

## Project 4 Lab Report

### 1.0 Program Input/Output

The first program we created took in three inputs from the user. All three inputs were signed numbers that would be used to complete the program. The program then utilized these inputs in a function. The value of this function was then output back out to the user. The only other output let the user know if there was overflow or no overflow as a result of the function. The second program prompted the user to input multiple different integers for data on two different processors. This data included the Instruction Count, the CPI, and the Clock Rate for each one respectively. The program collected this by outputting individual statements for each individual value. The final output of the program relied on which processor's CPU Time was greater and by how much. The third program we created only involved a single output, which was the sum of the array established in the program. We took in no input from the user.

### 2.0 Program Design

I began the first program by asking the user to input 3 different values for 3 variables. I then utilized mathematical operations to perform the equation put forth in the report. by the equation. I then printed the solution to the equation back out the user. I started the second program by first storing the CPU Time and "Zero" into floating point registers. I then prompted the user for all of the values I needed to complete the equation for Processor A. I then stored these values into individual floating point registers. I then jumped to the Calculate function, which served the purpose of completing the operations within the equation. We then returned to the original jump location and continued on. We then moved on to collect and store the values for the second processor, B, into floating point registers. The mathematical operations were conducted the same way as for processor A, utilizing a jump and return. The program then moved to the higherValue function in order to compare the two calculated CPU Times. The program did this by utilizing a single precision comparison in order to find which one was greater. Whichever one

was established to be bigger would be established as the larger value in the program. This larger value would be divided by the lower value. This calculated value would be printed back out to the user in order to identify how much greater the bigger one was then the smaller one. The third program started by establishing an array with values along with a size for the array. This array was then taken to a loop function. This function utilized a stack in order to add each individual value from the array onto the prior one. Once the loop had finished, the jump returned to its prior position. The calculated sum was then returned to the user prefaced with a statement informing the user of the operation and situation.

### 3.0 Symbol Table

Registers	Usage
<b>\$v0</b>	<b>Contains address of allocated memory</b>
<b>\$a0</b>	<b>The number of bytes to be allocated</b>
<b>\$s0</b>	<b>Used to store input along with output</b>
<b>\$s1</b>	<b>Used to store input along with outputs</b>
<b>\$s2</b>	<b>Used to store user input along with outputs</b>
<b>\$s3</b>	<b>Used to store input along with output</b>
<b>\$s4</b>	<b>Used to store input along with output</b>
<b>\$s5</b>	<b>Used to store input along with output</b>
<b>\$s6</b>	<b>Used to store input along with output</b>
<b>\$t0</b>	<b>Primarily used to store variables, sums, products, differences, and quotients between registers</b>

<b>\$t1</b>	<b>Primarily used to store variables, sums, products, differences, and quotients between registers</b>
<b>\$t2</b>	<b>Primarily used to store variables, sums, products, differences, and quotients between registers</b>
<b>\$f0</b>	<b>Single precision floating point register</b>
<b>\$f1</b>	<b>Single precision floating point register</b>
<b>\$f2</b>	<b>Single precision floating point register</b>
<b>\$f3</b>	<b>Single precision floating point register</b>
<b>\$f4</b>	<b>Single precision floating point register</b>
<b>\$f5</b>	<b>Single precision floating point register</b>
<b>\$f6</b>	<b>Single precision floating point register</b>

## 4.0 Learning Coverage

1. How to utilize a stack in order to push information on top of each and how to pop it off
2. Utilizing two inputted values in order to complete exponent operations
3. How to take two calculated values, compare them, and then conduct operations on them based on this comparison
4. Expansion on how to utilize floating points
5. The ability to utilize jump in MIPS and how to return this jump point

## 5.0 Test Results

## Project 2

The screenshot displays the MARS MIPS simulator interface. The top menu bar includes File, Edit, Run, Settings, Tools, and Help. A toolbar with various icons is located below the menu. The main window is divided into several panes:

- Text Segment:** Shows assembly code with columns for Bkpt, Address, Code, Basic, and Source. The code includes instructions like `lui $f1, 0x00001001`, `l.s $f1, CPUTime`, `lui $f2, 0x00001001`, `l.s $f2, Zero`, `addiu $2, $0, 0x00000004`, `li $v0, 4`, `la $a0, InstructionCountA`, `syscall`, and `addiu $2, $0, 0x00000006`.
- Data Segment:** Shows memory addresses and their corresponding values in different bases (Value (+0), Value (+4), Value (+8), Value (+c), Value (+10), Value (+14)).
- Registers:** A table showing the state of MIPS registers. The 'Coproc 0' tab is selected, displaying registers \$f0 through \$f31. Each register has a Name, Float, and Double column with their respective hexadecimal values.
- Mars Messages:** A log window at the bottom showing program execution messages, including prompts for CPI and Clock rate for various processors and completion messages.

At the top right, there is a notification for 'UPDATES AVAILABLE' and a timestamp of 8:53 PM. The status bar at the bottom indicates 'Run speed at max (no interaction)'.

## Project 3

File Edit Run Settings Tools Help

Run speed at max (no interaction)

UPDATES AVAILABLE  
Do you want to restart to install these updates now or try tonight?

8:53 PM

Registers Coproc 1 Coproc 0

Name	Number	Value
\$8 (vaddr)	8	0x00000000
\$12 (status)	12	0x0000ff11
\$13 (cause)	13	0x00000000
\$14 (epc)	14	0x00000000

Text Segment

Bkpt	Address	Code	Basic	Source
	0x00400000	0x24020000	addiu \$2,\$0,0x00000000	6: li \$v0, 0
	0x00400004	0x3c011001	lui \$1,0x00001001	7: la \$a0, arrayinput
	0x00400008	0x34240000	ori \$4,\$1,0x00000000	
	0x0040000c	0x24050005	addiu \$5,\$0,0x00000005	8: li \$a1, 5
	0x00400010	0x0c18000f	jal 0x0040003c	9: jal Calculate
	0x00400014	0x00024021	addu \$0,\$0,\$2	11: move \$t0, \$v0
	0x00400018	0x24020004	addiu \$2,\$0,0x00000004	13: li \$v0, 4
	0x0040001c	0x3c011001	lui \$1,0x00001001	14: la \$a0, output
	0x00400020	0x34240014	ori \$4,\$1,0x00000014	

Data Segment

Address	Value (+0)	Value (+4)	Value (+8)	Value (+c)	Value (+10)	Value (+14)
0x10010000	0x00000003	0x00000005	0x00000006	0x00000007	0x0000000f	0x20655f
0x10010020	0x73206465	0x66206d75	0x646e756f	0x20796220	0x69646461	0x6120c
0x10010040	0x2073746e	0x7420666f	0x61206568	0x79617272	0x20736920	0x00000e
0x10010060	0x00000000	0x00000000	0x00000000	0x00000000	0x00000000	0x00000e
0x10010080	0x00000000	0x00000000	0x00000000	0x00000000	0x00000000	0x00000e
0x100100a0	0x00000000	0x00000000	0x00000000	0x00000000	0x00000000	0x00000e
0x100100c0	0x00000000	0x00000000	0x00000000	0x00000000	0x00000000	0x00000e

0x10010000 (.data) ✓ Hexadecimal Addresses ✓ Hexadecimal Val

Mars Messages Run / O

The calculated sum found by adding all elements of the array is 31— program is finished running

The calculated sum found by adding all elements of the array is 31  
— program is finished running —

The calculated sum found by adding all elements of the array is 36  
— program is finished running —

Clear