

```

% 2.2

clear all; clf;

% This was not covered in class or in the book.
load handel.mat;

% Ostensibly, 'y' and 'Fs' are now available.

t = 0:Fs:1;

l = 0.5;

x1 = y;
x2 = 0.8*(y-l);
x3 = 0.5*(y-(2*l));

x = x1 + x2 + x3;

sound(x, Fs);
% Can then be compared against the command: sound(y, Fs);

% 2.5

clear all;

syms s t u(t);

f = 5*(exp(-2*t))*(cos(8*t))*(u(t));

r = -5:0.01:5;

L = laplace(f,t,s);

plot(t,L);

%zplane();

f = 5*(exp(-4*t))*(cos(8*t))*(u(t));

r = -5:0.01:5;

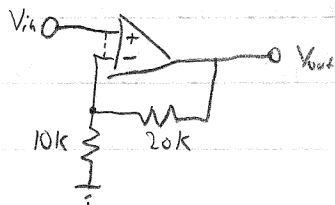
L = laplace(f,t,s);

```

HW #2

CPE 381

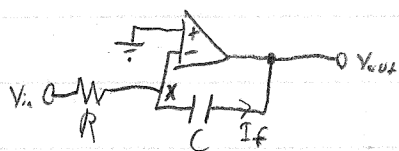
1.



$$i(t) =$$

$$\frac{V_{out}}{V_{in}} = 1 + \frac{R_f}{R_i} = 1 + \frac{20k}{10k} = 1 + 2 = 3$$

$$V_{out} = 3 V_{in}$$

Transfer Function: $F: \frac{V_{out}}{V_{in}}$

$$i(t) = \frac{V_{in} - 0}{R}$$

$$V_c(t) = \frac{1}{C} \int_0^t i(\tau) d\tau$$

$$V_c = \frac{1}{C} = V_{in} - V_{out} = -V_{out}$$

$$I_{in} = \frac{V_{in} - 0}{R_{in}} = \frac{V_{in}}{R_{in}} = \frac{dV_{out} \cdot C}{dt} = I_f$$

$$\frac{V_{out}}{V_{in}} = - \int_0^t \frac{dt}{R_{in} \cdot C}$$

$$3. \quad d(t) = \left(\frac{1}{\tau}\right) e^{-t/\tau} u(t)$$

$$u(t) = \begin{cases} 1 & t > 0 \\ 0 & t < 0 \end{cases}$$

$$4. \quad \frac{V_{out}}{V_{in}} = - \int_0^t \frac{dt}{R \cdot C}$$

6. The lower limit of the integral is 0^- .
Used for solving D.E. with initial conditions.

$$\begin{aligned} 7. \quad f_1(t) &= \sin(t) (u(t) - u(t-\pi)) \\ \mathcal{L}[f_1(t)] &= \mathcal{L}[\sin(t) \cdot u(t)] + \mathcal{L}[\sin(t-\pi) \cdot u(t-\pi)] \\ &= \frac{1}{s^2+1} + \frac{e^{-\pi s}}{s^2+1} = \frac{1+e^{-\pi s}}{s^2+1} \end{aligned}$$