view frames Result Recorded at time: 24.888 world Broadcaster: /robot state publisher Broadcaster: /dsr01a0509/robot state publisher Broadcaster: /map broadcaster Average rate: 10000.000 Hz Average rate: 10.189 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (24.888 sec old) Most recent transform: 24.940 (-0.052 sec old) Most recent transform: 0.000 (24.888 sec old) Buffer length: 4.809 sec Buffer length: 0.000 sec Buffer length: 0.000 sec base_link base_0 map Broadcaster: /robot state publisher Broadcaster: /dsr01/world tf Broadcaster: /dsr01a0509/robot state publisher Average rate: 10000.000 Hz Average rate: 20.290 Hz
Most recent transform: 24.981 (-0.093 sec old) Average rate: $45.24\overline{8}$ Hz Most recent transform: 0.000 (24.888 sec old) Most recent transform: 24.873 (0.015 sec old) Buffer length: 0.000 sec Buffer length: 4.830 sec Buffer length: 4.840 sec camera_bottom_screw_frame link1 dsr01/world Broadcaster: /dsr01a0509/robot state publisher Broadcaster: /robot state publisher Broadcaster: /dsr01/robot state publisher Broadcaster: /dsr01a0509 world broadcaster Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: $2\overline{0}.171 \overline{Hz}$ Average rate: $45.24\overline{8}$ Hz Most recent transform: 0.000 (24.888 sec old) Most recent transform: 0.000 (24.888 sec old) \ Most recent transform: 24.940 (-0.052 sec old) \ \ Most recent transform: 24.873 (0.015 sec old) Buffer length: 4.809 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.840 sec dsr01/base 0 dsr01a0509/world link2 camera link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /dsr01/robot state publisher Broadcaster: /dsr01a0509/robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /dsr01a0509 base 0 broadcaster Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: 45.332 Hz Average rate: 10000.000 Hz Average rate: 45.248 Hz Average rate: 10.193 Hz Most recent transform: 24.844 (0.044 sec old) Most recent transform: 24.873 (0.015 sec old) Most recent transform: 0.000 (24.888 sec old) Most recent transform: 0.000 (24.888 sec old) Most recent transform: 0.000 (24.888 sec old) \Most recent transform: 0.000 (24.888 sec old) Most recent transform: 0.000 (24.888 sec old) \Most recent transform: 0.000 (24.888 sec old) \Most recent transform: 24.940 (-0.052 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.709 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 4.831 sec Buffer length: 4.840 sec camera_gyro_frame camera_depth_frame camera_infra2_frame dsr01/link1 dsr01a0509/base 0 link3 camera_accel_frame camera_color_frame camera_infra1_frame Broadcaster: /dsr01/robot state publisher Broadcaster: /robot state publisher Broadcaster: /dsr01a0509/robot state publisher Broadcaster: /dsr01a0509 link1 broadcaster Broadcaster: /robot state publisher Average rate: 10000.000 Hz Average rate: 10.200 Hz Average rate: 45.332 Hz Average rate: 45.248 Hz Most recent transform: 0.000 (24.888 sec old) Most recent transform: 24.844 (0.044 sec old) Most recent transform: 24.873 (0.015 sec old) Most recent transform: 0.000 (24.888 sec old) ost recent transform: 0.000 (24.888 sec old) \Most recent transform: 24.939 (-0.051 sec old) Buffer length: 0.000 sec Buffer length: 4.831 sec Buffer length: 4.706 sec Buffer length: 4.840 sec camera_depth_optical_frame camera_infra1_optical_frame dsr01/link2 dsr01a0509/link1 link4 camera_accel_optical_frame camera_color_optical_frame camera_gyro_optical_frame camera_infra2_optical_frame Broadcaster: /dsr01/robot state publisher Broadcaster: /dsr01a0509/robot state publisher Broadcaster: /dsr01a0509 link2 broadcaster Average rate: 45.332 Hz Average rate: $1\overline{0}.206 \,\overline{\text{Hz}}$ Average rate: 45.248 Hz Buffer length: 4.831 sec Buffer length: 4.703 sec Buffer length: 4.840 sec dsr01/link3 link5 dsr01a0509/link2 Broadcaster: /dsr01/robot state publisher Broadcaster: /dsr01a0509 link3 broadcaster Broadcaster: /dsr01a0509/robot state publisher Average rate: $1\overline{0}.202 \; \overline{Hz}$ Average rate: 45.332 Hz Average rate: $45.24\overline{8}$ Hz Most recent transform: 24.844 (0.044 sec old) Most recent transform: 24.936 (-0.048 sec old) Most recent transform: 24.873 (0.015 sec old) Buffer length: 4.831 sec Buffer length: 4.705 sec Buffer length: 4.840 sec dsr01/link4 link6 dsr01a0509/link3 Broadcaster: /dsr01/robot state publisher Broadcaster: /dsr01a0509 link4 broadcaster Broadcaster: /dsr01a0509/robot state publisher Average rate: $10000.\overline{000}$ Hz Average rate: $1\overline{0}.157 \,\overline{\text{Hz}}$ Average rate: 45.332 Hz Most recent transform: 24.844 (0.044 sec old) \Most recent transform: 24.975 (-0.087 sec old) Most recent transform: 0.000 (24.888 sec old) Buffer length: 4.831 sec Buffer length: 4.726 sec Buffer length: 0.000 sec dsr01/link5 dsr01a0509/link4 tool Broadcaster: /dsr01/robot state publisher Broadcaster: /dsr01a0509/robot state publisher Broadcaster: /dsr01a0509 link5 broadcaster Average rate: 45.332 Hz Average rate: 10000.000 Hz Average rate: $1\overline{0}.191 \,\overline{\text{Hz}}$ Most recent transform: 24.844 (0.044 sec old) \Most recent transform: 24.937 (-0.049 sec old) Most recent transform: 0.000 (24.888 sec old) Buffer length: 4.831 sec Buffer length: 4.710 sec Buffer length: 0.000 sec dsr01/link6 dsr01a0509/link5 (tcp) Broadcaster: /dsr01/robot state publisher Broadcaster: /dsr01a0509 link6 broadcaster Average rate: $1000\overline{0}.000\overline{\text{Hz}}$ Average rate: 10.198 Hz Most recent transform: 0.000 (24.888 sec old) \Most recent transform: 24.938 (-0.050 sec old) Buffer length: 0.000 sec Buffer length: 4.707 sec dsr01/tool dsr01a0509/link6 Broadcaster: /dsr01/robot state publisher Broadcaster: /dsr01a0509 tool broadcaster Average rate: 10000.000 Hz Average rate: 10.198 Hz Most recent transform: 0.000 (24.888 sec old) \Most recent transform: 24.935 (-0.047 sec old) Buffer length: 0.000 sec Buffer length: 4.707 sec dsr01/tcp dsr01a0509/tool Broadcaster: /dsr01a0509 tcp broadcaster Average rate: 10.152 Hz Most recent transform: 24.976 (-0.088 sec old) Buffer length: 4.728 sec dsr01a0509/tcp