

PARAMETER NUMBERS AND THEIR CONTENTS (CONT'D)

#6316	(X-axis)
#6317	(Y-axis)
#6318	(Z-axis)
#6319	(4th-axis)

#6316 to #6319:

Specify the approach speed 2 for reference point return, respectively, on the X-, Y-, Z- and 4th-axes.

Setting: "1" = 7.5 mm/min.

NOTE: The parameters associated with reference point return operations are as follows:

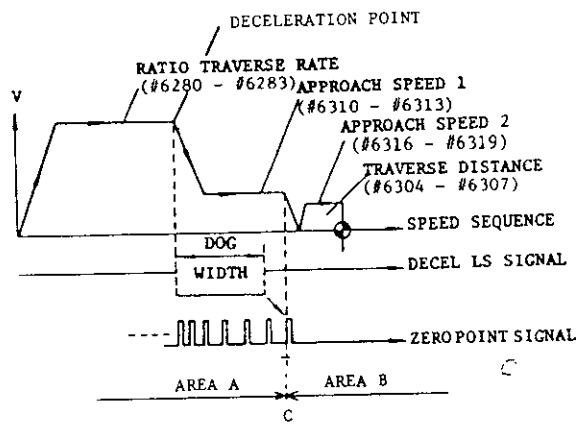


Fig. 3.3.6.5

- Reference point return direction:
#6010 D0 - D3
- Reference point return enabled/disabled:
#6016 D6 - D3

#6322	(X-axis)
#6323	(Y-axis)
#6324	(Z-axis)
#6325	(4th-axis)

#6322 to #6325:

Specify the number of the start point for pitch error compensation, respectively, on the X-, Y-, Z- and 4th-axes.

Setting: 0 - 511

#6328	(X-axis)
#6329	(Y-axis)
#6330	(Z-axis)
#6331	(4th-axis)

#6328 to #6331:

Specify the number of the start point for pitch error compensation, respectively, on the X-, Y-, Z- and 4th-axes.

Setting: 0 - 511

#6334	
#6335	
#6336	
#6337	

#6334 to #6337:

Specify the reference point for pitch error compensation, respectively, on the X-, Y-, Z- and 4th-axes.

Setting: 0 - 511

#6340	
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Specifies the external deceleration speed for rapid traverse.

Setting: "1" = 7.5 mm/min. (common to all axes)

#6341	
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Specifies the external deceleration speed for cutting feed.

Setting: "1" = 1 mm/min. (common to all axes)