

**PARAMETER NUMBERS AND THEIR CONTENTS  
(CONT'D)**

#6056	(X-axis)
#6057	(Y-axis)
#6058	(Z-axis)
#6059	(4th-axis)

**#6056 to #6059:**

Specify the position error offset, respectively, on the X-, Y-, Z- and 4th-axes (setting range: 0 - 255; "1" = least output increment). The standard setting is 32.

#6068	(X-axis)
#6069	(Y-axis)
#6070	(Z-axis)
#6071	(4th-axis)

**#6068 to 6071:**

Output in pitch error offset pulses the pitch error compensation times each magnification specification, respectively, for the X-, Y-, Z- and 4th axes. The setting range is 1 to 3, and "1" represents a magnification of 1.

#6062	(X-axis)
#6063	(Y-axis)
#6064	(Z-axis)
#6065	(4th-axis)

**#6062 to #6065:**

Specify the overtravel, respectively, on the X-, Y-, Z- and 4th-axes in unidirectional approach (G60; setting range: 0 - 255; "1" = least input increment).

#6074	(X-axis)
#6075	(Y-axis)
#6076	(Z-axis)
#6077	(4th-axis)

**#6074 to #6077:**

Causes an alarm "34\*" when a position deviation exceeding the critical servo error value is detected respectively, on the X-, Y-, Z- and 4th axes.