DOCUMENTATION OF AXIAL_DESCENT_ASCENT_OPERATING_ CURVES_ROTOR FUNCTION

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Chapter 1

Documentation

1.1 Algorithm Introduction

The function plots $w(V_{\infty})$ and $P(V_{\infty})$ curves according to rotor's simply impulsive theory.

To achieve this objective in the first step we defined the following vectors:

- ALTITUDE
- ASCENT VELOCITY
- DESCENT VELOCITY

Density is then calculated from the altitude vector with the MATLAB function atmosisa.

After calculated the density, the axial hovering induction is obtained from the following relation derived by rotor's simply impulsive theory:

$$w_h = \sqrt{\frac{Mg}{2\rho(h)\pi r^2}} \tag{1.1}$$

From this value, we calculated the non-dimensional variables:

•
$$\widetilde{V} = \frac{V_{\infty}}{w_h}$$

•
$$\widetilde{w}_{ascent} = -\frac{\widetilde{V}}{2} + \sqrt{\frac{\widetilde{V}^2}{4} + 1}$$

•
$$\widetilde{w}_{descent} = -\frac{\widetilde{V}}{2} + \sqrt{\frac{\widetilde{V}^2}{4} - 1}$$

•
$$\widetilde{P}_{ascent} = \widetilde{V} + \widetilde{w}_{ascent}$$

•
$$\widetilde{P}_{descent} = \widetilde{V} + \widetilde{w}_{descent}$$

Then, we used some cycles to obtain the matrices including the values of induction and power that are two variables functions.

Subsequently these functions are plotted. In the code the user has also the possibility to insert the interest altitude.

1.2 Algorithm Description

The code begins at line 40 with the function call, where are defined the inputs as well as described in section 1.3.

Dimensional variables, as the altitude and the velocity, are defined in the lines [41-43].

The density as a function of altitude is calculated in line 45 through the MAT-LAB function *atmosisa*. In line 46 this variable is interpolated in a function handle to obtain a numerical law to use whit any altitude that the user choice in lines 149 and 214.

From the line 50 to line 54 the code calculates the non-dimensional variables as mentioned in section 1.1.

At line 56 if the user has insert only 2 variables the code calculated the power and the induction distributions. Indeed At lines [62-63] the matrices which will contain the numerical value of induction as a function of velocity and altitude are initialized. Subsequently (lines [67-82]) those matrices are filled with *for loops* as show below, where you can see that is respected the limit of simply impulsive rotor theory:

Subsequently (lines [85-105]) the same thing is done for the non-dimensional power

The first type of outputs are the 3D plots of the induction and power as a function of altitude and velocity, which are in line [108-141]. After that, in lines [148-152] the user has the possibility to choose the altitude of interest to obtain the 2d plots of induction and power as function of only velocity at the entered altitude. In the following lines [154-185] the matrices containg the numerical value of induction and power are initialized and till as function of velocity at the entered altitude as show below:

```
prompt = {'Insert interest altitude in metres [min=0,Max=6000]: '};
dlgtitle = 'Altitude';
dims = [1 \ 35];
answer = inputdlg(prompt,dlgtitle,dims);
hnew = str2double(answer{1});
WTSnew = zeros(1,length(VVs));
WTDnew = zeros(1,length(VVd));
% Matrices fill
for j = 1 : length(VVs)
    WTSnew(1,j) = w_tilde_salita(VVs(j),hnew);
for j = 1 : length(VVd)
    if V_tilde(VVd(j),hh(i)) < -2</pre>
        WTDnew(1,j) = w_tilde_discesa(VVd(j),hnew);
        aanew = j;
        break
    end
end
PTSnew = zeros(1,length(VVs));
PTDnew = zeros(1,length(VVd));
for j = 1 : length(VVs)
    PTSnew(1,j) = P_tilde_salita(VVs(j),hnew);
for j = 1 : length(VVd)
    if V_tilde(VVd(j),hh(i)) < -2</pre>
        PTDnew(1,j) = P_tilde_discesa(VVd(j),hnew);
        bbnew = j;
    else
        break
    end
```

The values of induction and power as function of velocity at the entered altitude are plotted through the command in line[188-207].

While, in lines [208-234], if the user insert three inputs (rotorcraft's mass, rotor's radius and ascent or descent velocity) the code calculated and shows only the power and the induction at the interest altitude at the velocity inserted as third input.

1.3 Input and Output

The function takes in input:

- ROTORCRAFT'S MASS
- Rotor's radius
- ASCENT OR DESCENT VELOCITY

If the inputs values are two (Rotorcraft's mass and Rotor's radius) the outputs are the plots of induction and power and these are reported in section *Test Case*. If the inputs values are all three the outputs are only the value of power and induction at the interest altitude.

1.4 Error Indicators

The plots in axial discent operating condition have been obtained within the validity limits of simple impulsive rotor theory, that's until when $V_{\infty} < -2w$. Indeed for these values in inputs:

- $V_{\infty} = -10[m/s]$
- h = 1000[m]

the code shows this error message:

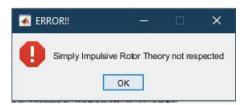


Figure 1.1: Error Message

1.5 Test Case

The numerical values in input for those plots are:

- Rotorcraft's mass = 5000 kg
- Rotor's radius = 7m

The outputs of the test case are the following plots:

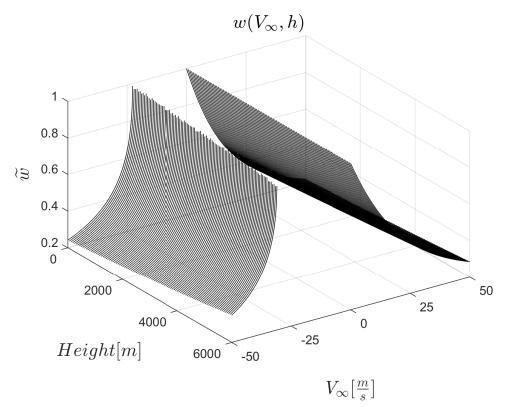


Figure 1.2: Induction

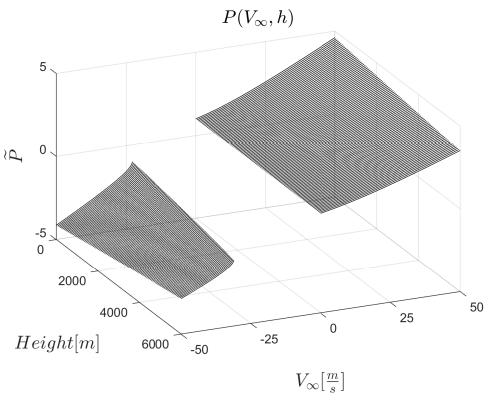


Figure 1.3: Power

In the code the user has also the possibility to insert the interest altitude: for example, at sea level we are obtained the following curves. In order to prove the validity of the code the curves were compared with some examples reported in [1] as follow.

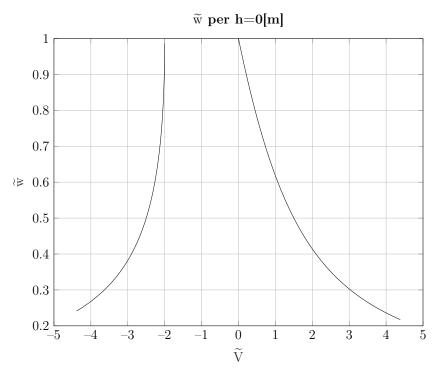
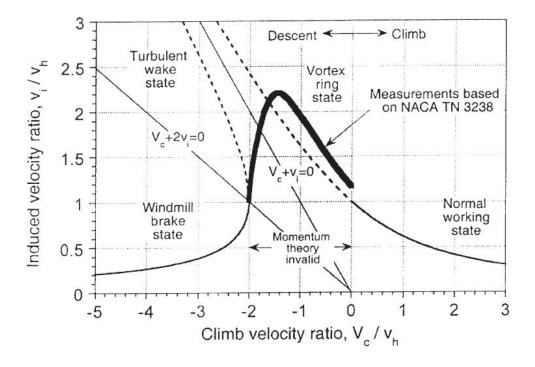


Figure 1.4: Induction



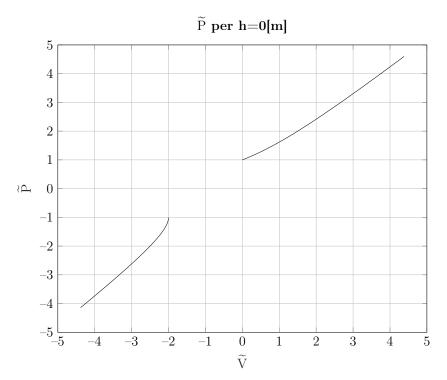
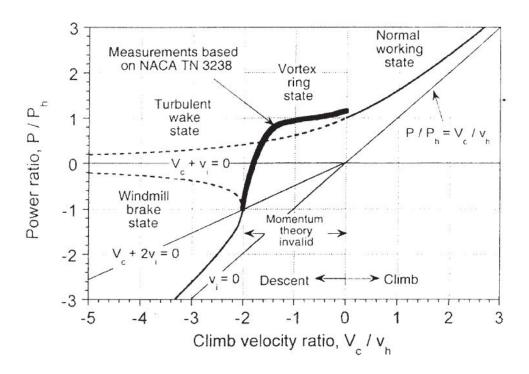


Figure 1.5: Power



Appendices

Appendix A

Function's code

```
\%\% \Axial_Descent_Ascent_Operating_Curves_Rotor.m \% \brief: the function plots w(V_infty) and P(V_infty) curves according to \% Impulsive theory. \% aerodynamic model
          \% \author: Colledà Moreno, Veneruso Salvatore \% \version: 1.00
          % Eli-TAARG is free software; you can redistribute it and/or % modify it under the terms of the GNU General Public % License as published by the Free Software Foundation; either % version 3 of the License, or (at your option) any later version.
          % Eli-TAARG is developed by the TAARG Educational organization for % educational purposes only. % Theoretical and Applied Aerodynamic Research Group - University of Naples Federico II. %
           % Eli-TAARG GitHub link: <https://github.com/TAARG-Education/Eli-TAARG>
          % Eli-TAARG is distributed in the hope that it will be useful, % but WITHOUT ANY WARRANTY; without even the implied warranty of % MERCHANTABILITY or FITNESS FOR A PARTICULAR PURPOSE. See the GNU % General Public License for more details. % <a href="http://www.gnu.org/licenses/">http://www.gnu.org/licenses/</a>. %
         25
30
        %
% Input
% Output
% Note
35
          function [Power,Induction] =Axial_Descent_Ascent_Operating_Curves_Rotor(M,R,V_inf)
g = 9.81;
%Altitude Range
hh = linspace(0,6000,100);
%Axial Induction
[~, ~, rho1] = atmosisa(hh);
rho = 0(h) interpi(hh,rhoi,h, 'pchip');
wh = 0(h) sqrt((M*g)/(2*rho(h)*pi*R^2));
           % Non-Dimensional Variables Definition
          % Non-Dimensional variables Definition V_{\rm tilde} = \Phi(V,h) \ V/wh(h); W_{\rm tilde} = \Phi(V,h) \ V/wh(h); W_{\rm tilde} = \Phi(V,h) \ (-V_{\rm tilde}(V,h)/2) + {\rm sqrt}((V_{\rm tilde}(V,h)/2)^2+1); W_{\rm tilde} = \Phi(V,h) \ (-V_{\rm tilde}(V,h)/2) - {\rm sqrt}((V_{\rm tilde}(V,h)/2)^2-1); P_{\rm tilde} = {\rm salita} = \Phi(V,h) \ V_{\rm tilde}(V,h) + W_{\rm tilde} = {\rm salita} (V,h); P_{\rm tilde} = {\rm discess} = \Phi(V,h) \ V_{\rm tilde}(V,h) + W_{\rm tilde} = {\rm discess}(V,h);
53
54
55
          if nargin==2
    VVs = linspace(0, 50, 100);
    VVd = linspace(-50, 0, 7000);
58
59
61
                   62
                   for i = 1 : length(hh)
    for j = 1 : length(VVd)
```

```
75
76
77
78
79
                                                                                       %Validity limit of simply impulsive theory;
                         else
WTD(i,j) = 0;
                  end
end
 80
 81
82
83
84
             %Non-Dimensional Power
             PTS = zeros(length(hh),length(VVs)); %Ascent Power
PTD = zeros(length(hh),length(VVd)); %Descent Power
bb = zeros(1,length(hh)); %Control Paramenter
 85
86
 88
 89
90
91
             % Matrices fill
for i = 1 : length(hh)
    for j = 1 : length(VVs)
        PTS(i,j) = P_tilde_salita(VVs(j),hh(i));
                   end
              end
 94
 95
96
97
             98
99
100
                                                                                        %Validity limit of simply impulsive theory;
                         else
break
101
102
                         end
103
             end
end
104
105
             %% 3D Plots of Induction [output]
figure(1)
plot3(hh(1)*ones(1,length(WTS(1,:))),VVs,WTS(1,:),'k')
hold on
for i = 2 : length(hh)
    plot3(hh(i)*ones(1,length(WTS(i,:))),VVs,WTS(i,:),'k')
end
107
108
110
111
113
              end
for i = 1 : length(hh)
    plot3(hh(i)*ones(1,length(WTD(i,1:aa(i)))),VVd(1,1:aa(i)),WTD(i,1:aa(i)),'k')
114
115
116
             end
yticks([-50 -25 0 25 50])
xlabel('$Height[m]$','Interpreter','latex', 'FontSize',15)
ylabel('$V_{\infty}[\frac{m}{s}]$','Interpreter','latex', 'FontSize',15)
zlabel('$\widetilde{w}$','Interpreter','latex', 'FontSize',15)
117
118
120
              grid on title('$w (V_{\infty}, h)$','Interpreter','latex', 'FontSize', 15) view(71,32)
121
123
124
\frac{124}{125}
\frac{126}{126}
              % 3D Plots of Power [output]
             rigure(2)
plot3(hh(1)*ones(1,length(PTS(1,:))),VVs,PTS(1,:),'k')
hold on
for i = 2 : length(hh)
    plot3(hh(i)*ones(1,length(PTS(i,:))),VVs,PTS(i,:),'k')
end
127
128
130
131
              end
for i = 1 : length(hh)
    plot3(hh(i)*ones(1,length(PTD(i,1:bb(i)))),VVd(1,1:bb(i)),PTD(i,1:bb(i)),'k')
131 \\ 132 \\ 133
134
             end
yticks([-50 -25 0 25 50])
xlabel('$Height[m]$','Interpreter','latex', 'FontSize',15)
ylabel('$V_{\infty}[\frac{m}{s}]$','Interpreter','latex', 'FontSize',15)
zlabel('$\widetilde{P}$','Interpreter','latex', 'FontSize',15)
135
136
137
138
139
             grid on title('$P (V_{\infty}, h)$','Interpreter','latex', 'FontSize', 15)
140
141
              view(71,32)
142
             %% Insertion of Interes Altitude;
143
144
\frac{145}{146}
              prompt = {'Insert interest altitude in metres [min=0,Max=6000]: '};
dlgtitle = 'Altitude';
             dims = [1 35];
147
              answer = inputdlg(prompt,dlgtitle,dims);
hnew = str2double(answer{1});
148
150
             151
153
              % Matrices fill
154
155
              for j = 1 : length(VVs)
    WTSnew(1,j) = w_tilde_salita(VVs(j),hnew);
156
             end
157
158
             for j = 1 : length(VVd)
  if V_tilde(VVd(j),hnew) <= -2
     WTDnew(1,j) = w_tilde_discesa(VVd(j),hnew);
     aanew = j;</pre>
                                                                                          %Validity limit of simply impulsive theory;
160
161
163
                    else
break
             end end
164
165
166
167
             PTSnew = zeros(1,length(VVs));
PTDnew = zeros(1,length(VVd));
168
169
170
171
             for j = 1 : length(VVs)
    PTSnew(1,j) = P_tilde_salita(VVs(j),hnew);
\frac{172}{173}
174
175
176
```

```
PTDnew(1,j) = P_tilde_discesa(VVd(j),hnew); bbnew = j;
178
179
180
                        break
181
183
184
                 %% 2D Plots of induction [Output]
figure(3)
plot(V_tilde(VVs,hnew), WTSnew, '-k')
hold on
plot(V_tilde(VVd(1:aanew),hnew), WTDnew(1:aanew), '-k')
185
186
187
188
                 grid on
xlabel('$\widetilde{V}\$','Interpreter','latex','FontSize',15)
ylabel('\widetilde{W}\$','Interpreter','latex','FontSize',15)
title(['\widetilde{W}\$ per h=' num2str(hnew) '[m]'],'Interpreter','latex')
190
191
192
193
194
                 % 2D Plots of power [Output] figure(4)
                 plot(V_tilde(VVs,hnew), PTSnew, '-k')
hold on
plot(V_tilde(VVd(1:aanew),hnew), PTDnew(1:bbnew), '-k')
\frac{197}{198}
                 plot(V_tilde(vva(1:aanew), nnew),
grid on
    xlabel('$\widetilde{V}\$','Interpreter','latex','FontSize',15)
    ylabel('$\widetilde{P}\$','Interpreter','latex','FontSize',15)
    title(['$\widetilde{P}\$' per h=' nun2Str(hnew) '[m]'],'Interpreter','latex')
%% Numerical Output of Power and Induction for the interest altitude;
Power = [PTDnew(1:bbnew), PTSnew];
Induction = [WTDnew(1:aanew), WTSnew];
200
201
202
203
204
205
206
207
          208
210
211
212
213
214
215
216
                 if V_tilde(V_inf,hnew) >= 0
    w = w_tilde_salita(V_inf,hnew)*wh(hnew);
    P = (M*g)*(V_inf + w);
elseif V_tilde(V_inf,hnew) <= -2</pre>
\frac{217}{218}
219
                        w= w_tilde_discesa(V_inf,hnew)*wh(hnew);
P = (M*g)*(V_inf + w);
220
221
222
223
                 else
    errordlg('Simply Impulsive Rotor Theory not respected', 'ERROR!!');
                        Power = [];
Induction = [];
224
\frac{224}{225}
\frac{226}{226}
                  return end
227
                 228
229
230
231
                 Power = P;
Induction = w;
233
          end
234
235
236
          end
237
```

Bibliography

[1] Renato Tognaccini, Appunti Aerodinamica dell'Ala Rotante. Univeristà degli studi di Napoli Federico II, a.a. 2020/2021