# FEM 3D

#### October 18, 2023

```
[]: # Restart the kernel
import os
    current_dir ='../../'
    os.chdir(current_dir)

[]: from src.codes.basic import *
    from src.codes.utils import *
    from src.codes.base_classes import Base_class_fem_heat_conduction
    from src.codes.reductor.rom_class import FEM_solver_rom_ecsw
    from src.codes.algorithms.ecsw import ecsw_red
```

#### 0.0.1 class for data (geometry, material property, mesh)

```
[]: nref= [3,3,3]
L = [10.,12.,14.]

mat_layout = np.zeros((4,4,4),dtype=int)
src_layout = np.zeros((4,4,4),dtype=int)

# src_layout[0,0,0] = 1
# src_layout[1,1,1] = 1
# src_layout[2,2,2] = 1
# src_layout[3,3,3] = 1
```

```
[]: fdict = {}

cond_list = []
cond_list.append( lambda T,mu: mu*T + 100. + 0.*T )
fdict["cond"] = cond_list

dcond_list = []
dcond_list.append( lambda T,mu: mu + 0. + 0.*T )
fdict["dcond"] = dcond_list

qext_list = []
qext_list.append( lambda T,mu: 0.0+100.0 + 0.*T )
fdict["qext"] = qext_list
```

```
# gext_list = []
     # gext list.append(lambda T,mu: mu + 0.*T)
     # qext_list.append(lambda T,mu: 2.0*mu + 0.*T)
     # fdict["qext"] = qext_list
[]: bc = {}
     bc['x_min']={'type':'dirichlet','value':0.}
     bc['x_max']={'type':'dirichlet','value':0.}
     bc['y_min']={'type':'dirichlet','value':0.}
     bc['y_max']={'type':'dirichlet','value':0.}
     bc['z min']={'type':'dirichlet','value':0.}
     bc['z_max']={'type':'dirichlet','value':0.}
[]: class probdata:
         def __init__(self, bc, cond_layout, qext_layout, fdict, nref, L, mu,__
      →pb_dim=3):
             self.dim_ = pb_dim
             # refine the mesh and update material and source layouts
             repeats = np.asarray(nref, dtype=int)
             self.cell2mat_layout = self.repeat_array(mat_layout,repeats)
             self.cell2src_layout = self.repeat_array(src_layout,repeats)
             ## change this mapping if needed.
             self.fdict = fdict
             # mesh data
             # cells
             self.ncells = [None] * pb_dim
             self.npts = [None] * pb_dim
             self.deltas = [None] * pb_dim
             self.xi=[]
             for i in range(pb dim):
                 self.ncells[i] = self.cell2mat_layout.shape[i]
                 self.npts[i] = self.ncells[i]+1
                 self.xi.append(np.linspace(0,L[i],self.npts[i]))
                 self.deltas[i] = L[i]/self.ncells[i]
             self.n_verts = np.prod(np.array(self.npts))
             # Create nodal connectivity for the continuous Finite Element Method_{\sqcup}
      \hookrightarrow (cFEM)
             self.connectivity()
             # Store parameter value
```

```
self.mu = mu
       # Store the dirichlet nodes if any
      handle_boundary_conditions(self, bc)
       \# Determining the global equation numbers based on dirichlet nodes and \sqcup
⇔storing in class
      get_glob_node_equation_id(self, self.dir_nodes)
       # Get global node numbers and equation IDs for the current element
      self.glob_node_eqnId = []
      self.glob_node_nonzero_eqnId = []
      self.local_node_nonzero_eqnId = []
      self.Le = []
      self.global_indices = []
      self.local_indices = []
      for i in range(self.n_cells):
           get_element_global_nodes_and_nonzero_eqnId(self, i, self.node_eqnId)
  def repeat_array(self, arr,repeats):
      for dim,n in enumerate(repeats):
           arr = np.repeat(arr,n,axis=dim)
      return arr
  def connectivity(self):
      Define nodal connectivity for each cell in the mesh.
       11 11 11
       # Initialize the connectivity array
      self.n_cells = np.prod(np.array(self.ncells))
      self.gn = np.zeros((self.n_cells,2**self.dim_),dtype=int)
       # # compute node ID from (i,j) cell identifiers
       # def node(*args):
            index = 0
       #
       #
             multiplier = 1
       #
            for i, n in enumerate(args):
                index += n * multiplier
       #
       #
                if i < len(self.npts) - 1:
                     multiplier *= self.npts[i]
       #
           return index
```

```
node = lambda i,j,k: i+j*self.npts[0]+k*self.npts[0]*self.npts[1]
# Loop over all cells to define their nodal connectivity
iel = 0
for k in range(self.ncells[2]):
    for j in range(self.ncells[1]):
        for i in range(self.ncells[0]):
            # counter-clockwise
            self.gn[iel,0] = node(i ,j ,k )
            self.gn[iel,1] = node(i+1,j,k)
            self.gn[iel,2] = node(i+1,j+1,k)
            self.gn[iel,3] = node(i ,j+1,k)
            self.gn[iel,4] = node(i ,j ,k+1)
            self.gn[iel,5] = node(i+1,j,k+1)
            self.gn[iel,6] = node(i+1,j+1,k+1)
            self.gn[iel,7] = node(i,j+1,k+1)
            iel += 1
```

#### 0.0.2 Simulate FOS

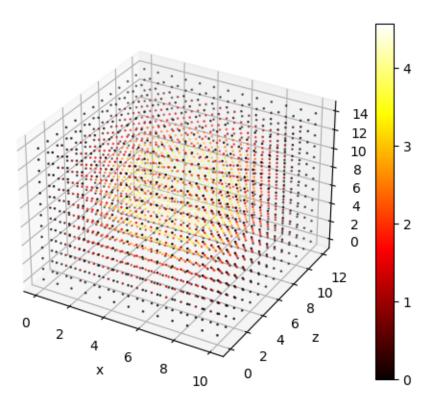
```
[]: random.seed(25)
    params = np.r_[1.:4.0:0.01]
    quad_deg = 3
    N_snap = 15 # Training Snapshots
    NL_solutions = []
    param_list = []
    K_mus = []
    q_mus = []
```

```
[]: for i in range(N_snap):
         print(f"\n\n Snap {i} \n\n")
         param = random.choice(params) # Choose from parameter list
         param_list.append(param)
         if i==0:
             d = probdata(bc, mat_layout, src_layout, fdict, nref, L, param, __
      →pb dim=3)
            FOS = Base_class_fem_heat_conduction(d,quad_deg)
         else:
            FOS.mu = param
         T_init = np.zeros(d.n_verts) + 4.0
         NL_solution_p, Ke, rhs_e, mask = solve_fos(FOS, T_init)
         NL_solutions.append(NL_solution_p.flatten())
         K_mus.append(Ke)
         q_mus.append(rhs_e)
         plot3D(d.xi[0], d.xi[1], d.xi[2], NL_solution_p, hmap=True)
```

# Snap 0

initial residual = 18117.552677045067

iter 0, NL residual=533.9782187764824, delta=0.5697469128754653
iter 1, NL residual=0.4834584379398597, delta=0.0016675880758734644
iter 2, NL residual=3.7614567642077317e-07, delta=1.3735956903112144e-06
Convergence !!!

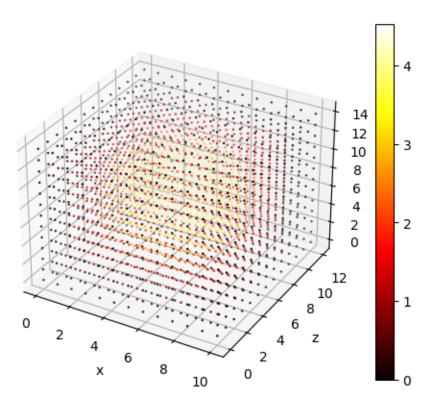


Snap 1

initial residual = 18288.267332881194

iter 0, NL residual=645.9681917378493, delta=0.5258757410483998

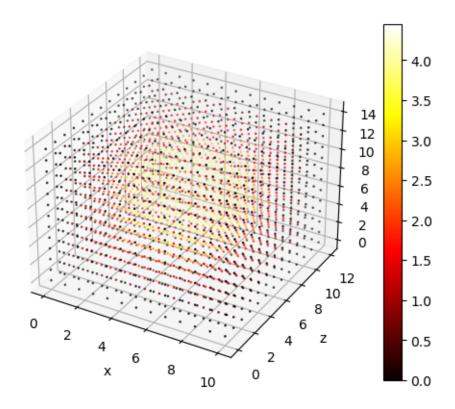
iter 1, NL residual=0.8607385206306576, delta=0.001998499189011799
iter 2, NL residual=1.4522230751466062e-06, delta=2.4066851166497225e-06
Convergence !!!



Snap 2

initial residual = 18600.766504046573

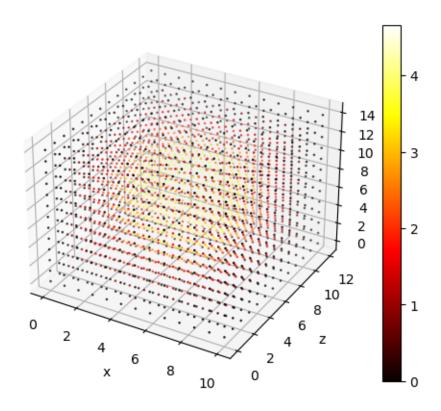
iter 0, NL residual=844.2156209013255, delta=0.4493618841156839
iter 1, NL residual=1.9384070759347636, delta=0.0025318222252974257
iter 2, NL residual=9.73960266898583e-06, delta=5.2544066205114045e-06
Convergence !!!



Snap 3

initial residual = 17798.055313415505

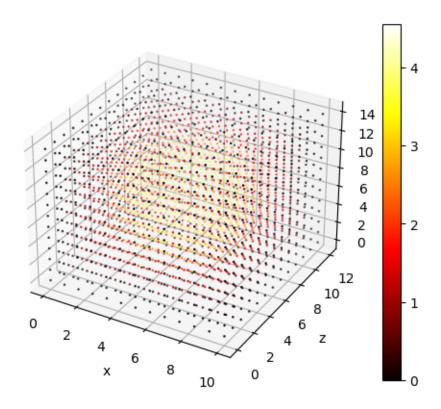
iter 0, NL residual=316.71583003352015, delta=0.6561249039239331
iter 1, NL residual=0.09965461030146461, delta=0.0010417137341543934
iter 2, NL residual=9.351537500071055e-09, delta=2.9133191695019417e-07
Convergence !!!



Snap 4

initial residual = 18193.823207306414

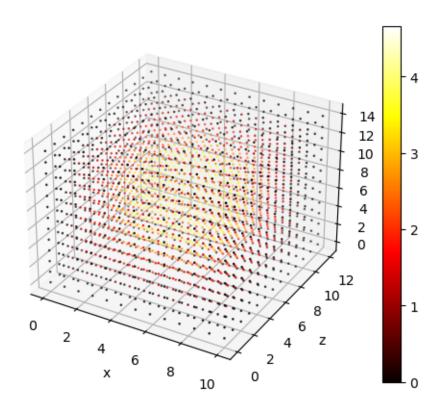
iter 0, NL residual=584.3492061615696, delta=0.5499579885604017
iter 1, NL residual=0.6352311864892305, delta=0.0018203479482646419
iter 2, NL residual=7.128377280614371e-07, delta=1.7920820055787548e-06
Convergence !!!



Snap 5

initial residual = 17783.537120764522

iter 0, NL residual=306.5916195945243, delta=0.6601893786462559
iter 1, NL residual=0.09034512145985259, delta=0.0010120215720621222
iter 2, NL residual=7.435679210499309e-09, delta=2.6444940120450214e-07
Convergence !!!



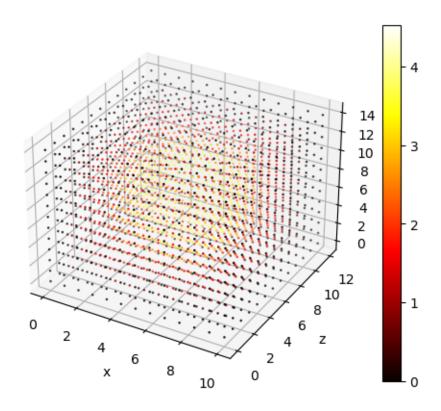
Snap 6

initial residual = 18288.267332881194

iter 0, NL residual=645.9681917378493, delta=0.5258757410483998

iter 1, NL residual=0.8607385206306576, delta=0.001998499189011799

iter 2, NL residual=1.4522230751466062e-06, delta=2.4066851166497225e-06 Convergence  $\verb|!!|$ 



Snap 7

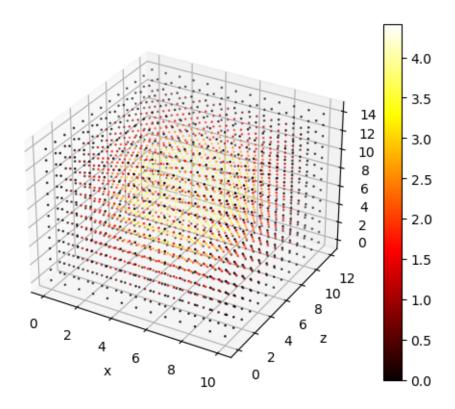
initial residual = 18771.61827851778

iter 0, NL residual=949.1655057206987, delta=0.4094734080267834

iter 1, NL residual=2.7662278113019036, delta=0.0028078426363524907

iter 2, NL residual=2.2436349084964118e-05, delta=7.364409292441698e-06

iter 3, NL residual=1.0199582960630771e-11, delta=1.1915620180343032e-10 Convergence !!!



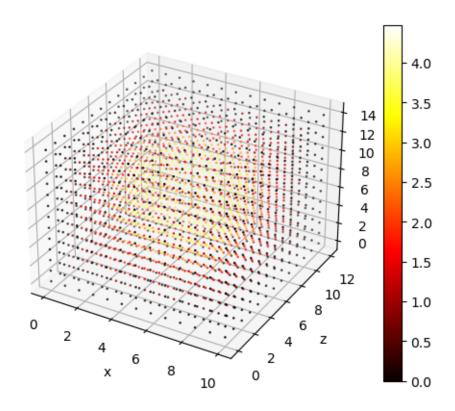
Snap 8

initial residual = 18509.90706023723

iter 0, NL residual=787.4371656493331, delta=0.4711220817290562

iter 1, NL residual=1.5692626021337823, delta=0.0023662950100068465

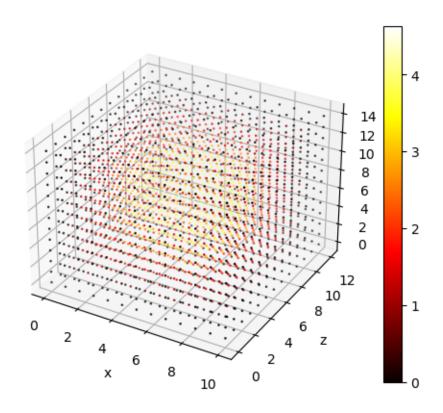
iter 2, NL residual=5.9341315484264025e-06, delta=4.2933712580403645e-06 Convergence !!!



Snap 9

initial residual = 17899.69354182025

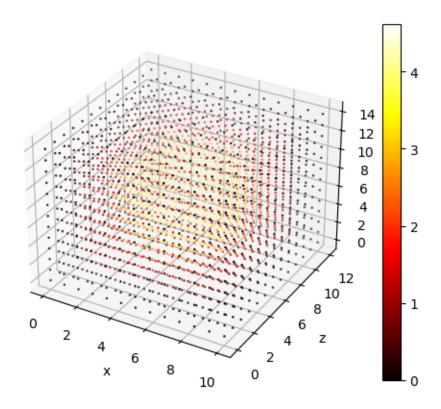
iter 0, NL residual=386.9646732844921, delta=0.6280177055766263
iter 1, NL residual=0.18251291279116122, delta=0.0012379822617973127
iter 2, NL residual=3.849506198021581e-08, delta=5.288330070566306e-07
Convergence !!!



Snap 10

initial residual = 17950.519729505824

iter 0, NL residual=421.6896126462212, delta=0.6141860320188067
iter 1, NL residual=0.2366555721480079, delta=0.0013281191160809378
iter 2, NL residual=7.068332619550028e-08, delta=6.826274871884853e-07
Convergence !!!



Snap 11

initial residual = 18789.79672548325

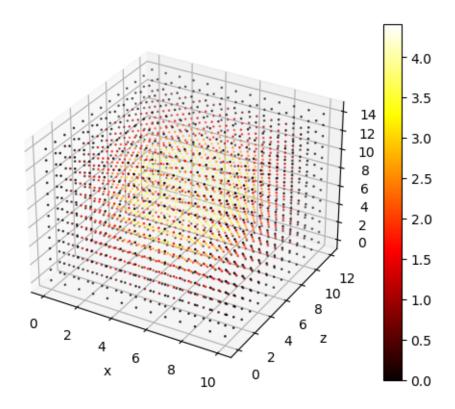
iter 0, NL residual=960.1966340809689, delta=0.4053062862488349

iter 1, NL residual=2.864961836761371, delta=0.002834262767953909

iter 2, NL residual=2.4361625068702574e-05, delta=7.612280562251588e-06

iter 3, NL residual=1.0180507940014421e-11, delta=1.2915752846016243e-10 Convergence !!!

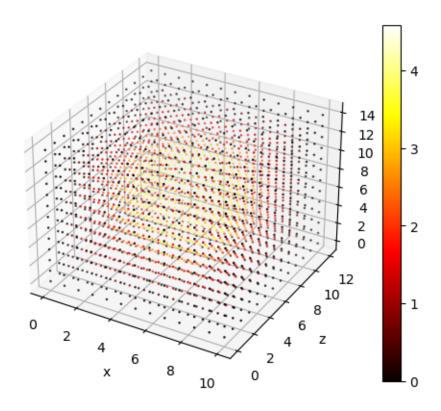
15



Snap 12

initial residual = 18084.868422779025

iter 0, NL residual=512.2222336685539, delta=0.5783222287086509
iter 1, NL residual=0.42625093030648264, delta=0.0015999626190413606
iter 2, NL residual=2.8010512542719486e-07, delta=1.2146951333539937e-06
Convergence !!!



Snap 13

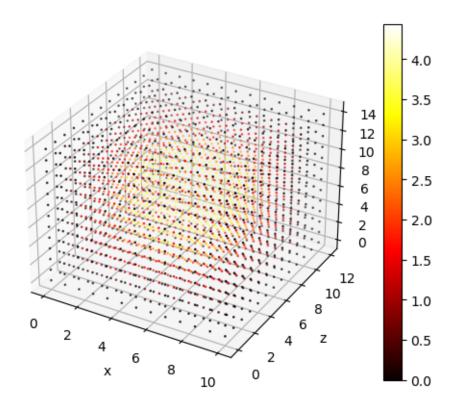
initial residual = 18673.463689258715

iter 0, NL residual=889.1563802268982, delta=0.43222775168387995

iter 1, NL residual=2.268833375265241, delta=0.0026551951918203985

iter 2, NL residual=1.4090182752463841e-05, delta=6.103699092921879e-06

iter 3, NL residual=9.919319105922168e-12, delta=7.553475234051824e-11 Convergence !!!



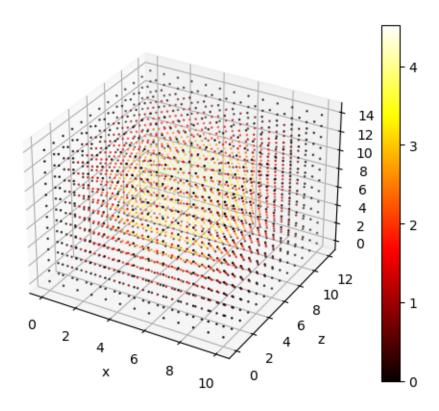
Snap 14

initial residual = 18306.43141530489

iter 0, NL residual=657.7254602079772, delta=0.5212965998998546

iter 1, NL residual=0.9091122594432312, delta=0.002031233365694381

iter 2, NL residual=1.6506987671216231e-06, delta=2.5375237500045293e-06 Convergence !!!



```
[]: NLS = np.asarray(NL_solutions)
np.shape(NLS)
```

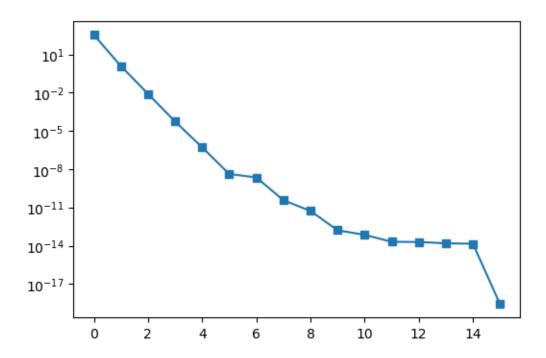
[]: (16, 2197)

# 0.0.3 ECSW Hyper-reduction

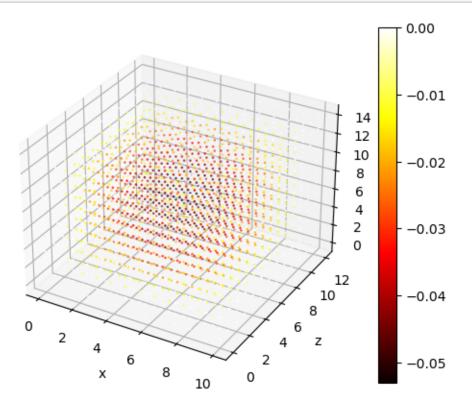
# Step 1: Perform SVD on the snapshots (calculate V(=W)):

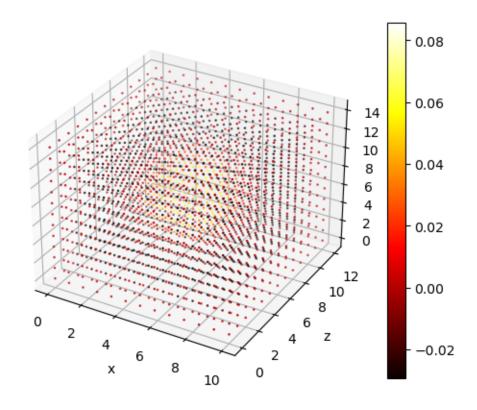
```
[]: n_sel = 4
U, S, Vt = np.linalg.svd(np.transpose(NLS), full_matrices=False)
V_sel = U[:, :n_sel]
P_sel = V_sel[mask,:]@np.transpose(V_sel[mask,:])
```

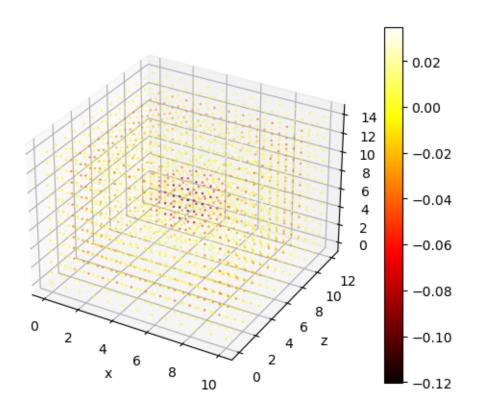
```
[]: plt.figure(figsize = (6,4))
plt.semilogy(S,'s-')
plt.show()
```

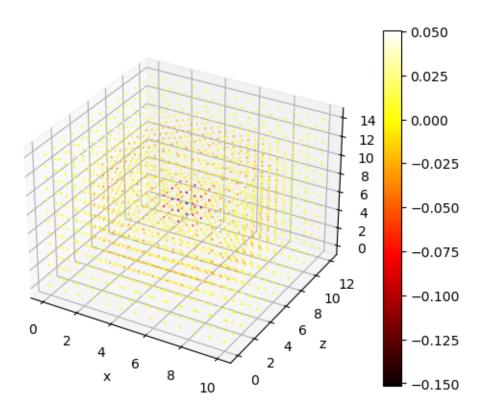


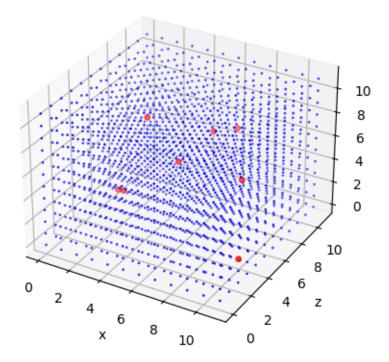
# []: for i in range(n\_sel): plot3D(d.xi[0],d.xi[1],d.xi[2],V\_sel[:,i],hmap=True)











```
[]: print(f"Fraction of total elements active in the ROM: {len(xi[xi>0])*100/

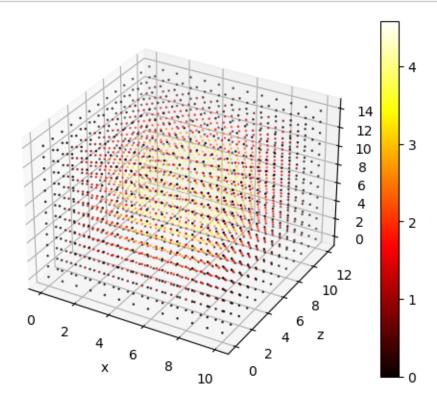
⇔len(xi)}%")
```

Fraction of total elements active in the ROM: 0.46296296296296297%

#### 0.0.4 ROM Simulation

```
⇔quess is contained in the reduced subspace
[]: # Time taken to perform a FO simulation with the current parameter value
     tic_fos = time.time()
     NL_solution_p_fos_test, _, _, = solve_fos(FOS_test,T_init_fos)
    toc_fos = time.time()
    initial residual = 8079.874303895742
    iter 0, NL residual=90.98947141461974, delta=2.641653937311153
    iter 1, NL residual=0.023837146074121008, delta=0.0005654350722311937
    iter 2, NL residual=6.33522211204243e-09, delta=1.543071649831387e-07
    Convergence !!!
[]: # Time taken to simulate a ROM without hyper-reduction
     tic_rom_woh = time.time()
     NL_solution_p_reduced_woh = ROM.solve_rom(T_init_rom,np.ones_like(xi),V_sel)
    toc_rom_woh = time.time()
    initial residual = 7458.240635062873
    c:\Users\supar\anaconda3\lib\site-
    packages\scipy\sparse\linalg\_dsolve\linsolve.py:229: SparseEfficiencyWarning:
    spsolve requires A be CSC or CSR matrix format
      warn('spsolve requires A be CSC or CSR matrix format',
    iter 0, NL residual=73.43842226815724, delta=28.772669226103133
    iter 1, NL residual=0.023211417809151206, delta=0.4308494662851837
    iter 2, NL residual=5.144466299108868e-09, delta=0.00011542492542628045
    Convergence !!!
[]: # Time taken to simulate a ROM *with* hyper-reduction
     tic_rom = time.time()
     NL_solution_p_reduced = ROM.solve_rom(T_init_rom,xi,V_sel)
     toc_rom = time.time()
    initial residual = 0.003165384319024413
    iter 0, NL residual=5.2110750489225636e-05, delta=28.72488533954444
    iter 1, NL residual=9.371194037645073e-09, delta=0.36600691370477545
    Convergence !!!
[]: sol_red = V_sel@NL_solution p_reduced.reshape(-1,1) #+pca.mean .reshape(-1,1)
     plot3D(d_test.xi[0], d_test.xi[1], d_test.xi[2], sol_red,hmap=True)
```

T\_init\_rom = np.transpose(V\_sel)@T\_init\_fos # crucial to ensure the initial\_



RMS\_error is 0.006302997441614514 %

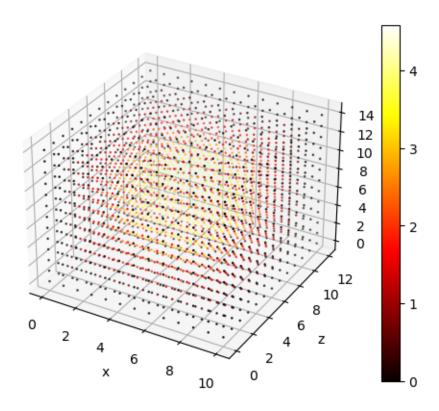
```
[]: plot3D(d_test.xi[0], d_test.xi[1], d_test.xi[2], u

→NL_solution_p_fos_test,hmap=True)

print(f"\n\nROM Error without hyperreduction is {np.linalg.

→norm(V_sel@NL_solution_p_reduced_woh.reshape(-1,1)-NL_solution_p_fos_test.

→reshape(-1,1))*100/np.linalg.norm(NL_solution_p_fos_test.reshape(-1,1))} %")
```



ROM Error without hyperreduction is 4.822551703168323e-08 %

# 0.0.5 Speedups

```
[]: fos_sim_time = toc_fos - tic_fos
    rom_sim_time_woh = toc_rom_woh - tic_rom_woh
    rom_sim_time = toc_rom - tic_rom
[]: print(f"speedup without hyperreduction:{fos_sim_time/rom_sim_time_woh}")
```

```
[]: print(f"speedup without hyperreduction:{fos_sim_time/rom_sim_time_woh}")
print(f"speedup with hyperreduction:{fos_sim_time/(rom_sim_time)}")

# h_total_setup_time = (toc_h_setup_b+toc_h_setup_a) -_

\( \lefta(tic_h_setup_b+tic_h_setup_a) \) #this is one time
```

speedup without hyperreduction:1.0042087314381656 speedup with hyperreduction:187.5209505864067