

## **Uttara University**

**COURS CODE: CSEC428** 

## **COURSE NAME:**

**Computer Graphics** 

# **Assignment**

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**BATCH: 57** 

**SECTION: A** 

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# Answere to the question no. 1:

In Cyrus-Beck algorithm, the fundamental fore correlation is the segment is visible only if tests: If tests, it means the line enters after it leaves, which is not possible. Hence, no visible segment inside the window.

### Evaluation:

1. Tenz

Here TEXt

.. The result is valid and the line segment is partially visible betwee t=0.74 and t=1.06, though the portion from 1.0 to 1.06 lies beyond the boundary.

# 2. Nivera:

Here te>t\_, this violates. the Cyrcus-Beck condition.

So the result is invalid as there Is no visible poretion and line segment is outside the clipping window.

3. Jampi:

Here te = 0.69, te = 0.81

: te <tL

The result is valid with a visible segment from t = 0.69 to t = 0.81

i. Jampi used the Cyrus-Beck algorithm connectly, because the result satisfies the condition te<tl and both values lie within the typical promoter range [0,1] making the line segment visible inside the dipping window.

$$P_0 = (10,60)$$
,  $P_7(25,30)$   
 $P_1 - P_0 = (\chi_1 - \chi_0, \chi_1 - \chi_0)$   
 $= (25 - 10, 30 - 60)$   
 $= (15, -30)$   
Parametric equation:  
 $P(t) = P_0 + t(P_1 - P_0)$   
 $= (10,60) + t(15, -30)$   
At,  $t = \frac{3}{5}$ ,  $(10 + 15t, 60 - 30t)$   
 $P(\frac{3}{5}) = (10 + 15(\frac{2}{5}), 60 - 30(\frac{2}{5}) = (19, 42)$ 

Clipping region: (-30,15) and (20,25) 7min = -30 / 1max = 20 Ymin = 15, Ymar = 25 P(10,18) and P2(-45,20) ·. x = 10 x2=-45 71218 72520 Outcode for P1: 21 ≥ 2 min => 10 > -30 => True ; left =0 71 < 7 mar => 10 < 20 => True; Right=0 81 > ymin => 18 > 15 => True; Bottom = 0 01 5 8 may => 18 < 25 => Treve; Top=0 Outcode, P1 = 0000 Outcode for P2: 72> 7min =>-45> -30 => false; Left =1 725 7max =>-45<20=> True, Right =0 y2> 8min => 20 > 15 => True; Bottom = 0 y2 ≤ yman => 20 ≤ 25 => True; Top = 0 Outcode, P2 = 0001 OCP1 AND OCP2 0000 The line is partially inside of the clipping region.

 $m = \frac{20 - 18}{-45 - 10} = -\frac{2}{55}$ 

OCP2 =0001

OCP2 != 0000 and has a left bit.

Applying left boundary intersection:

P2 (-45, 20)

ttere

2, = -45, y2=20

 $x_2 = x_{mim} = -30$   $y_2 = y_2 + m(x_{mim} - x_2)$   $y_2 = 20 - \frac{2}{55}(-30 + 45)$ 

 $y_{2} = 20 - \frac{2}{55} (15)$  $y_{2} = 19.45$ 

New , P2 = (-30, 19.45);

Outcode P2 (-30,19.45):

-30 2 -30 => True; left =0

-30 ≤ 20 => True; Right=0

19.45 > 15 => True; Bottom =0

19.45 < 25 =) True; Top = 0

0.00P2 = 0000

Since OCP1 = = OCP2 = = 0000, the line is now completely inside the window and the points are P1(10,18) and P2(-30,19.45)

# Amswere to the question no. 2:

60 degrees clockwise rotatore with respect to the point (6,6)

Composite matrix, M = T(6,6) × R(-60) × T(-6,-6)

$$= \begin{bmatrix} 1 & 0 & 6 \\ 0 & 16 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \cos(-60) & -\sin(-60) & 0 \\ \cos(-60) & \cos(-60) & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -6 \\ 0 & 1 & -6 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 6 \\ 0 & 1 & 6 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0.5 & 0.866 & 0 \\ -0.866 & 0.5 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -6 \\ 0 & 1 & -6 \\ 0 & 0 & 0 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 6 \\ 0 & 0 & 6 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0.5 & 0.866 & -8.196 \\ -0.866 & 0.5 & 2.196 \\ 0 & 0 & 1 \\ \end{bmatrix}$$

$$= \begin{array}{c|cccc} 0.5 & 0.866 & 3.804 \\ -0.866 & 0.5 & 14.196 \\ \hline 0 & 0 & 1 \end{array}$$

Lime => y = 
$$\sqrt{3}$$
  $\times$  +3  
b = 3, m= $\sqrt{3}$ ,  $\theta$  =  $\tan^{-1}\sqrt{3}$  = 60  
Moomposite =  $T(0, 3) \times R(\cos) \times Reflect(\alpha - axis) \times R(6) \times T(0, 7)$   
=  $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 3 \\ 0 & 0 & 1 \end{bmatrix}$   $\begin{bmatrix} \cos 60 & -\sin 60 & 0 \\ \sin 60 & \cos 60 & 0 \\ 0 & 0 & 1 \end{bmatrix}$   $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$   $\begin{bmatrix} \cos 60 & -\sin 60 & 0 \\ \sin 60 & \cos 60 & 0 \\ 0 & 0 & 1 \end{bmatrix}$   $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$   $\begin{bmatrix} \cos 60 & -\sin 60 & 0 \\ \cos 60 & \cos 60 & 0 \\ 0 & 0 & 1 \end{bmatrix}$   $\begin{bmatrix} \cos 60 & -\sin 60 & 0 \\ \cos 60 & \cos 60 & 0 \\ \cos 60 & \cos 60 & 0 \end{bmatrix}$   $\begin{bmatrix} \cos 60 & -2.598 \\ 0.866 & 0.5 & -1.5 \\ 0 & 0 & 1 \end{bmatrix}$   $\begin{bmatrix} -0.5 & 0.866 & -2.598 \\ 0.866 & 0.5 & -1.5 \\ 0 & 0 & 1 \end{bmatrix}$   $\begin{bmatrix} -0.5 & 0.866 & -2.598 \\ 0.866 & 0.5 & -1.5 \\ 0 & 0 & 1 \end{bmatrix}$   $\begin{bmatrix} -0.5 & 0.866 & -2.598 \\ 0.866 & 0.5 & -1.5 \\ 0 & 0 & 1 \end{bmatrix}$   $\begin{bmatrix} -0.5 & 0.866 & -2.598 \\ 0.866 & 0.5 & -1.5 \\ 0 & 0 & 1 \end{bmatrix}$   $\begin{bmatrix} -0.5 & 0.866 & -2.598 \\ 0.866 & 0.5 & -1.5 \\ 0 & 0 & 1 \end{bmatrix}$ 

$$= \begin{bmatrix} -0.5 & 0.866 & -2.598 \\ 0.866 & 0.5 & 7.5 \\ 0 & 0 & 1 \end{bmatrix}$$