil, 'k:', Vinf, Ptot_request(j,:), 'k-', Vinf, Pavaiable(j,:), '.-k');
                    xlabel('V \propto [m/s]'); ylabel('P [W]'); title('Total Required Power in forward Power in forward Power II); ylabel('P [W]'); title('Total Required Power II); ylabel('P [W]'); ylabel('P [W]'); title('Total Required Power II); ylabel('P [W]'); ylabel('P [
flight');
                    subtitle(['altitude h = ',num2str(h(i)), 'm']);
                    legend('P_m_a_i_n _r_o_t_o_r.','P_t_a_i_l
rotor','Paux','Ptot','Pavai');
                     grid on
                end
    end
            figure
                plot(Vinf,Ptot_request(j,:),'.-k');
                xlabel('V \infty [m/s]'); ylabel('P [W]');
                subtitle(['altitude h = ', num2str(h(i)), 'm']);
                hold on;
                plot(Vinf, Pavaiable(j,:),'k');
                assey = linspace(0,Ptot request(end),num);
                plot(V NE*ones(1, num), assey, 'k-.');
                plot(V BE*ones(1, num), assey, 'k--');
                plot(V_BR*ones(1,num),assey,'k');
                legend('P_t_o_t', 'P_a_v_a_i', 'V_N_E', 'V_B_E', 'V_B_R');
    % Total required power in forward flight at different WTO
                figure
                        plot(Vinf, Ptot request(1,:), 'k-',...
                       Vinf, Ptot_request(2,:), 'k--',...
Vinf, Ptot_request(3,:), 'k-.',...
Vinf, Pavaiable(j,:) , '.-k');
                title('Total required power in forward flight at different W T O')
                subtitle(['altitude h = ',num2str(h(i)), 'm']);
                xlabel('V_{\infty} [m/s]'); ylabel('P [W]');
                legend('7\overline{5}% WTO',...
                                               '90% WTO',...
                                                 'WTO',...
                                                   'Pavailable');
                grid on;
% Rate of climb, fastest climb speed and maximum climbing angle at different WTO
% and different altitude.
[RC(1,:), Vy(i,1), RC \ rapid(i,1), Vx(i,1), gamma \ ripid(i,1)] = RateOfClimb( v WTO(j), gamma ripid(i,1)) = RateOfClimb(i,1)) = RateOfClimb(i,1) = 
Ptot request(1,:), Pavaiable(1,:), Vinf);
                [RC(2,:), Vy(i,2), RC \ rapid(i,2), Vx(i,2), gamma \ ripid(i,2)] = RateOfClimb( v WTO(j), rapid(i,2), Vx(i,2), rapid(i,2), r
Ptot request(2,:),Pavaiable(1,:),Vinf);
```

```
[RC(3,:),Vy(i,3),RC \ rapid(i,3),Vx(i,3),gamma \ ripid(i,3)] = RateOfClimb( v WTO(j),
Ptot request(3,:),Pavaiable(1,:),Vinf);
       figure
    plot(Vinf, RC(1,:), 'k-',...
          Vinf, RC(2,:), 'k--',...
Vinf, RC(3,:), 'k--');
    title('Rate of climb RC at different W_T_O')
    subtitle(['altitude h = ', num2str(h(i)), 'm']);
    xlabel('V_{\infty} [m/s]'); ylabel('RC [m/s]');
    legend(['75% Wto'],...
            ['90% Wto'],...
            ['Wto']);
    grid on;
end
 % table in excel with the value of RC at different weight and altitude
    Testi = {'h = 0m', 'h = 1000m''m', 'h = 1800m'};
    Tabella = table(Vy(1,:)', Vy(2,:)', Vy(3,:)', 'VariableNames', Testi);
    writetable(Tabella,'Vinf - Salita Rapida.xlsx');
    Testi = {'h = 0m','h = 1000m''m','h = 1800m'};
    Tabella = table(RC_rapid(1,:)',RC_rapid(2,:)',RC_rapid(3,:)', 'VariableNames',Testi);
    writetable (Tabella, 'RC - Salita Ripida.xlsx');
    Testi = {'h = 0m', 'h = 1000m''m', 'h = 1800m'};
    Tabella = table(Vx(1,:)', Vx(2,:)', Vx(3,:)', 'VariableNames', Testi); writetable(Tabella,'Vinf - Salita Ripida.xlsx');
```

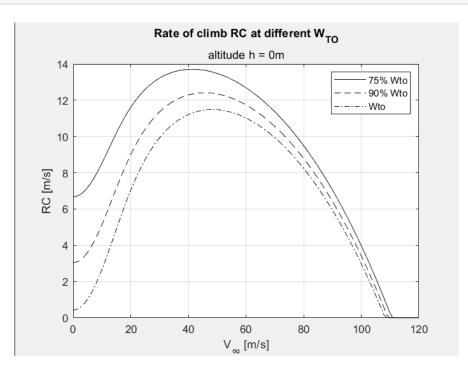


Figura 1.2: Rate of climb at different weights at Sea Level for the helicopter Sykorsky UH-60A.

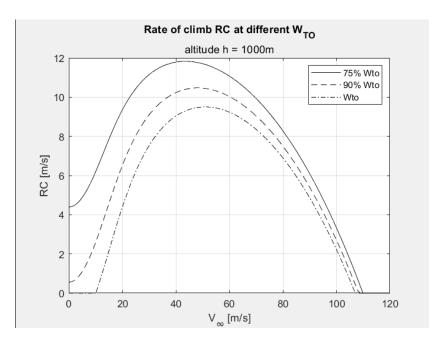


Figura 1.3: Rate of climb at different weights at 1000m for the helicopter Sykorsky UH-60A.

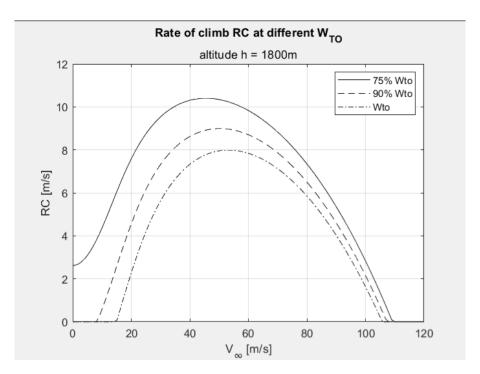


Figura 1.4: Rate of climb at different weights at 1800m for the helicopter Sykorsky UH-60A.

h = 0m	h = 1000m'm	h = 1800m
13,708277	11,8272705	10,4009325
12,4103886	10,4697231	8,99230462
11,4867618	9,50240863	7,98867904

**Figura 1.5:** Table in excel with the value of RC at different weights (75% Wto, 90% Wto, Wto) and altitudes (SL, 1000m, 1800m) for the helicopter Sykorsky UH-60A.

It can be observed that the rate of climb decreases with increasing altitude and weight; in fact, at fixed weight and with increasing altitude there is a reduction in available power, while at fixed altitude there is an increase in required power with weight. In both cases the difference at first member of (1.1) decreases and consequently there is a reduction in the rate of climb.

# 5 Bibliography

[1] aa 2022-2023 Didattica integrativa AAR Federico II Di Giorgio.pdf