https://colab.research.google.com/drive/1u-610KA-urqfJjDH5O0pecwfP--V9DQs?usp=sharing

模型任務:聲音特徵分類原本的模型架構:

```
class Classifier(nn.Module):
 def __init__(self, d_model=80, n_spks=600, dropout=0.1):
     super().__init__()
     # Project the dimension of features from that of input into d model.
     self.prenet = nn.Linear(40, d model)
     # TODO:
        Change Transformer to Conformer.
        https://arxiv.org/abs/2005.08100
     self.encoder_layer = nn.TransformerEncoderLayer(
         d model=d model, dim feedforward=256, nhead=2
     # self.encoder = nn.TransformerEncoder(self.encoder layer, num layers=2)
     # Project the the dimension of features from d model into speaker nums.
     self.pred layer = nn.Sequential(
         nn.Linear(d model, d model),
         nn.Sigmoid(),
         nn.Linear(d_model, n_spks),
def forward(self, mels):
     args:
        mels: (batch size, length, 40)
     return:
        out: (batch size, n_spks)
     # out: (batch size, length, d_model)
     out = self.prenet(mels)
     # out: (length, batch size, d model)
     out = out.permute(1, 0, 2)
     # The encoder layer expect features in the shape of (length, batch size, d model).
     out = self.encoder_layer(out)
     # out: (batch size, length, d_model)
    out = out.transpose(0, 1)
     # mean pooling
     stats = out.mean(dim=1)
     # out: (batch, n_spks)
     out = self.pred layer(stats)
     return out
```

修改過後的模型架構: 增加 self-attention pooling class SelfAttentionPooling(nn.Module): def __init__(self, d_model): super(SelfAttentionPooling, self).__init__() self.attention = nn.Linear(d_model, 1) def forward(self, x): # x: (length, batch size, d_model) attn_weights = torch.softmax(self.attention(x), dim=0) attn_output = torch.sum(attn_weights * x, dim=0) # (ba return attn_output class Classifier (nn. Module): def __init__(self, d_model=80, n_spks=600, dropout=0.1): super().__init__() self.prenet = nn.Linear(40, d_model) self.self_attention_pooling = SelfAttentionPooling(d_model) self.encoder_layer = nn.TransformerEncoderLayer(d_model=d_model, dim_feedforward=256, nhead=2 self.pred_layer = nn.Sequential(nn.Linear(d_model, d_model), nn. Sigmoid(), nn.Linear(d_model, n_spks),) def forward(self, mels): args: mels: (batch size, length, 40) return: out: (batch size, n_spks) out = self.prenet(mels) out = out.permute(1, 0, 2)out = self.encoder_layer(out) out = self.self_attention_pooling(out) out = self.pred_layer(out)

修改過後的效果:53.2%

return out

```
Train: 100% 2000/2000 [00:42<00:00, 46.67 step/s, accuracy=0.59, loss=1.87, step=7e+4] Valid: 100% 5664/5667 [00:02<00:00, 1911.74 uttr/s, accuracy=0.53, loss=2.17] Train: 0% 0/2000 [00:00<?, ? step/s] Step 70000, best model saved. (accuracy=0.5323)
```