

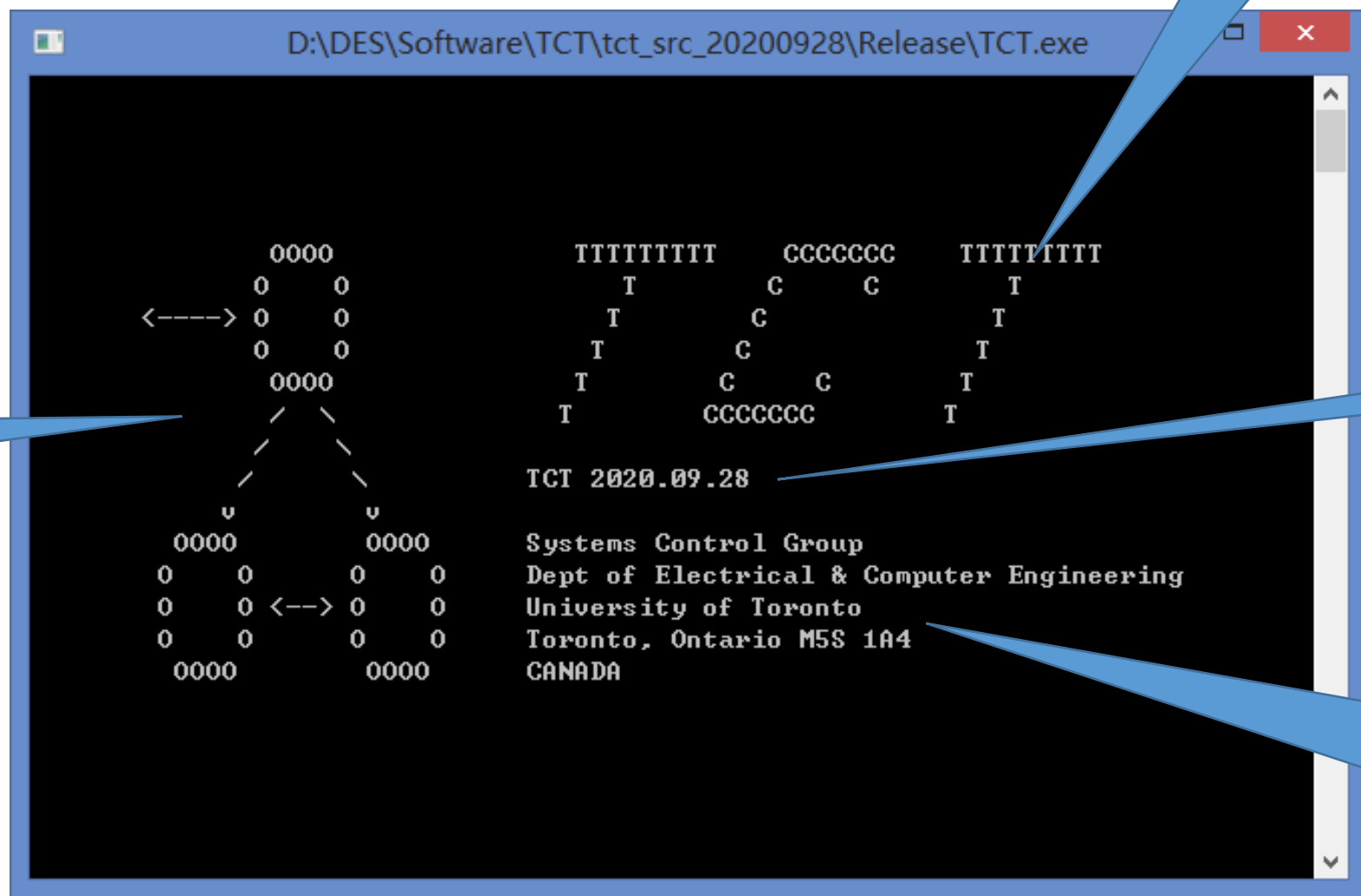
# Introduction to TCT

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2022.04.21

# Welcom page of TCT



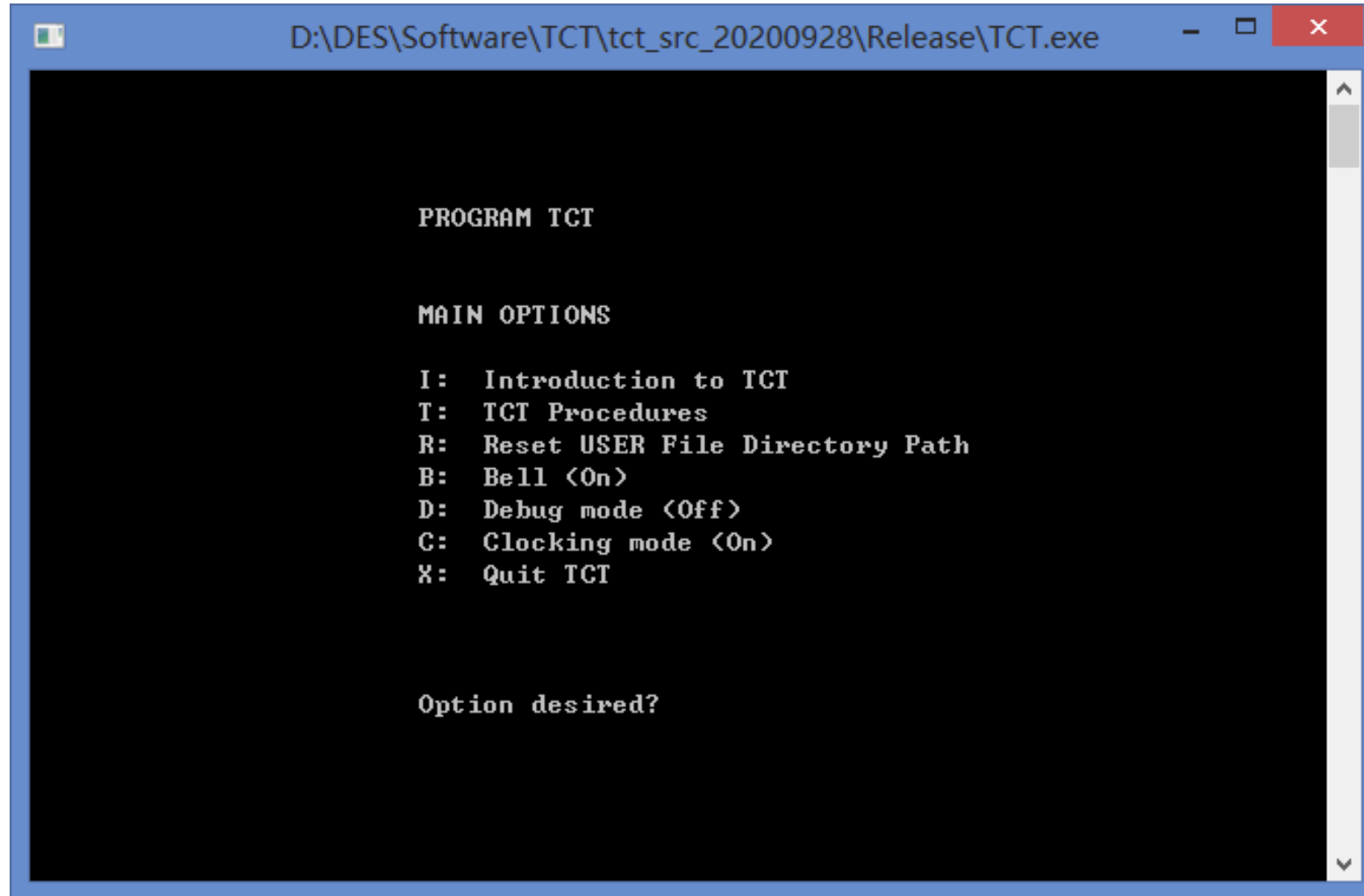
Name of TCT

Date of update

Created and developed by members (including me) of Prof. Wonham's group

Transition graph of a DES generator

# Main menu of TCT

A screenshot of a Windows application window titled "D:\DES\Software\TCT\tct\_src\_20200928\Release\TCT.exe". The window has a blue title bar with standard minimize, maximize, and close buttons. The main content area has a black background with white text. The text is centered and reads: "PROGRAM TCT", followed by "MAIN OPTIONS", then a list of options: "I: Introduction to TCT", "T: TCT Procedures", "R: Reset USER File Directory Path", "B: Bell <On>", "D: Debug mode <Off>", "C: Clocking mode <On>", and "X: Quit TCT". At the bottom, it asks "Option desired?". A vertical scrollbar is visible on the right side of the window.

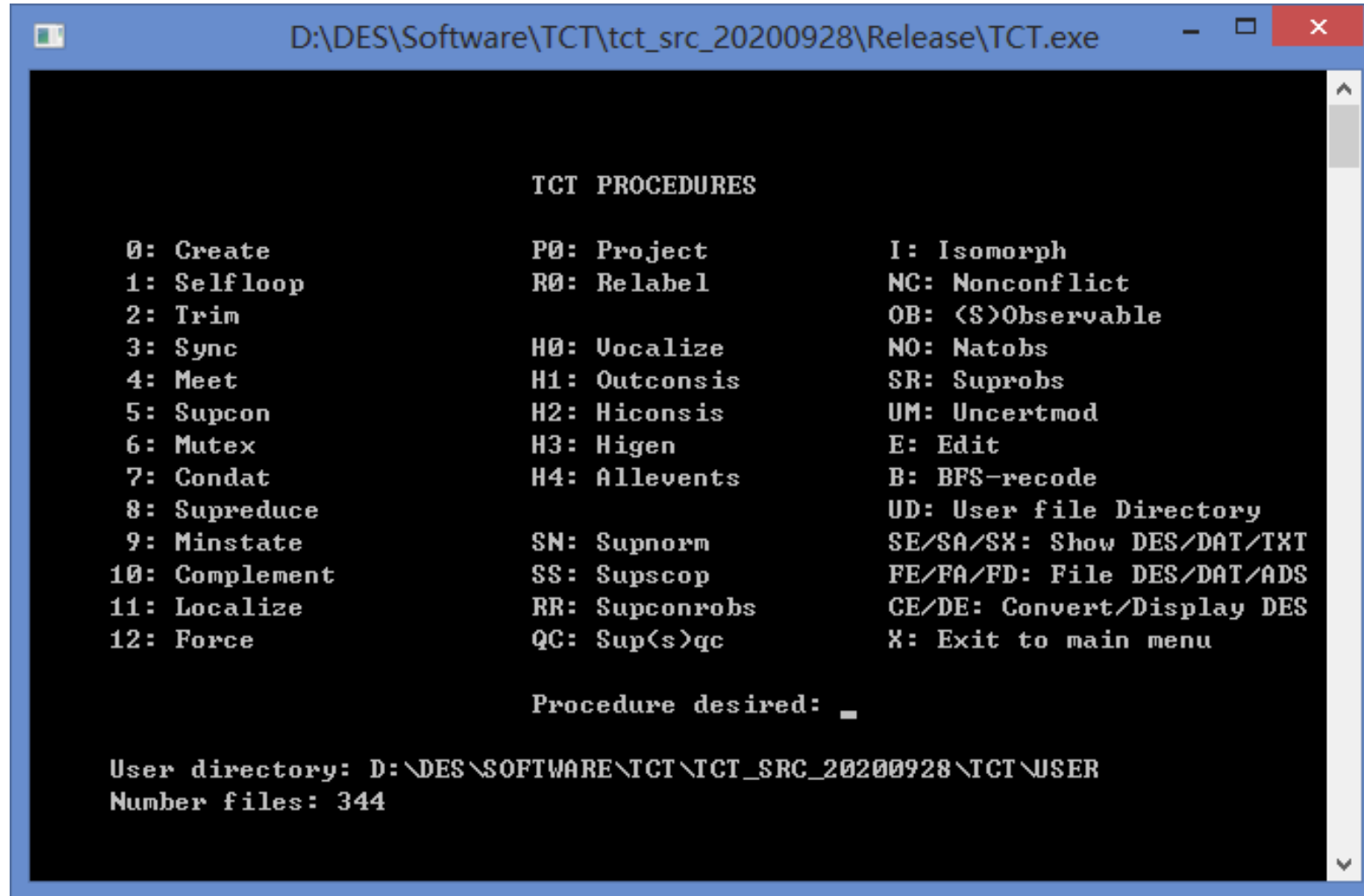
```
PROGRAM TCT

MAIN OPTIONS

I:  Introduction to TCT
T:  TCT Procedures
R:  Reset USER File Directory Path
B:  Bell <On>
D:  Debug mode <Off>
C:  Clocking mode <On>
X:  Quit TCT

Option desired?
```

# TCT procedures



```
D:\DES\Software\TCT\tct_src_20200928\Release\TCT.exe

TCT PROCEDURES

0: Create      P0: Project    I: Isomorph
1: Selfloop    R0: Relabel    NC: Nonconflict
2: Trim        H0: Vocalize   OB: <S>Observable
3: Sync        H1: Outconsis NO: Natobs
4: Meet        H2: Hiconsis  SR: Suprobs
5: Supcon      H3: Higen     UM: Uncertmod
6: Mutex       H4: Allevents E: Edit
7: Condat      SN: Supnorm   B: BFS-recode
8: Supreduce   SS: Supscop   UD: User file Directory
9: Minstate    RR: Supconrobs SE/SA/SX: Show DES/DAT/TXT
10: Complement QC: Sup(s)qc  FE/FA/FD: File DES/DAT/ADS
11: Localize   X: Exit to main menu
12: Force

Procedure desired: _

User directory: D:\DES\SOFTWARE\TCT\TCT_SRC_20200928\TCT\USER
Number files: 344
```

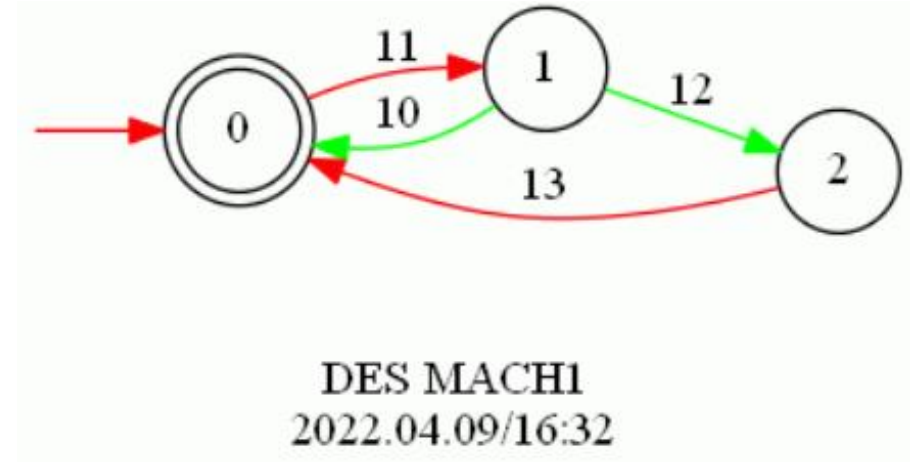
# Section 1:

## TCT procedures

- Procedures for creating/showing/displaying a DES
- Procedures for implementing general operations on DES
- Procedures for (monolithic/partial-observation/hierarchical/distributed) supervisory control

# (1) Create\Show\Display a DES

- $DES = create(DES)$
- $DES2 = edit(DES1)$
- $ScreenDisplay = show(DES1)$
- $GIF = CE(DES)$
- $LabeledTransitionGraph = DE(GIF)$



## (2) General Operations on DES

- $DES2 = \text{selfloop}(DES1, [\text{SELF-LOOPED EVENTS}])$
- $DES2 = \text{trim}(DES1)$
- $DES2 = \text{minstate}(DES1)$
- $DES2 = \text{complement}(DES1, [\text{AUXILIARY-EVENTS}])$
- $DES2 = \text{allevents}(DES1)$

## (2) General Operations on DES

- $DES2 = \text{BFS}(DES1)$
- $DES2 = \text{force}(DES1, [\text{FORCIBLE EVENTS}], [\text{PREEMPTABLE EVENTS}], [\text{TIMEOUT EVENT}]$
- $DES2 = \text{project}(DES1, [\text{NULL/IMAGE EVENTS}])$
- $DES2 = \text{uncertmod}(DES1, [\text{NULL/IMAGE EVENTS}])$
- $DES2 = \text{relabel}(DES1, [\text{OLD-NEW EVENT LABEL PAIRS}])$



## (2) General Operations on DES

- $\text{DES} = \text{meet}(\text{DES1}, \text{DES2}, \dots, \text{DES}_k)$
- $\text{DES} = \text{sync}(\text{DES1}, \text{DES2}, \dots, \text{DES}_k)$
- $\text{true/false} = \text{isomorph}(\text{DES1}, \text{DES2})$
- $\text{true/false} = \text{nonconflict}(\text{DES1}, \text{DES2})$
- $\text{DES3} = \text{mutex}(\text{DES1}, \text{DES2}, [\text{EXCLUDED-STATE-PAIRS}])$

### (3) Procedures for (Monolithic) Supervisory Control

- $DES3 = \text{supcon}(DES1, DES2)$

is a trim generator for the supremal controllable sublanguage of the marked legal language generated by  $DES2$  with respect to the plant  $DES1$ .  $DES3$  provides a proper supervisor for  $DES1$ .

- $DAT2 = \text{condat}(DES1, DES2)$

returns control data  $DAT2$  for the supervisor  $DES2$  of the controlled system  $DES1$ .

- $DES3 = \text{supreduce}(DES1, DES2, DAT2)$

is a reduced supervisor for plant  $DES1$  which is control-equivalent to  $DES2$ , where  $DES2$  and control data  $DAT2$  were previously computed using **supcon** and **condat**. Also returned is an estimated lower bound  $slb$  for the state size of a strictly state-minimal reduced supervisor.

### (3) Procedures for (Partial-Observation) Supervisory Control

- $DES2 = \text{sup}\langle s \rangle \text{qc}(DES1, [\text{NULL}/\text{IMAGE EVENTS}])$
- $\text{true/false} = (s)\text{observ}(DES1, DES2, [\text{NULL}/\text{IMAGE EVENTS}])$
- $(DES3, DES4) = \text{natobs}(DES1, DES2)$
- $DES3 = \text{supnorm}(DES1, DES2, [\text{NULL}/\text{IMAGE EVENTS}])$
- $DES3 = \text{supscop}(DES1, DES2, [\text{NULL}/\text{IMAGE EVENTS}])$
- $DES3 = \text{suprobs}(DES1, DES2, [\text{NULL}/\text{IMAGE EVENTS}])$
- $DES3 = \text{supconrobs}(DES1, DES2, [\text{NULL}/\text{IMAGE EVENTS}])$

### (3) Procedures for (Hierarchical) Supervisory Control

- $DES2 = \text{vocalize}(DES1, [\text{STATE-OUTPUT PAIRS}])$
- $DES2 = \text{outconsis}(DES1)$
- $DES2 = \text{hiconsis}(DES1)$
- $DES2 = \text{higen}(DES1)$

### (3) Procedures for (distributed) Supervisory Control

- $\{LOC1, LOC2, \dots, LOC_m\} = \text{localize}(\text{PLANT}, \{\text{PLANT}_1, \dots, \text{PLANT}_m\}, \text{SUPER})$

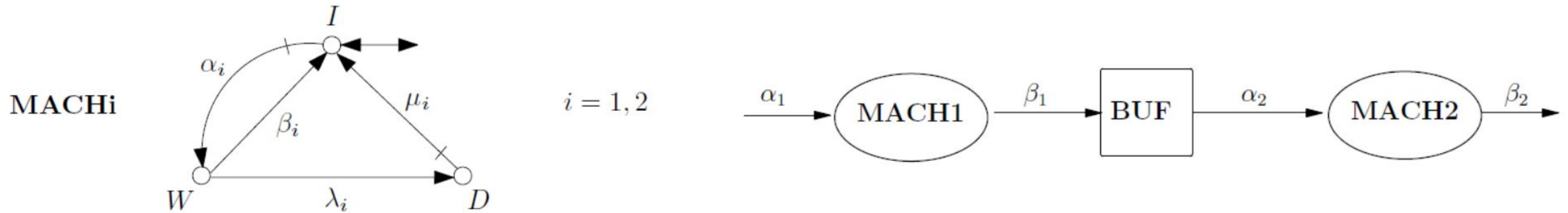
is the set of localizations of SUPER to the  $m$  independent components  $\text{PLANT}_1, \dots, \text{PLANT}_m$  of PLANT. Optionally, correctness of localization is verified and reported as  $\text{ControlEqu}(\dots)$  in MAKEIT.TXT. **localize** is mainly for use when SUPER is a decentralized supervisor with authority over  $\text{PLANT}_1, \dots, \text{PLANT}_m$ , and PLANT is their synchronous product.

Section 2:

An example of Using TCT

## Small Factory (cf. Wonham & Cai's book on SCDES):

- Small factory consists of two machines, which are connected by a buffer with one slot.



- The specifications on small factory are:
  - (1) The buffer must not overflow or underflow.
  - (2) If both machines are broken down, then MACH2 must be repaired before MACH1.

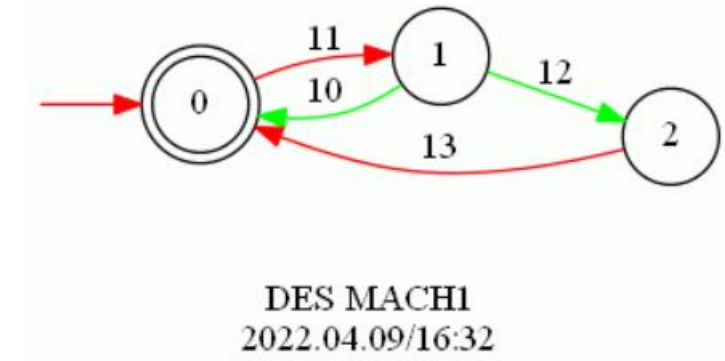
1. MACH1 = Create(MACH1,[mark0], [tran[0,11,1],[1,10,0],[1,12,2],[2,13,0]]) (3,4)

```
TCT PROCEDURES

0: Create      P0: Project      I: Isomorph
1: Selfloop   R0: Relabel      NC: Nonconflict
2: Trim       H0: Vocalize     OB: (S)Observable
3: Sync       H1: Outconsis    NO: Natobs
4: Meet       H2: Hiconsis     SR: Suprobs
5: Supcon     H3: Higen        UM: Uncertmod
6: Mutex      H4: Allevents    E: Edit
7: Condat     SN: Supnorm      B: BFS-recode
8: Supreduce  SS: Supscop      UD: User file Directory
9: Minstate   RR: Supconrobs   SE/SA/SX: Show DES/DAT/TXT
10: Complement QC: Sup(s)qc     FE/FA/FD: File DES/DAT/ADS
11: Localize  X: Exit to main menu
12: Force

Procedure desired:

User directory: F:\NWPU\DES\USER
Number files: 47
```





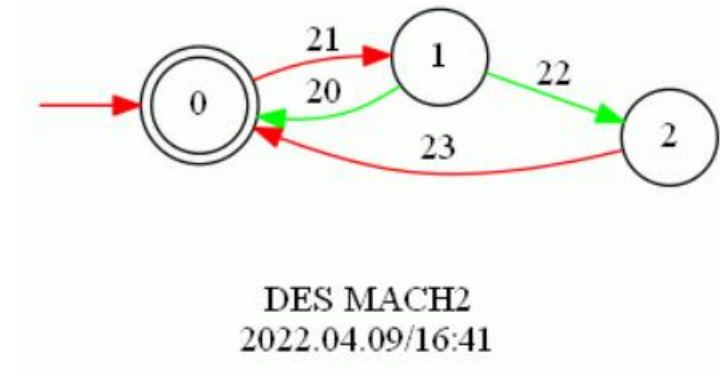
2. MACH2 = Relabel(MACH1,[[10,20],[11,21],[12,22],[13,23]]) (3,4)

```
TCT PROCEDURES

0: Create      P0: Project      I: Isomorph
1: Selfloop    R0: Relabel      NC: Nonconflict
2: Trim        H0: Vocalize     OB: (S)Observable
3: Sync        H1: Outconsis    NO: Natobs
4: Meet        H2: Hiconsis     SR: Suprobs
5: Supcon      H3: Higen        UM: Uncertmod
6: Mutex       H4: Allevents    E: Edit
7: Condat      SN: Supnorm      B: BFS-recode
8: Supreduce   SS: Supscop      UD: User file Directory
9: Minstate    RR: Supconrobs   SE/SA/SX: Show DES/DAT/TXT
10: Complement QC: Sup(s)qc     FE/FA/FD: File DES/DAT/ADS
11: Localize   X: Exit to main menu
12: Force

Procedure desired:

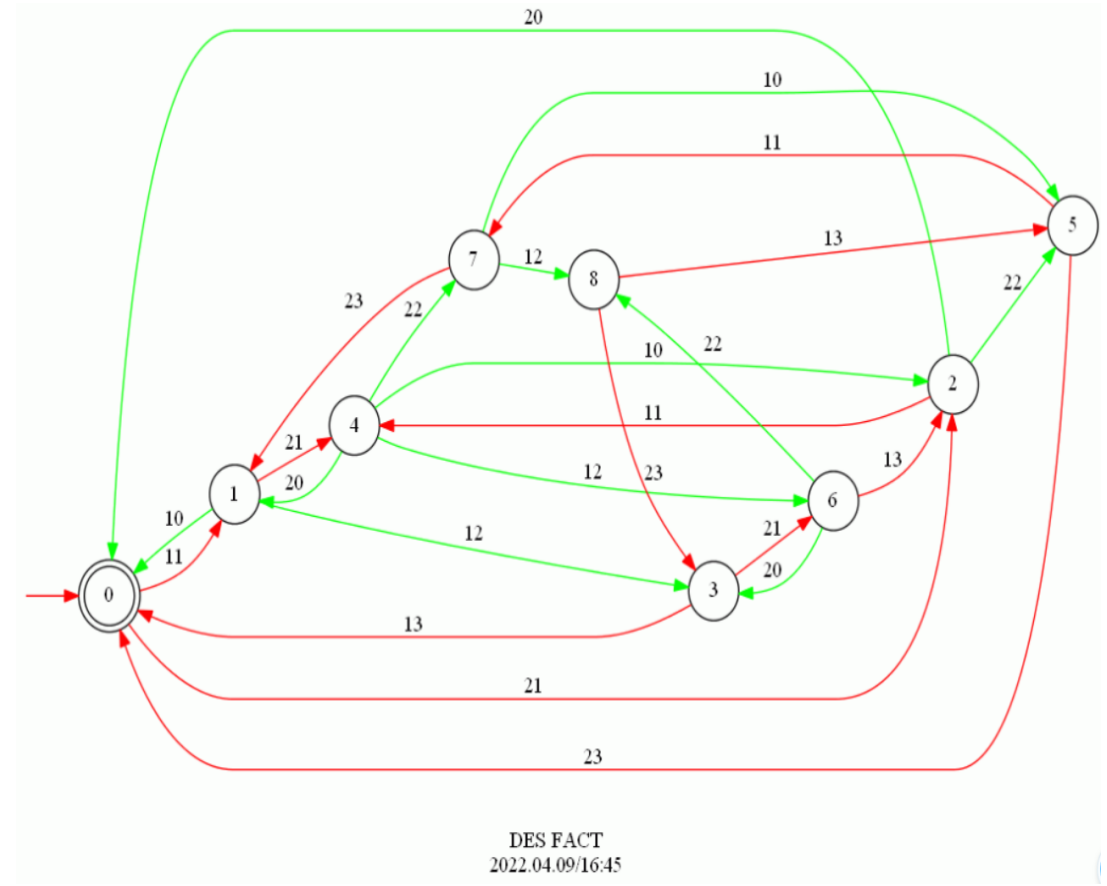
User directory: F:\NWPU\DES\USER
Number files: 47
```



### 3. FACT = Sync(MACH1,MACH2) (9,24) Blocked\_events = None

```
SYNC
DES = SYNC (DES1, DES2, ..., DESk, k)
Enter value of k ..... (between 2 and 30) 2
Enter name of DES1 ..... MACH1
Enter name of DES2 ..... MACH2
Enter name of DES ..... FACT
Filename FACT already exists. OK to overwrite? (*y/n) Y

Events blocked in FACT: None.
Press <Enter> to return to TCT Procedures
```



#### 4. ALLFACT = Allevents(FACT) (1,8)

```
ALLEVENTS
DES2 = ALLEVENTS (DES1/DAT1/[EVENTLIST])

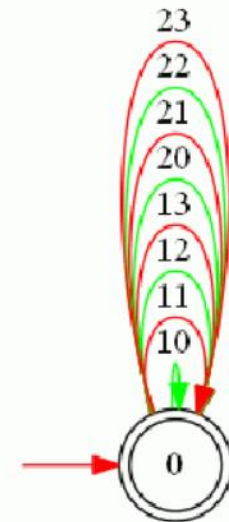
Select DES1 (to report all events occurring in existing DES1),
or DAT1 (to report all events tabled in existing Condat file DAT1),
or EVENTLIST (to report all events entered by user):
DES1/DAT1/EVENTLIST? (*d/a/e) ... D

Enter name of DES1 to be searched ..... FACT

Enter name of target DES2 (single state, marked,
with desired events attached as selfloops) ..... ALLFACT

Filename ALLFACT already exists. OK to overwrite? (*y/n) Y

Press <Enter> to return to TCT Procedures
```



DES ALLFACT  
2022.04.09/16:48

5. BUFSPEC = Create(BUFSPEC,[mark 0],[tran [0,10,1],[1,21,0]]) (2,2)

```
CREATE (BUFSPEC)

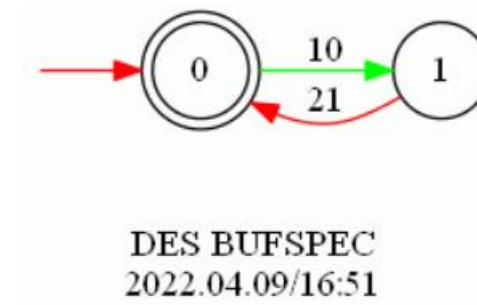
Enter transitions using:

States          : integers 0,1,2,...,Size-1
Uncontrollable Events : even integers 0,2,4,... <= 9998 and e
Controllable Events  : odd integers 1,3,5,... <= 9999

To quit, enter -1 for Exit State.

Exit State: 0      Event Label: 10      Entrance State: 1
Exit State: 1      Event Label: 21      Entrance State: 0
Exit State: -1

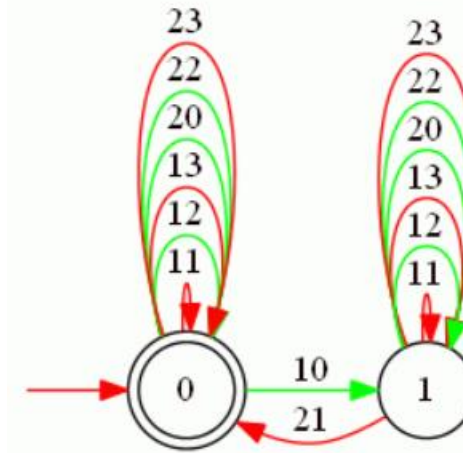
Press <ESC> to cancel
```



6. BUFSPEC = Sync(BUFSPEC,ALLFACT) (2,14) Blocked\_events = None

```
SYNC
DES = SYNC (DES1, DES2, ..., DESk, k)
Enter value of k ..... (between 2 and 30) 2
Enter name of DES1 ..... BUFSPEC
Enter name of DES2 ..... ALLFACT
Enter name of DES ..... BUFSPEC
Filename BUFSPEC already exists. OK to overwrite? (*y/n) Y

Events blocked in BUFSPEC: None.
Press <Enter> to return to TCT Procedures
```



DES BUFSPEC  
2022.04.09/16:54

7. BRSPEC = Create(BRSPEC,[mark 0],[tran [0,13,0],[0,22,1],[1,23,0]]) (2,3)

```
CREATE (BRSPEC)

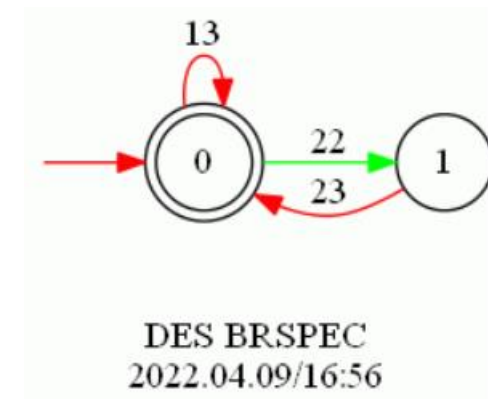
Enter transitions using:

States      : integers 0,1,2,...,Size-1
Uncontrollable Events : even integers 0,2,4,... <= 9998 and e
Controllable Events   : odd integers 1,3,5,... <= 9999

To quit, enter -1 for Exit State.

Exit State: 0      Event Label: 13      Entrance State: 0
Exit State: 0      Event Label: 22      Entrance State: 1
Exit State: 1      Event Label: 23      Entrance State: 0
Exit State: -1

Press <ESC> to cancel
```

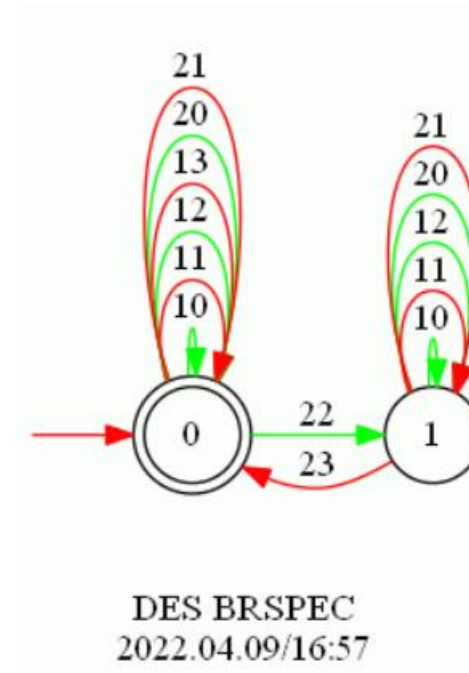


8.  $\text{BRSPEC} = \text{Sync}(\text{BRSPEC}, \text{ALLFACT})$  (2,13) Blocked\_events = None

```
SYNC
DES = SYNC (DES1, DES2, ..., DESk, k)
Enter value of k ..... (between 2 and 30) 2
Enter name of DES1 ..... BRSPEC
Enter name of DES2 ..... ALLFACT
Enter name of DES ..... BRSPEC
Filename BRSPEC already exists. OK to overwrite? (*y/n) Y

Events blocked in BRSPEC: None.

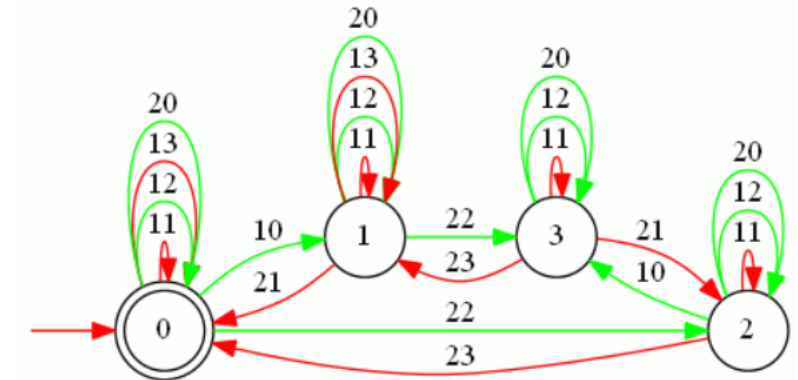
Press <Enter> to return to TCT Procedures
```



## 9. SPEC = Meet(BRSPEC, BUFSPEC) (4,22)

```
MEET
DES = MEET (DES1, DES2, ..., DESk, k)
Enter value of k ..... (between 2 and 30) 2
Enter name of DES1 ..... BRSPEC
Enter name of DES2 ..... BUFSPEC
Enter name of DES ..... SPEC
Filename SPEC already exists.  OK to overwrite? (*y/n)  y

Press <Enter> to return to TCT Procedures
```



DES SPEC  
2022.04.09/17:03



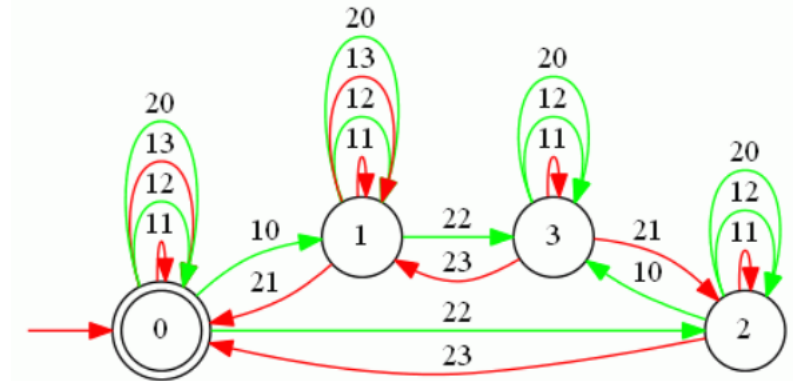
## 10. SPEC = Convert(SPEC)

### TCT PROCEDURES

0: Create	P0: Project	I: Isomorph
1: Selfloop	R0: Relabel	NC: Nonconflict
2: Trim		OB: (S)Observable
3: Sync	H0: Vocalize	NO: Natobs
4: Meet	H1: Outconsis	SR: Suprobs
5: Supcon	H2: Hiconsis	UM: Uncertmod
6: Mutex	H3: Higen	E: Edit
7: Condat	H4: Allevents	B: BFS-recode
8: Supreduce		UD: User file Directory
9: Minstate	SN: Supnorm	SE/SA/SX: Show DES/DAT/TXT
10: Complement	SS: Supscop	FE/FA/FD: File DES/DAT/ADS
11: Localize	RR: Supconrobs	CE/DE: Convert/Display DES
12: Force	QC: Sup(s)qc	X: Exit to main menu

Procedure desired:

User directory: F:\NWPU\DES\USER  
Number files: 48



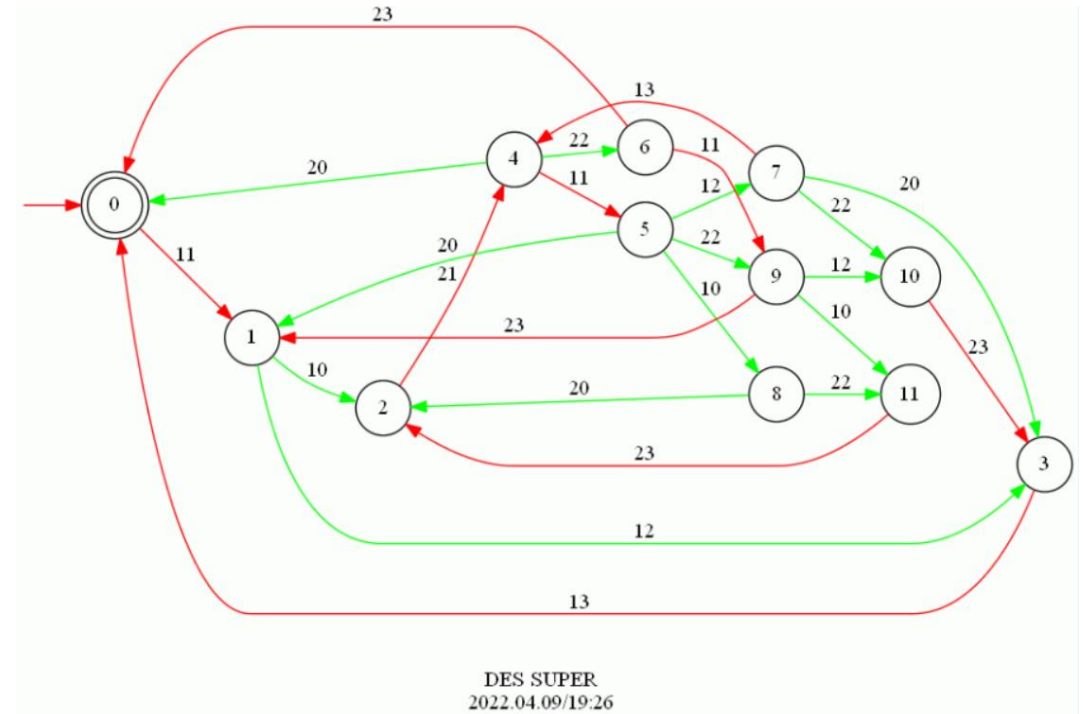
DES SPEC  
2022.04.09/17:03

## 11. SUPER = Supcon(FACT,SPEC) (12,24)

```
SUPCON
DES3 = SUPCON (DES1, DES2)

Enter name of plant generator DES1 ..... FACT
Enter name of legal language generator DES2 .... SPEC
Enter name of supremal
controllable sublanguage generator DES3 ..... SUPER
Filename SUPER already exists. OK to overwrite? (*y/n) y

Press <Enter> to return to TCT Procedures
```



## 12. SUPER = Condat(FACT,SUPER) Controllable.

```
CONDAT
DES3 = CONDAT (DES1, DES2)
Enter name of plant generator DES1 ..... FACT
Enter name of supervisor DES2 ..... SUPER
Enter name of control data file DES3 .... SUPER
Filename SUPER already exists. OK to overwrite? (*y/n) y

Press <Enter> to return to TCT Procedures
```

```
D:\Archives\Untimed DES\DES Examples\TCT.exe

Control data are displayed as a list of supervisor states
where disabling occurs, together with the events that must
be disabled there.

SUPER is CONTROLLABLE

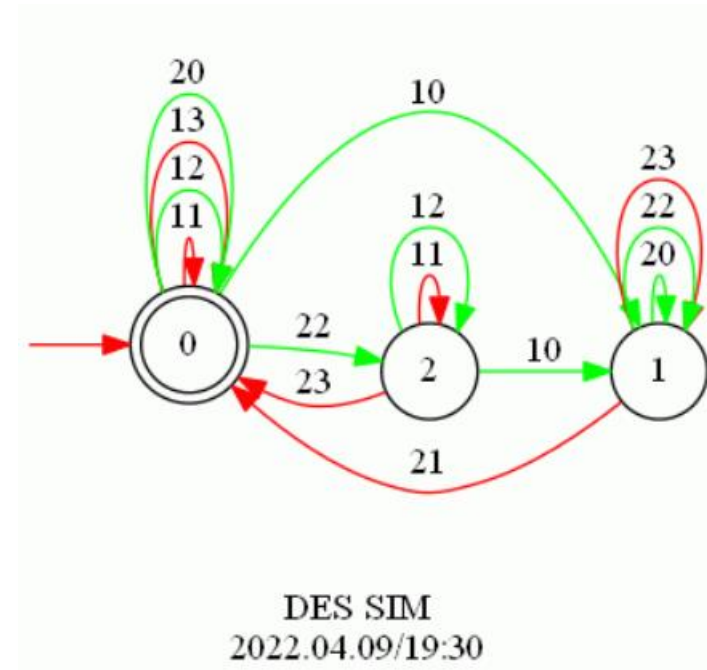
control data:

      0: 21      1: 21
      2: 11      3: 21
      8: 11     10: 13
     11: 11

Press <Enter> to return to TCT Procedures
```

### 13. SIM = Supreduce(FACT,SUPER,SUPER) (3,14;slb=3)

```
SUPREDUCE
DES3 = SUPREDUCE (DES1, DES2, DAT2)
Enter name of plant generator DES1 ..... FACT
Enter name of DES2 [= Supcon(DES1,DES?)] .... SUPER
Enter name of DAT2 [= Condat(DES1,DES2)] .... SUPER
Enter name of DES3 ..... SIM
Filename SIM already exists. OK to overwrite? (*y/n) y
Compute slb estimate (at cost of run time increase)? ..... (*y/n)
Press <ESC> to cancel
```



## 14. TEST=Sync(SIM,FACT)

SYNC

DES = SYNC (DES1, DES2, ..., DESk, k)

Enter value of k ..... (between 2 and 30) 2

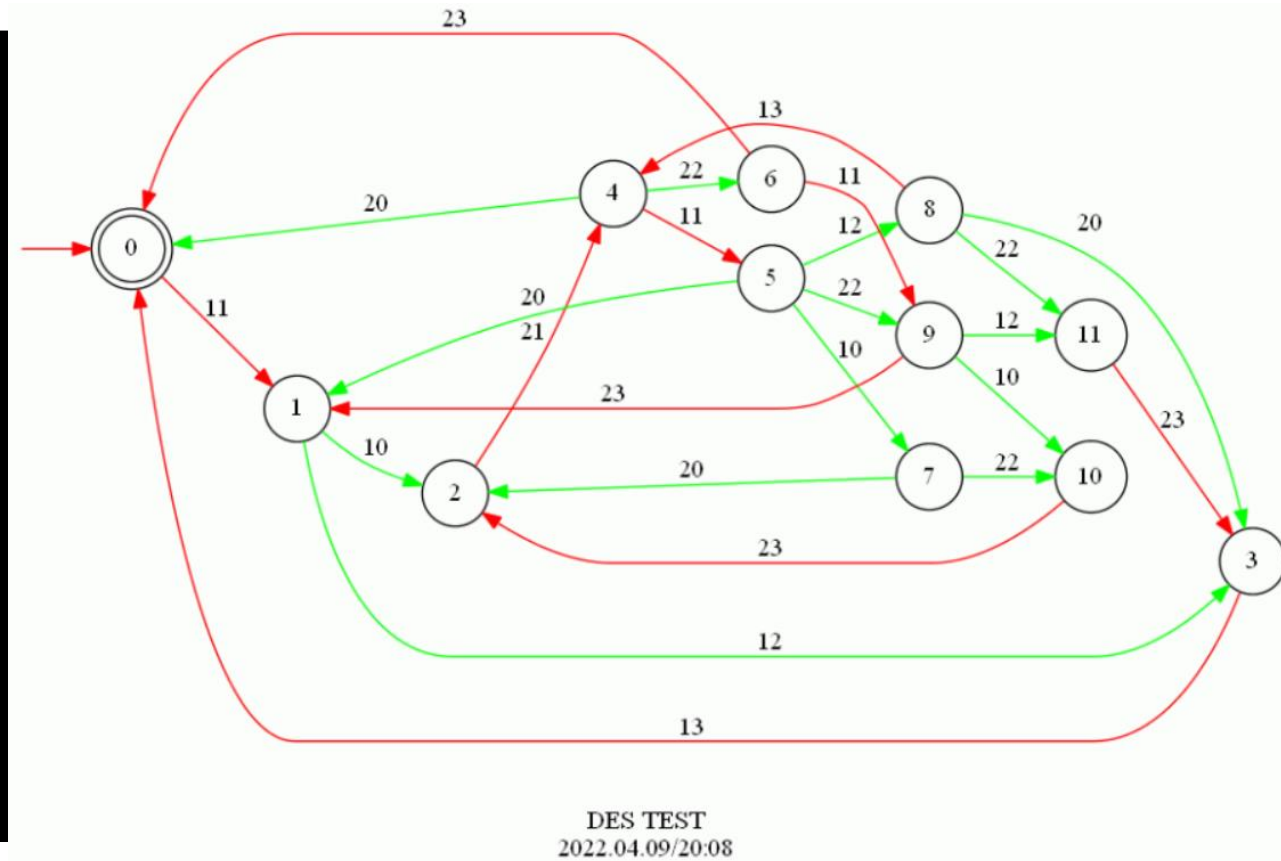
Enter name of DES1 ..... SIM

Enter name of DES2 ..... FACT

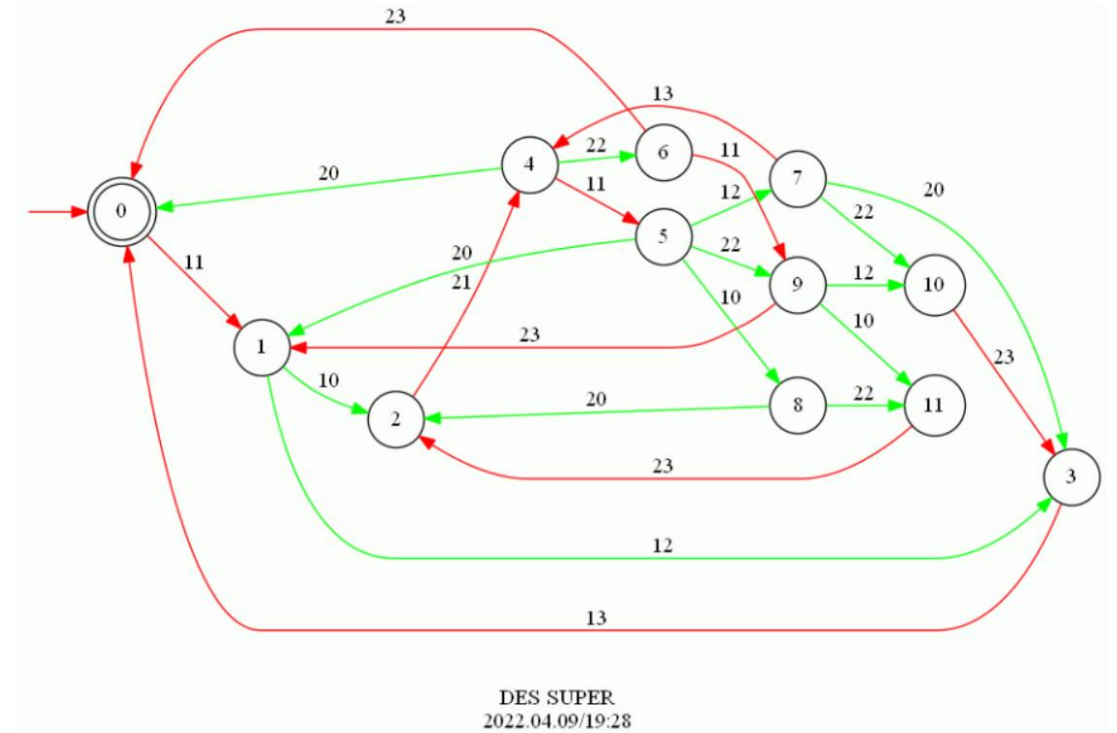
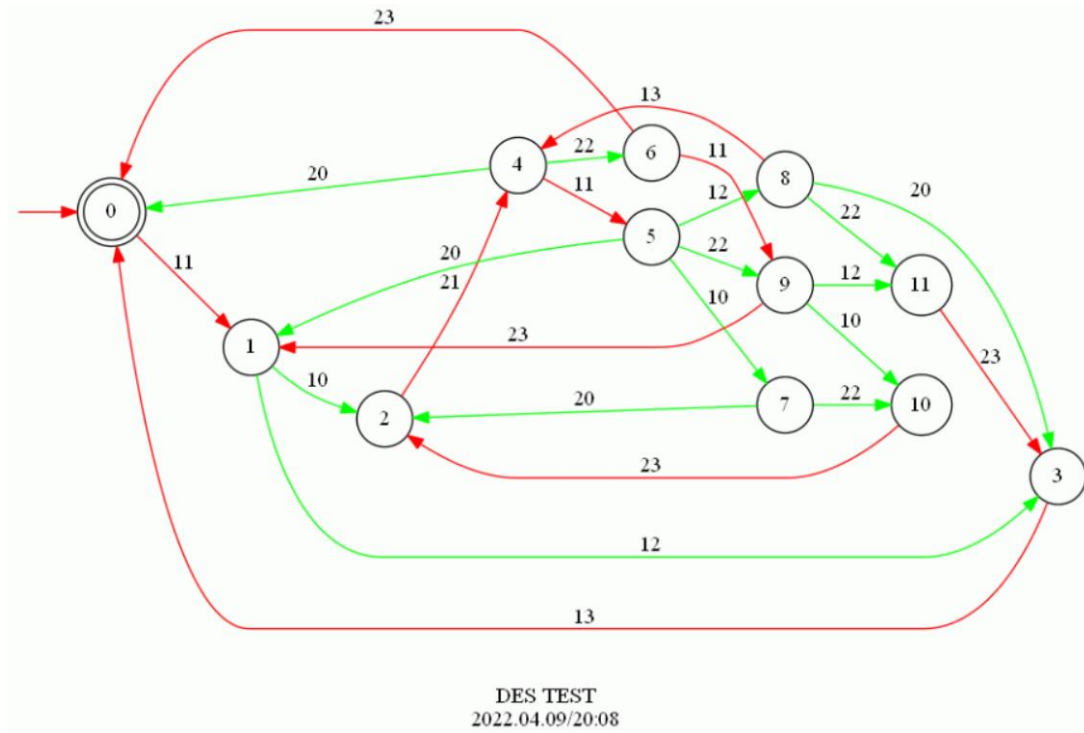
Enter name of DES ..... TEST

Events blocked in TEST: None.

Press <Enter> to return to TCT Procedures



# 15. true=Isomorph(TEST, SUPER)



Section 3:

New Feature: call TCT procedures  
in Matlab

# Call TCT procedures in matlab

```
编辑器 - E:\DES\Software\TCT\MatTCT\Transferline.m
1 % Clear and close everything
2 clear all; close all; fclose all;
3
4 % Run setup.m
5 setup;
6 settctname('TCT64'); % Set the name of tct
7
8 % Set working folder
9 init('TRANLINE1');
10
11 % Supervisor design procedure
12 % Step 1
13
14 % Creat plant (components)
15 Q = 2; % number of states
16 % the initial state q0 is always labeled "0"
17 Qm = [0]; % marker state set
18 delta = [0,1,1; % transition triples (exit state, event, enter st
19         1,2,0
20         ];
21 create('M1', Q, delta, Qm); % create automaton
22
23 % Creat plant (components)
24 Q = 2; % number of states
25 % the initial state q0 is always labeled "0"
26 Qm = [0]; % marker state set
27 delta = [0,3,1; % transition triples (exit state, event, enter st
28         1,4,0
29         ];
30 create('M2', Q, delta, Qm); % create automaton
31

编辑器 - E:\DES\Software\TCT\MatTCT\Transferline.m
31
32 % Creat plant (components)
33 Q = 2; % number of states
34 % the initial state q0 is always labeled "0"
35 Qm = [0]; % marker state set
36 delta = [0,5,1; % transition triples (exit state, event, enter st
37         1,6,0;
38         1,8,0
39         ];
40 create('TU', Q, delta, Qm); % create automaton
41
42 % Creat specification (components)
43 Q = 2; % number of states
44 % the initial state q0 is always labeled "0"
45 Qm = [0]; % marker state set
46 delta = [0,2,1; % transition triples (exit state, event, enter st
47         0,8,1;
48         1,3,0
49         ];
50 create('B1', Q, delta, Qm); % create automaton
51
52 % Creat specification (components)
53 Q = 2; % number of states
54 % the initial state q0 is always labeled "0"
55 Qm = [0]; % marker state set
56 delta = [0,4,1; % transition triples (exit state, event, enter st
57         1,5,0
58         ];
59 create('B2', Q, delta, Qm); % create automaton
60
61

编辑器 - E:\DES\Software\TCT\MatTCT\Transferline.m
61
62 %Step 2
63
64 sync('PLANT', 'M1', 'M2', 'TU');
65
66 %displaydes('PLANT') % display automaton
67
68 allevents('ALL', 'PLANT');
69
70
71 %Step 3
72
73 sync('SPEC', 'B1', 'B2', 'ALL');
74
75
76 %Step 4
77
78 supcon('SUP', 'PLANT', 'SPEC');
79 %figure(1)
80 %displaydes('SUP') % display automaton
81
82
83 %Step 5
84
85 condatt('SUPDAT', 'PLANT', 'SUP');
86 printdat('SUPDAT', 'SUPDAT')
87
```



# The End!

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