

# Templating

Victor Eijkhout, Susan Lindsey

Fall 2024

last formatted: November 5, 2024

# 1. What's the problem?

Do you have multiple vector classes?

```
class vector_of_int {  
    public:  
    int size();  
    int at(int i);  
};
```

```
class vector_of_float {  
    public:  
    int size();  
    float at(int i);  
};
```

You have already seen the solution: `vector<int>`

## 2. Templated type name

If you have multiple functions or classes that do 'the same' for multiple types, you want the type name to be a variable, a template parameter. Syntax:

```
template <typename yourtypevariable>
// ... stuff with yourtypevariable ...

// usually:
template <typename T>
```

### 3. Example: function

Definition:

```
1 // template/func.cpp
2 template <typename Real>
3 void sqrt_diff( Real x ) {
4     cout << std::sqrt(x)-1.772 << '\n';
5 };
```

We use this with a templated function:

Code:

```
1 // template/func.cpp
2 sqrt_diff<float>( 3.14f );
3 sqrt_diff<double>( 3.14 );
```

Output:

```
4.48513e-06
4.51467e-06
```

## 4. Type deduction

The compiler can deduce the template:

```
1 // template/func.cpp  
2 sqrt_diff( 3.14f );  
3 sqrt_diff( 3.14 );
```

# Exercise 1

Machine precision, or 'machine epsilon', is sometimes defined as the smallest number  $\epsilon$  so that  $1 + \epsilon > 1$  in computer arithmetic.

Write a templated function *epsilon* so that the following code prints out the values of the machine precision for the `float` and `double` type respectively:

Code:

```
1 // template/eps.cpp
2 float float_eps =
3     epsilon<float>();
4 cout << "Epsilon float: "
5     << setw(10) <<
6     setprecision(4)
7     << float_eps << '\n';
8
9 double double_eps =
10    epsilon<double>();
11    cout << "Epsilon double: "
12    << setw(10) <<
13    setprecision(4)
14    << double_eps << '\n';
```

Output:

```
Epsilon float:
    ↪1.1921e-07
Epsilon double:
    ↪2.2204e-16
```

## 5. Templated point class

Coordinates can be `float` or `double`:

```
1 // geom/pointtemplate.cpp
2 template<typename T>
3 class Point {
4 private:
5     T x,y;
6 public:
7     Point(T ux,T uy) { x = ux; y = uy; };
```

Coordinates can also be other things, but that doesn't always make sense.

## Exercise 2

Take your *Point* class from a previous exercise and templatize the class definition.

Write the *distance* function for the templated class Write a main program that tests this.



## 6. Templated vector

The templated vector class looks roughly like:

```
template<typename T>
class vector {
private:
    T *vectordata; // internal data
public:
    T at(int i) { return vectordata[i] };
    int size() { /* return size of data */ };
    // much more
}
```

## 7. Class that stores one element

Intended behavior:

Code:

```
1 // template/example1.cpp
2 Store<int> i5(5);
3 cout << i5.value() << '\n';
```

Output:

5

## 8. Class definition

Template parameter is used for private data, return type, etc.

```
1 // template/example1.cpp
2 template< typename T >
3 class Store {
4 private:
5     T stored;
6 public:
7     Store(T v) : stored(v) {};
8     T value() { return stored;};
```

## 9. Templated class as return

Given:

```
1 // template/example1.cpp
2 Store<float> f314(3.14);
```

Methods that return a templated object:

Code:

```
1 // template/example1.cpp
2 Store<float> also314 =
    f314.copy();
3 cout << also314.value() << '\n';
4 Store<float> min314 =
    f314.negative();
5 cout << min314.value() << '\n';
```

Output:

```
3.14
-3.14
```

(easier to write with `auto`!)

## 10. Class name injection

Template parameter can often be left out in methods:

```
1 // template/example1.cpp
2 // spell out the template parameter
3 Store<T> copy() const { return Store<T>(stored); };
4 // using CTAD:
5 Store negative() const { return Store(-stored); };
```

‘Class Template Argument Deduction’

## Separate compilation

# 11. Templated class

```
1 // namespace/instantlib.h
2 template< typename T >
3 class instant {
4     public:
5         instant() = default;
6         void out();
7 };
```

## 12. Use

Assume that we know what the template parameter will be:

```
1 // namespace/instant.cpp
2 instant<char> ic;
3 ic.out();
4 instant<int> ii;
5 ii.out();
```



# 13. Instantiation

Lines added to implementation file:

```
1 // namespace/instantlib.cpp
2 template class instant<char>;
3 template class instant<int>;
```

## Intermezzo: complex numbers

## 14. Complex

Code:

```
1 // complex/basic.cpp
2 #include <complex>
3 using std::complex;
4     /* ... */
5     complex<double> d(1.,3.);
6     cout << d << '\n';
7     complex<float> f;
8     f.real(1.); f.imag(2.);
9     cout << f << '\n';
```

Output:

```
(1,3)
(1,2)
```

# 15. Operations and literals

Operations on complex scalars:

Code:

```
1 // complex/basic.cpp
2 using namespace
   std::complex_literals;
3 auto e = d*2.;
4 cout << e << '\n';
5 auto g = e + 2.5i + 3.; // note
   3dot
6 cout << g << '\n';
```

Output:

```
(2,6)
(5,8.5)
```

## 16. Complex functions

Functions on complex numbers:

```
std::complex<T> conj( const std::complex<T>& z );  
std::complex<T> exp( const std::complex<T>& z );
```

Also abs, norm, polar

## Exercise 3

Let  $x = .5 + i$  and compute

$$x + \bar{x} - e^{2\pi i}$$

which should be one. Is it actually one? How close do you get in `float` and `double` complex?

# Templated Newton's method

## Exercise 4

Rewrite your Newton program so that it works for complex numbers. Here is the main; you need to write the functions:

```
1 // newton/newton-complex.cpp
2 complex<double> z{.5,.5};
3 while ( true ) {
4     auto fz = f(z);
5     cout << "f( " << z << " ) = " << fz << '\n';
6     if (std::abs(fz)<1.e-10 ) break;
7     z = z - fz/fprime(z);
8 }
```

You may run into the problem that you can not operate immediately between a complex number and a `float` or `double`. Use `static_cast`;

```
static_cast< complex<double> >(2)
```



## 17. Templatized Newton, first attempt

You can templatize your Newton function and derivative:

```
1 // newton/newton-double.cpp
2 template<typename T>
3 T f(T x) { return x*x - 2; };
4 template<typename T>
5 T fprime(T x) { return 2 * x; };
```

and then write

```
1 // newton/newton-double.cpp
2 double x{1.};
3 while ( true ) {
4     auto fx = f<double>(x);
5     cout << "f( " << x << " ) = " << fx << '\n';
6     if (std::abs(fx)<1.e-10 ) break;
7     x = x - fx/fprime<double>(x);
8 }
```

## 18. Templatized newton root function

The final step is to have a templated Newton function that you can instantiate with any suitable type:

```
auto x_float = newton_root<float>( 2.0f );  
auto x_double = newton_root<double>( 2.0 );  
auto x_complex = newton_root<complex<float>>( 2.0+2.i );
```

## Exercise 5

Update your `newton_root` function with a template parameter. Test it by having a main program that computes some roots in `float`, `double`, and `complex<double>`.

## Exercise 6

Write a Newton method where the objective function is itself a template parameter, not just its arguments and return type. Hint: no changes to the main program are needed.

Then compute  $\sqrt{2}$  as:

```
1 // newton/lambda-complex.cpp
2 cout << "sqrt -2 = " <<
3   newton_root<complex<double>>
4   ( // objective function
5     [] (complex<double> x) -> complex<double> {
6         return x*x + static_cast<complex<double>>(2); },
7     // derivative
8     [] (complex<double> x) -> complex<double> {
9         return x * static_cast<complex<double>>(2); },
10    // initial value
11    complex<double>{.1,.1}
12  )
13    << '\n';
```