

CNN-RNN FORWARD PROXY MODELING FOR CO2 MONITORING

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GEO 391 – Machine Learning Applications in Geoscience

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PROBLEM STATEMENT

Question, Problem, and Proposal

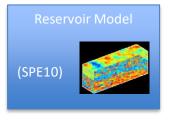


Problem Statement

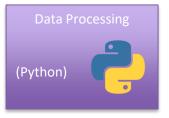
- Reservoir simulation is crucial for subsurface energy resource engineering
 - Often, it is very complex and time-consuming
- Develop a deep learning framework for forward reservoir simulation
 - Better computational efficiency
 - Accuracy trade-off
- Exploit latent space dynamics for timelapse predictions using CNN-RNN architecture



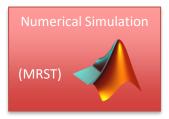
Problem Statement



 $(220 \times 60 \times 85) \rightarrow 85 @ (60 \times 60)$ 1 injector @ (30,30) CO2 @ 5 m^3/day 5 years injection, monitor monthly Tarbert (Gaussian) + Ness (fluvial)



Reshape to images
Data augmentation (rotation)
Random Shuffling
Min-Max Normalization
Train/Test split



Two-phase water-gas model FD + Automatic Differentiation Output: dynamic pressure & saturation fields (255, 3600) & (255, 3600, 60)



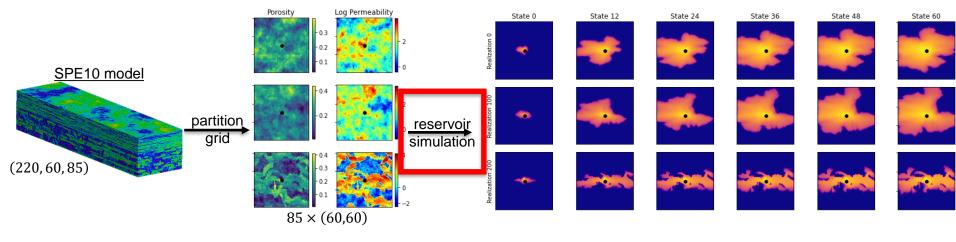
Encoder: Conv2D Recurrent: GRU

Decoder: Conv3DTranspose

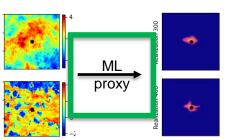
Compile, Fit & Predict

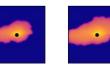


Problem Statement



CNN-RNN proxy to exploit latent space dynamics

















RESERVOIR SIMULATION

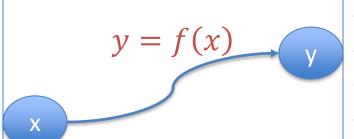
Model construction and computation



Reservoir Simulation

Inputs

- Grid
- Rock properties
- Fluid properties
- Initial state
- Wells
- Boundary conditions
- Schedule
- Solver



Outputs

- Numerical report
- Well solution
- Pressure states
- Saturation states

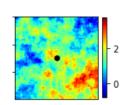
$$\overrightarrow{\nabla} \cdot \left(\rho_{\alpha} \overrightarrow{\mathbf{u}}_{\alpha} \right) + \widetilde{\mathbf{q}}_{\mathbf{m},\alpha} = -\frac{\partial (\phi \mathbf{S}_{\alpha} \rho_{\alpha})}{\partial \mathbf{t}}, \quad \ \widetilde{\mathbf{q}}_{\mathbf{m},\alpha} = \frac{\mathbf{q}_{\mathbf{m},\alpha}}{\mathbf{V}_{\mathbf{b}}},$$

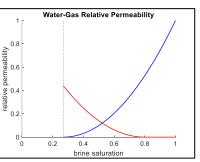
$$\overrightarrow{u}_{a}(x) = -\frac{k_{r,a}K}{\eta_{a}}(\overrightarrow{\nabla}p_{a} - \rho_{a}g\overrightarrow{\nabla}D),$$



Reservoir Simulation

- High-fidelity simulations are performed using MRST
- 255, 2D realizations with 1 injector
 - Initially water saturated
 - CO2 injection @ 5 m³/day
 - 5 years, monitored monthly
 - Automatic Differentiation framework
- Parallelized over 10 cores on an Intel i9-10900K @ 5000 MHz
 - ≈ 20 seconds per realization







DATA PROCESSING

Preparing data for deep learning



- 1. HFS results are sliced to: $x \Rightarrow [poro, perm]$ and $y \Rightarrow [saturation, pressure]$
 - Exported as MATLAB (*.m) files
 - Imported using SciPy

```
Porosity shape: (255, 3600) | Permeability shape: (255, 3600)

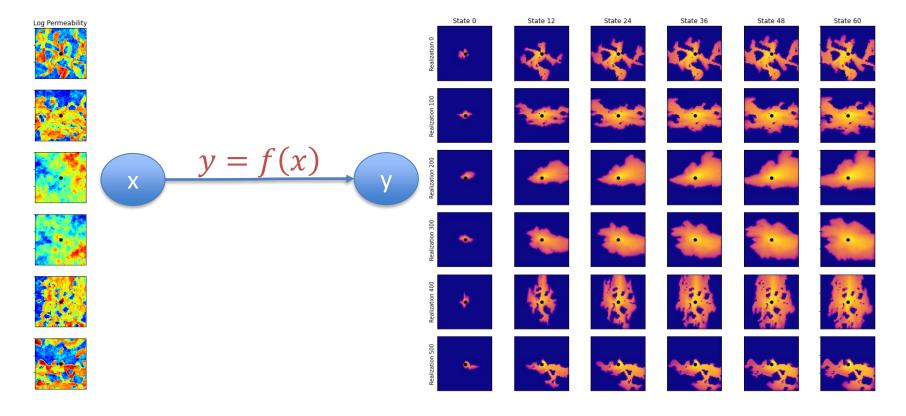
Pressure shape: (255, 3600, 60) | Saturation shape: (255, 3600, 60)

Porosity shape: (255, 60, 60) | Permeability shape: (255, 60, 60)

Pressure shape: (255, 60, 60, 60) | Saturations shape: (255, 60, 60, 60)
```

- Reshape to 2D images and 3D "videos"
- 3. Data augmentation by 90° rotation
- 4. Shuffle concatenated dataset
 - Make proxy agnostic to orientation, learn true flow physics



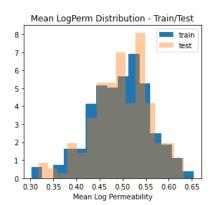




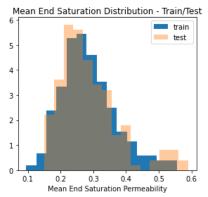
- 5. Min-Max Normalization
 - For each realization & for each state:

$$\hat{y} = \frac{y - y_{\min}}{y_{max} - y_{min}}$$

- 6. Train/Test split
 - Randomly assigned train/test index



```
X_train shape: (340, 60, 60, 1) | y_train shape: (340, 60, 60, 60, 1)
X_test shape: (170, 60, 60, 1) | y_test shape: (170, 60, 60, 60, 1)
```





CNN-RNN PROXY MODEL

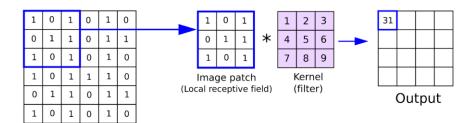
Convolution & Recurrent layers, Latent space representations, and Model building

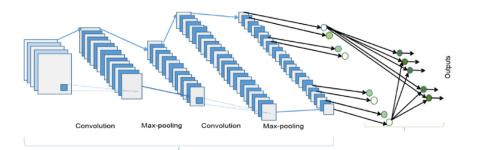


Input

CNN-RNN Proxy Model

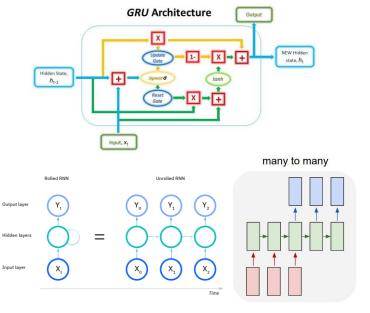
The convolutional layer





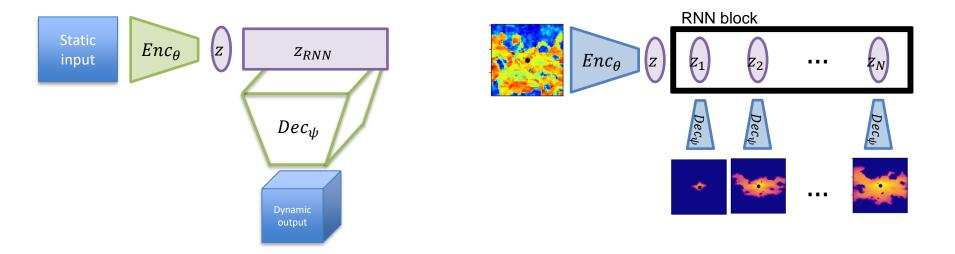
Features extraction

The recurrent layer



Return sequence = *True*





Total # of Parameters: 930,121



The Encoder





 $N_f = 16$



(None, 60, 60, 1)

Conv Block 1

 $N_f = 8$

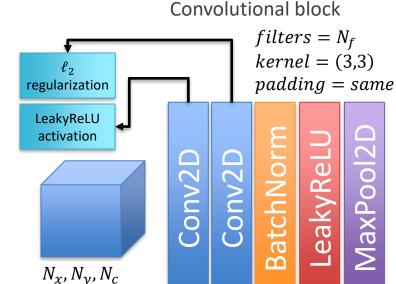
Conv Block 2

 $N_f = 32$

Conv Block 3

Conv Block 4 $N_f = 64$

(None, 3, 3, 64)

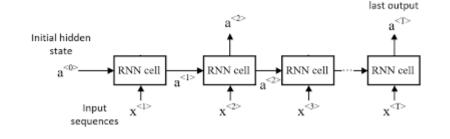






The Recurrent block





(None, 3, 3, 64)

Flatten

RepeatVector

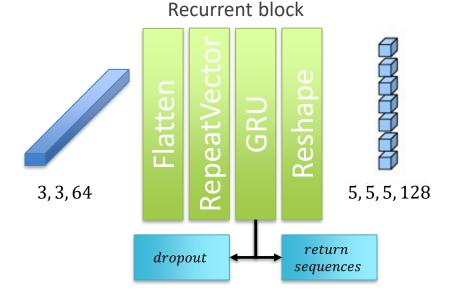
(None, 125, 576)

GRU

(None, 125, 128)

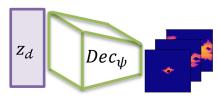
Reshape

(*None*, 5, 5, 5, 128)









(None, 5, 5, 5, 128)

ConvT Block 1

ConvT Block 2

ConvT Block 3

Output Block

(None, 60, 60, 60, 1)

$$N_f = 64$$
, $stride = 1$

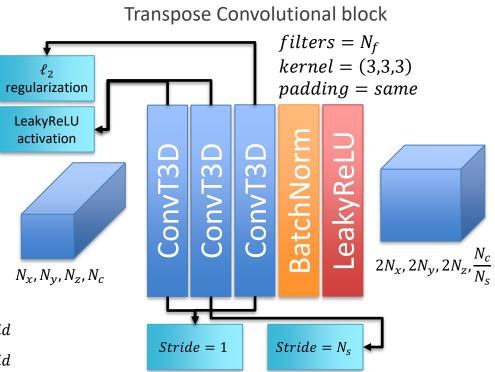
$$N_f = 32$$
, $stride = N_s$

$$N_f = 16$$
, $stride = 1$

Conv3D

ConvT3D $N_f = 8$, sigmoid

 $N_f = 1$, sigmoid





TRAINING & TESTING

Performance and Visualization



Training & Testing

- Compile
 - Optimizer = Nadam (Adam with Nesterov momentum)
 - Loss = MSE
- Fit
 - Epochs = 300
 - Batch size = 40
 - Validation split = 0.25
 - Workers = 10

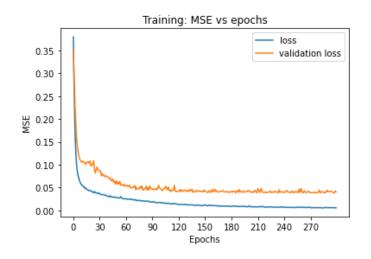
• ≈ 17 minutes on Nyidia RTX 3080

$$\mathbf{g}_{t} \leftarrow \nabla_{\theta_{t-1}} f_{t}(\theta_{t-1})$$

$$\mathbf{m}_{t} \leftarrow \mu_{t} \mathbf{m}_{t-1} + \alpha_{t} \mathbf{g}_{t}$$

$$\theta_{t} \leftarrow \theta_{t-1} - (\mu_{t+1} \mathbf{m}_{t} + \alpha_{t} \mathbf{g}_{t})$$

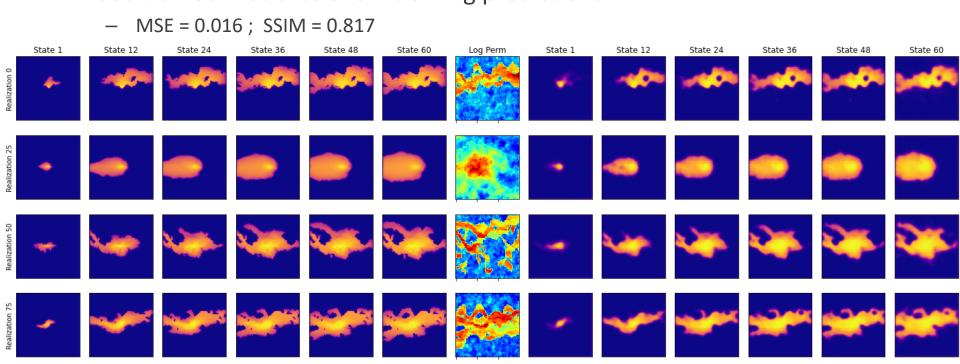
$$\theta_{t} \leftarrow \theta_{t-1} - \alpha_{t} \left(\frac{\mu_{t+1} \mathbf{m}_{t}}{1 - \prod_{i=1}^{t+1} \mu_{i}} + \frac{(1 - \mu_{t}) \mathbf{g}_{t}}{1 - \prod_{i=1}^{t} \mu_{i}} \right)$$





Training & Testing

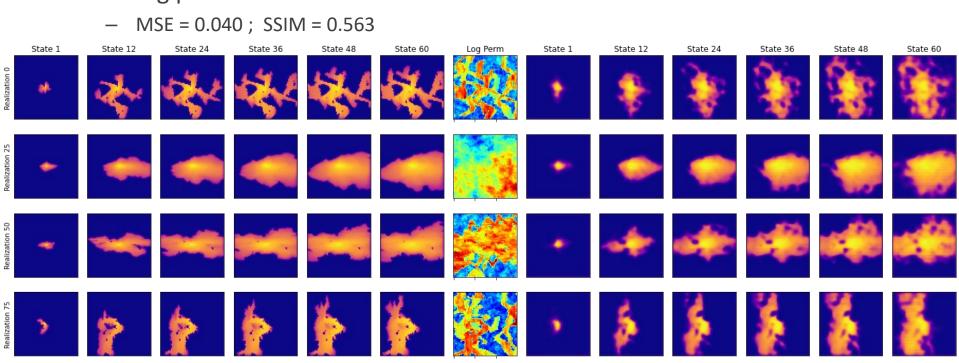
Use trained model to show training predictions





Training & Testing

Testing predictions





RESULTS, DISCUSSION & CONCLUSIONS

Lessons Learned, Possible Applications, and Future Directions



Results, Discussion & Conclusions

- High-Fidelity Simulations
 - Crucial yet costly step in reservoir characterization and forecasting
 - HFS performed in MRST from SPE10 partition
 - Approximately 20 seconds per realizations

- Data: feature (static permeability) & target (dynamic saturation)
- Augmentation by rotation; Random shuffling; Min-Max Normalization; Train/Test split
- Optimized for use in Keras deep learning framework to make proxy model learn the physics of the system



Results, Discussion & Conclusions

Proxy Model

- Block architecture: Encoder Recurrent Decoder
- Approximately 930,000 parameters
- Each prediction is ≈ 0.5 milliseconds $\Rightarrow 40,000$ x speedup!

Results

- The proxy model is extremely efficient in predicting dynamic saturation states from a static permeability map.
- Train MSE, SSIM = 0.016, 0.817
- Test MSE, SSIM = 0.040, 0.563



Results, Discussion & Conclusions

Conclusion

- Including a SSIM loss function to improve testing predictions
- Expand training data through augmentation or generate more realizations
- Applications:
 - Uncertainty quantification
 - History matching / parameter estimation / model calibration
 - Closed-loop optimization
- Other areas:
 - Groundwater flows
 - Contaminant transport
 - Petroleum production



3.

5.

23.

25.

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Thank you! Questions?

Link to notebook:

https://github.com/misaelmmorales/CNN-RNN-CO2

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Machine: *learns*
Me:

Oriyomi Raheem:

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BACKUP SLIDES



Simulation Variables

- Reference pressure: 30 mega Pascals
- Reference temperature: 94°C
- Water compressibility: 0
- Rock compressibility: 4.35×10^{-5} bars
- Water viscosity: 8×10^{-4} Pascal-second
- CO2 viscosity: 5.68×10^{-5} Pascal-second
- Residual water saturation: 0.27
- Residual CO2 saturation: 0.20
- Water viscosity: 1000



Simulation Variables (continued)

- Grid size: 60x60x1
- Grid dimensions: 20x10x5 ft
- Initial reservoir pressure: 3000 psia
- Initial reservoir saturation: [0,1] [gas, water]
- Total simulation time: 5 years
- Monitor steps: 1 month
- Total steps: 60
- Wellbore radius: 0.05
- AD Solver: TwoPhaseWaterGasModel



Proxy Model Variables

- L2 regularization: 1e-4
- LeakyReLU alpha: 0.3
- RNN dropout: 0.2
- Nadam learning rate: 5e-4