

Namespaces

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1. What is the problem?

Name conflicts:

- there is the `std::vector`
- you want to write your own geometry library with a `vector` class
⇒ conflict
- also unintentional conflicts from using multiple libraries

2. Solution: namespaces

A namespace is a 'prefix' for identifiers:

```
std::vector xstd; // standard namespace  
geo::vector xgeo; // my geo namespace  
lib::vector xlib; // from some library.
```

3. Namespaces in action

How do you indicate that something comes from a namespace?

Option: explicitly indicated.

```
#include <vector>
int main() {
    std::vector<stuff> foo;
}
```

Import the whole namespace:

```
#include <vector>
using namespace std;
int main() {
    vector<stuff> foo;
}
```

Good compromise:

```
#include <vector>
using std::vector;
int main() {
    vector<stuff> foo;
}
```

4. Defining a namespace

Introduce new namespace:

```
namespace geometry {  
    // definitions  
    class vector {  
        // stuff  
    };  
}
```

5. Namespace usage

Double-colon notation for namespace and type:

```
geometry::vector myobject();
```

or

```
using geometry::vector;  
vector myobject();
```

or even

```
using namespace geometry;  
vector myobject();
```

6. Why not 'using namespace std'?

Illustrating the dangers of `using namespace std`:

This compiles, but should not:

```
1 // func/swapname.cpp
2 #include <iostream>
3 using namespace std;
4
5 def swop(int i,int j) {};
6
7 int main() {
8     int i=1,j=2;
9     swap(i,j);
10    cout << i << '\n';
11    return 0;
12 }
```

This gives an error:

```
1 // func/swapusing.cpp
2 #include <iostream>
3 using std::cout;
4
5 def swop(int i,int j) {};
6
7 int main() {
8     int i=1,j=2;
9     swap(i,j);
10    cout << i << '\n';
11    return 0;
12 }
```

7. Guideline

- `using namespace` is ok in main program or implementation file
- Never! Ever! in a header file

Example

8. Example of using a namespace

Suppose we have a *geometry* namespace containing a `vector`, in addition to the `vector` in the standard namespace.

```
1 // namespace/geo.cpp
2 #include <vector>
3 #include "geolib.hpp"
4 using namespace geometry;
5 int main() {
6     // std vector of geom segments:
7     std::vector< segment > segments;
8     segments.push_back( segment( point(1,1),point(4,5) ) );
```

What would the implementation of this be?

9. Namespace'd declarations

```
1 // namespace/geolib.hpp
2 namespace geometry {
3     class point {
4     private:
5         double xcoord,ycoord;
6     public:
7         point( double x,double y );
8         double dx(point);
9         double dy(point);
10    };
11    class segment {
12    private:
13        point from,to;
```

10. Namespace'd implementations

```
1 // namespace/geolib.cpp
2 namespace geometry {
3     point::point( double x,double y ) {
4         xcoord = x; ycoord = y; };
5     double point::dx( point other ) {
6         return other.xcoord-xcoord; };
7     /* ... */
8     template< typename T >
9     vector<T>::vector( std::string name,int size )
10         : _name(name),std::vector<T>::vector(size) {};
11 }
```