



Calibration Certificate

Gegenstand: Spinning Rotor Gauge (SRG)

Object:

Hersteller: The Manufacturer

Manufacturer:

Typ: A998

Type:

Kennnummer: 99999-998

Serial No.:

Auftraggeber: Physikalisch-Technische Bundesanstalt

Applicant: Abbestraße 2–12

10597 Berlin

Anzahl der Seiten: 4

Number of pages:

Geschäftszeichen: 7.5-9.9-99-98

Reference No.:

Kalibrierzeichen: 75998PTB20

Calibration mark:

Ort der Kalibrierung: PTB Berlin

Location of calibration:

Datum der Kalibrierung: 2020-06-17

Date of calibration:

On behalf of PTB

Im Auftrag Berlin, 2020-07-31 Im Auftrag

Siegel

Seal

Givenname1 Name1 Givenname2 Name2

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On behalf of PTB

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1. Description relating to calibration device

The device was shipped under atmospheric pressure. During the shipping the rotor was fixed by means of a magnet.

The rotor was not baked before calibration.

The previous calibration performed by PTB is described in the calibration certificate 75998 PTB 18.

2. Calibration procedure

The effective accommodation coefficient $\sigma(p)$ was determined between 0.1 Pa and 1 Pa by using the pressures generated in the PTB primary standard SE3 metrologically linked to the primary standard SE2, which is based on the static expansion method. The extrapolated effective accommodation coefficient σ_0 ($p < 1 \times 10^{-2}$ Pa) was determined by extrapolation for $p \to 0$ of the linear regression analysis of the data. A run-in-time of at least 12 h was provided before calibration.

The measurements were performed with 6 readings for each of the 5 target points.

The gas temperature T during calibration using the static expansion method with nitrogen was (295.849 ± 0.033) K at a room temperature of (296.16 ± 0.04) K.

The device was operated with the following setup:

Diameter of the rotor (d): 4.5 mm Density of the rotor (ρ): 7.7 g cm⁻³ Sigma: 1.0 Viscosity: 0 Unit: 1/s (DCR)

For the measurement with nitrogen, a molar mass (M) of 28.013 g mol⁻¹ was used.

A sample of the residual drag (RD) including its scatter was measured before the calibration at a base pressure below 1×10^{-6} Pa. Before the measurement with the calibration gas nitrogen, a RD of 1.5429×10^{-6} s⁻¹ with a standard deviation of 8.0×10^{-10} s⁻¹ was determined. Before each calibration point, RD (6 readings) was checked at the base pressure and subtracted from the subsequent measurement of the relative deceleration rate.

3. Accommodation coefficient

The effective accommodation coefficient was obtained by:

$$\sigma(p_{\rm cal}) = \frac{1}{p_{\rm cal}} \frac{\pi \rho d}{20} \sqrt{\frac{8RT}{\pi M}} \left(-\frac{\dot{\omega}}{\omega} - RD(\omega) \right)$$

with *R* the gas constant, $-\dot{\omega}/\omega$ the relative deceleration rate and $p_{\rm cal}$ the calibration pressure generated by the primary standard. For the calibration with the measurement gas nitrogen the extrapolated effective accommodation coefficient σ_0 for $p < 1 \times 10^{-2}$ Pa was:

$$\sigma_0 = \lim_{p_{\text{cal}} \to 0} \sigma(p_{\text{cal}}) = 0.9555$$
 (nitrogen)

With this σ_0 together with d and ρ from the parameter set under section 2, the SRG controller will give the correct reading of pressure within the measurement uncertainties according to this calibration for

pressures $p < 1 \times 10^{-2}$ Pa. Alternatively, the pressure can be calculated from the relative deceleration rate according to

$$p_{\text{ind}} = \frac{\pi \rho d}{20\sigma_0} \sqrt{\frac{8RT}{\pi M}} \left(-\frac{\dot{\omega}}{\omega} - \text{RD}(\omega) \right).$$

In both cases offset and temperature have to be determined for each measurement.

In the pressure range $p > 1 \times 10^{-2}$ Pa up to p = 2 Pa, the real pressure p will be received by multiplication of the indicated pressure $p_{\rm ind}$ with a correction factor $f(p_{\rm ind})$:

$$p = p_{ind} f(p_{ind})$$

and viscosity = 0 entered in the controller. From our calibration, $f(p_{ind})$ was obtained for this rotor by the following equation:

$$f(p_{\text{ind}}) = (1 + ((0.01796 \pm 0.00060) \text{ Pa}^{-1}) \cdot p_{\text{ind}})$$
 (nitrogen)

4. Uncertainty

The uncertainty of σ_0 at the time of calibration is estimated to 0.26% (this includes the relative deviation of σ_0 with different orientations after a new suspension). The uncertainty stated is the expanded measurement uncertainty obtained by multiplying the standard measurement uncertainty by the coverage factor k = 2. It has been determined in accordance with the "Guide to the Expression of Uncertainty in Measurement (GUM)". The value of the measurand then normally lies, with a probability of approximately 95%, within the attributed coverage interval.

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