# **fdasrsf Documentation**

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A python package for functional data analysis using the square root slope framework and curves using the square root velocity framework which performs pair-wise and group-wise alignment as well as modeling using functional component analysis and regression.

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### **FUNCTIONAL ALIGNMENT**

Group-wise function alignment using SRSF framework and Dynamic Programming

moduleauthor:: Derek Tucker <jdtuck@sandia.gov>

time\_warping.align\_fPCA (f, time, num\_comp=3, showplot=True, smoothdata=False, cores=-1) aligns a collection of functions while extracting principal components. The functions are aligned to the principal components

#### **Parameters**

- f (np.ndarray) numpy ndarray of shape (M,N) of N functions with M samples
- time (np.ndarray) vector of size M describing the sample points
- num\_comp number of fPCA components
- **showplot** Shows plots of results using matplotlib (default = T)
- $smooth_{data} (bool) Smooth$  the data using a box filter (default = F)
- cores number of cores for parallel (default = -1 (all))

**Return type** tuple of numpy array

**Return fn** aligned functions - numpy ndarray of shape (M,N) of N functions with M samples

Return qn aligned srvfs - similar structure to fn

Return q0 original srvf - similar structure to fn

Return mqn srvf mean or median - vector of length M

Return gam warping functions - similar structure to fn

Return q\_pca srsf principal directions

Return f\_pca functional principal directions

Return latent latent values

Return coef coefficients

Return U eigenvectors

Return orig\_var Original Variance of Functions

Return amp\_var Amplitude Variance

Return phase\_var Phase Variance

time\_warping.align\_fPLS(f, g, time, comps=3, showplot=True, smoothdata=False, delta=0.01, max itr=100)

This function aligns a collection of functions while performing principal least squares

### **Parameters**

- **f** (np.ndarray) numpy ndarray of shape (M,N) of N functions with M samples
- g (np.ndarray) numpy ndarray of shape (M,N) of N functions with M samples
- time (np.ndarray) vector of size M describing the sample points
- comps number of fPLS components
- **showplot** Shows plots of results using matplotlib (default = T)
- smooth\_data (bool) Smooth the data using a box filter (default = F)
- delta gradient step size
- max\_itr maximum number of iterations

**Return type** tuple of numpy array

Return fn aligned functions - numpy ndarray of shape (M,N) of N

functions with M samples :return gn: aligned functions - numpy ndarray of shape (M,N) of N functions with M samples :return qfn: aligned srvfs - similar structure to fn :return qgn: aligned srvfs - similar structure to fn :return qg0: original srvf - similar structure to fn :return qg0: original srvf - similar structure to fn :return qg0: original srvf - similar structure to fn :return wqf: srsf principal weight functions :return wqg: srsf principal weight functions :return wg: srsf principal weight functions :return cost: cost function value

### class time\_warping.fdawarp(f, time)

This class provides alignment methods for functional data using the SRVF framework

Usage: obj = fdawarp(f,t)

- $\mathbf{f} (M,N)$ : matrix defining N functions of M samples
- time time vector of length M
- fn aligned functions
- qn aligned srvfs
- q0 initial srvfs
- **fmean** function mean
- mqn mean srvf
- gam warping functions
- psi srvf of warping functions
- **stats** alignment statistics
- qun cost function
- lambda lambda
- method optimization method
- gamI invserse warping function
- rsamps random samples
- **fs** random aligned functions
- gams random warping functions

- ft random warped functions
- qs random aligned srvfs
- type alignment type
- mcmc mcmc output if bayesian

Author: J. D. Tucker (JDT) < idtuck AT sandia.gov > Date: 15-Mar-2018

```
gauss model (n=1, sort \ samples=False)
```

This function models the functional data using a Gaussian model extracted from the principal components of the srvfs

### **Parameters**

- n (integer) number of random samples
- sort\_samples (bool) sort samples (default = T)

```
joint_gauss_model (n=1, no=3)
```

This function models the functional data using a joint Gaussian model extracted from the principal components of the srsfs

### **Parameters**

- n (integer) number of random samples
- **no** (*integer*) number of principal components (default = 3)

This function aligns a collection of functions using the elastic square-root slope (srsf) framework.

Usage: obj.multiple\_align\_functions(mu) obj.multiple\_align\_functions(lambda)

obj.multiple\_align\_functions(lambda, ...)

### **Parameters**

- mu vector of function to align to
- omethod optimization method (DP, DP2, RBFGS) (default = DP)
- **smoothdata** (bool) Smooth the data using a box filter (default = F)
- **parallel** run in parallel (default = F)
- lam (double) controls the elasticity (default = 0)
- cores number of cores for parallel (default = -1 (all))

### plot()

plot plot functional alignment results

Usage: obj.plot()

**srsf\_align** (*method='mean'*, *omethod='DP'*, *smoothdata=False*, *parallel=False*, *lam=0.0*, *cores=-1*) This function aligns a collection of functions using the elastic square-root slope (srsf) framework.

- method (string) warp calculate Karcher Mean or Median (options = "mean" or "median") (default="mean")
- omethod optimization method (DP, DP2, RBFGS) (default = DP)
- **smoothdata** (bool) Smooth the data using a box filter (default = F)

- parallel run in parallel (default = F)
- lam (double) controls the elasticity (default = 0)
- cores number of cores for parallel (default = -1 (all))

Examples >>> import tables >>> fun=tables.open\_file("../Data/simu\_data.h5") >>> f = fun.root.f[:] >>> f = f.transpose() >>> time = fun.root.time[:] >>> obj = fs.fdawarp(f,time) >>> obj.srsf\_align()

time\_warping.normal(loc=0.0, scale=1.0, size=None)

Draw random samples from a normal (Gaussian) distribution.

The probability density function of the normal distribution, first derived by De Moivre and 200 years later by both Gauss and Laplace independently<sup>2</sup>, is often called the bell curve because of its characteristic shape (see the example below).

The normal distributions occurs often in nature. For example, it describes the commonly occurring distribution of samples influenced by a large number of tiny, random disturbances, each with its own unique distribution<sup>2</sup>.

**Note:** New code should use the normal method of a default\_rng() instance instead; see *random-quick-start*.

loc [float or array\_like of floats] Mean ("centre") of the distribution.

**scale** [float or array\_like of floats] Standard deviation (spread or "width") of the distribution. Must be non-negative.

size [int or tuple of ints, optional] Output shape. If the given shape is, e.g., (m, n, k), then m \* n \* k samples are drawn. If size is None (default), a single value is returned if loc and scale are both scalars. Otherwise, np.broadcast (loc, scale).size samples are drawn.

**out** [ndarray or scalar] Drawn samples from the parameterized normal distribution.

scipy.stats.norm [probability density function, distribution or] cumulative density function, etc.

Generator.normal: which should be used for new code.

The probability density for the Gaussian distribution is

$$p(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}},$$

where  $\mu$  is the mean and  $\sigma$  the standard deviation. The square of the standard deviation,  $\sigma^2$ , is called the variance.

The function has its peak at the mean, and its "spread" increases with the standard deviation (the function reaches 0.607 times its maximum at  $x + \sigma$  and  $x - \sigma^2$ ). This implies that normal is more likely to return samples lying close to the mean, rather than those far away.

Draw samples from the distribution:

```
>>> mu, sigma = 0, 0.1 # mean and standard deviation
>>> s = np.random.normal(mu, sigma, 1000)
```

Verify the mean and the variance:

<sup>&</sup>lt;sup>2</sup> P. R. Peebles Jr., "Central Limit Theorem" in "Probability, Random Variables and Random Signal Principles", 4th ed., 2001, pp. 51, 51, 125.

```
>>> abs(mu - np.mean(s))
0.0 # may vary
```

```
>>> abs(sigma - np.std(s, ddof=1))
0.1 # may vary
```

Display the histogram of the samples, along with the probability density function:

Two-by-four array of samples from N(3, 6.25):

```
>>> np.random.normal(3, 2.5, size=(2, 4))
array([[-4.49401501, 4.00950034, -1.81814867, 7.29718677], # random
[ 0.39924804, 4.68456316, 4.99394529, 4.84057254]]) # random
```

time\_warping.pairwise\_align\_bayes (fli, f2i, time, mcmcopts=None)

This function aligns two functions using Bayesian framework. It will align f2 to f1. It is based on mapping warping functions to a hypersphere, and a subsequent exponential mapping to a tangent space. In the tangent space, the Z-mixture pCN algorithm is used to explore both local and global structure in the posterior distribution.

The Z-mixture pCN algorithm uses a mixture distribution for the proposal distribution, controlled by input parameter zpcn. The zpcn\$betas must be between 0 and 1, and are the coefficients of the mixture components, with larger coefficients corresponding to larger shifts in parameter space. The zpcn["probs"] give the probability of each shift size.

Usage: out = pairwise align bayes(f1i, f2i, time) out = pairwise align bayes(f1i, f2i, time, mcmcopts)

### Parameters

- fli vector defining M samples of function 1
- **f2i** vector defining M samples of function 2
- time time vector of length M
- mcmopts dict of mcmc parameters

default mcmc options: tmp = {"betas":np.array([0.5,0.5,0.005,0.0001]),"probs":np.array([0.1,0.1,0.7,0.1])} mcmcopts = {"iter":2\*(10\*\*4), "burnin":np.minimum(5\*(10\*\*3),2\*(10\*\*4)//2),

```
"alpha0":0.1, "beta0":0.1,"zpcn":tmp,"propvar":1, "initcoef":np.repeat(0,20), "npoints":200, "extrainfo":True}
```

:rtype collection containing :return f2\_warped: aligned f2 :return gamma: warping function :return g\_coef: final g\_coef :return psi: final psi :return sigma1: final sigma

if extrainfo :return accept: accept of psi samples :return betas\_ind :return logl: log likelihood :return gamma\_mat: posterior gammas :return gamma\_stats: posterior gamma stats :return xdist: phase distance posterior :return ydist: amplitude distance posterior)

```
\texttt{time\_warping.rand} (d0, d1, ..., dn)
```

Random values in a given shape.

**Note:** This is a convenience function for users porting code from Matlab, and wraps *random\_sample*. That function takes a tuple to specify the size of the output, which is consistent with other NumPy functions like *numpy.zeros* and *numpy.ones*.

Create an array of the given shape and populate it with random samples from a uniform distribution over [0, 1).

**d0**, **d1**, ..., **dn** [int, optional] The dimensions of the returned array, must be non-negative. If no argument is given a single Python float is returned.

```
out [ndarray, shape (d0, d1, ..., dn)] Random values.
```

### random

### FUNCTIONAL PRINCIPAL COMPONENT ANALYSIS

Vertical and Horizontal Functional Principal Component Analysis using SRSF

moduleauthor:: Derek Tucker <jdtuck@sandia.gov>

 ${\tt class} \ \, {\tt fPCA.fdahpca} \, (\textit{fdawarp})$ 

This class provides horizontal fPCA using the SRVF framework

Usage: obj = fdahpca(warp\_data)

#### **Parameters**

- warp\_data fdawarp class with alignment data
- gam\_pca warping functions principal directions
- psi\_pca srvf principal directions
- latent latent values
- **U** eigenvectors
- coef coeficients
- **vec** shooting vectors
- mu Karcher Mean
- tau principal directions

Author: J. D. Tucker (JDT) <jdtuck AT sandia.gov> Date: 15-Mar-2018

```
calc_fpca(no=3)
```

This function calculates horizontal functional principal component analysis on aligned data

**Parameters** no (int) – number of components to extract (default = 3)

Return type fdahpca object of numpy ndarray

**Return q\_pca** srsf principal directions

**Return f\_pca** functional principal directions

Return latent latent values

Return coef coefficients

Return U eigenvectors

plot()

plot plot elastic horizontal fPCA results

Usage: obj.plot()

## class fPCA.fdajpca(fdawarp) This class provides joint fPCA using the SRVF framework Usage: obj = fdajpca(warp\_data) **Parameters** • warp data – fdawarp class with alignment data • q\_pca – srvf principal directions • **f\_pca** – f principal directions • latent – latent values • coef – principal coefficients • id – point used for f(0)• mqn - mean srvf • **U** – eigenvectors • mu\_psi - mean psi • **mu\_g** – mean g • C – scaling value • **stds** – geodesic directions Author: J. D. Tucker (JDT) < jdtuck AT sandia.gov > Date: 18-Mar-2018 calc\_fpca (no=3, id=None) This function calculates joint functional principal component analysis on aligned data **Parameters** • **no** (*int*) – number of components to extract (default = 3) • id(int) – point to use for f(0) (default = midpoint) **Return type** fdajpca object of numpy ndarray **Return q\_pca** srsf principal directions **Return f\_pca** functional principal directions Return latent latent values Return coef coefficients Return U eigenvectors plot()

plot plot elastic vertical fPCA result

Usage: obj.plot()

### class fPCA.fdavpca(fdawarp)

This class provides vertical fPCA using the SRVF framework

Usage: obj = fdavpca(warp\_data)

- warp\_data fdawarp class with alignment data
- q\_pca srvf principal directions

- **f\_pca** f principal directions
- latent latent values
- coef principal coefficients
- id point used for f(0)
- mqn mean srvf
- **U** eigenvectors
- **stds** geodesic directions

Author: J. D. Tucker (JDT) < jdtuck AT sandia.gov> Date: 15-Mar-2018

```
calc_fpca (no=3, id=None)
```

This function calculates vertical functional principal component analysis on aligned data

### **Parameters**

- **no** (*int*) number of components to extract (default = 3)
- **id** (*int*) point to use for f(0) (default = midpoint)

Return type fdavpca object containing

Return q\_pca srsf principal directions

Return f\_pca functional principal directions

Return latent latent values

Return coef coefficients

Return U eigenvectors

### plot()

plot plot elastic vertical fPCA result Usage: obj.plot()

### **ELASTIC FUNCTIONAL BOXPLOTS**

**Elastic Functional Boxplots** 

moduleauthor:: Derek Tucker <jdtuck@sandia.gov>

class boxplots.ampbox(fdawarp)

This class provides amplitude boxplot for functional data using the SRVF framework

Usage: obj = ampbox(warp\_data)

### **Parameters**

- warp\_data (fdawarp) fdawarp class with alignment data
- Q1 First quartile
- Q3 Second quartile
- Q1a First quantile based on alpha
- Q3a Second quantile based on alpha
- minn minimum extreme function
- maxx maximum extreme function
- outlier\_index indexes of outlier functions
- **f\_median** median function
- q median median srvf
- plt surface plot mesh

Author: J. D. Tucker (JDT) <jdtuck AT sandia.gov> Date: 15-Mar-2018

```
construct\_boxplot(alpha=0.05, k\_a=1)
```

This function constructs the amplitude boxplot using the elastic square-root slope (srsf) framework.

### **Parameters**

- **alpha** quantile value (e.g.,=.05, i.e., 95%)
- **k\_a** scalar for outlier cutoff (e.g.,=1)

class boxplots.phbox (fdawarp)

This class provides phase boxplot for functional data using the SRVF framework

Usage: obj = phbox(warp\_data)

### **Parameters**

• warp data (fdawarp) - fdawarp class with alignment data

- Q1 First quartile
- Q3 Second quartile
- Q1a First quantile based on alpha
- Q3a Second quantile based on alpha
- minn minimum extreme function
- maxx maximum extreme function
- outlier\_index indexes of outlier functions
- median\_x median warping function
- psi\_median median srvf of warping function
- plt surface plot mesh

Author: J. D. Tucker (JDT) <jdtuck AT sandia.gov> Date: 15-Mar-2018

### construct\_boxplot (alpha=0.05, k\_a=1)

This function constructs phase boxplot for functional data using the elastic square-root slope (srsf) framework.

### **Parameters**

- **alpha** quantile value (e.g.,=.05, i.e., 95%)
- **k\_a** scalar for outlier cutoff (e.g.,=1)

### plot()

plot box plot and surface plot

Usage: obj.plot()

**CHAPTER** 

**FOUR** 

### **FUNCTIONAL PRINCIPAL LEAST SQUARES**

Partial Least Squares using SVD

moduleauthor:: Derek Tucker <jdtuck@sandia.gov>

fPLS.pls\_svd(time, qf, qg, no, alpha=0.0)

This function computes the partial least squares using SVD

### **Parameters**

- time vector describing time samples
- $\mathbf{qf}$  numpy ndarray of shape (M,N) of N functions with M samples
- qg numpy ndarray of shape (M,N) of N functions with M samples
- **no** number of components
- alpha amount of smoothing (Default = 0.0 i.e., none)

Return type numpy ndarray

Return wqf f weight function

Return wqg g weight function

Return alpha smoothing value

Return values singular values

### **ELASTIC REGRESSION**

Warping Invariant Regression using SRSF

moduleauthor:: Derek Tucker <jdtuck@sandia.gov>

regression.elastic\_logistic (f, y, time, B=None, df=20, max\_itr=20, cores=-1, smooth=False)
This function identifies a logistic regression model with phase-variablity using elastic methods

### **Parameters**

- **f** (np.ndarray) numpy ndarray of shape (M,N) of N functions with M samples
- **y** numpy array of labels (1/-1)
- time (np.ndarray) vector of size M describing the sample points
- B optional matrix describing Basis elements
- **df** number of degrees of freedom B-spline (default 20)
- max\_itr maximum number of iterations (default 20)
- cores number of cores for parallel processing (default all)

**Return type** tuple of numpy array

Return alpha alpha parameter of model

Return beta beta(t) of model

**Return fn** aligned functions - numpy ndarray of shape (M,N) of M

functions with N samples :return qn: aligned srvfs - similar structure to fn :return gamma: calculated warping functions :return q: original training SRSFs :return B: basis matrix :return b: basis coefficients :return Loss: logistic loss

```
regression.elastic_mlogistic(f, y, time, B=None, df=20, max_itr=20, cores=-1, delta=0.01, parallel=True, smooth=False)
```

This function identifies a multinomial logistic regression model with phase-variablity using elastic methods

- **f** (np.ndarray) numpy ndarray of shape (M,N) of N functions with M samples
- $y \text{numpy array of labels } \{1, 2, ..., m\}$  for m classes
- time (np.ndarray) vector of size M describing the sample points
- **B** optional matrix describing Basis elements
- **df** number of degrees of freedom B-spline (default 20)
- max itr maximum number of iterations (default 20)

• cores – number of cores for parallel processing (default all)

**Return type** tuple of numpy array

Return alpha alpha parameter of model

Return beta beta(t) of model

Return fn aligned functions - numpy ndarray of shape (M,N) of N

functions with M samples :return qn: aligned srvfs - similar structure to fn :return gamma: calculated warping functions :return q: original training SRSFs :return B: basis matrix :return b: basis coefficients :return Loss: logistic loss

regression.elastic\_prediction(f, time, model, y=None, smooth=False)

This function performs prediction from an elastic regression model with phase-variablity

#### **Parameters**

- **f** numpy ndarray of shape (M,N) of N functions with M samples
- time vector of size M describing the sample points
- model indentified model from elastic\_regression
- y truth, optional used to calculate SSE

Return type tuple of numpy array

Return alpha alpha parameter of model

Return beta beta(t) of model

Return fn aligned functions - numpy ndarray of shape (M,N) of N

functions with M samples :return qn: aligned srvfs - similar structure to fn :return gamma: calculated warping functions :return q: original training SRSFs :return B: basis matrix :return b: basis coefficients :return SSE: sum of squared error

```
regression.elastic_regression(f, y, time, B=None, lam=0, df=20, max\_itr=20, cores=- 1, smooth=False)
```

This function identifies a regression model with phase-variablity using elastic methods

### **Parameters**

- **f** (np.ndarray) numpy ndarray of shape (M,N) of N functions with M samples
- **y** numpy array of N responses
- time (np. ndarray) vector of size M describing the sample points
- **B** optional matrix describing Basis elements
- lam regularization parameter (default 0)
- **df** number of degrees of freedom B-spline (default 20)
- max\_itr maximum number of iterations (default 20)
- cores number of cores for parallel processing (default all)

**Return type** tuple of numpy array

Return alpha alpha parameter of model

Return beta beta(t) of model

Return fn aligned functions - numpy ndarray of shape (M,N) of M

functions with N samples :return qn: aligned srvfs - similar structure to fn :return gamma: calculated warping functions :return q: original training SRSFs :return B: basis matrix :return b: basis coefficients :return SSE: sum of squared error

regression.logistic\_warp (beta, time, q, y) calculates optimal warping for function logistic regression

#### **Parameters**

- beta numpy ndarray of shape (M,N) of N functions with M samples
- time vector of size N describing the sample points
- q numpy ndarray of shape (M,N) of N functions with M samples
- y numpy ndarray of shape (1,N) responses

Return type numpy array

Return gamma warping function

regression.logit\_gradient (b, X, y) calculates gradient of the logistic loss

#### **Parameters**

- **b** numpy ndarray of shape (M,N) of N functions with M samples
- **X** numpy ndarray of shape (M,N) of N functions with M samples
- y numpy ndarray of shape (1, N) responses

Return type numpy array

Return grad gradient of logisitc loss

regression.logit\_hessian (s, b, X, y) calculates hessian of the logistic loss

#### **Parameters**

- $\mathbf{s}$  numpy ndarray of shape (M,N) of N functions with M samples
- **b** numpy ndarray of shape (M,N) of N functions with M samples
- **X** numpy ndarray of shape (M,N) of N functions with M samples
- y numpy ndarray of shape (1,N) responses

Return type numpy array

**Return out** hessian of logistic loss

regression.logit\_loss(b, X, y)

logistic loss function, returns Sum{-log(phi(t))}

### **Parameters**

- **b** numpy ndarray of shape (M,N) of N functions with M samples
- **X** numpy ndarray of shape (M,N) of N functions with M samples
- y numpy ndarray of shape (1,N) of N responses

Return type numpy array

Return out loss value

```
regression.mlogit_gradient (b, X, Y)
```

calculates gradient of the multinomial logistic loss

#### **Parameters**

- **b** numpy ndarray of shape (M,N) of N functions with M samples
- **X** numpy ndarray of shape (M,N) of N functions with M samples
- y numpy ndarray of shape (1,N) responses

Return type numpy array

Return grad gradient

```
regression.mlogit_loss(b, X, Y)
```

calculates multinomial logistic loss (negative log-likelihood)

### **Parameters**

- **b** numpy ndarray of shape (M,N) of N functions with M samples
- **X** numpy ndarray of shape (M,N) of N functions with M samples
- **y** numpy ndarray of shape (1,N) responses

Return type numpy array

Return nll negative log-likelihood

regression.mlogit\_warp\_grad(alpha, beta, time, q, y, max\_itr=8000, tol=1e-10, delta=0.008, display=0)

calculates optimal warping for functional multinomial logistic regression

#### **Parameters**

- alpha scalar
- beta numpy ndarray of shape (M,N) of N functions with M samples
- time vector of size M describing the sample points
- $\mathbf{q}$  numpy ndarray of shape (M,N) of N functions with M samples
- y numpy ndarray of shape (1,N) responses
- max\_itr maximum number of iterations (Default=8000)
- tol stopping tolerance (Default=1e-10)
- **delta** gradient step size (Default=0.008)
- **display** display iterations (Default=0)

**Return type** tuple of numpy array

Return gam\_old warping function

```
regression.phi(t)
```

calculates logistic function, returns  $1/(1 + \exp(-t))$ 

**Parameters** t – scalar

Return type numpy array

Return out return value

regression.regression\_warp (beta, time, q, y, alpha) calculates optimal warping for function linear regression

### **Parameters**

- beta numpy ndarray of shape (M,N) of M functions with N samples
- time vector of size N describing the sample points
- **q** numpy ndarray of shape (M,N) of M functions with N samples
- **y** numpy ndarray of shape (1,N) of M functions with N samples

responses :param alpha: numpy scalar

Return type numpy array

Return gamma\_new warping function

### **ELASTIC PRINCIPAL COMPONENT REGRESSION**

Warping Invariant PCR Regression using SRSF

moduleauthor:: Derek Tucker <jdtuck@sandia.gov>

### class pcr\_regression.elastic\_lpcr\_regression(f, y, time)

This class provides elastic logistic pcr regression for functional data using the SRVF framework accounting for warping

Usage: obj = elastic\_lpcr\_regression(f,y,time)

### **Parameters**

- $\mathbf{f} (M,N)$  % matrix defining N functions of M samples
- y response vector of length N (-1/1)
- warp\_data fdawarp object of alignment
- pca class dependent on fPCA method used object of fPCA

:param information :param alpha: intercept :param b: coefficient vector :param Loss: logistic loss :param PC: probability of classification :param ylabels: predicted labels

Author: J. D. Tucker (JDT) < jdtuck AT sandia.gov > Date: 18-Mar-2018

**calc\_model** (*pca\_method='combined'*, *no=5*, *smooth\_data=False*, *sparam=25*, *parallel=False*)

This function identifies a logistic regression model with phase-variability using elastic pca

### **Parameters**

- pca\_method string specifing pca method (options = "combined", "vert", or "horiz", default = "combined")
- no scalar specify number of principal components (default=5)
- **smooth\_data** smooth data using box filter (default = F)
- **sparam** number of times to apply box filter (default = 25)
- parallel calculate in parallel (default = F)

predict (newdata=None)

This function performs prediction on regression model on new data if available or current stored data in object Usage: obj.predict()

obj.predict(newdata)

### **Parameters**

• **newdata** (dict) – dict containing new data for prediction (needs the keys below, if None predicts on training data)

- $\mathbf{f} (M,N)$  matrix of functions
- time vector of time points
- **y** truth if available
- smooth smooth data if needed
- sparam number of times to run filter

### **class** pcr regression.**elastic mlpcr regression**(f, y, time)

This class provides elastic multinomial logistic per regression for functional data using the SRVF framework accounting for warping

Usage: obj = elastic\_mlpcr\_regression(f,y,time)

#### **Parameters**

- $\mathbf{f} (M,N)$  % matrix defining N functions of M samples
- y response vector of length N
- Y coded label matrix
- warp\_data fdawarp object of alignment
- pca class dependent on fPCA method used object of fPCA

:param information :param alpha: intercept :param b: coefficient vector :param Loss: logistic loss :param PC: probability of classification :param ylabels: predicted labels :param

Author: J. D. Tucker (JDT) < jdtuck AT sandia.gov > Date: 18-Mar-2018

**calc\_model** (*pca\_method='combined'*, *no=5*, *smooth\_data=False*, *sparam=25*, *parallel=False*)

This function identifies a logistic regression model with phase-variability using elastic pca

### **Parameters**

- **f** (np.ndarray) numpy ndarray of shape (M,N) of N functions with M samples
- **y** numpy array of N responses
- time (np.ndarray) vector of size M describing the sample points
- pca\_method string specifing pca method (options = "combined", "vert", or "horiz", default = "combined")
- no scalar specify number of principal components (default=5)
- **smooth\_data** smooth data using box filter (default = F)
- sparam number of times to apply box filter (default = 25)
- parallel run model in parallel (default = F)

### predict (newdata=None)

This function performs prediction on regression model on new data if available or current stored data in object Usage: obj.predict()

obj.predict(newdata)

- **newdata** (dict) dict containing new data for prediction (needs the keys below, if None predicts on training data)
- $\mathbf{f} (M,N)$  matrix of functions

- time vector of time points
- y truth if available
- smooth smooth data if needed
- sparam number of times to run filter

### class pcr\_regression.elastic\_pcr\_regression(f, y, time)

This class provides elastic pcr regression for functional data using the SRVF framework accounting for warping

Usage: obj = elastic\_pcr\_regression(f,y,time)

### **Parameters**

- $\mathbf{f} (M,N)$  % matrix defining N functions of M samples
- y response vector of length N
- warp\_data fdawarp object of alignment
- pca class dependent on fPCA method used object of fPCA
- alpha intercept
- **b** coefficient vector
- **SSE** sum of squared errors

Author: J. D. Tucker (JDT) <jdtuck AT sandia.gov> Date: 18-Mar-2018

 ${\tt calc\_model}\ (pca\_method='combined',\ no=5,\ smooth\_data=False,\ sparam=25,\ parallel=False,\ C=None)$ 

This function identifies a regression model with phase-variability using elastic pca

### **Parameters**

- pca\_method string specifing pca method (options = "combined", "vert", or "horiz", default = "combined")
- no scalar specify number of principal components (default=5)
- **smooth\_data** smooth data using box filter (default = F)
- **sparam** number of times to apply box filter (default = 25)
- **parallel** run in parallel (default = F)
- **C** scale balance parameter for combined method (default = None)

### predict (newdata=None)

This function performs prediction on regression model on new data if available or current stored data in object Usage: obj.predict()

obj.predict(newdata)

- **newdata** (dict) dict containing new data for prediction (needs the keys below, if None predicts on training data)
- $\mathbf{f} (M,N)$  matrix of functions
- time vector of time points
- y truth if available
- smooth smooth data if needed

• sparam – number of times to run filter

### **ELASTIC FUNCTIONAL TOLERANCE BOUNDS**

Functional Tolerance Bounds using SRSF

moduleauthor:: Derek Tucker <jdtuck@sandia.gov>

tolerance.bootTB (f, time, a=0.5, p=0.99, B=500, no=5, parallel=True)

This function computes tolerance bounds for functional data containing phase and amplitude variation using bootstrap sampling

#### **Parameters**

- f (np.ndarray) numpy ndarray of shape (M,N) of N functions with M samples
- time (np.ndarray) vector of size M describing the sample points
- $\mathbf{a}$  confidence level of tolerance bound (default = 0.05)
- $\mathbf{p}$  coverage level of tolerance bound (default = 0.99)
- B number of bootstrap samples (default = 500)
- no number of principal components (default = 5)
- parallel enable parallel processing (default = T)

Return type tuple of boxplot objects

Return amp amplitude tolerance bounds

Rtype out\_med ampbox object

Return ph phase tolerance bounds

Rtype out\_med phbox object

Return out\_med alignment results

Rtype out\_med fdawarp object

tolerance.mvtol\_region (x, alpha, P, B)

Computes tolerance factor for multivariate normal

Krishnamoorthy, K. and Mondal, S. (2006), Improved Tolerance Factors for Multivariate Normal Distributions, Communications in Statistics - Simulation and Computation, 35, 461–478.

- $\mathbf{x} (M,N)$  matrix defining N variables of M samples
- alpha confidence level
- **P** coverage level
- **B** number of bootstrap samples

### Return type double

Return tol tolerance factor

```
tolerance.pcaTB (f, time, a=0.5, p=0.99, no=5, parallel=True)
```

This function computes tolerance bounds for functional data containing phase and amplitude variation using fPCA

### **Parameters**

- **f** (np.ndarray) numpy ndarray of shape (M,N) of N functions with M samples
- time (np.ndarray) vector of size M describing the sample points
- $\mathbf{a}$  confidence level of tolerance bound (default = 0.05)
- $\mathbf{p}$  coverage level of tolerance bound (default = 0.99)
- **no** number of principal components (default = 5)
- parallel enable parallel processing (default = T)

Return type tuple of boxplot objects

**Return warp** alignment data from time\_warping

Return pca functional pca from jointFPCA

Return tol tolerance factor

tolerance.rwishart (df, p)

Computes a random wishart matrix

#### **Parameters**

- **df** degree of freedom
- p number of dimensions

Return type double

Return R matrix

### SRVF GEODESIC COMPUTATION

geodesic calculation for SRVF (curves) open and closed)

moduleauthor:: Derek Tucker <jdtuck@sandia.gov>

geodesic.back\_parallel\_transport (u1, alpha, basis, T=100, k=5) backwards parallel translates q1 and q2 along manifold

### **Parameters**

- u1 numpy ndarray of shape (2,M) of M samples
- alpha numpy ndarray of shape (2,M) of M samples
- basis list numpy ndarray of shape (2,M) of M samples
- $\mathbf{T}$  Number of samples of curve (Default = 100)
- $\mathbf{k}$  number of samples along path (Default = 5)

Return type numpy ndarray

Return utilde translated vector

geodesic.calc\_alphadot (alpha, basis, T=100, k=5) calculates derivative along the path alpha

### **Parameters**

- alpha numpy ndarray of shape (2,M) of M samples
- basis list of numpy ndarray of shape (2,M) of M samples
- $\mathbf{T}$  Number of samples of curve (Default = 100)
- $\mathbf{k}$  number of samples along path (Default = 5)

**Return type** numpy ndarray

Return alphadot derivative of alpha

geodesic.calculate\_energy (alphadot, T=100, k=5) calculates energy along path

### **Parameters**

- alphadot numpy ndarray of shape (2,M) of M samples
- $\mathbf{T}$  Number of samples of curve (Default = 100)
- $\mathbf{k}$  number of samples along path (Default = 5)

Return type numpy scalar

### **Return E** energy

geodesic.calculate\_gradE (u, utilde, T=100, k=5) calculates gradient of energy along path

#### **Parameters**

- **u** numpy ndarray of shape (2,M) of M samples
- utilde numpy ndarray of shape (2,M) of M samples
- $\mathbf{T}$  Number of samples of curve (Default = 100)
- $\mathbf{k}$  number of samples along path (Default = 5)

Return type numpy scalar

**Return gradE** gradient of energy

Return normgradE norm of gradient of energy

geodesic.cov\_integral (alpha, alphadot, basis, T=100, k=5)

Calculates covariance along path alpha

#### **Parameters**

- alpha numpy ndarray of shape (2,M) of M samples (first curve)
- alphadot numpy ndarray of shape (2,M) of M samples
- basis list numpy ndarray of shape (2,M) of M samples
- $\mathbf{T}$  Number of samples of curve (Default = 100)
- $\mathbf{k}$  number of samples along path (Default = 5)

Return type numpy ndarray

Return u covariance

### geodesic.find\_basis\_normal\_path(alpha, k=5)

computes orthonormalized basis vectors to the normal space at each of the k points (q-functions) of the path alpha

### **Parameters**

- alpha numpy ndarray of shape (2,M) of M samples (path)
- $\mathbf{k}$  number of samples along path (Default = 5)

Return type numpy ndarray

**Return basis** basis vectors along the path

```
geodesic.geod_dist_path_strt(beta, k=5)
```

calculate geodisc distance for path straightening

### **Parameters**

- beta numpy ndarray of shape (2,M) of M samples
- $\mathbf{k}$  number of samples along path (Default = 5)

Return type numpy scalar

Return dist geodesic distance

```
geodesic.geod sphere (beta1, beta2, k=5)
```

This function caluclates the geodecis between open curves beta1 and beta2 with k steps along path

### **Parameters**

- beta1 numpy ndarray of shape (2,M) of M samples
- beta2 numpy ndarray of shape (2,M) of M samples
- $\mathbf{k}$  number of samples along path (Default = 5)

Return type numpy ndarray

Return dist geodesic distance

Return path geodesic path

Return O rotation matrix

```
geodesic.init_path_geod(beta1, beta2, T=100, k=5)
```

Initializes a path in cal{C}. beta1, beta2 are already standardized curves. Creates a path from beta1 to beta2 in shape space, then projects to the closed shape manifold.

### **Parameters**

- beta1 numpy ndarray of shape (2,M) of M samples (first curve)
- **beta2** numpy ndarray of shape (2,M) of M samples (end curve)
- $\mathbf{T}$  Number of samples of curve (Default = 100)
- $\mathbf{k}$  number of samples along path (Default = 5)

Return type numpy ndarray

Return alpha a path between two q-functions

Return beta a path between two curves

Return O rotation matrix

```
geodesic.init_path_rand(beta1, beta_mid, beta2, T=100, k=5)
```

Initializes a path in cal{C}. beta1, beta\_mid beta2 are already standardized curves. Creates a path from beta1 to beta\_mid to beta2 in shape space, then projects to the closed shape manifold.

### **Parameters**

- beta1 numpy ndarray of shape (2,M) of M samples (first curve)
- **betamid** numpy ndarray of shape (2,M) of M samples (mid curve)
- beta2 numpy ndarray of shape (2,M) of M samples (end curve)
- $\mathbf{T}$  Number of samples of curve (Default = 100)
- k number of samples along path (Default = 5)

**Return type** numpy ndarray

Return alpha a path between two q-functions

Return beta a path between two curves

Return O rotation matrix

```
geodesic.path straightening (beta1, beta2, betamid, init='rand', T=100, k=5)
```

Perform path straigtening to find geodesic between two shapes in either the space of closed curves or the space of affine standardized curves. This algorithm follows the steps outlined in section 4.6 of the manuscript.

### **Parameters**

• beta1 – numpy ndarray of shape (2,M) of M samples (first curve)

- **beta2** numpy ndarray of shape (2,M) of M samples (end curve)
- **betamid** numpy ndarray of shape (2,M) of M samples (mid curve Default = NULL, only needed for init "rand")
- init initilizae path geodesic or random (Default = "rand")
- **T** Number of samples of curve (Default = 100)
- $\mathbf{k}$  number of samples along path (Default = 5)

**Return type** numpy ndarray

Return dist geodesic distance

Return path geodesic path

Return pathsque geodesic path sequence

Return E energy

 $\verb|geodesic.update_path| (alpha, beta, gradE, delta, T=100, k=5)$ 

Update the path along the direction -gradE

#### **Parameters**

- alpha numpy ndarray of shape (2,M) of M samples
- beta numpy ndarray of shape (2,M) of M samples
- gradE numpy ndarray of shape (2,M) of M samples
- **delta** gradient paramenter
- $\mathbf{T}$  Number of samples of curve (Default = 100)
- $\mathbf{k}$  number of samples along path (Default = 5)

Return type numpy scalar

**Return alpha** updated path of srvfs

Return beta updated path of curves

# **CHAPTER**

# NINE

# **UTILITY FUNCTIONS**

Utility functions for SRSF Manipulations

moduleauthor:: Derek Tucker < jdtuck@sandia.gov>

utility\_functions.SqrtMean(gam)

calculates the srsf of warping functions with corresponding shooting vectors

Parameters gam – numpy ndarray of shape (M,N) of M warping functions with N samples

Return type 2 numpy ndarray and vector

Return mu Karcher mean psi function

**Return gam\_mu** vector of dim N which is the Karcher mean warping function

**Return psi** numpy ndarray of shape (M,N) of M SRSF of the warping functions

**Return vec** numpy ndarray of shape (M,N) of M shooting vectors

utility\_functions.SqrtMeanInverse(gam)

finds the inverse of the mean of the set of the diffeomorphisms gamma

Parameters gam – numpy ndarray of shape (M,N) of M warping functions with N samples

Return type vector

Return gamI inverse of gam

utility functions. SqrtMedian (gam)

calculates the median srsf of warping functions with corresponding shooting vectors

**Parameters** gam – numpy ndarray of shape (M,N) of M warping functions with N samples

Return type 2 numpy ndarray and vector

Return gam\_median Karcher median warping function

Return psi\_meidan vector of dim N which is the Karcher median srsf function

**Return psi** numpy ndarray of shape (M,N) of M SRSF of the warping functions

Return vec numpy ndarray of shape (M,N) of M shooting vectors

utility\_functions.cumtrapzmid(x, y, c, mid)

cumulative trapezoidal numerical integration taken from midpoint

#### **Parameters**

- $\mathbf{x}$  vector of size N describing the time samples
- y vector of size N describing the function
- c midpoint

• mid - midpiont location

Return type vector

Return fa cumulative integration

utility\_functions.diffop(n, binsize=1)

Creates a second order differential operator

#### **Parameters**

- n dimension
- binsize dx (default = 1)

Return type numpy ndarray

**Return m** matrix describing differential operator

utility\_functions.elastic\_distance(f1,f2,time,method='DP',lam=0.0)

" calculates the distances between function, where f1 is aligned to f2. In other words calculates the elastic distances

#### **Parameters**

- **f1** vector of size N
- **f2** vector of size N
- time vector of size N describing the sample points
- lam controls the elasticity (default = 0.0)

Return type scalar

Return Dy amplitude distance

Return Dx phase distance

utility\_functions.f\_K\_fold(Nobs, K=5)

generates sample indices for K-fold cross validation

:param Nobs number of observations :param K number of folds

Return type numpy ndarray

**Return train** train indexes (Nobs\*(K-1)/K X K)

**Return test** test indexes (Nobs\*(1/K) X K)

utility\_functions.**f\_to\_srsf** (*f*, *time*, *smooth=False*) converts f to a square-root slope function (SRSF)

## **Parameters**

- **f** vector of size N samples
- time vector of size N describing the sample points

**Return type** vector

Return q srsf of f

utility\_functions.geigen(Amat, Bmat, Cmat)
generalized eigenvalue problem of the form

max tr L'AM / sqrt(tr L'BL tr M'CM) w.r.t. L and M

:param Amat numpy ndarray of shape (M,N):param Bmat numpy ndarray of shape (M,N):param Bmat numpy ndarray of shape (M,N)

Return type numpy ndarray

Return values eigenvalues

Return Lmat left eigenvectors

**Return Mmat** right eigenvectors

utility\_functions.gradient\_spline(time, f, smooth=False)

This function takes the gradient of f using b-spline smoothing

#### **Parameters**

- time vector of size N describing the sample points
- $\mathbf{f}$  numpy ndarray of shape (M,N) of M functions with N samples
- smooth smooth data (default = F)

Return type tuple of numpy ndarray

**Return f0** smoothed functions functions

**Return g** first derivative of each function

Return g2 second derivative of each function

utility\_functions.innerprod\_q(time, q1, q2)

calculates the innerproduct between two srsfs

:param time vector describing time samples :param q1 vector of srsf 1 :param q2 vector of srsf 2

Return type scalar

Return val inner product value

utility\_functions.invertGamma(gam)

finds the inverse of the diffeomorphism gamma

Parameters gam – vector describing the warping function

Return type vector

Return gamI inverse of gam

utility\_functions.optimum\_reparam (q1, time, q2, method='DP', lam=0.0, f1o=0.0, f2o=0.0) calculates the warping to align srsf q2 to q1

#### **Parameters**

- q1 vector of size N or array of NxM samples of first SRSF
- time vector of size N describing the sample points
- q2 vector of size N or array of NxM samples samples of second SRSF
- method method to apply optimization (default="DP") options are "DP", "DP2" and "RBFGS"
- lam controls the amount of elasticity (default = 0.0)

Return type vector

**Return gam** describing the warping function used to align q2 with q1

utility\_functions.optimum\_reparam\_pair (q, time, q1, q2, lam=0.0) calculates the warping to align srsf pair q1 and q2 to q

#### **Parameters**

- q vector of size N or array of NxM samples of first SRSF
- time vector of size N describing the sample points
- q1 vector of size N or array of NxM samples samples of second SRSF
- q2 vector of size N or array of NxM samples samples of second SRSF
- lam controls the amount of elasticity (default = 0.0)

## Return type vector

**Return gam** describing the warping function used to align q2 with q1

utility\_functions.outlier\_detection (q, time, mq, k=1.5) calculates outlier's using geodesic distances of the SRSFs from the median

#### **Parameters**

- **q** numpy ndarray of N x M of M SRS functions with N samples
- time vector of size N describing the sample points
- mq median calculated using time\_warping.srsf\_align()
- $\mathbf{k}$  cutoff threshold (default = 1.5)

**Returns** q\_outlier: outlier functions

utility\_functions.randomGamma (gam, num)
generates random warping functions

## **Parameters**

- gam numpy ndarray of N x M of M of warping functions
- num number of random functions

Returns rgam: random warping functions

utility\_functions.resamplefunction (x, n) resample function using n points

#### **Parameters**

- **x** functions
- n number of points

**Return type** numpy array

Return xn resampled function

utility\_functions.rgam(N, sigma, num)
Generates random warping functions

#### **Parameters**

- N length of warping function
- **sigma** variance of warping functions
- num number of warping functions

**Returns** gam: numpy ndarray of warping functions

```
utility_functions.smooth_data(f, sparam)
```

This function smooths a collection of functions using a box filter

#### **Parameters**

- **f** numpy ndarray of shape (M,N) of M functions with N samples
- **sparam** Number of times to run box filter (default = 25)

**Return type** numpy ndarray

Return f smoothed functions functions

```
utility_functions.srsf_to_f (q, time, f0=0.0) converts q (srsf) to a function
```

#### **Parameters**

- q vector of size N samples of srsf
- time vector of size N describing time sample points
- **f0** initial value

Return type vector

**Return f** function

```
utility_functions.update_progress(progress)
```

This function creates a progress bar

Parameters progress – fraction of progress

```
utility_functions.warp_f_gamma(time, f, gam)
```

warps a function f by gam

:param time vector describing time samples :param q vector describing srsf :param gam vector describing warping function

Return type numpy ndarray

Return f\_temp warped srsf

```
utility_functions.warp_q_gamma(time, q, gam) warps a srsf q by gam
```

:param time vector describing time samples :param q vector describing srsf :param gam vector describing warping function

Return type numpy ndarray

Return q temp warped srsf

```
utility_functions.zero_crossing (Y, q, bt, time, y\_max, y\_min, gmax, gmin) finds zero-crossing of optimal gamma, gam = s*gmax + (1-s)*gmin from elastic regression model
```

#### **Parameters**

- **Y** response
- **q** predicitve function
- bt basis function
- time time samples
- y max maximum repsonse for warping function gmax
- y min minimum response for warping function gmin

- gmax max warping function
- gmin min warping fucntion

Return type numpy array

Return gamma optimal warping function

## **CHAPTER**

# TEN

# **CURVE FUNCTIONS**

```
functions for SRVF curve manipulations
moduleauthor:: Derek Tucker <jdtuck@sandia.gov>
curve_functions.Basis_Normal_A(q)
     Find Normal Basis
          Parameters q – numpy ndarray (n,T) defining T points on n dimensional SRVF
     :rtype list :return delg: basis
curve_functions.calc_j(basis)
     Calculates Jacobian matrix from normal basis
          Parameters basis – list of numpy ndarray of shape (2,M) of M samples basis
          Return type numpy ndarray
          Return j Jacobian
curve_functions.calculate_variance(beta)
     This function calculates variance of curve beta
          Parameters beta – numpy ndarray of shape (2,M) of M samples
          Return type numpy ndarray
          Return variance variance
curve functions.calculatecentroid(beta)
     This function calculates centroid of a parameterized curve
          Parameters beta – numpy ndarray of shape (2,M) of M samples
          Return type numpy ndarray
          Return centroid center coordinates
\verb|curve_functions.curve_to_q| (\textit{beta}, \textit{scale=True}, \textit{mode='O'}) \\
     This function converts curve beta to srvf q
          Parameters
                 • beta – numpy ndarray of shape (2,M) of M samples
                 • scale – scale curve to length 1
                 • mode – Open ('O') or closed curve ('C') (default 'O')
```

Return type numpy ndarray

Return q srvf of curve

## Return len length of curve

curve\_functions.curve\_zero\_crossing(Y, beta, bt, y\_max, y\_min, gmax, gmin)

finds zero-crossing of optimal gamma, gam = s\*gmax + (1-s)\*gmin from elastic curve regression model

#### **Parameters**

- Y response
- beta predicitve function
- bt basis function
- y\_max maximum repsonse for warping function gmax
- y\_min minimum response for warping function gmin
- gmax max warping function
- gmin min warping fucntion

Return type numpy array

Return gamma optimal warping function

Return O hat rotation matrix

```
curve_functions.elastic_distance_curve (beta1, beta2)
```

Calculates the two elastic distances between two curves :param beta1: numpy ndarray of shape (2,M) of M samples :param beta2: numpy ndarray of shape (2,M) of M samples

Return type scalar

Return dist distance

```
curve_functions.elastic_shooting (q1, v)
```

Calculates shooting vector from v to q1

#### **Parameters**

- q1 vector of srvf
- **v** shooting vector

:rtype numpy ndarray :return q2n: vector of srvf

```
curve_functions.find_basis_normal(q)
```

Finds the basis normal to the srvf

**Parameters** q1 – numpy ndarray of shape (2,M) of M samples

**Return type** list of numpy ndarray

Return basis list containing basis vectors

```
curve_functions.find_best_rotation (q1, q2)
```

This function calculates the best rotation between two srvfs using procustes rigid alignment

#### **Parameters**

- $\mathbf{q1}$  numpy ndarray of shape (2,M) of M samples
- q2 numpy ndarray of shape (2,M) of M samples

Return type numpy ndarray

**Return q2new** optimal rotated q2 to q1

Return R rotation matrix

## curve functions.find rotation and seed coord(beta1, beta2)

This function returns a candidate list of optimally oriented and registered (seed) shapes w.r.t. beta1

#### **Parameters**

- beta1 numpy ndarray of shape (2,M) of M samples
- beta2 numpy ndarray of shape (2,M) of M samples

Return type numpy ndarray

Return beta2new optimal rotated beta2 to beta1

Return O rotation matrix

Return tau seed

#### curve\_functions.find\_rotation\_and\_seed\_q(q1, q2)

This function returns a candidate list of optimally oriented and registered (seed) shapes w.r.t. beta1

#### **Parameters**

- q1 numpy ndarray of shape (2,M) of M samples
- **q2** numpy ndarray of shape (2,M) of M samples

**Return type** numpy ndarray

Return beta2new optimal rotated beta2 to beta1

Return O rotation matrix

Return tau seed

```
curve_functions.gram_schmidt(basis)
```

Performs Gram Schmidt Orthogonlization of a basis\_o

param basis list of numpy ndarray of shape (2,M) of M samples

rtype list of numpy ndarray

return basis\_o orthogonlized basis

## curve\_functions.group\_action\_by\_gamma(q, gamma)

This function reparamerized srvf q by gamma

#### **Parameters**

- $\mathbf{f}$  numpy ndarray of shape (2,M) of M samples
- gamma numpy ndarray of shape (2,M) of M samples

**Return type** numpy ndarray

Return qn reparatermized srvf

# curve\_functions.group\_action\_by\_gamma\_coord(f, gamma)

This function reparamerized curve f by gamma

#### **Parameters**

- $\mathbf{f}$  numpy ndarray of shape (2,M) of M samples
- gamma numpy ndarray of shape (2,M) of M samples

Return type numpy ndarray

Return fn reparatermized curve

```
curve_functions.innerprod_q2 (q1, q2)
```

This function calculates the inner product in srvf space

#### **Parameters**

- q1 numpy ndarray of shape (2,M) of M samples
- **q2** numpy ndarray of shape (2,M) of M samples

Return type numpy ndarray

Return val inner product

```
curve_functions.inverse_exp(q1, q2, beta2)
```

Calculate the inverse exponential to obtain a shooting vector from q1 to q2 in shape space of open curves

#### **Parameters**

- q1 numpy ndarray of shape (2,M) of M samples
- q2 numpy ndarray of shape (2,M) of M samples
- beta2 numpy ndarray of shape (2,M) of M samples

Return type numpy ndarray

**Return v** shooting vectors

```
curve_functions.inverse_exp_coord(beta1, beta2)
```

Calculate the inverse exponential to obtain a shooting vector from beta1 to beta2 in shape space of open curves

#### **Parameters**

- beta1 numpy ndarray of shape (2,M) of M samples
- beta2 numpy ndarray of shape (2,M) of M samples

**Return type** numpy ndarray

Return v shooting vectors

Return dist distance

```
curve_functions.optimum_reparam_curve (q1, q2, lam=0.0) calculates the warping to align srsf q2 to q1
```

### **Parameters**

- q1 matrix of size nxN or array of NxM samples of first SRVF
- time vector of size N describing the sample points
- q2 matrix of size nxN or array of NxM samples samples of second SRVF
- lam controls the amount of elasticity (default = 0.0)

Return type vector

Return gam describing the warping function used to align q2 with q1

```
curve_functions.parallel_translate (w, q1, q2, basis, mode=0) parallel translates q1 and q2 along manifold
```

## **Parameters**

- w numpy ndarray of shape (2,M) of M samples
- q1 numpy ndarray of shape (2,M) of M samples
- q2 numpy ndarray of shape (2,M) of M samples

- basis list of numpy ndarray of shape (2,M) of M samples
- mode open 0 or closed curves 1 (default 0)

Return type numpy ndarray

Return wbar translated vector

curve functions.pre proc curve (beta, T=100)

This function prepcoessed a curve beta to set of closed curves

#### **Parameters**

- beta numpy ndarray of shape (2,M) of M samples
- $\mathbf{T}$  number of samples (default = 100)

Return type numpy ndarray

Return betanew projected beta

Return qnew projected srvf

**Return A** alignment matrix (not used currently)

curve\_functions.project\_curve(q)

This function projects srvf q to set of close curves

**Parameters q** – numpy ndarray of shape (2,M) of M samples

Return type numpy ndarray

Return qproj project srvf

 $\verb|curve_functions.project_tangent| (w, q, basis)$ 

projects srvf to tangent space w using basis

## **Parameters**

- w numpy ndarray of shape (2,M) of M samples
- $\mathbf{q}$  numpy ndarray of shape (2,M) of M samples
- basis list of numpy ndarray of shape (2,M) of M samples

Return type numpy ndarray

Return wproj projected q

curve\_functions.psi(x, a, q)

This function formats variance output

#### **Parameters**

- $\mathbf{x}$  numpy ndarray of shape (2,M) of M samples curve
- **a** numpy ndarray of shape (2,1) mean
- **q** numpy ndarray of shape (2,M) of M samples srvf

Return type numpy ndarray

Return psi1 variance

Return psi2 cross variance

Return psi3 curve end

Return psi4 curve end

```
curve_functions.q_to_curve(q, scale=1)
```

This function converts srvf to beta

#### **Parameters**

- **q** numpy ndarray of shape (n,M) of M samples
- scale scale of curve

Return type numpy ndarray

Return beta parameterized curve

```
curve_functions.resamplecurve(x, N=100, mode='O')
```

This function resamples a curve to have N samples

#### **Parameters**

- $\mathbf{x}$  numpy ndarray of shape (2,M) of M samples
- N Number of samples for new curve (default = 100)
- mode Open ('O') or closed curve ('C') (default 'O')

Return type numpy ndarray

Return xn resampled curve

Parameters beta – numpy ndarray of shape (2,M) of M samples

Return type numpy ndarray

Return beta\_scaled scaled curve

Return scale scale factor used

```
curve_functions.shift_f (f, tau) shifts a curve f by tau
```

### **Parameters**

- **f** numpy ndarray of shape (2,M) of M samples
- tau scalar

Return type numpy ndarray

Return fn shifted curve

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