<https://github.com/TAdragon1/mobile_robotics_assignments/tree/master/my_stdr_control>

My solution to this assignment makes use of making the robot drive in reverse. Anytime the robot moves to the left, it does so in reverse. This way, I don’t need to worry about rotating the robot precisely for horizontal motion, as it just reverses its previous rotation. If the robot couldn’t reach the top left with my current solution, I would calculate the angular velocity needed to allow for straight vertical motion.