CSE 2202
Design and Analysis of Algorithms – I

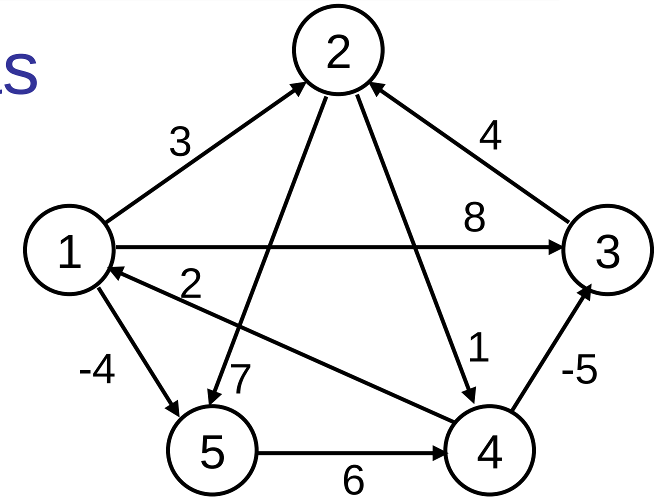
All Pair Shortest Path

All-Pairs Shortest Paths - Solutions

- Run **BELLMAN-FORD** once from each vertex:
  - $O(V^2E)$, which is $O(V^4)$ if the graph is dense ($E = \Theta(V^2)$)
- If no negative-weight edges, could run **Dijkstra's** algorithm once from each vertex:
  - $O(VE\lg V)$ with binary heap, $O(V^3\lg V)$ if the graph is dense
- We can solve the problem in $O(V^3)$, with no elaborate data structures

All-Pairs Shortest Paths

- Assume the graph (G) is given as adjacency matrix of weights
  - $W = (w_{ij})$, $n \times n$ matrix, $|V| = n$
  - Vertices numbered 1 to n



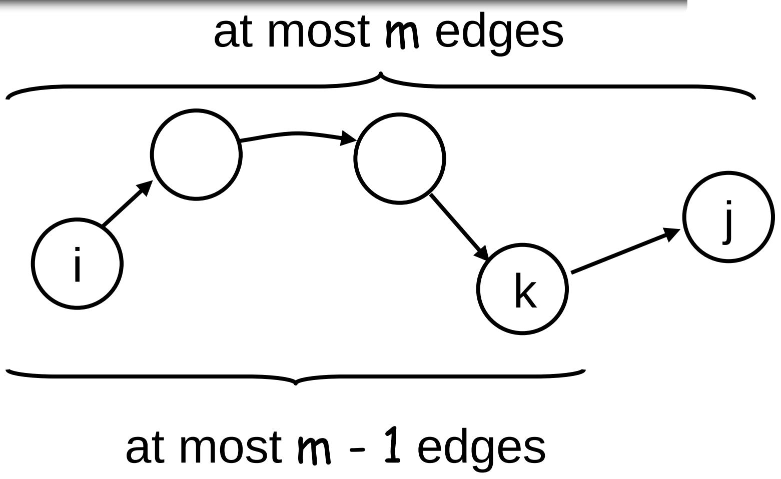
$$w_{ij} = \begin{cases} 0 & \text{if } i = j \\ \text{weight of } (i, j) & \text{if } i \neq j, (i, j) \in E \\ \infty & \text{if } i \neq j, (i, j) \notin E \end{cases}$$

- Output the result in an $n \times n$ matrix

  $D = (d_{ij})$, where $d_{ij} = \delta(i, j)$
- Solve the problem using dynamic programming

Optimal Substructure of a Shortest Path

- All subpaths of a shortest path are shortest paths
- Let p: a shortest path p from vertex i to j that contains at most m edges
- If $i = j$
  - $w(p) = 0$ and p has no edges

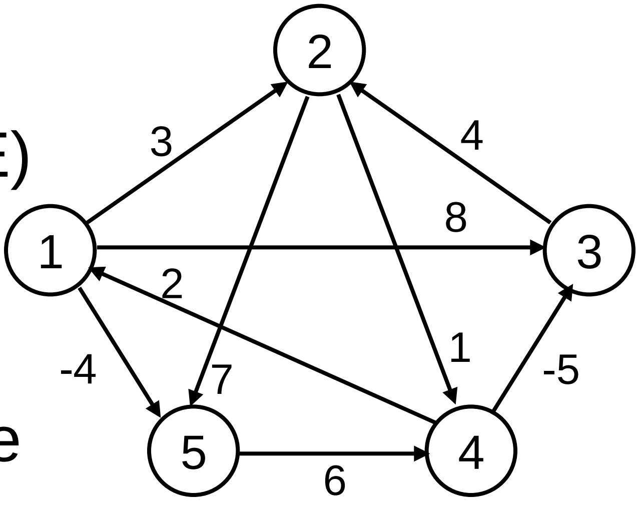


- If $i \neq j$: $p = i \overset{p'}{\leadsto} k \rightarrow j$
  - p' has at most m-1 edges
  - p' is a shortest path

$\delta(i, j) = \delta(i, k) + w_{kj}$

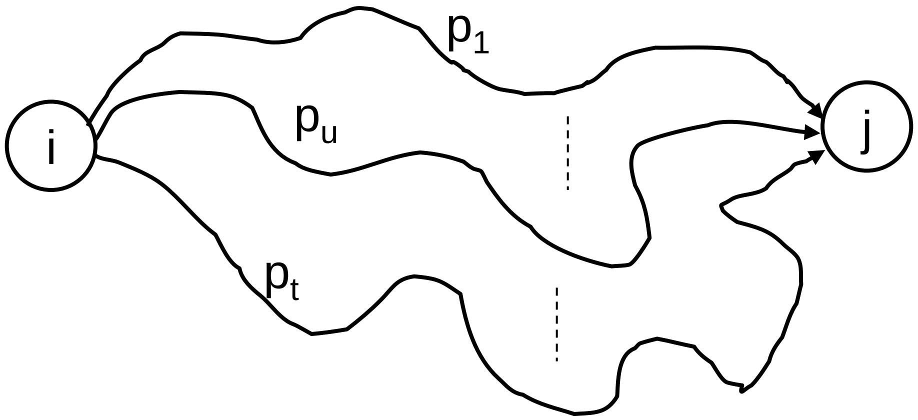
The Floyd-Warshall Algorithm

- **Given:**
  - Directed, weighted graph G = (V, E)
  - Negative-weight edges may be present
  - No negative-weight cycles could be present in the graph
- **Compute:**
  - The shortest paths between all pairs of vertices in a graph



The Structure of a Shortest Path

- For any pair of vertices $i, j \in V$, consider all paths from i to j whose intermediate vertices are all drawn from a subset {1, 2, …, k}
  - Find p, a minimum-weight path from these paths

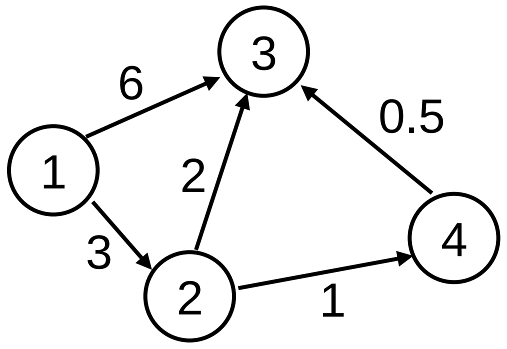


No vertex on these paths has index > k

Example

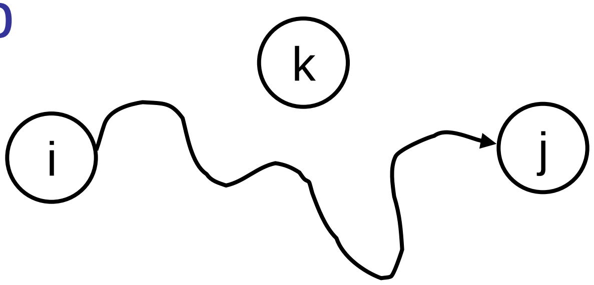
$d_{ij}^{(k)}$ = the weight of a shortest path from vertex i to vertex j with all intermediary vertices drawn from {1, 2, …, k}

- $d_{13}^{(0)} =$ 6
- $d_{13}^{(1)} =$ 6
- $d_{13}^{(2)} =$ 5
- $d_{13}^{(3)} =$ 5
- $d_{13}^{(4)} =$ 4.5

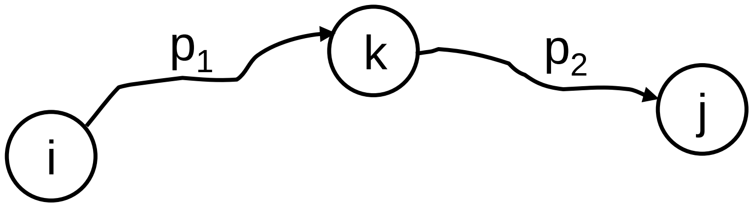


The Structure of a Shortest Path

- k is not an intermediate vertex of path p
  - Shortest path from i to j with intermediate vertices from {1, 2, …, k} is a shortest path from i to j with intermediate vertices from {1, 2, …, k - 1}



- k is an intermediate vertex of path p
  - p_1 is a shortest path from i to k
  - p_2 is a shortest path from k to j
  - k is not intermediary vertex of p_1, p_2
  - p_1 and p_2 are shortest paths from i to k with vertices from {1, 2, …, k - 1}



A Recursive Solution (cont.)

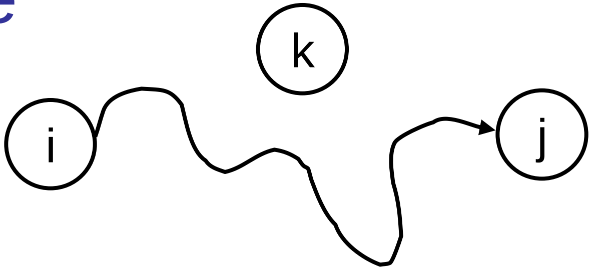
$d_{ij}^{(k)}$ = the weight of a shortest path from vertex i to vertex j with all intermediary vertices drawn from $\{1, 2, \ldots, k\}$

- $k = 0$
- $d_{ij}^{(k)} = w_{ij}$

A Recursive Solution (cont.)

$d_{ij}^{(k)}$ = the weight of a shortest path from vertex i to vertex j with all intermediary vertices drawn from $\{1, 2, \ldots, k\}$

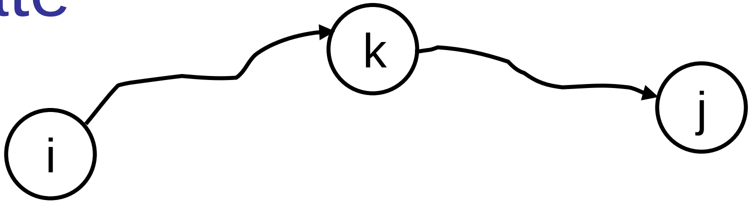
- $k \geq 1$
- **Case 1:** k is not an intermediate vertex of path p
- $d_{ij}^{(k)} = d_{ij}^{(k-1)}$



A Recursive Solution (cont.)

$d_{ij}^{(k)}$ = the weight of a shortest path from vertex i to vertex j with all intermediary vertices drawn from $\{1, 2, \dots, k\}$

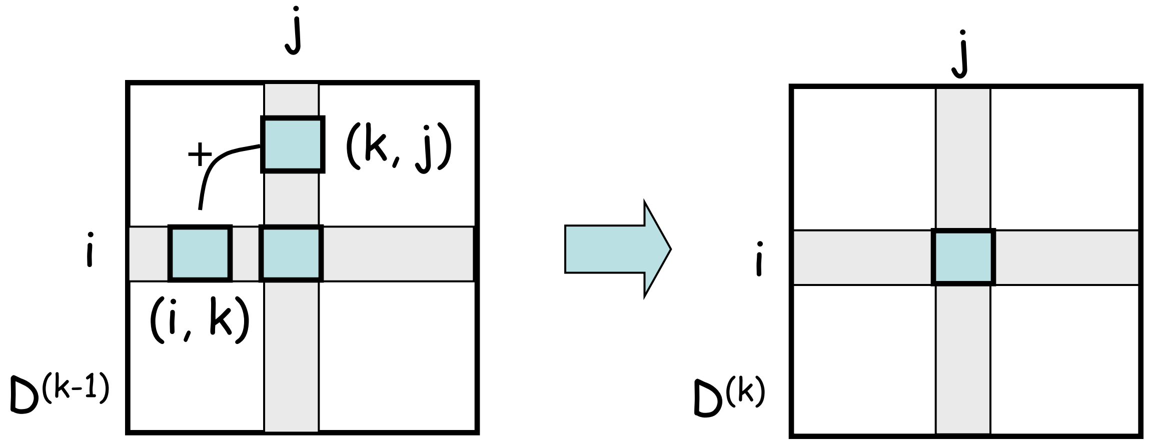
- $k \geq 1$
- **Case 2:** k is an intermediate vertex of path p
- $d_{ij}^{(k)} = d_{ik}^{(k-1)} + d_{kj}^{(k-1)}$



Computing the Shortest Path Weights

- $$d_{ij}^{(k)} = \begin{cases} w_{ij} & \text{if } k = 0 \\ \min\{d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)}\} & \text{if } k \geq 1 \end{cases}$$
- The final solution: $D^{(n)} = (d_{ij}^{(n)})$:

$$d_{ij}^{(n)} = \delta(i, j) \ \forall\ i, j \in V$$



The Floyd-Warshall algorithm

```
Floyd-Warshall(W[1..n][1..n])
D ← W    // $D^{(0)}$
for k ← 1 to n do // compute $D^{(k)}$
    for i ← 1 to n do
        for j ← 1 to n do
            if D[i][k] + D[k][j] < D[i][j] then
                D[i][j] ← D[i][k] + D[k][j]
return D
```

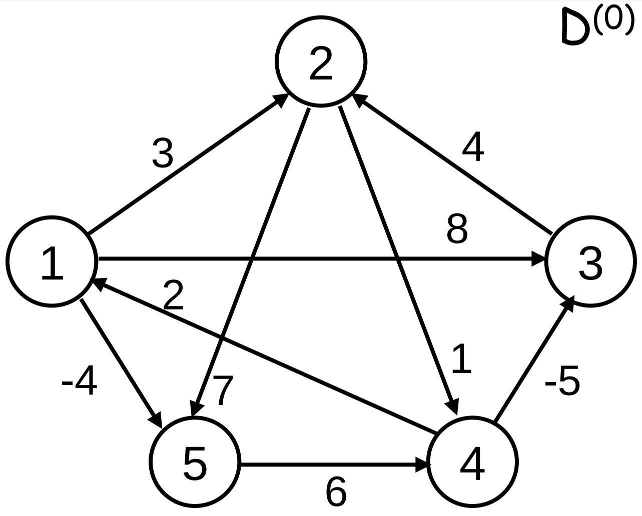
Running Time: $O(n^3)$

Computing predecessor matrix

- *How do we compute the predecessor matrix?*
  - Initialization: $$p^{(0)}(i,j) = \begin{cases} nil & \text{if } i = j \text{ or } w_{ij} = \infty \\ i & \text{if } i \neq j \text{ and } w_{ij} < \infty \end{cases}$$

```
Floyd-Warshall(W[1..n][1..n])
01 …
02 for k ← 1 to n do // compute D^(k)
03     for i ←1 to n do
04         for j ←1 to n do
05             if D[i][k] + D[k][j] < D[i][j] then
06                 D[i][j] ← D[i][k] + D[k][j]
07                 P[i][j] ← k
08 return D
```

Example $d_{ij}^{(k)} = \min\{d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)}\}$



$D^{(0)} = W$

$$\begin{array}{c|ccccc} & 1 & 2 & 3 & 4 & 5 \\ \hline 1 & 0 & 3 & 8 & \infty & -4 \\ 2 & \infty & 0 & \infty & 1 & 7 \\ 3 & \infty & 4 & 0 & \infty & \infty \\ 4 & 2 & \infty & -5 & 0 & \infty \\ 5 & \infty & \infty & \infty & 6 & 0 \end{array}$$

$D^{(1)}$

$$\begin{array}{c|ccccc} & 1 & 2 & 3 & 4 & 5 \\ \hline 1 & 0 & 3 & 8 & \infty & -4 \\ 2 & \infty & 0 & \infty & 1 & 7 \\ 3 & \infty & 4 & 0 & \infty & \infty \\ 4 & 2 & 5 & -5 & 0 & -2 \\ 5 & \infty & \infty & \infty & 6 & 0 \end{array}$$

$D^{(2)}$

$$\begin{array}{c|ccccc} & 1 & 2 & 3 & 4 & 5 \\ \hline 1 & 0 & 3 & 8 & 4 & -4 \\ 2 & \infty & 0 & \infty & 1 & 7 \\ 3 & \infty & 4 & 0 & 5 & 11 \\ 4 & 2 & 5 & -5 & 0 & -2 \\ 5 & \infty & \infty & \infty & 6 & 0 \end{array}$$

$D^{(3)}$

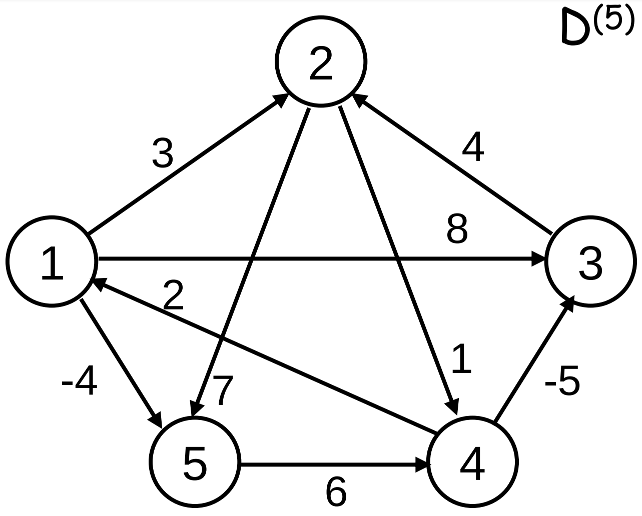
$$\begin{array}{|ccccc|} 0 & 3 & 8 & 4 & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & 5 & 11 \\ 2 & -1 & -5 & 0 & -2 \\ \infty & \infty & \infty & 6 & 0 \end{array}$$

$D^{(4)}$

$$\begin{array}{|ccccc|} 0 & 3 & -1 & 4 & -4 \\ 3 & 0 & -4 & 1 & -1 \\ 7 & 4 & 0 & 5 & 3 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & 5 & 1 & 6 & 0 \end{array}$$

Example

$$d_{ij}^{(k)} = \min\{d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)}\}$$



$D^{(5)}$

$$\begin{array}{c|ccccc} & 1 & 2 & 3 & 4 & 5 \\ \hline 1 & 0 & 1 & -3 & 2 & -4 \\ 2 & 3 & 0 & -4 & 1 & -1 \\ 3 & 7 & 4 & 0 & 5 & 3 \\ 4 & 2 & -1 & -5 & 0 & -2 \\ 5 & 8 & 5 & 1 & 6 & 0 \end{array}$$

$P^{(5)}$

$$\begin{array}{c|ccccc} & 1 & 2 & 3 & 4 & 5 \\ \hline 1 & - & 3 & 4 & 5 & 1 \\ 2 & 4 & - & 4 & 2 & 1 \\ 3 & 4 & 3 & - & 2 & 1 \\ 4 & 4 & 3 & 4 & - & 1 \\ 5 & 4 & 3 & 4 & 5 & - \end{array}$$

Source: 5, Destination: 1

Shortest path: 8

Path: 5 …1 : 5…4…1: 5->4…1: 5->4->1

Source: 1, Destination: 3

Shortest path: -3

Path: 1 …3 : 1…4…3: 1…5…4…3: 1->5->4->3

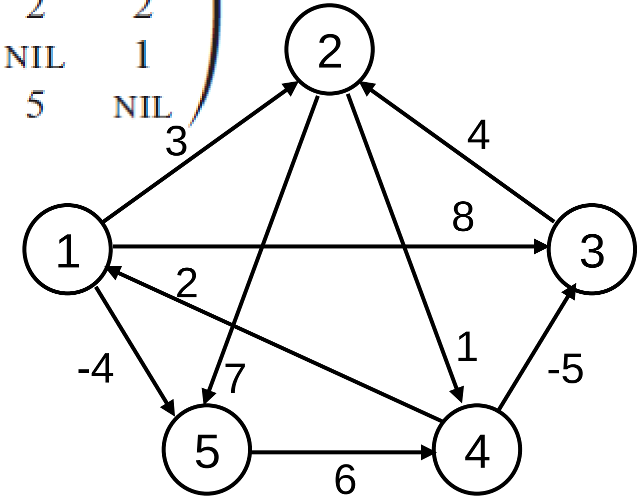
Example

$$d_{ij}^{(k)} = \min\{d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)}\}$$

$$D^{(0)} = \begin{pmatrix} 0 & 3 & 8 & \infty & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & \infty & \infty \\ 2 & \infty & -5 & 0 & \infty \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix} \quad \Pi^{(0)} = \begin{pmatrix} \text{NIL} & 1 & 1 & \text{NIL} & 1 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & 3 & \text{NIL} & \text{NIL} & \text{NIL} \\ 4 & \text{NIL} & 4 & \text{NIL} & \text{NIL} \\ \text{NIL} & \text{NIL} & \text{NIL} & 5 & \text{NIL} \end{pmatrix}$$

$$D^{(1)} = \begin{pmatrix} 0 & 3 & 8 & \infty & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & \infty & \infty \\ 2 & 5 & -5 & 0 & -2 \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix} \quad \Pi^{(1)} = \begin{pmatrix} \text{NIL} & 1 & 1 & \text{NIL} & 1 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & 3 & \text{NIL} & \text{NIL} & \text{NIL} \\ 4 & 1 & 4 & \text{NIL} & 1 \\ \text{NIL} & \text{NIL} & \text{NIL} & 5 & \text{NIL} \end{pmatrix}$$

$$D^{(2)} = \begin{pmatrix} 0 & 3 & 8 & 4 & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & 5 & 11 \\ 2 & 5 & -5 & 0 & -2 \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix} \quad \Pi^{(2)} = \begin{pmatrix} \text{NIL} & 1 & 1 & 2 & 1 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & 3 & \text{NIL} & 2 & 2 \\ 4 & 1 & 4 & \text{NIL} & 1 \\ \text{NIL} & \text{NIL} & \text{NIL} & 5 & \text{NIL} \end{pmatrix}$$



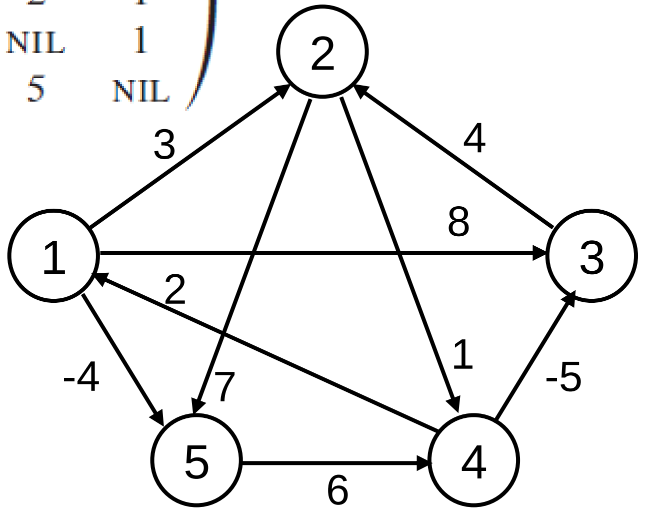
Example

$$d_{ij}^{(k)} = \min\{d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)}\}$$

$$D^{(2)} = \begin{pmatrix} 0 & 3 & 8 & 4 & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & 5 & 11 \\ 2 & 5 & -5 & 0 & -2 \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix} \qquad \Pi^{(2)} = \begin{pmatrix} \text{NIL} & 1 & 1 & 2 & 1 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & 3 & \text{NIL} & 2 & 2 \\ 4 & 1 & 4 & \text{NIL} & 1 \\ \text{NIL} & \text{NIL} & \text{NIL} & 5 & \text{NIL} \end{pmatrix}$$

$$D^{(3)} = \begin{pmatrix} 0 & 3 & 8 & 4 & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & 5 & 11 \\ 2 & -1 & -5 & 0 & -2 \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix} \qquad \Pi^{(3)} = \begin{pmatrix} \text{NIL} & 1 & 1 & 2 & 1 \\ \text{NIL} & \text{NIL} & \text{NIL} & 2 & 2 \\ \text{NIL} & 3 & \text{NIL} & 2 & 2 \\ 4 & 3 & 4 & \text{NIL} & 1 \\ \text{NIL} & \text{NIL} & \text{NIL} & 5 & \text{NIL} \end{pmatrix}$$

$$D^{(4)} = \begin{pmatrix} 0 & 3 & -1 & 4 & -4 \\ 3 & 0 & -4 & 1 & -1 \\ 7 & 4 & 0 & 5 & 3 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & 5 & 1 & 6 & 0 \end{pmatrix} \qquad \Pi^{(4)} = \begin{pmatrix} \text{NIL} & 1 & 4 & 2 & 1 \\ 4 & \text{NIL} & 4 & 2 & 1 \\ 4 & 3 & \text{NIL} & 2 & 1 \\ 4 & 3 & 4 & \text{NIL} & 1 \\ 4 & 3 & 4 & 5 & \text{NIL} \end{pmatrix}$$

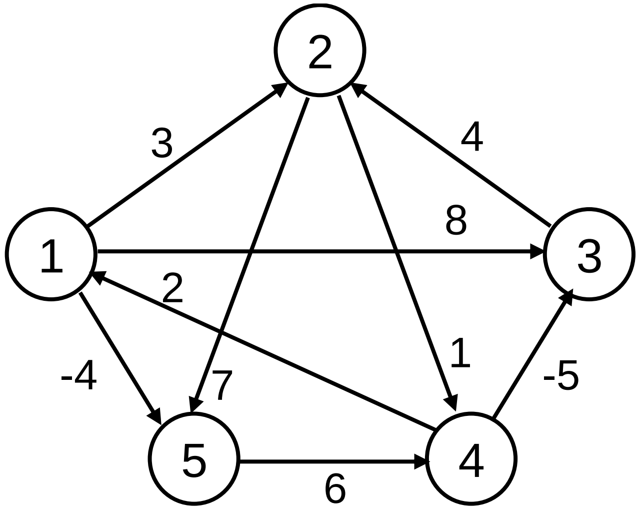


Example

$$d_{ij}^{(k)} = \min\{d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)}\}$$

$$D^{(4)} = \begin{pmatrix} 0 & 3 & -1 & 4 & -4 \\ 3 & 0 & -4 & 1 & -1 \\ 7 & 4 & 0 & 5 & 3 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & 5 & 1 & 6 & 0 \end{pmatrix} \qquad \Pi^{(4)} = \begin{pmatrix} \text{NIL} & 1 & 4 & 2 & 1 \\ 4 & \text{NIL} & 4 & 2 & 1 \\ 4 & 3 & \text{NIL} & 2 & 1 \\ 4 & 3 & 4 & \text{NIL} & 1 \\ 4 & 3 & 4 & 5 & \text{NIL} \end{pmatrix}$$

$$D^{(5)} = \begin{pmatrix} 0 & 1 & -3 & 2 & -4 \\ 3 & 0 & -4 & 1 & -1 \\ 7 & 4 & 0 & 5 & 3 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & 5 & 1 & 6 & 0 \end{pmatrix} \qquad \Pi^{(5)} = \begin{pmatrix} \text{NIL} & 3 & 4 & 5 & 1 \\ 4 & \text{NIL} & 4 & 2 & 1 \\ 4 & 3 & \text{NIL} & 2 & 1 \\ 4 & 3 & 4 & \text{NIL} & 1 \\ 4 & 3 & 4 & 5 & \text{NIL} \end{pmatrix}$$



PrintPath for Warshall’s Algorithm

```
PrintPath(s, t)
{
   if(P[s][t]==nil) {print(“No path”);return;}
   else if (P[s][t]==s){
         print(s);
   }
   else{
         print_path(s,P[s][t]);
         print_path(P[s][t], t);
   }
}
Print (t) at the end of the PrintPath(s,t)
```

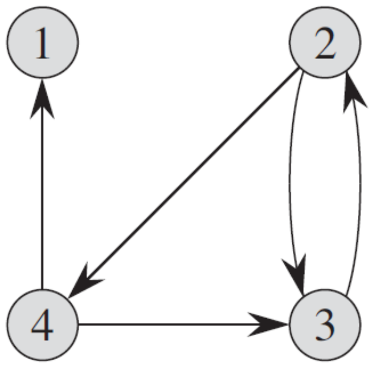
Question

- Why should we use D[i, j] instead of $D^{(k)}$[i, j]?
- Exercise:
  - 25.2-4: Memory $O(n^2)$
  - 25.2-6: Negative weight cycle
  - Find the shortest positive cycle

Transitive closure of the graph

- Input:
  - Un-weighted graph G: $W[i][j] = 1$, if $(i,j) \in E$, $W[i][j] = 0$ otherwise.
- Output:
  - $T[i][j] = 1$, if there is a path from i to j in G, $T[i][j] = 0$ otherwise.
- Algorithm:
  - Just run Floyd-Warshall with weights 1, and make $T[i][j] = 1$, whenever $D[i][j] < \infty$.
  - More efficient: use only Boolean operators

Transitive closure algorithm



```
Transitive-Closure(W[1..n][1..n])
T ← W    // T^(0)
for k ←1 to n do // compute T^(k)
    for i ←1 to n do
        for i ←1 to n do
            T[i][j] ← T[i][j] ∨ (T[i][k] ∧ T[k][j])
return T
```

$$T^{(0)} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 1 \end{pmatrix} \quad T^{(1)} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 1 \end{pmatrix} \quad T^{(2)} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 \end{pmatrix}$$

$$T^{(3)} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{pmatrix} \quad T^{(4)} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{pmatrix}$$

Complexity

- Bellman-Ford algorithm:

  Running time: O(VE)

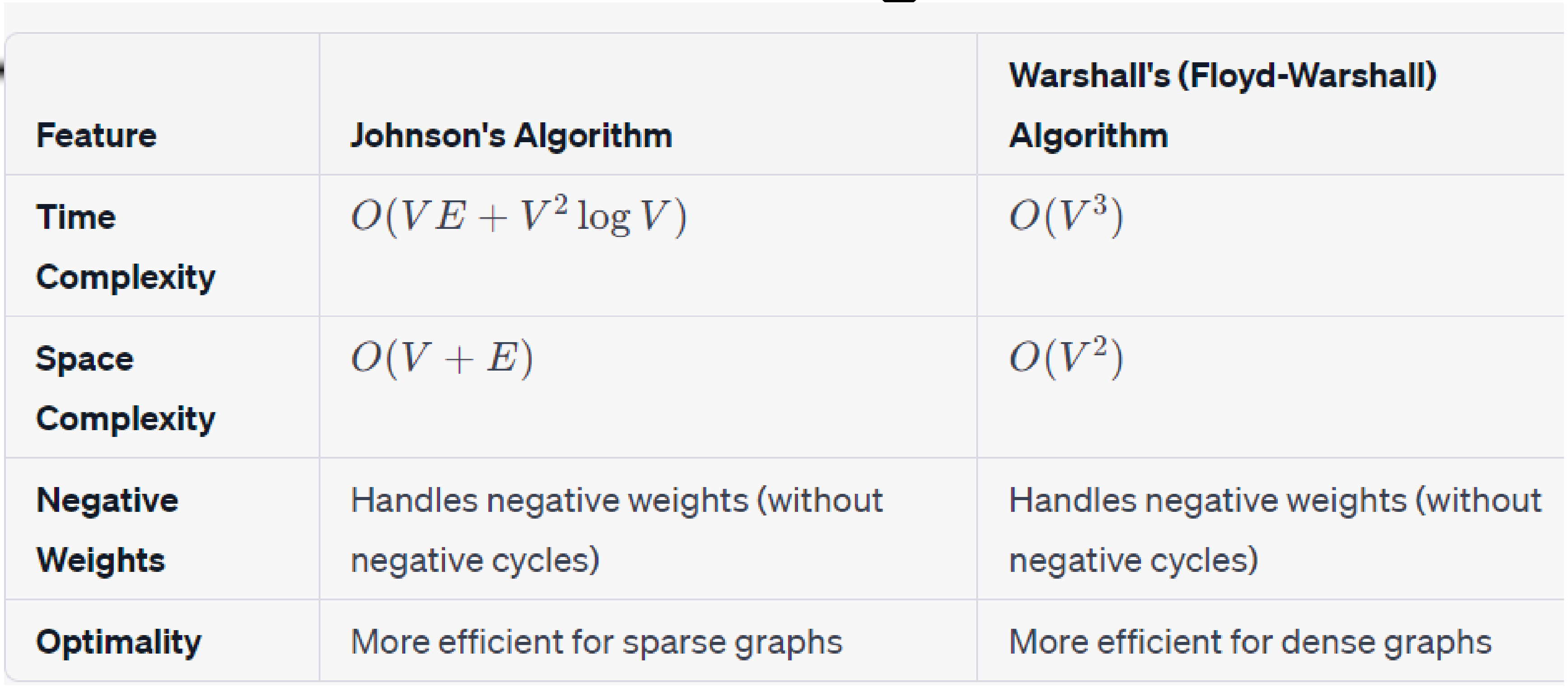
- Dijkstra's Algorithm

Q	Total
array	$O(V^2)$
binary heap	$O(E \lg V)$
Fibonacci heap	$O(V \lg V + E)$

Complexity

- Run **BELLMAN-FORD** once from each vertex:
  - $O(V^2E)$, which is $O(V^4)$ if the graph is dense ($E = \Theta(V^2)$)
- If no negative-weight edges, could run **Dijkstra's** algorithm once from each vertex:
  - $O(VE\lg V)$ with binary heap, $O(V^3\lg V)$ if the graph is dense
- We can solve the problem in $O(V^3)$, with no elaborate data structures

Johnson's Algorithm



Feature	Johnson's Algorithm	Warshall's (Floyd-Warshall) Algorithm
Time Complexity	$O(VE + V^2 \log V)$	$O(V^3)$
Space Complexity	$O(V + E)$	$O(V^2)$
Negative Weights	Handles negative weights (without negative cycles)	Handles negative weights (without negative cycles)
Optimality	More efficient for sparse graphs	More efficient for dense graphs

Time Complexity: The main steps in the algorithm are Bellman-Ford Algorithm called once and Dijkstra called V times.

Time complexity of Bellman Ford is **O(VE)** and time complexity of Dijkstra is **O(VLogV).** So overall time complexity is **$O(V^2 \log V + VE)$**.

Johnson's Algorithm

Johnson's algorithm uses the technique of **reweighting**

- If all edge weights w in a graph G are nonnegative, we can find shortest paths between all pairs of vertices by running Dijkstra's algorithm once from each vertex;

- with the Fibonacci-heap min-priority queue, the running time of this all-pairs algorithm is $O(V^2 \lg V + VE)$.

- If G has negative-weight edges but no negative-weight cycles, we simply compute **a new set of nonnegative edge weights** that allows us to use the same method…

Johnson’s Algorithm

The new set of edge weights $\widehat{w}$ must satisfy two important properties:

1. For all pairs of vertices $u, v \in V$, a path p is a shortest path from u to v using weight function w if and only if p is also a shortest path from u to v using weight function $\widehat{w}$.
2. For all edges (u, v), the new weight $\widehat{w}(u, v)$ is nonnegative.

As we shall see in a moment, we can preprocess G to determine the new weight function $\widehat{w}$ in $O(VE)$ time.

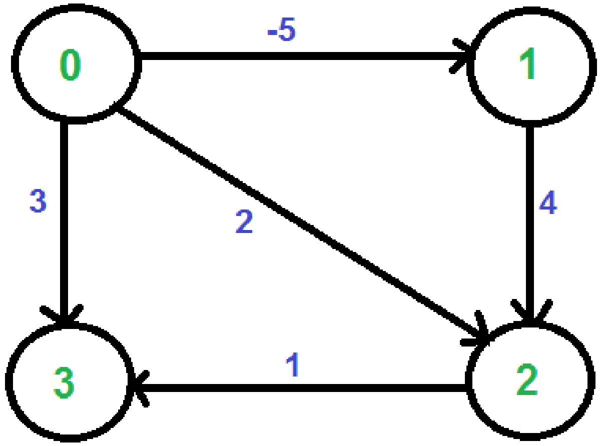
Lemma 25.1 (Reweighting does not change shortest paths)

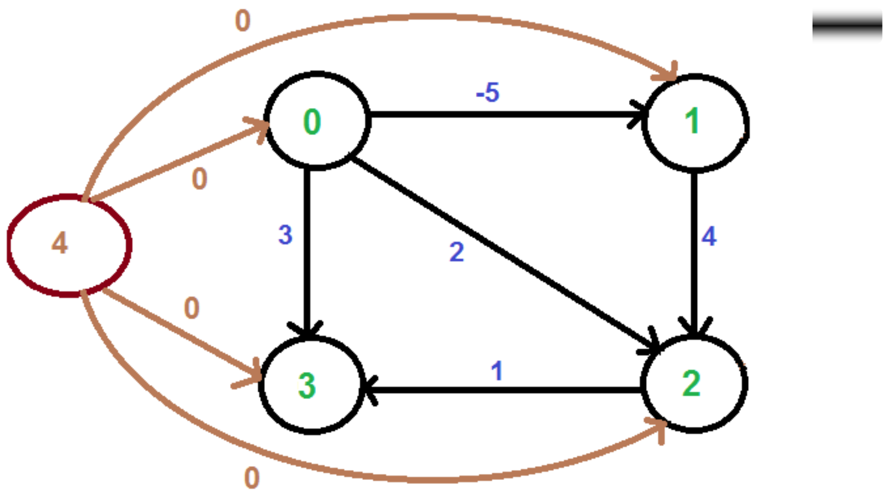
Johnson’s Algorithm

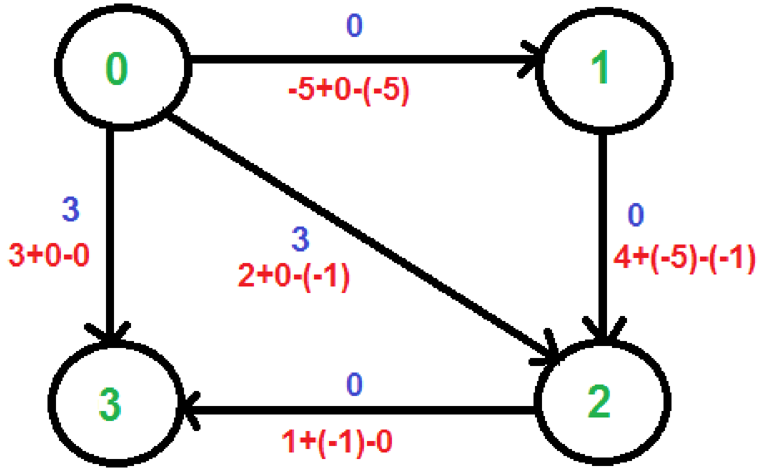
Johnson's algorithm has three main steps.

1. A new vertex is added to the graph, and it is connected by edges of zero weight to all other vertices in the graph.
2. All edges go through a reweighting process that eliminates negative weight edges.
3. The added vertex from step 1 is removed and Dijkstra's algorithm is run on every node in the graph.

Johnson’s Algorithm







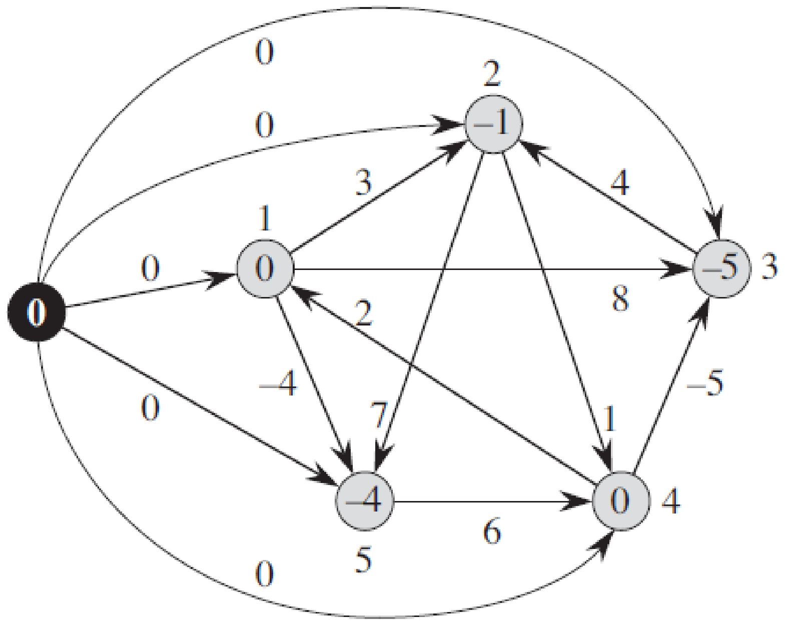
Distances from 4 to 0, 1, 2 and 3 are 0, -5, -1 and 0 respectievely.

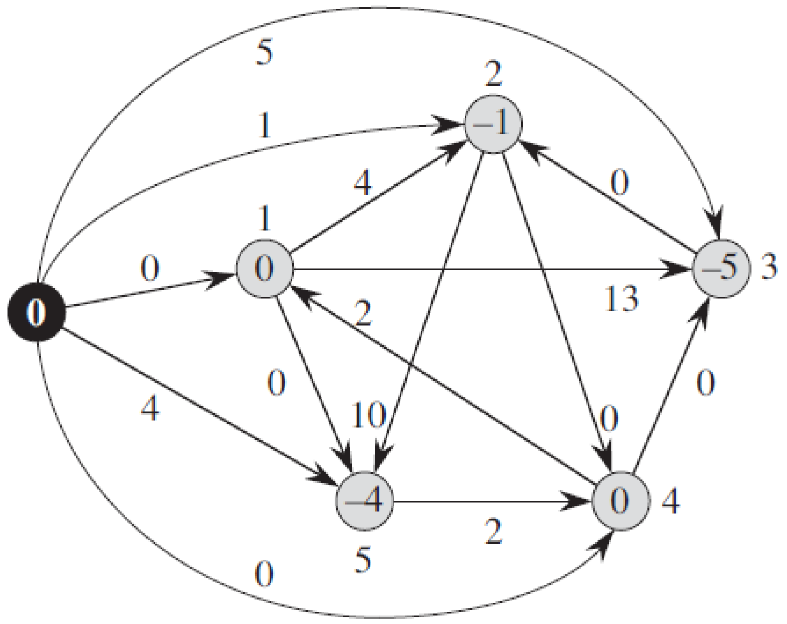
- We calculate the shortest distances from 4 to all other vertices using Bellman-Ford algorithm.
- The shortest distances from 4 to 0, 1, 2 and 3 are 0, -5, -1 and 0 respectively,

  i.e., **h[] = {0, -5, -1, 0}.**
- Once we get these distances, we remove the source vertex 4 and reweight the edges using following formula.

$$\hat{w}(u,v) = w(u,v) + h(u) - h(v)$$

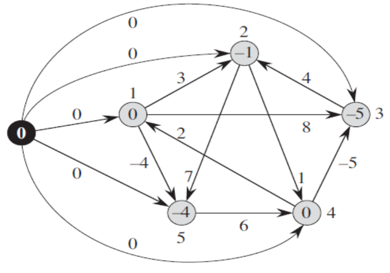
Johnson's Algorithm



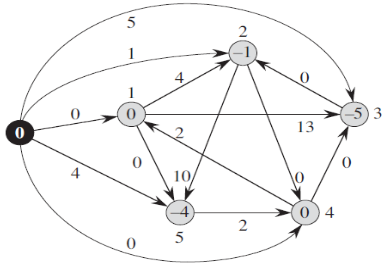


(a) The graph G' with the original weight function w. The new vertex s is black. Within each vertex v is $h(v) = \delta(s, v)$.

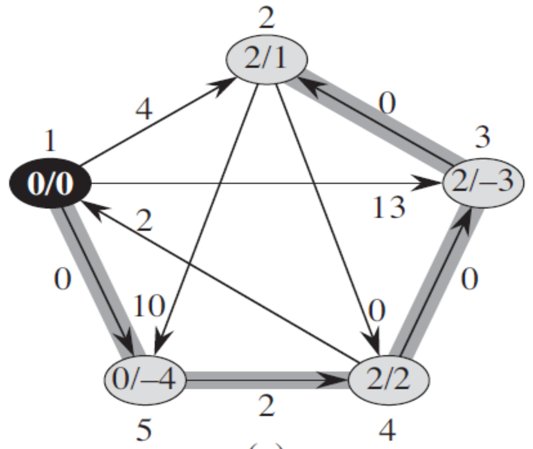
(b) After reweighting each edge (u, v) with weight function $\hat{w}(u, v) = w(u, v) + h(u) - h(v)$.



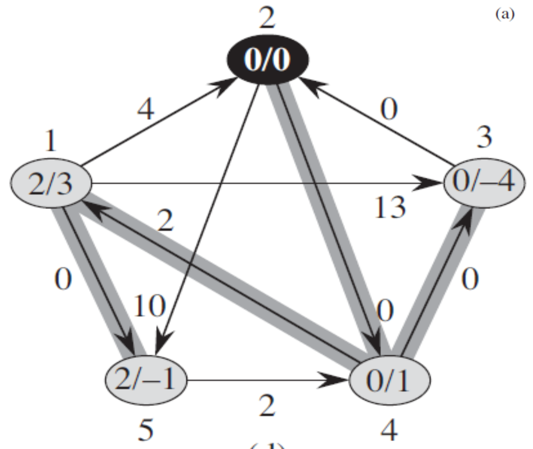
(a)



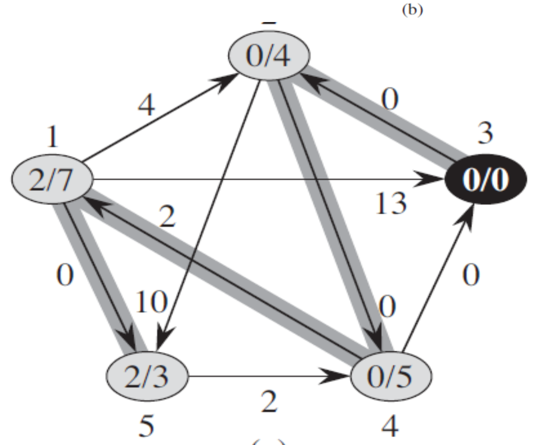
(b)



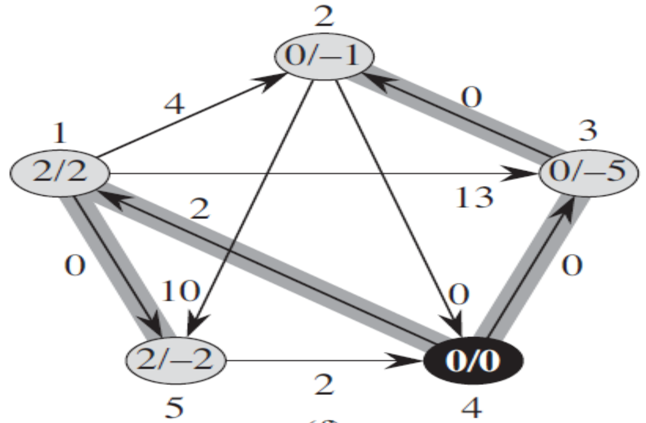
(c)



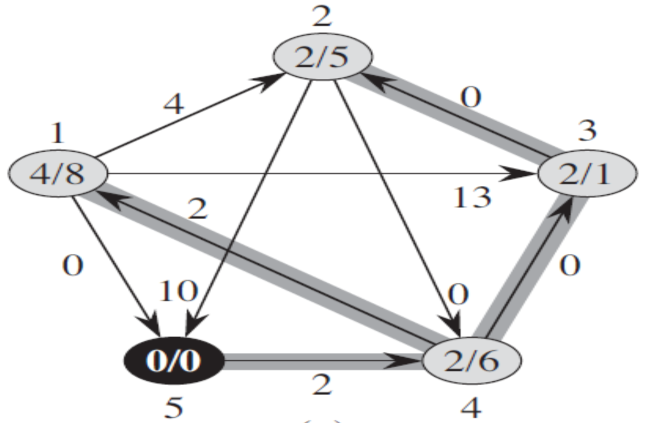
(d)



(e)



(f)



(g)

Dijkstra's algorithm on each vertex of G using weight function $\widehat{w}$. In each part, the source vertex u is black, and shaded edges are in the shortest-paths tree computed by the algorithm. Within each vertex v are the values $\widehat{\delta}(u,v)$ and $\delta(u,v)$, separated by a slash. The value $d_{uv} = \delta(u,v)$ is equal to $\widehat{\delta}(u,v) + h(v) - h(u)$.

```
JOHNSON($G, w$)
compute $G'$, where $G'.V = G.V \cup \{s\}$,
        $G'.E = G.E \cup \{(s, v) : v \in G.V\}$, and
        $w(s, v) = 0$ for all $v \in G.V$
if BELLMAN-FORD($G', w, s$) == FALSE
        print "the input graph contains a negative-weight cycle"
else for each vertex $v \in G'.V$
                set $h(v)$ to the value of $\delta(s, v)$
                        computed by the Bellman-Ford algorithm
        for each edge $(u, v) \in G'.E$
                $\widehat{w}(u, v) = w(u, v) + h(u) - h(v)$
        let $D = (d_{uv})$ be a new $n \times n$ matrix
        for each vertex $u \in G.V$
                run DIJKSTRA($G, \widehat{w}, u$) to compute $\widehat{\delta}(u, v)$ for all $v \in G.V$
                for each vertex $v \in G.V$
                        $d_{uv} = \widehat{\delta}(u, v) + h(v) - h(u)$
        return $D$
```

```
JOHNSON$(G, w)$
compute $G'$, where $G'.V = G.V \cup \{s\}$,
        $G'.E = G.E \cup \{(s, v) : v \in G.V\}$, and
        $w(s, v) = 0$ for all $v \in G.V$
if BELLMAN-FORD$(G', w, s)$ == FALSE
    print "the input graph contains a negative-weight cycle"
else for each vertex $v \in G'.V$
        set $h(v)$ to the value of $\delta(s, v)$
            computed by the Bellman-Ford algorithm
    for each edge $(u, v) \in G'.E$
        $\widehat{w}(u, v) = w(u, v) + h(u) - h(v)$
    let $D = (d_{uv})$ be a new $n \times n$ matrix
    for each vertex $u \in G.V$
        run DIJKSTRA$(G, \widehat{w}, u)$ to compute $\widehat{\delta}(u, v)$ for all $v \in G.V$
        for each vertex $v \in G.V$
            $d_{uv} = \widehat{\delta}(u, v) + h(v) - h(u)$
    return $D$
```

If we implement the min-priority queue in Dijkstra's algorithm by a Fibonacci heap, Johnson's algorithm runs in $O(V^2 \lg V + VE)$ time. The simpler binary min-heap implementation yields a running time of $O(VE \lg V)$, which is still asymptotically faster than the Floyd-Warshall algorithm if the graph is sparse.