

CPE381 HW4
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P1

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% HW4 - P1
% Christopher Bero

clear all;

syms s;

% H1(s)
numerator=((s-1)*(s-(1+pi))*(s-(1-pi)));
denominator=((s+1)*(s-(-1+pi))*(s-(-1-pi)));
fig1=figure;
magnitudeResponse(numerator, denominator, fig1);

% H2(s)
numerator=((s-pi)*(s+pi));
denominator=((s+1)*(s-(-1+pi))*(s-(-1-pi)));
fig2=figure;
magnitudeResponse(numerator, denominator, fig2);

% H3(s)
numerator=(s-1);
denominator=((s+1)*(s-(-1+pi))*(s-(-1-pi)));
fig3=figure;
magnitudeResponse(numerator, denominator, fig3);
```

magnitudeResponse()

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function [ ] = magnitudeResponse( numerator , denominator, fig )
% Helper function for CPE381 homework #4
% Expected input format: un-tiered polynomial: (s-1)*(s-(z))*(s-(-z))

% expand() to break equation into polynomial form
% coeffs() to pull just coefficients from the equation
% double() to turn syms matrix back into numerical form
% roots() to calculate the roots of the polynomial,
%       which are plotted with splane()

% Sections adapted from ex5_18.m

syms s;

numerator_poly=fliplr(double(coeffs(expand(numerator),s)));
denominator_poly=fliplr(double(coeffs(expand(denominator),s)));

%n=roots(numerator_poly)
%d=roots(denominator_poly)

n=numerator_poly;
d=denominator_poly;
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wmax=50;
[w,Hm,Ha]=freqresp_s(n,d,wmax);
figure(fig);
subplot(211)
plot(w,Hm)
axis([0 wmax 0 1.1*max(Hm)])
ylabel('|H(j \omega)|')
grid
xlabel('\omega')
title(' Magnitude response')
subplot(212)
plot(w,Ha)
axis([0 wmax 1.1*min(Ha) 1.1*max(Ha)])
ylabel('< H(j \omega)')
xlabel('\omega')
title(' Phase response')
grid
%subplot(223)
%splane(n,d)
%title('Poles/Zeros')
%grid

```

P6

```

X=[1 zeros(1,4)];
B=ones(1,5);
A=ones(1,5)/5;
y=filter(A,B,X);
x=[0:1:4];
stem(x,y);

```

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1. For a $H(s)$, given K, p_k, z_i .

Know

$$H(s) = K \cdot \left(\frac{s - z_i}{s - p_k} \right)$$

Using script "p1" in Matlab,

$$Q \ H_1(s): K=1; p=-1, -1+\pi, -1-\pi; z=1, 1+\pi, 1-\pi$$

$$\text{Numerator: } (s-1)(s-(1+\pi))(s-(1-\pi))$$

$$\text{Denominator: } (s+1)(s-(-1+\pi))(s-(-1-\pi))$$

- Is an "all-pass" filter.

$$Q \ H_2(s): K=1; p=-1, -1+\pi, -1-\pi; z=\pi, -\pi$$

$$\text{Numerator: } (s-\pi)(s+\pi)$$

$$\text{Denominator: } (s+1)(s-(-1+\pi))(s-(-1-\pi))$$

- Is a notch filter.

$$Q \ H_3(s): K=1; p=-1, -1+\pi, -1-\pi; z=1$$

$$\text{Numerator: } (s-1)$$

$$\text{Denominator: } (s+1)(s-(-1+\pi))(s-(-1-\pi))$$

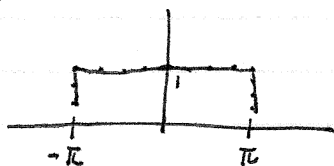
- Is a band pass filter.

HW 4

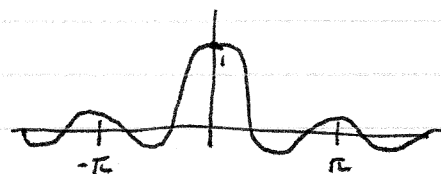
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2. a) $h(t) = \sin(t) / t$.

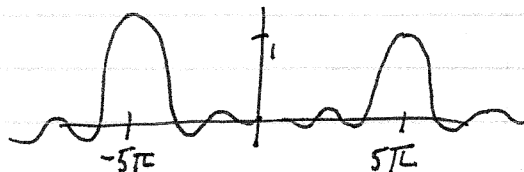
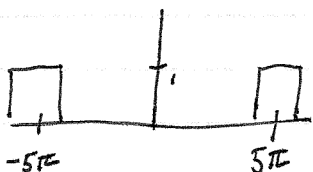
f:



t:



b)



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3. 12-bit ADC, $V_{R-} = 0.5V$, $V_{R+} = 2.5V$ a) Quantization Step: $(V_{R+} - V_{R-}) / (2^n - 1)$

$$(2.5V - 0.5V) / (4095) = \boxed{0.0004884V} = \Delta$$

$$b) V_{R-} + (V_{al} \cdot \Delta) = V_{in} \Rightarrow V_{al} \cdot \Delta = V_{in} - V_{R-}$$

$$V_{al} = (V_{in} - V_{R-}) / \Delta$$

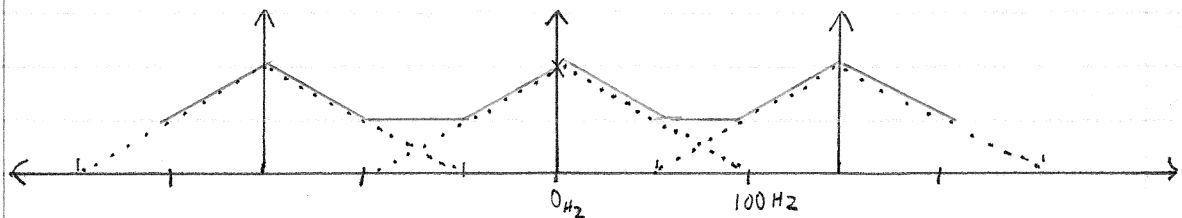
$$(2.2V - 0.5V) / 0.0004884V = \boxed{3480}$$

$$c) 0.4V < 0.5V_{R-}, \quad V_{al} = \boxed{0}$$

$$d) 3V > V_{R+}, \quad V_{al} = \boxed{4095}$$

4. $\Omega_{\max}: 100 \text{ Hz}$; $F_s = 150 \text{ Hz}$

Sampled Signal:



Because $F_s = 150 \text{ Hz} \neq 2 \cdot \Omega_{\max}$, Nyquist Conditions are not met and the sampled signal is distorted.

5. 12 or 16 bit ADC; $f_m = 5\text{KHz}$; Range: 2.5V

□ Determine sampling period T_s .

- $f_s = 2 \cdot f_m = 10\text{KHz}$ minimum to satisfy Nyquist Criteria.
- $T_s = 1/f_s = 0.0001\text{s}$

□ For 12 bit ADC:

- $\Delta = 2.5\text{V}/4095 = 0.000610$

- Quantization Error: $0 \leq \epsilon(nT_s) \leq \Delta$

□ For 16 bit ADC:

- $\Delta = 2.5\text{V}/65535 = 0.000038$

- Quantization Error = $0 \leq \epsilon(nT_s) \leq \Delta$

□ Testing With a Value from the high end of a given Viable range $V_{R-} = 0\text{V}$ $V_{R+} = 2.5\text{V}$:

- 12 bit error: $((\Delta)/2.5\text{V}) \times 100\% = 0.024\%$

- 16 bit error: $((\Delta)/2.5\text{V}) \times 100\% = 0.002\%$

□ Going from a 12 bit to a 16 bit ADC results in more than a magnitude of order reduction in error.

6.

$$y[n] = 0.2 \cdot y[n-2] + x[n]$$

a) $y[n] = h[n] = 0, n < 0 ; x[n] = \delta[n]$

$$y[n] = 0.2 \cdot y[n-2] + x[n]$$

$$y[n-2] = 0.2 \cdot y[n-4] + x[n-2]$$

$$y[n] = 0.2[0.2 \cdot y[n-4] + x[n-2]] + x[n]$$

$$= 0.04 \cdot y[n-4] + (x[n-2] + x[n])$$

$$y[0] = 0.04 \cdot y[-4] + (x[-2] + x[0])$$

$$y[n] = \sum_{k=0}^n 0.2^k \cdot x[n-k] \quad n \geq 0$$

$$h[n] = \sum_{k=0}^n 0.2^k \cdot x[n-k] \quad n \geq 0$$

b) $h[0] = 0.2 \cdot h[-2] + \delta[0] = 0 + 1$

$$h[1] = 0.2 \cdot h[-1] + \delta[1] = 0 + 0$$

$$h[2] = 0.2 \cdot h[0] + \delta[2] = 0.2 + 0$$

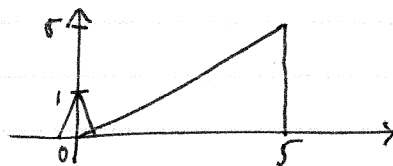
$$h[3] = 0.2 \cdot h[1] + \delta[3] = 0 + 0$$

$$h[4] = 0.2 \cdot h[2] + \delta[4] = 0.2^2 + 0$$

$$h[n] = \sum_{k=0}^n 0.2^k \text{ for } n \in [\text{Even Numbers}]$$

$$h[n] = 0 \text{ for } n \in [\text{Odd Numbers}]$$

7. a)
$$h[n] = 0 + 1[n-1] + 2[n-2] + 3[n-3] + 4[n-4] + 5[n-5]$$



b) for no $n < 0$ is $h[n] > 0$, is not causal.
Does not damp, is not stable.

d) $h[5] = 5$