Table 6.7 List of G Codes

							B: Basic	
G.	Group	F 10313	B: Basic O: Optional	G	Group	Function	O: Optional	
code G00		Positioning	В			Shitt to work coordinate		
G01	}	Linear interpolation	В	G54		system I	O	
001	01	Circular interpolation,			1	Shift to work coordinate	0	
G02		CW, Helical interpola-	B, O	G55		system 2		
		tion CW		95/	12	Shift to work coordinate	0	
		Circular interpolation		G56		system 3		
		CCW, Helical interpola-	B, O !	0.5.7		Shift to work coordinate	0	
003		tion CCW		G57		system 4		
G04		Dwell	В	G58		Shift to work coordinate	0	
	1	Positioning in error	В	G 26		system 5		
G06		detect off mode	1	G59		Shift to work coordinate	0	
G09	1	Exact stop	В	i	<u> </u>	system 6		
	*	Tool offset value and	:	G60	01	Unidirectional approach	O B	
G10		work coordinate, Shift-	В,О	G61	13	Exact stop mode	B B	
		value modification		G64		Exact stop mode cancel	+	
G12		Circle cutting CW	0	G65	*	Non-modal call of user	0	
G13	1	Circle cutting CCW	0	Lĵ	L	macro	 	
G17		XY plane designation	В	G66	J ,,	Modal call of user macro Modal call of user macro	 	
G 18	02	ZX plane designation	B	G67	14	cancel	C	
G19		YZ plane designation	B .	l		Bolt hole circle		
G20	06	Inch input designation	0	G70	*	Arc		
GZI	1	Metric input designation	0	G71 G72	- T	Line-at-angle	Ö	
G22	04	Stored stroke limit ON	0	G73	 	Canned cycle 10	0	
G23		Stored stroke limit OFF		G74		Canned cycle 11		
G27	_	Reference point check Automatic return to	 	G76		Canned cycle 12	()	
G28	- {	reference point	0	G77		Canned cycle 13	0	
		Return from reference		G80	09	Canned cycle cancel	0	
G29		point	0	G81	1	Canned cycle 1, Output	0	
	4	Return to 2nd, 3rd,			-	for external motion		
G 30		4th reference point	0	G82		Canned cycle 2	()	
G 31	1	Skip function	Ö	G83		Canned cycle 3	()	
G 33	01	Thread cutting	0	G84	· · · · ·	Canned cycle 4	()	
G 36	+	Automatic centering	0	G85	7	Canned cycle 5	()	
G 37	*	Automatic centering	0	G86	09	Canned cycle 6	0	
		Z-axis reference sur-	0	G87		Canned cycle 7	0	
G38		face offset		G88		Canned cycle 8	0	
	4	Tool radius compensa-	0	G89		Canned cycle 9		
G40 		tion cancel		. G90	03	Absolute command	13	
	07	Tool radius compensa-	0			designation		
		tion, left		-G91		Incremental command	3	
G42		Tool radius compensa-	0			designation Programming of absolute		
042		tion, right		- G92	*	zero point	- В	
G43		Tool length compensa-	В	i	J	Feed per minute		
G44		tion, plus direction		G94 G95	05	(mm/min) designation	0	
		Tool length compensa-	В			Feed per revolution		
		tion, minus direction				(mm/rev.) designation	0	
G49		Tool length compensa-	В			Return to initial point		
		Tool position offset,		- G98	10	for canned cycles	0	
G45	i		B	1:		Return to point R for	0	
	7	extension Tool position offset,	+ · · · · · · · · · · · · · · · · · · ·	- G99	L	canned cycles		
G46		retraction	В	_ G10		High-speed cutting canc	ei 'O	
		Tool position offset,		- 919		High-speed cutting in		
G47		double extension	В	G10	16	sequential processing	0	
•		Tool position offset,	† <u>-</u> -			mode ON	ì	
G48	3	double retraction	В	1	, ,	High-speed cutting in	Э	
G 5 (Scaling OFF	0	- G10)2	processing mode ON		
G51		Scaling ON	0	- 		V		
		Return to base coordi-		- N	otes:			
G 5	2 12	nate system	0	1	. The G codes in the * group are non-modal,			
		Temporary shift to ma-		- 2	and the effective only for the block in which			

- 1. The G codes in the * group are non-modal, and the effective only for the block in which they are commanded. They cannot be programmed twice or more in a block. They must be programmed only once in a block of its own.

О

Temporary shift to ma-

chine coordinate system