#6007		D_6		D_4	D_3	D_2		D_0

D_6 1: Employs the newly entered tool compensation value in place of the old value.

0: Adds the newly entered tool compensation value to the soterd value to establish another offset.

D_4 1: Provides output during rewinding.

0: Provides no output during rewinding.

D_3 1: Sets the least increment to 0.0001 in.

0: Sets the least increment to 0.001 mm.

D_2 1: Makes the spindle override 100% during tapping.

0: Does not make the spindle override 100% during tapping.

D_0 1: Establishes the 2nd prohibited area of the stored stroke limit outside the boundary.

0: Establishes the 2nd prohibited area of the stored stroke limit inside the boundary.

#6008							D1	

D1 1: Does not clear the common variables of #100 through #149.

0: Clears the common variables of #100 through #149.

Note: Some controls are not provided with the parameter #6008.

#6009					D_3	D_2	D_1	D_0

D_3, D_2, D_1, D_0

Specify the start direction of backlash compensation on the 4th-, Z-, Y- and X-axes, respectively, upon power application.

1: Minus direction

0: Plus direction

#6010					D_3	D_2	D_1	D_0

D_3, D_2, D_1, D_0

Specify the direction of reference point return on the 4th-, Z-, Y- and X-axes, respectively.

1: Minus direction

0: Plus direction

NOTE: The specification is effective for an axis with #6016 at "1."

#6012					D_3	D_2	D_1	D_0

D_3, D_2, D_1, D_0

Specify whether or not the plus-direction external deceleration signal is effective on the 4th-, Z-, Y- and X-axes, respectively.

1: Makes the plus-direction external deceleration signal effective.

0: Makes the plus-direction external deceleration signal ineffective.

#6013					D_3	D_2	D_1	D_0

D_3, D_2, D_1, D_0

Specify whether or not the minus-direction external deceleration signal is effective on the 4th-, Z-, Y- and X-axes, respectively.

1: Makes the minus direction external deceleration signal effective.

0: Makes the minus direction external deceleration signal ineffective.

#6014					D_3	D_2	D_1	D_0

D_3, D_2, D_1, D_0

Specify the direction of the G60 unidirection approach upper limit on the 4th-, Z-, Y- and X axes, respectively.

1: Minus direction

0: Plus direction

NOTE: The approach upper limit is set with #6062 to #6065.