

Chapter 2

Getting Connected



Problems

- In Chapter 1 we saw networks consists of links interconnecting nodes. How to connect two nodes together?
- We also introduced the concept of “cloud” abstractions to represent a network without revealing its internal complexities. How to connect a host to a cloud?



Chapter Outline

Chapter 2

- Perspectives on Connecting nodes
- Encoding
- Framing
- Error Detection
- Reliable Transmission
- Ethernet and Multiple Access Networks
- Wireless Networks



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Chapter Goal

Chapter 2

- Exploring different communication medium over which we can send data
- Understanding the issue of encoding bits onto transmission medium so that they can be understood by the receiving end
- Discussing the matter of delineating the sequence of bits transmitted over the link into complete messages that can be delivered to the end node
- Discussing different technique to detect transmission errors and take the appropriate action



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Chapter Goal (contd.)

Chapter 2

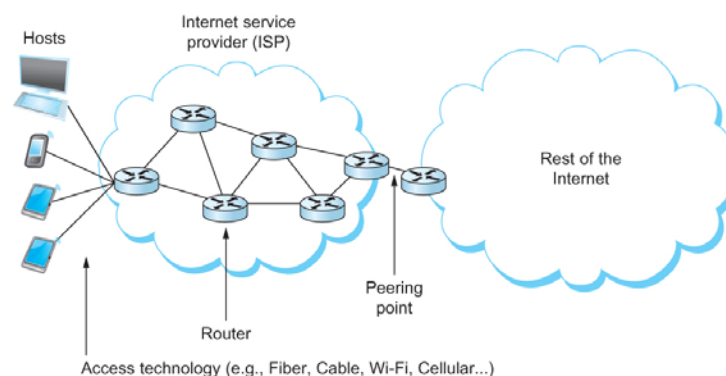
- Discussing the issue of making the links reliable in spite of transmission problems
- Introducing Media Access Control Problem
- Introducing Carrier Sense Multiple Access (CSMA) networks
- Introducing Wireless Networks with different available technologies and protocol

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Perspectives on Connecting

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An end-user's view of the Internet

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Link Capacity and Shannon-Hartley Theorem

- Gives the upper bound to the capacity (C) of a link in terms of bits per second (bps) as a function of signal-to-noise ratio of the link measured in decibels (dB).
- $C = B \cdot \log_2(1 + S/N)$
 - Where $B = 3300 - 300 = 3000\text{Hz}$ is the bandwidth
 - S is the signal power over the bandwidth
 - N the average noise over the bandwidth.
 - The signal to noise ratio (S/N) is measured in decibels is related to $\text{dB} = 10 \times \log_{10}(S/N)$. If the result 30dB then $S/N = 1000$.
 - Now $C = 3000 \times \log_2(1001) = 30\text{kbps}$ (29.902kbps)
 - How can we get 56kbps?

Links

- All practical links rely on some sort of electromagnetic radiation propagating through a medium or, in some cases, through free space
- One way to characterize links, then, is by the medium they use
 - Typically copper wire in some form (as in Digital Subscriber Line (DSL) and coaxial cable),
 - Optical fiber (as in both commercial fiber-to-the home services and many long-distance links in the Internet's backbone), or
 - Air/free space (for wireless links)

Links

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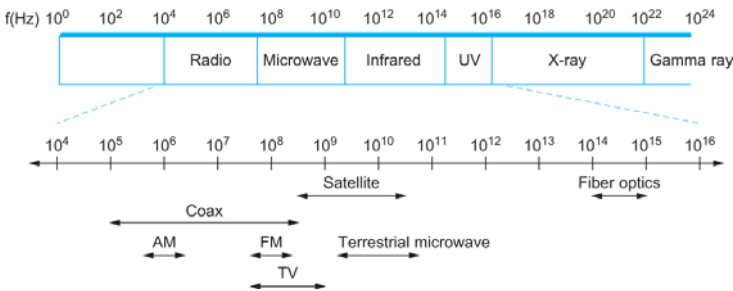
- Another important link characteristic is the *frequency*
 - Measured in hertz, with which the electromagnetic waves oscillate
- Distance between the adjacent pair of maxima or minima of a wave measured in meters is called *wavelength*
 - Speed of light divided by frequency gives the wavelength.
 - Frequency on a copper cable range from 300Hz to 3300Hz; Wavelength for 300Hz wave through copper is
 $(\text{speed of light on copper}) / \text{frequency} = 2/3 \cdot (3 \times 10^8) / 300 = 667 \times 10^3 \text{ meters.}$
- Placing binary data on a signal is called *encoding*.
- Modulation involves modifying the signals in terms of their frequency, amplitude, and phase.



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Links

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Electromagnetic spectrum



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Links

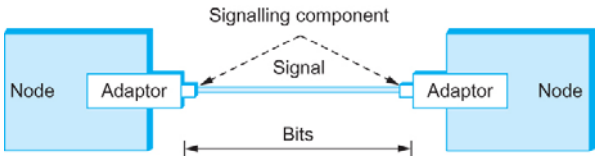
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| Service | Bandwidth (typical) |
|--------------------------|---------------------|
| Dial-up | 28–56 kbps |
| ISDN | 64–128 kbps |
| DSL | 128 kbps–100 Mbps |
| CATV (cable TV) | 1–40 Mbps |
| FTTH (fibre to the home) | 50 Mbps–1 Gbps |

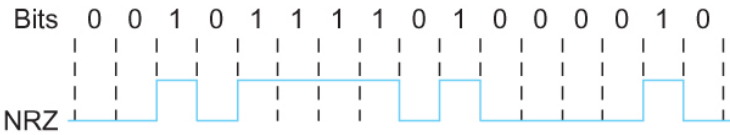
Common services available to connect your home

Encoding

Chapter 2



Signals travel between signaling components; bits flow between adaptors



NRZ encoding of a bit stream

Encoding

Chapter 2

- Problem with NRZ - Baseline wander
 - The receiver keeps an average of the signals it has seen so far
 - Uses the average to distinguish between low and high signal
 - When a signal is significantly lower than the average, it is 0, else it is 1
 - Too many consecutive 0's and 1's cause this average to change, making it difficult to detect



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Encoding

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- Problem with NRZ - Clock recovery
 - Frequent transition from high to low or vice versa are necessary to enable clock recovery
 - Both the sending and decoding process is driven by a clock
 - Every clock cycle, the sender transmits a bit and the receiver recovers a bit
 - The sender and receiver have to be precisely synchronized



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Encoding

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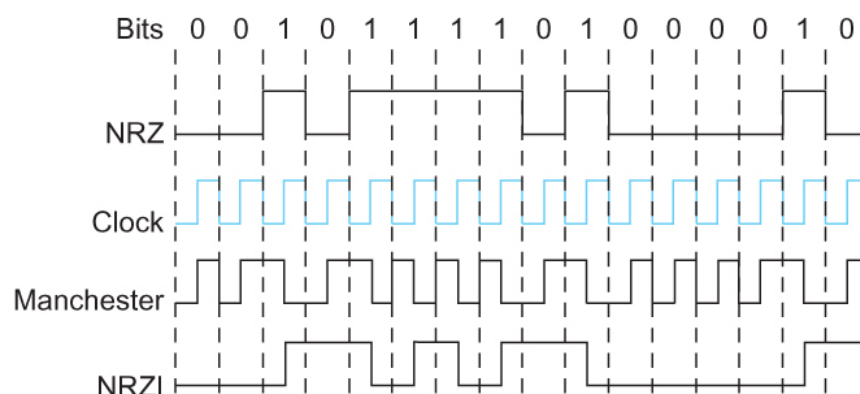
- NRZI - Non Return to Zero Inverted
 - Sender makes a transition from the current signal to encode 1 and stay at the current signal to encode 0
 - Solves for consecutive 1's
 - Does not solve problem with consecutive 0's
 - Transition occurs on rising clock edge
 - Bit rate is the same as the baud rate

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NRZI Waveform

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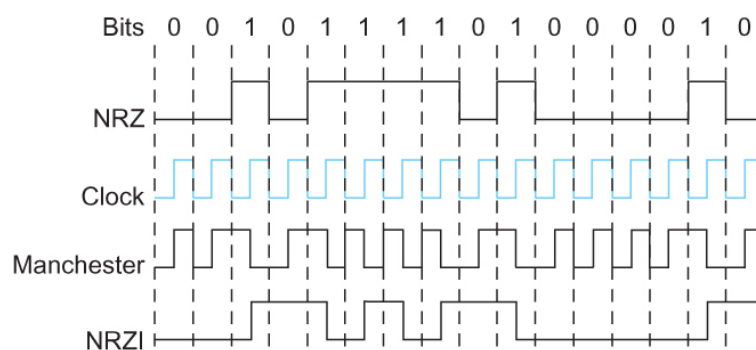
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Encoding

- Manchester encoding
 - Merging the clock with signal by transmitting Ex-OR of the NRZ encoded data and the clock
 - Clock is an internal signal that alternates from low to high, a low/high pair is considered as one clock cycle
 - In Manchester encoding
 - 0: low → high transition
 - 1: high → low transition

Encoding



Different encoding strategies

Encoding

- Problem with Manchester encoding
 - Doubles the rate at which the signal transitions are made on the link
 - Which means the receiver has half of the time to detect each pulse of the signal
 - The rate at which the signal changes is called the link's baud rate
 - In Manchester the bit rate is half the baud rate (50% efficiency)

Encoding

- 4B/5B encoding
 - Insert extra bits into bit stream so as to break up the long sequence of 0's and 1's
 - Every 4-bits of actual data are encoded in a 5-bit code that is transmitted to the receiver
 - 5-bit codes are selected in such a way that each one has no more than one leading 0(zero) and no more than two trailing 0's.
 - No pair of 5-bit codes results in more than three consecutive 0's
 - Transmitted using NRZI
 - 80% efficient

Encoding

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■ 4B/5B encoding

| <i>Data</i> | <i>Transmit</i> | <i>Other 5B codes</i> |
|-------------|-----------------|--|
| 0000 | → 11110 | 16 left (16 used for data) |
| 0001 | → 01001 | 11111 – when the line is idle |
| 0010 | → 10100 | 00000 – when the line is dead |
| .. | | 00100 – to mean halt |
| .. | | |
| 1111 | → 11101 | 13 left : 7 invalid, 6 for various control signals |



Encoding

Chapter 2

■ 4B/5B encoding

| 4-bit Data | 5-bit code | 4-bit Data | 5-bit code |
|------------|------------|------------|------------|
| 0000 | 11110 | 1000 | 10010 |
| 0001 | 01001 | 1001 | 10011 |
| 0010 | 10100 | 1010 | 10110 |
| 0011 | 10101 | 1011 | 10111 |
| 0100 | 01010 | 1100 | 11010 |
| 0101 | 01011 | 1101 | 11011 |
| 0110 | 01110 | 1110 | 11100 |
| 0111 | 01111 | 1111 | 11101 |

