Table 2.21 List of G codes

			
G	Group	Function	B: Basic
code	3.001		O: Optional
G00		Positioning	В
G01	[Linear interpolation	В
		Circular interpolation	
G02		CW, Helical interpola-	В, О
GUL	01	tion CW	-, -
		Circular interpolation	
~ ~ ~		Circular interpolation	p o
G03		CCW, Helical interpola-	В, О
		tion CCW	
G04		Dwell	В
C0/		Positioning in error	В
G06		detect off mode	В
G09	t	Exact stop	В
	*	Tool offset value and	
G10	1	work coordinate, Shift-	В, О
410	1	value modification	_, -
C13	4	Circle cutting CW	0
G12	1	Circle cutting Cw	0
G13		Circle cutting CCW	
G17		XY plane designation	В
G18	02	ZX plane designation	В
G19]	YZ plane designation	В
GZ0	06	Inch input designation	0
G21	1 00	Metric input designation	Ō
G22		Stored stroke limit ON	0
G23	04	Stored stroke limit OFF	0
G27	 	Reference point check	Ō
	1	Automatic return to	
G28	1	reference point	0
	-	Return from reference	
G29	*	1 .	0
	4	point	
G30	1	Return to 2nd, 3rd,	0
	1	4th reference point	
G31		Skip function	0
G33	01	Thread cutting	0
G 36]	Automatic centering	0
G 37] *	Automatic centering	0
	1	Z-axis reference sur-	0
G 38	1	face offset	0
	·	Tool radius compensa-	0
G40		tion cancel	0
	-	Tool radius compensa-	
G41	07	tion, left	0
	4	Tool radius compensa-	
G42			О
	-	tion, right	
G43	1	Tool length compensa-	В
	╛	tion, plus direction	
G44	08	Tool length compensa-	В
411] "	tion, minus direction	
G49	1	Tool length compensa-	В
G49		tion, cancel	
C 45	—	Tool position offset,	В
G45		extension	D
	4	Tool position offset,	n
G46	l	retraction	В
	-i ∗	Tool position offset,	
G47	1	double extension	В
	4	double extension	···-
G48	1	Tool position offset,	В
		double retraction	
G 50	15	Scaling OFF	0
G51		Scaling ON	0
G 52	12	Return to base coordi-	0
U 52	12	nate system	O
	*	Temporary shift to ma-	0
G53	"	chine coordinate system	U
			

û code	Group	Function	B: Basic O: Optional
G54	12	Shift to work coordinate system 1	0
G55		Shift to work coordinate system 2	0
G56		Shift to work coordinate system 3	0
G57		Shift to work coordinate system 4	0
G58		Shift to work coordinate system 5	0
G59		Shift to work coordinate system 6	0
$\overline{G}60$	01	Unidirectional approach	0
G61	13	Exact stop mode	В
G64	1 13	Exact stop mode cancel	В
G65	*	Non-modal call of user macro	0
G66		Modal call of user macro	0
G67	14	Modal call of user macro cancel	0
G70	 	Bolt hole circle	0
G71	1 *	Arc	0
G72	†	Line-at-angle	0
G73	 	Canned cycle 10	0
G74	1	Canned cycle 11	ŏ
G76	1	Canned cycle 12	ō
	-	Canned cycle 12	
G77	ا مما	Canned cycle 13	
G80	09	Canned cycle cancel	0
G81		Canned cycle 1, Output for external motion	0
G82		Canned cycle 2	0
G83	1.	Canned cycle 3	0
G84		Canned cycle 4	0
G85	1	Canned cycle 5	0
G86	1	Canned cycle 6	0
G87	09	Canned cycle 7	0
G88		Canned cycle 8	0
G89	-	Canned cycle 9	0
007		Absolute command	
G 90	03	designation	В
G91		Incremental command designation	В
G 92	*	Programming of absolute zero point	В
G94	٦	Feed per minute	0
G / I	05	(mm/min) designation	
G95	7 05	Feed per revolution (mm/rev.) designation	0
G 98	10	Return to initial point for canned cycles	0
G99		Return to point R for canned cycles	0
G100	5	High-speed cutting cance	1 0
<u></u>		High-speed cutting in	
G10	16	sequential processing mode ON	0
G10	2	High-speed cutting in processing mode ON	0

Notes:

- 1. The G codes in the * group are non-modal, and are effective only for the block in which they are commanded. They cannot be programmed twice or more in a block. They must be programmed only once in a block of its own.
- 2. The codes marked with \P is automatically selected at power on or resct.