

Lec 1. Computational Complexity Crash Course

#project-hardness

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Course info

- Course page: <https://github.com/koosaga/project-hardness>
- Hosts: Aeren, ainta, Karuna, koosaga, leejseo, TAMREF
- Book: <https://hardness.mit.edu/>
- Time: Tue 22:00-24:00+ KST

Roadmap of the course

I've managed to guess some main questions of this course.

- How we deduce **NP-hardness** of a problem?
- How hard is **SAT**? what does it imply?
- Among all the NP-hard problems, which are **tractible** with some parameters fixed?
- Which problems are even hard to **approximate**, finding efficient approximation is **NP-hard**?
- Which problems are strongly believed to have **polynomial lower bound**?

Roadmap of the course

There are some **optional** topics in this course.

- **Unique Game Conjecture:** I didn't make enough research for this topic to discuss importance.
- How can we classify the complexities of **Counting Problems**?
- We have too little memory to store all the input, how can we solve the problem by **online** or **streaming** setup?

Roadmap of the course

There are some questions **out of** this course.

- Does a problem have a **polynomial memory** solution?
- Can we adopt a **random algorithm** to find a solution with certain probability?

Content

1. Basic Complexities (P, NP and NP-hardness)
2. Randomized Complexities
3. Higher Complexities

Today is the “Crash course” for complexity theory, to settle basic notions and concepts.

I tried to briefly introduce a variety of topics.

Definition of \mathbb{P}

A *decision problem* is a set membership problem. It can be formulated into “Given a string x , Does it belong to a set A ?”

\mathbb{P} and \mathbb{FP}

- \mathbb{P} is the class of decision problems that can be solved in time bounded by a polynomial p of input size $|x|$.
 - in short, in “polynomial time”.
- \mathbb{FP} is the class of functions that can be computed in polynomial time.

In this sense, we just identify a problem to the underlying set.

Polynomial time, by which machine?

- Standard model of computation theory is the **Turing Machine**, using tape/head/state/action table.
 - We won't define it precisely due to its complexity.
- **Word-RAM** model is somewhat more familiar, consists of a sequence of fixed-size bit/arithmetic operations and random accesses, assumed to run in constant time.
- Or, we can just simply assume any fine Programming Languages as C++, or Python.

Existence of polynomial time algorithm for all models above are in equivalency.

Turing Machine as the standard

- **Church-Turing Thesis** insists that *anything that can be computed at all* is computable in TMs.
- **Extended Church-Turing Thesis** claims that *anything that can be computed in polynomial time* is in \mathbb{P} .
 - Some recent results, such as *Shor's algorithm* are currently inconsistent of the thesis.

Reductions

Reduction is the simplest way to compare the “hardness” of problems.

Reductions

For a decision problem A, B , we say $A \leq_p B$ if there is a function $f \in \mathbb{FP}$ such that $x \in A \iff f(x) \in B$.

■ Aliases: “ A reduces to B ”. or “There’s a reduction from A to B ”.

Indeed, \leq_p is transitive. i.e. $A \leq_p B, B \leq_p C$ leads to $A \leq_p C$.

Types of reduction

- (Polynomial-time) **Karp reduction** from A to B is a type of reduction that we learned above, requiring $f \in \mathbb{FP}$ such that $x \in A \iff f(x) \in B$. Note that $f(x)$ must be in B .
- (Polynomial-time) **Cook reduction** from A to B is a reduction, being a polynomial-time algorithm requiring polynomial B -oracles. It generalizes Karp reduction.

Mostly we deal with only Karp reductions.

NP

To prove the “hardness” of a problem B , we may take an “easier” problem $A \notin \mathbb{P}$ and prove that $A \leq_p B$. And we all know that having a good problem out of \mathbb{P} is hard.

NP

A decision problem A is in \mathbb{NP} , if there is a problem $B \in \mathbb{P}$ such that

$$A = \{x \mid \exists^p y \text{ s.t. } (x, y) \in B\}$$

Here $\exists^p y$ denotes that “there is a polynomial-sized y ”, and $\forall^p y$ is analogously defined.

y is called **witness**. It's hard to find unless $A \in \mathbb{P}$.

List of NP problems

- Indeed $\mathbb{P} \subseteq \mathbb{NP}$, taking $B = A \times \{0\}$.
- 4-colorability of graph is an NP-problem. Given a graph G with n vertices, a 4-coloring of G can be its witness.
 - The coloring requires at most $2n$ bits.
 - Validating a given 4-coloring requires $O(n^2)$ time.
- **SAT** is in NP, indeed.
- **HAM CYCLE** (Hamiltonian Cycle) problem is in NP.
- **FACTORING** is in NP.
 - Given a positive integer N , is there any integer $1 < a < N$ such that N/a is also an integer?

co-NP

Quickly introducing its dual to prevent misconception.

co-NP

A problem A is in co-NP if there is a problem $B \in \mathbb{P}$ such that

$$A = \{x \mid \forall^p y \text{ s.t. } (x, y) \in B\}$$

It seems tricky, but it states the existence of (anti-)witness y , that falsifies $x \in A$.

co-NP problems

- Indeed, $\mathbb{P} \subseteq \text{co-NP}$.
- It is believed that $\text{NP} \neq \text{co-NP}$. In other words, no NP-complete problems are found to be in co-NP. Also, no co-NP-complete problems are verified to be in NP.
- Surprisingly, **FACTORING** is in co-NP, as **PRIMES** is in \mathbb{P} . (AKS primality test)
 - Hence **FACTORING** $\in \text{NP} \cap \text{co-NP}$, implying that we don't know if **FACTORING** is NP-complete.

NP-hard and NP-complete

We omitted the definition of NP-complete.

NP-hard

A problem A is NP-hard if $B \leq_p A$ holds for all $B \in \text{NP}$.
Also, A is NP-complete if $A \in \text{NP} \cap \text{NP-hard}$.

SAT is NP-complete, thus **SAT** $\in \mathbb{P}$ implies that $\mathbb{P} = \text{NP}$. We will make a further research on **SAT** in the following lecture.

Strongly NP-complete problems

The **SUBSET SUM** problem is NP-complete.

SUBSET SUM

- Input: a_1, \dots, a_n, B
 - Input size: $\lg a_1 + \dots + \lg a_n + \lg B$
- Is there any subset $S \subseteq \{1, \dots, n\}$ with size $\leq k$, giving $\sum_{i \in S} a_i = B$?

However, if inputs are given **unary** instead of binary, (i.e. input size is $a_1 + \dots + a_n + B$) **SUBSET SUM** is in \mathbb{P} by dynamic programming.

Strongly NP-complete problems

Strongly NP-complete problems

Given a problem A ,

- A is **(weakly)** NP-complete if it's NP-complete with binary input.
- A is **strongly** NP-complete if it's NP-complete with even unary input.

Indeed, same definition goes for NP-hard problems. The problem **TSP** is strongly NP-complete.

Strong NP-complete problems are studied in Ch. 6 of the book, which is out of our scope.

Intermediate problems

Most common problems are in dichotomy: P or NP -complete. Are there problems in NP but neither in P nor in NP -complete?

NP -intermediate

A is NP -intermediate if $A \in NP \setminus (P \cup NP\text{-complete})$.

And they are very likely to exist.

Theorem. (Ladner 1975)

If $P \neq NP$, there exists an NP -intermediate problem.

Candidates of the intermediate problems

Most of them are currently working as “one-way functions” in cryptography.

- **FACTORING**: no polynomial algorithm for factoring. The best is $2^{\tilde{O}(n^{1/3})}$ for n -digit numbers.
- **DLP**: Given a prime p and generator g and $a \in \mathbb{Z}_p$ and upper bound U , is there an integer $0 \leq x \leq U$ such that $g^x = a$?
 - Both **FACTORING** and **DLP** are in $\text{NP} \cap \text{co-NP}$, thus they are believed to be intermediates.

Candidates of the intermediate problems

Other intriguing examples follow.

- **GRAPH ISOMORPHISM:** Given a pair G, H of graphs, is there an isomorphism $\phi : V(G) \rightarrow V(H)$ such that $uv \in E(G) \iff \phi(u)\phi(v) \in E(H)$?
 - It's solvable in $2^{(\lg n)^{O(1)}}$ time, implying its NP-completeness gives **quasi-polynomial** solution for all NP-complete problems, violating some kinds of **ETH**.
 - If **GRAPH ISOMORPHISM** is NP-complete, $\Sigma_2 = \Pi_2$ follows. We'll define the class below and discuss its aftermath.
- **MINIMUM CIRCUIT PROBLEM:** Given a truth table of boolean function f , is there a circuit with $\leq N$ logic gates?
 - OK...

RP

Class of problems coping with **Randomized Algorithm** is nothing to do with *hardness*, as they don't have complete problems.

Thus we simply introduce them, and estimate their positions in Complexity Hierarchy.

RP

A problem A is in RP if there is a polynomial-time algorithm M mapping the input x into $\{\text{yes}, \text{no}\}$, such that

- $\Pr[M(x) = \text{yes} \mid x \in A] \geq \frac{1}{2}$.
- $\Pr[M(x) = \text{no} \mid x \notin A] = 1$.

Thus, yes of M is absolutely true.

co-RP is analogously defined.

RP-problems

- **PRIMES**(until 2002) were known to be in \mathbb{RP} by Miller-Rabin algorithm (1980).
- **POLYNOMIAL ZERO TESTING**: Given $f \in \mathbb{Z}[x_1, \dots, x_n]$ and a prime p , is f identically zero in \mathbb{Z}_p ?

Note that the constant $1/2$ can be replaced to any $0 < \alpha < 1$, giving a few independent runs of M .

ZPP

ZPP are the class adopting a polynomial-time Las-Vegas algorithm. Equivalently,

ZPP

A problem A is in ZPP if there is a polynomial-time algorithm M mapping the input x into $\{\text{yes}, \text{no}, \text{idk}\}$, such that

- $\Pr[M(x) = \text{idk}] \leq \frac{1}{2}$.
- M is always correct when it outputs yes or no.

It is known that $\text{ZPP} = \text{RP} \cap \text{co-RP}$, being a rare example of precise agreement of some complexity classes.

It is believed that $\text{P} = \text{ZPP} = \text{RP}$.

BPP

BPP relaxes both RP and co-RP by allowing two-sided error.

BPP

A problem A is in BPP if there is a polynomial-time algorithm M mapping the input x into {yes, no}, such that

- $\Pr[M(x) = \text{yes} \mid x \in A] \geq \frac{3}{4}$.
- $\Pr[M(x) = \text{no} \mid x \notin A] \geq \frac{3}{4}$.

We can reach the answer by a majority vote after running M several times.

BPP

BPP relaxes both RP and co-RP by allowing two-sided error.

BPP

A problem A is in BPP if there is a polynomial-time algorithm M mapping the input x into $\{\text{yes}, \text{no}\}$, such that

- $\Pr[M(x) = \text{yes} \mid x \in A] \geq \frac{3}{4}.$
- $\Pr[M(x) = \text{no} \mid x \notin A] \geq \frac{3}{4}.$

There are no known problems in BPP beyond RP (or co-RP), but at least some facts are known.

- $\text{BPP} \subseteq \Sigma_2 \cap \Pi_2 \subseteq \text{EXPTIME}.$ (Sipser-Lautemann theorem)
- $\text{BPP} \subseteq \text{PSPACE} \subseteq \text{EXPTIME}.$

Higher complexities

Higher Complexities

A problem A is in:

- EXPTIME if it can be solved in $2^{n^{O(1)}}$ time.
- PSPACE if it can be solved using $n^{O(1)}$ memory.
- NPSPACE if there is a $B \in \text{PSPACE}$ such that

$$A = \{x \mid \exists^p y \text{ s.t. } (x, y) \in B\}$$

- EXPSPACE if it can be solved using $2^{n^{O(1)}}$ memory.

Complexity Separation

Proper inclusions

- $P \neq \text{EXPTIME}$. Thus, if A is EXPTIME -complete, $A \notin P$.
- $\text{PSPACE} \neq \text{EXPSPACE}$.

Note that, EXPTIME -hardness is defined under relation \leq_p . We won't employ a notation like \leq_e or sth.

Other inclusions

- $\text{NP} \subseteq \text{PSPACE} \subseteq \text{EXPTIME}$.

Oracle complexity

Although it's the last time to treat higher complexities, I decided to introduce the concept of **Oracle machine**.

Oracle machine

Given a complexity class C , \mathcal{D} and a problem B , the class C^B is defined to be the problems being in C , assuming the “oracle” $x \in B$ as a constant-time operation.

Also, $C^{\mathcal{D}} := \bigcup_{B \in \mathcal{D}} C^B$.

If C is large enough to conduct a reduction to a \mathcal{D} -complete problem X , then $C^{\mathcal{D}} = C^X$.

e.g. $\mathsf{P}^{\mathsf{NP}} = \mathsf{P}^{\mathsf{SAT}}$.

Polynomial Hierarchy

Polynomial Hierarchy is an infinite sequence of complexity classes.

Polynomial Hierarchy

- $\Sigma_0, \Pi_0, \Delta_0 := \mathbb{P}.$
- $\Sigma_{i+1} := \text{NP}^{\Sigma_i}.$
- $\Pi_{i+1} := \text{co-NP}^{\Pi_i}.$
- $\Delta_{i+1} := \text{P}^{\Sigma_i}.$

This is neat, but hard to break down.

Polynomial Hierarchy

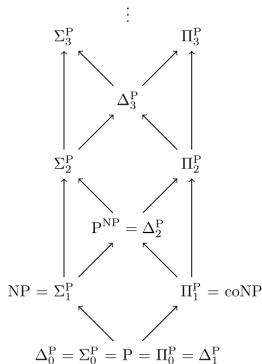
In fact, the alternative definition of PH can be established.

Alternative definition

- $\Sigma_0, \Pi_0 := \mathbb{P}$.
- $A \in \Sigma_{i+1} \iff \exists B \in \Pi_i \text{ s.t. } A = \{x \mid \exists^p y \text{ s.t. } (x, y) \in B\}$.
- $B \in \Pi_{i+1} \iff \exists A \in \Sigma_i \text{ s.t. } B = \{x \mid \forall^p y \text{ s.t. } (x, y) \in A\}$.

Inclusions between Polynomial Hierarchies

There is a set of interwoven inclusion relations between hierarchies.



Polynomial Hierarchy Collapse

Theorem. (PHC)

If $\Sigma_i = \Pi_i$, $\Sigma_i = \Sigma_j = \Pi_j$ for all $j \geq i$.

- Thus, NP -completeness of **GRAPH ISOMORPHISM** removes all complexity classes beyond Σ_2 .

Higher order SAT

Σ_2 **SAT** is defined as below.

Σ_2 -SAT

Given a boolean formula (CNF) $\phi(\vec{x}, \vec{y})$, is there an assignment $\vec{x}^0 = (x_1, \dots, x_n)$ such that $\phi(\vec{x}^0, \vec{y})$ is true regardless of \vec{y} ?

Known that Σ_2 -**SAT** is Σ_2 -complete. Σ_i -**SAT** can be defined equivalently.

QBF

QBF is the most comprehensive form of Σ_k **SAT**.

QBF

Given a boolean formula $\phi(\vec{x}_1, \dots, \vec{x}_k)$, answer the question:

$$\exists \vec{x}_1 \forall \vec{x}_2 \exists \dots Q_k \vec{x}_k \text{ s.t. } \phi(x_1, \dots, x_k) = \text{true?}$$

while Q_j is \exists for j odd, otherwise \forall .

Hardness of QBF

QBF is PSPACE-complete.

Beyond the PSPACE?

Mostly, the notion NPSPACE is tedious.

Theorem. (Savitch)

For $f(n) \geq n$, $\text{NPSPACE}(f(n)) \subseteq \text{PSPACE}(f(n)^2)$. Thus,
 $\text{NPSPACE} = \text{PSPACE}$.

Here $\text{NPSPACE}(f(n))$ denotes the NPSPACE problem allowing $f(n)$ extra space.

Sublinear NPSpace problems

If $f(n) = O(\log n)$, we define $NL := NPSpace(f(n))$ as the problem could be solved in logarithmic extra r/w memory other than input, and the input is read-only.

Reachability problem

Given a directed graph G and $s, t \in V(G)$, is there a path from s to t ?

The problem above is NL -complete. It is weakly believed $L \neq NL$.

Thank You for Your Attention!