

# *Topological Data Analysis and Neuroscience*

## Chapter 2: Simplicial Complex

*Instructor: Alex McCleary*

---

# Section 1: Simplicial Complex



# A (Geometric) Simplex

- ▶ Points  $\{p_0, p_1, \dots, p_d\} \subset R^N$  are linearly independent
  - ▶ if vectors  $v_i = p_i - p_0, i \in [0, d]$ , are linearly independent
- ▶ Geometric  **$p$ -simplex**  $\sigma = \{v_0, v_1, \dots, v_p\}$ 
  - ▶ Convex combination of  $p + 1$  **linearly-independent** points in  $R^N$ 
    - ▶  $\sigma = \{ \sum_{i=0}^p a_i v_i \mid a_i \geq 0, \sum a_i = 1 \}$

## ▶ Examples

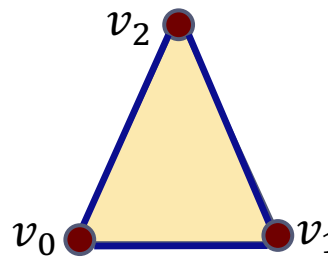


$v_0$

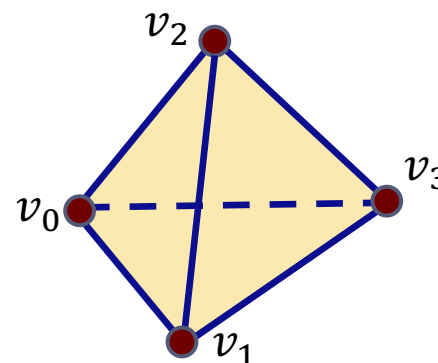
0-simplex



1-simplex



2-simplex



3-simplex

# A (Geometric) Simplex

---

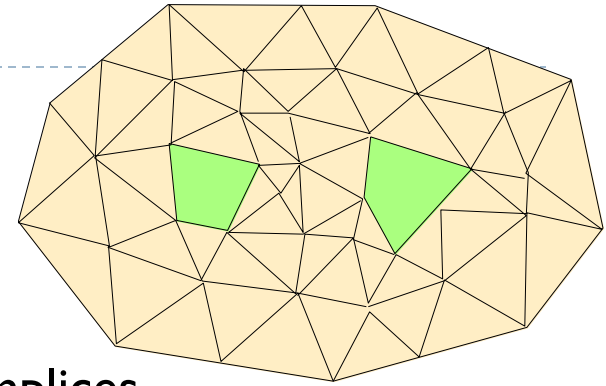
- ▶ Points  $\{p_0, p_1, \dots, p_d\} \subset R^N$  are linearly independent
  - ▶ if vectors  $v_i = p_i - p_0, i \in [0, d]$ , are linearly independent
- ▶ Geometric  **$p$ -simplex**  $\sigma = \{v_0, v_1, \dots, v_p\}$ 
  - ▶ Convex combination of  $p + 1$  **linearly-independent** points in  $R^N$ 
    - ▶  $\sigma = \{ \sum_{i=0}^p a_i v_i \mid a_i \geq 0, \sum a_i = 1 \}$
- ▶ Simplex  $\tau$  formed by a subset of  $\{v_0, v_1, \dots, v_p\}$  is called a **face** of  $\sigma$ , denoted by  $\tau \subseteq \sigma$ 
  - ▶  $\tau$  is a proper face of  $\sigma$  if  $\dim(\tau) = \dim(\sigma) - 1$
  - ▶  $bd(\sigma) =$  collection of all proper faces of  $\sigma$
- ▶ For a  $d$ -simplex  $\sigma$ 
  - ▶  $\sigma \cong R^{d+1}, bd(\sigma) \cong S^d, int(\sigma) \cong R^d$



# Simplicial complex

---

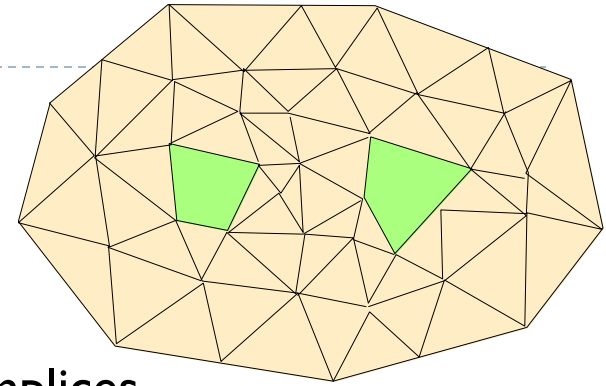
- ▶ A geometric simplicial complex  $K$ 
  - ▶ A collection of simplices such that
    - ▶ If  $\sigma \in K$ , then any face  $\tau \subseteq \sigma$  is also in  $K$
    - ▶ If  $\sigma \cap \sigma' \neq \emptyset$ , then  $\sigma \cap \sigma'$  is a face of both simplices.
  - ▶  $\dim(K) =$  highest dim of any simplex in  $K$



# Simplicial complex

---

- ▶ A geometric simplicial complex  $K$ 
  - ▶ A collection of simplices such that
    - ▶ If  $\sigma \in K$ , then any face  $\tau \subseteq \sigma$  is also in  $K$
    - ▶ If  $\sigma \cap \sigma' \neq \emptyset$ , then  $\sigma \cap \sigma'$  is a face of both simplices.
  - ▶  $\dim(K) =$  highest dim of any simplex in  $K$
- ▶ Subcomplex
  - ▶  $L \subseteq K$  and  $L$  is a complex
- ▶ Underlying space  $|K|$  of  $K$ 
  - ▶ is the pointwise union of all points in all simplices of  $K$ ,
  - ▶ i.e,  $|K| = \bigcup_{\sigma \in K} \{x \mid x \in \sigma\}$



# Abstract simplicial complex

---

- ▶ An **(abstract)  $p$ -simplex**  $\sigma = \{v_0, v_1, \dots, v_p\}$ 
  - ▶ a set of cardinality  $p + 1$
  - ▶ A subset  $\tau \subseteq \sigma$  is a **face** of  $\sigma$
- ▶ An **(abstract) simplicial complex**  $K$ 
  - ▶ A collection of simplices such that
    - ▶ If  $\sigma \in K$ , then any face  $\tau \subseteq \sigma$  is also in  $K$
- ▶ Geometric realization of an abstract simplicial complex  $S$ 
  - ▶ is a geometric simplicial complex  $K$  such that there is an isomorphism between  $Vert(K)$  and  $Vert(S)$  inducing an isomorphism between all simplices in  $K$  and in  $S$



# Geometric realization

---

- ▶ Geometric realization of  $S$  in the standard simplex  $\Delta \subset R^N$  with  $N = |\text{Vert}(S)|$

- ▶ Theorem:

- ▶ Any abstract simplicial complex  $S$  of dimension  $d$  has a geometric realization  $K \subset R^{2d+1}$

- ▶ Sketch of proof

- ▶ Underlying space  $|S|$  of an abstract simplicial complex
  - ▶ is the underlying space of its geometric realization into the standard simplex  $\Delta$





# Star and links

---

- ▶ Given a simplex  $\tau \in K$ 
  - ▶ Star:  $St(\tau) = \{ \sigma \in K \mid \tau \subset \sigma \}$
  - ▶ Closed star:  $clSt(\tau) = \bigcup_{\sigma \in St(\tau)} \{ \sigma' \mid \sigma' \subset \sigma \}$
  - ▶ Link:  $Lk(\tau) = \{ \sigma \in clSt(\tau) \mid \sigma \cap \tau = \emptyset \}$
- ▶ Intuition and examples



# Simplicial map

---

- ▶ Intuitively, analogous to continuous maps between topological spaces
- ▶ Given simplicial complexes  $K$  and  $L$ 
  - ▶ a function  $f: K \rightarrow L$  is a **simplicial map** if
    - ▶  $f(\text{Vert}(K)) \subseteq \text{Vert}(L)$
    - ▶ for any  $\sigma = \{p_0, \dots, p_d\}$ ,  $f(\sigma) = \{f(p_0), \dots, f(p_d)\}$  spans a simplex in  $L$
- ▶ A function  $f: K \rightarrow L$  is an isomorphism
  - ▶ if  $f$  is a simplicial map and it is bijective



# Simplicial map

---

- ▶ A simplicial map  $f: K \rightarrow L$  induces a natural continuous function  $f': |K| \rightarrow |L|$ 
  - ▶ s.t  $f'(x) = \sum_{i \in [0,d]} a_i f(p_i)$  for  $x = \sum_{i \in [0,d]} a_i p_i \in \sigma = \{p_0, \dots, p_d\}$

## ▶ Theorem:

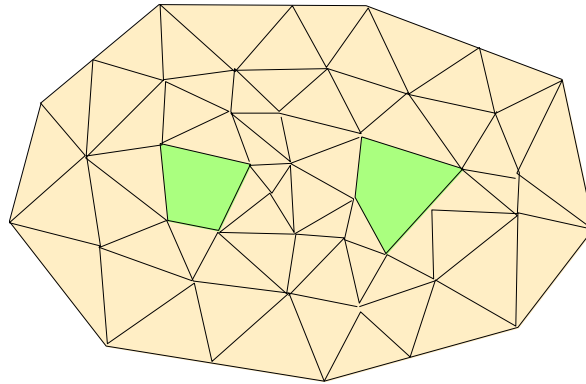
- ▶ An isomorphism  $f: K \rightarrow L$  induces a homeomorphism  $f': |K| \rightarrow |L|$



# Triangulation of a manifold

---

- ▶ Given a manifold (with or without boundary)  $M$ , a simplicial complex  $K$  is a **triangulation** of  $M$ 
  - ▶ if the underlying space  $|K|$  of  $K$  is homeomorphic to  $M$



# Triangulation of a manifold

---

- ▶ Given a manifold (with or without boundary)  $M$ , a simplicial complex  $K$  is a **triangulation** of  $M$ 
  - ▶ if the underlying space  $|K|$  of  $K$  is homeomorphic to  $M$
- ▶ If  $K$  is a triangulation of  $d$ -manifold  $M$ 
  - ▶ then the dimension of  $K$  is also  $d$
  - ▶ for any vertex  $v \in \text{Vert}(K)$ ,  $St(v) \cong B_d^o \cong R^d$
- ▶ Examples of 2-manifolds / 2-complex



---

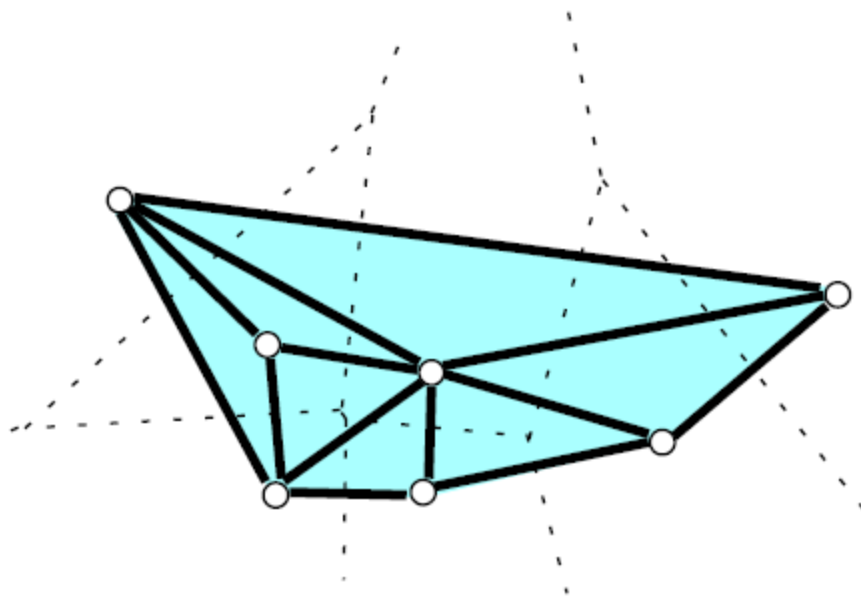
## Section 2: Common Complexes



# Delaunay Complex

---

- ▶ Given a set of points  $P = \{p_1, p_2, \dots, p_n\} \subset R^d$
- ▶ Delaunay complex  $Del(P)$ 
  - ▶ A simplex  $\sigma = [p_{i_0}, p_{i_1}, \dots, p_{i_k}]$  is in  $Del(P)$  if and only if
    - ▶ There exists a ball  $B$  whose boundary contains vertices of  $\sigma$ , and that the interior of  $B$  contains no other point from  $P$ .



# Delaunay Complex

---

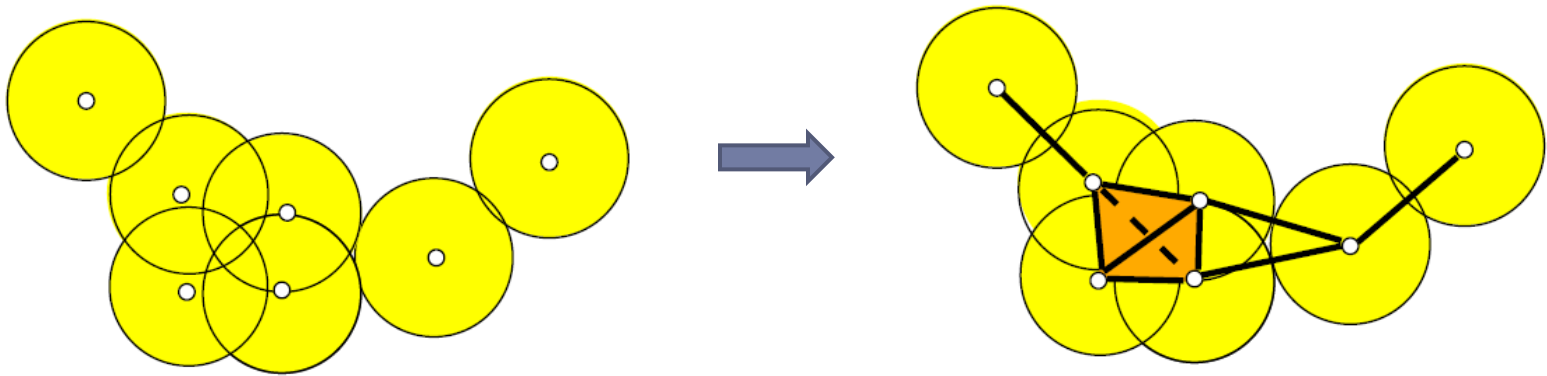
- ▶ Many beautiful properties
  - ▶ Connection to Voronoi diagram
- ▶ Foundation for surface reconstruction and meshing in 3D
  - ▶ *[Dey, Curve and Surface Reconstruction, 2006],*
  - ▶ *[Cheng, Dey and Shewchuk, Delaunay Mesh Generation, 2012]*
- ▶ However,
  - ▶ Computationally very expensive in high dimensions





# Čech Complex

- ▶ Given a set of points  $P = \{p_1, p_2, \dots, p_n\} \subset R^d$
- ▶ Given a real value  $r > 0$ , the **Čech complex**  $C^r(P)$  is the **nerve** of the set  $\{B(p_i, r)\}_{i \in [1, n]}$ 
  - ▶ i.e,  $\sigma = \{p_{i_0}, \dots, p_{i_s}\} \in C^r(P)$  iff  $\bigcap_{j \in [0, s]} B(p_{i_j}, r) \neq \emptyset$
- ▶ The definition can be extended to a finite sample  $P$  of a metric space.



# Nerves

---

- ▶ Given a finite set  $F$ , its **nerve complex**  $Nrv(F)$  is
  - ▶ defined as all non-empty subset of  $F$  with non-empty common intersection
  - ▶ i.e,  $Nrv(F) = \{ X \subseteq F \mid \bigcap_{\sigma \in X} \sigma \neq \emptyset \}$
- ▶ Hence Čech complex  $C^r(P)$ 
  - ▶ is the nerve of  $F = \{ B(p, r) \mid p \in P \}$
  - ▶ i.e,  $C^r(P) = Nrv(F)$



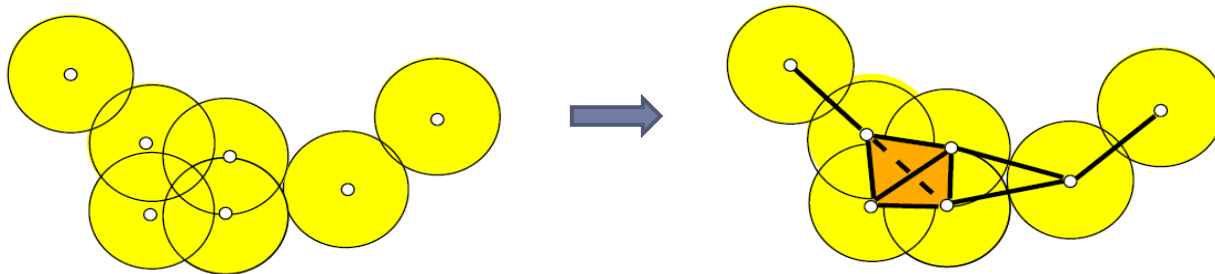
# Nerve Lemma

## ► Nerve Lemma:

- Let  $F$  be a finite set of closed, convex set in  $R^d$ . Then  $Nrv(F) \simeq |F|$ , that is,  $Nrv(F)$  is homotopy equivalent to  $|F|$ .

## ► Corollary:

- $C^r(P) \simeq \bigcup_{p \in P} B(p, r)$ , i.e,  $C^r(P)$  is homotopy equivalent to the union of  $r$ -balls around points in  $P$



# Nerve Lemma

## ► Nerve Lemma:

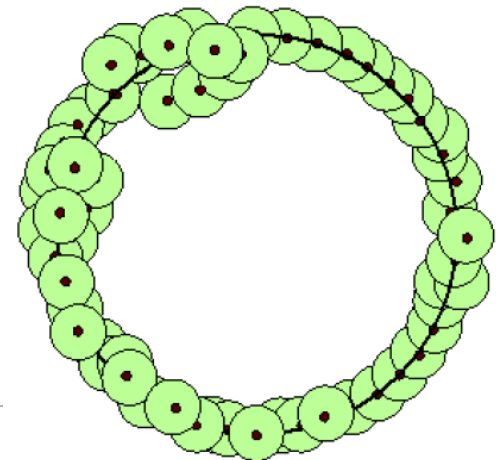
- Let  $F$  be a finite set of closed, convex set in  $R^d$ . Then  $Nrv(F) \simeq |F|$ , that is,  $Nrv(F)$  is homotopy equivalent to  $|F|$ .

## ► Corollary:

- $C^r(P) \simeq \bigcup_{p \in P} B(p, r)$ , i.e,  $C^r(P)$  is homotopy equivalent to the union of  $r$ -balls around points in  $P$

## ► Given a set of points $P$

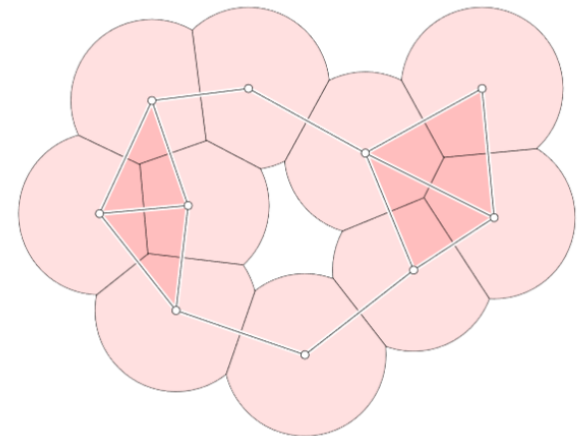
- approximating a hidden domain  $M$
- $U^r(P) = \bigcup_{p \in P} B(p, r)$  approximates  $M$
- $C^r(P)$  approximates  $U^r(P)$



# More on Čech

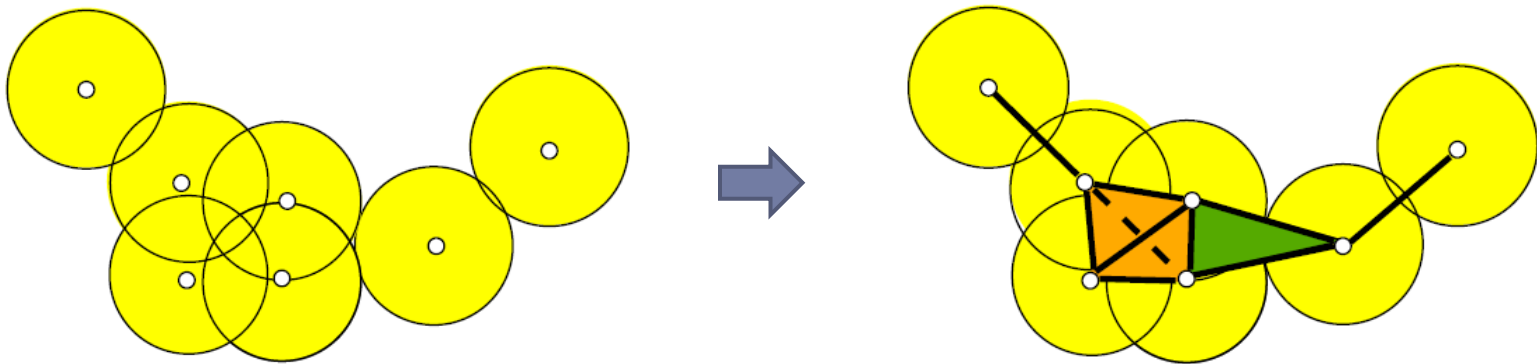
---

- ▶ Given a set of points  $P \subset \mathbb{R}^d$ 
  - ▶  $C^r(P)$  could have simplex of dimension larger than  $d$
  - ▶ often only  $d$ -skeleton of  $C^r(P)$  is needed
    - ▶ as  $U^r(P)$  has trivial topology beyond dimension  $d$
- ▶ Čech and Delaunay
  - ▶ Delaunay complex:  $Del(P) = Nrv(\{Vor(p) \mid p \in P\})$
  - ▶  $\alpha$ -complex:  $Del^r(P) = Nrv(\{Vor(p) \cap B(p, r) \mid p \in P\})$
  - ▶  $Del^{r(P)} \subseteq C^r(P)$
- ▶  $C^r(P)$  typically has much larger size



# Rips Complex

- ▶ Given a set of points  $P = \{p_1, p_2, \dots, p_n\} \subset R^d$
- ▶ Given a real value  $r > 0$ , the *Vietoris-Rips (Rips) complex*  $R^r(P)$  is:
  - ▶  $\{ (p_{i_0}, p_{i_1}, \dots, p_{i_k}) \mid B_r(p_{i_l}) \cap B_r(p_{i_j}) \neq \emptyset, \forall l, j \in [0, k] \}$ .



- Rips complex shares the same edge set as the Cech complex w.r.t same  $r$ .
- It is the *clique complex* induced by its edge set.

# Rips and Čech Complexes

---

- ▶ Relation in general metric spaces
  - ▶  $C^r(P) \subseteq R^r(P) \subseteq C^{2r}(P)$
  - ▶ Bounds better in Euclidean space
- ▶ Simple to compute
- ▶ Able to capture geometry and topology
  - ▶ One of the most popular choices for topology inference in recent years
- ▶ However:
  - ▶ Huge sizes
  - ▶ Computation also costly



# Witness Complexes

---

- ▶ A simplex  $\sigma = \{q_0, \dots, q_k\}$  is *weakly witnessed* by a point  $x$  if  $d(q_i, x) \leq d(q, x)$  for any  $i \in [0, k]$  and  $q \in Q \setminus \{q_0, \dots, q_k\}$ .
  - ▶ is *strongly witnessed* if in addition  $d(q_i, x) = d(q_j, x), \forall i, j \in [0, k]$
- ▶ Given a set of points  $P = \{p_1, p_2, \dots, p_n\} \subset R^d$  and a subset  $Q \subseteq P$
- ▶ The *witness complex*  $W(Q, P)$  is the collection of simplices with vertices from  $Q$  whose all subsimplices are weakly witnessed by a point in  $P$ .
  - ▶ *[de Silva and Carlsson, 2004] [de Silva 2003]*
  - ▶ Can be defined for a general metric space
  - ▶  $P$  does not have to be a finite subset of points

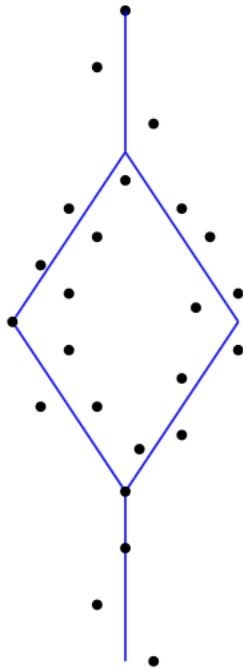




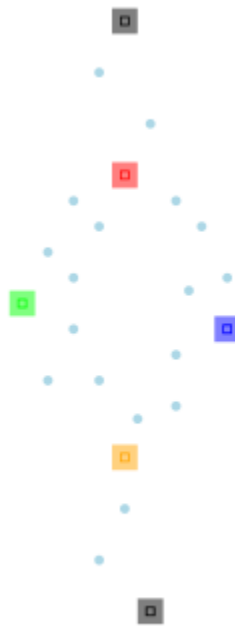
# Intuition

---

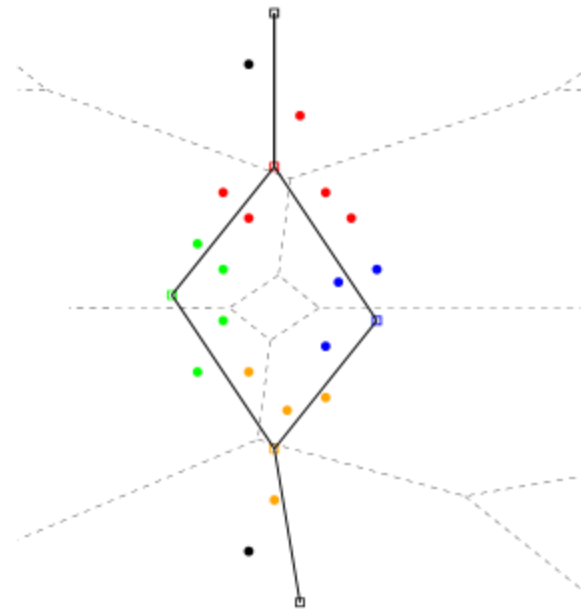
- $L$ : landmarks from  $P$ , a way to subsample.



$P$



$L \subseteq P$

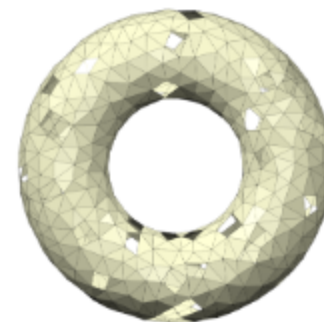


$W(L, P)$

# Witness Complexes

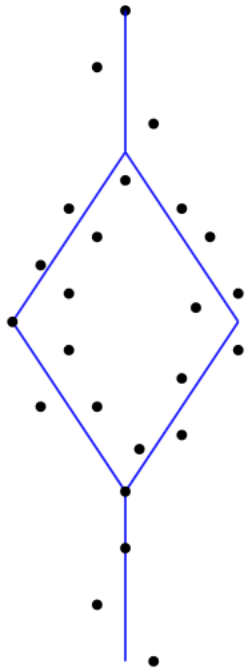
---

- ▶ Greatly reduce size of complex
  - ▶ Similar to Delaunay triangulation, remove redundancy
- ▶ Relation to Delaunay complex
  - ▶  $W(Q, P) \subseteq Del Q$  if  $Q \subseteq P \subset R^d$
  - ▶  $W(Q, R^d) = Del Q$
  - ▶  $W(Q, M) = Del|_M Q$  if  $M \subseteq R^d$  is a smooth 1-c
  - ▶ *[Attali et al, 2007]*
- ▶ However,
  - ▶ Does not capture full topology easily for high-dimensional manifolds

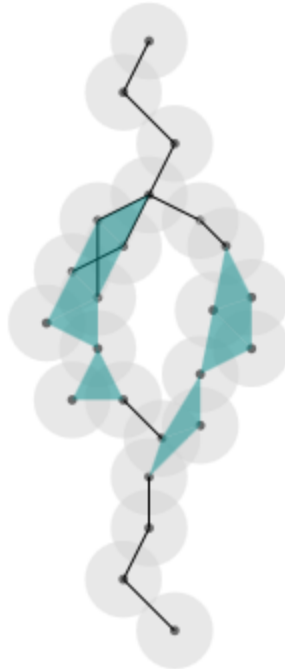


# Subsampling

---



$P$

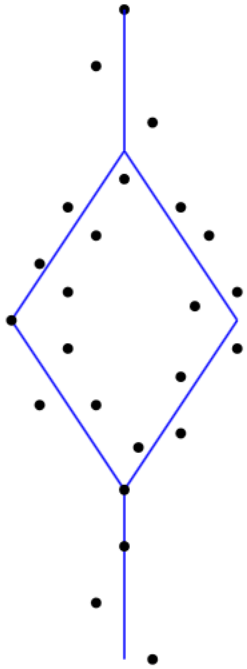


$R^\epsilon(P)$



# Subsampling -cont

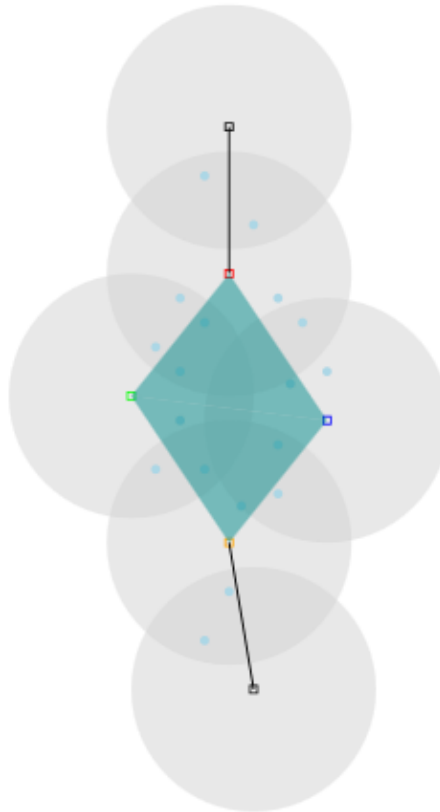
---



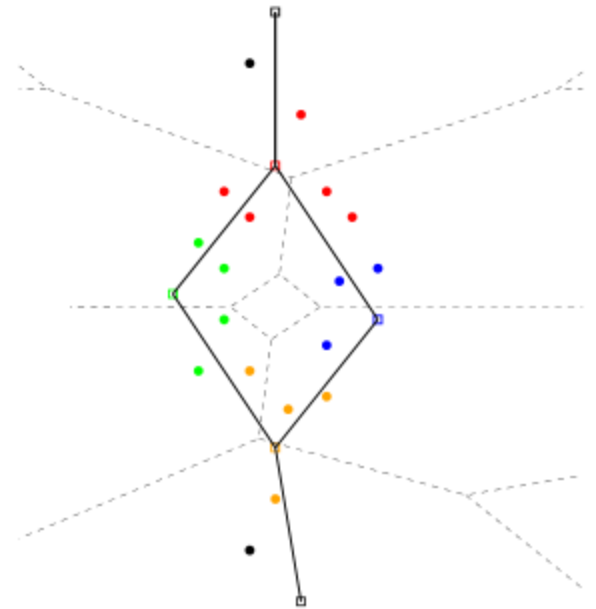
$P$



$Q \subseteq P$



$R^r(Q)$

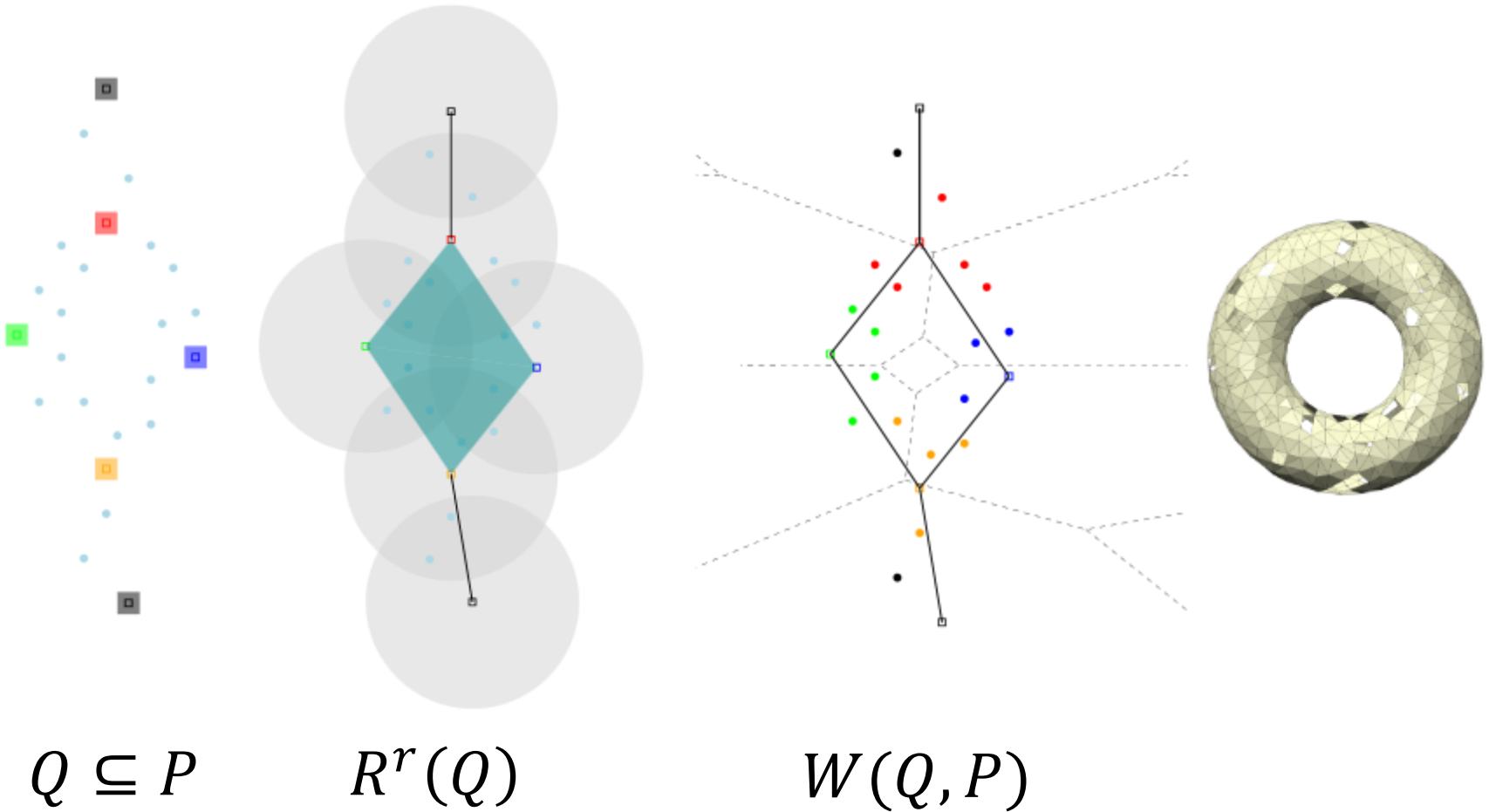


$W(Q, P)$



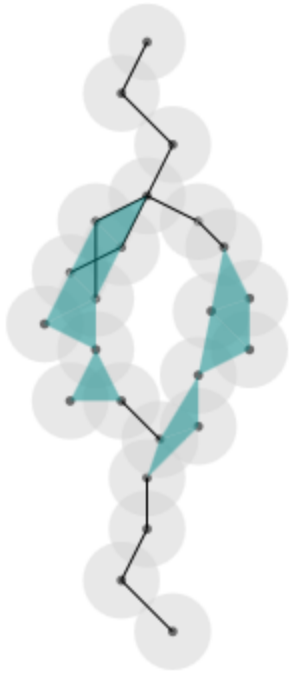
# Subsampling -cont

---

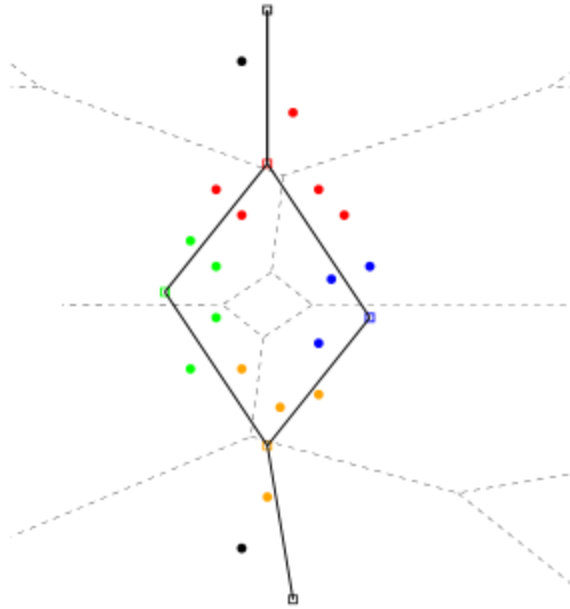


# Subsampling - cont

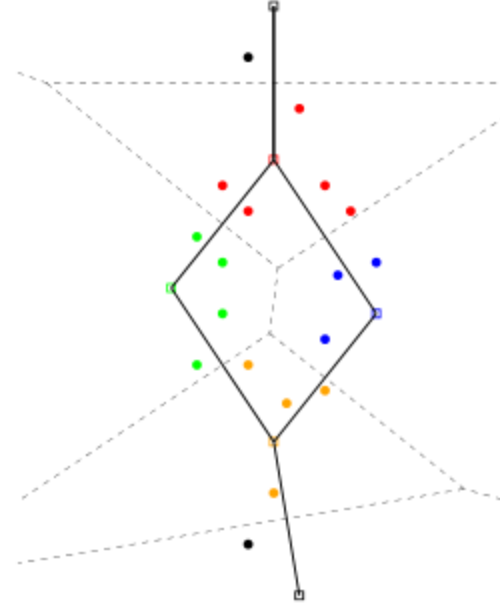
---



$$R^\epsilon(P)$$



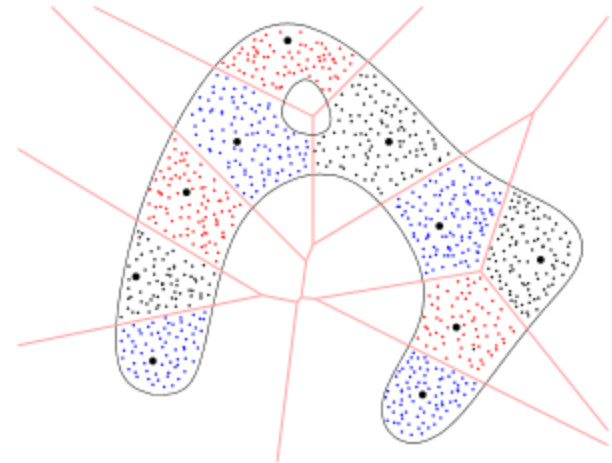
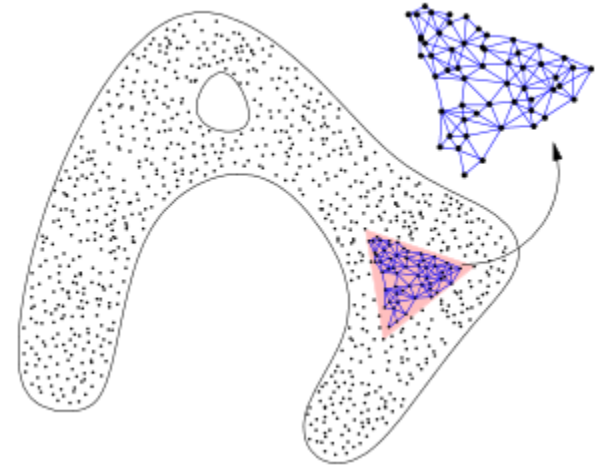
$$W(Q, P)$$



$$G^r(Q, P)$$

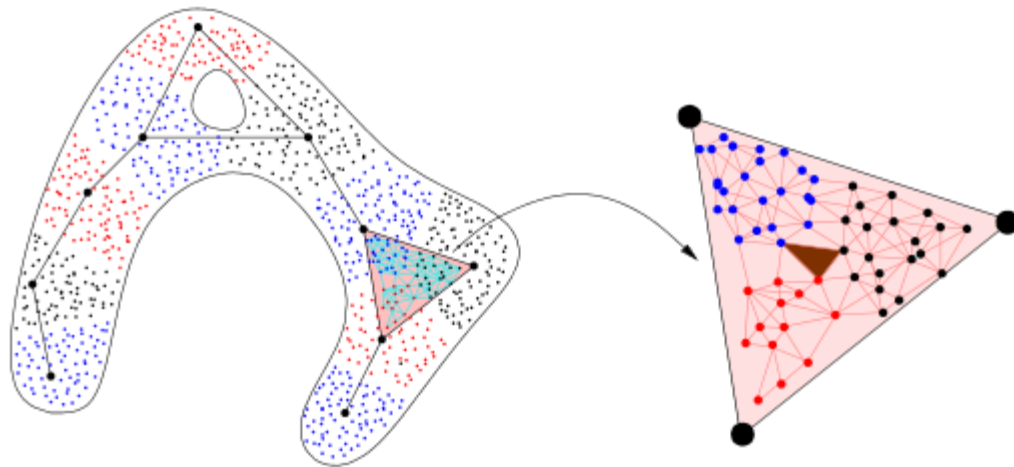
# Graph Induced Complex

- ▶ *[Dey, Fan, Wang, SoCG 2013]*
  - ▶  $P$ : finite set of points
  - ▶  $(P, d)$ : metric space
  - ▶  $G(P)$ : a graph
- 
- ▶  $Q \subset P$ : a subset
  - ▶  $\pi(p)$ : the closest point of  $p \in P$  in  $Q$



# Graph Induced Complex

- ▶ **Graph induced complex**  $\mathcal{G}(P, Q, d): \{q_0, \dots, q_k\} \subseteq Q$ 
  - ▶ if and only if there is a  $(k+1)$ -clique in  $G(P)$  with vertices  $p_0, \dots, p_k$  such that  $\pi(p_i) = q_i$ , for any  $i \in [0, k]$ .

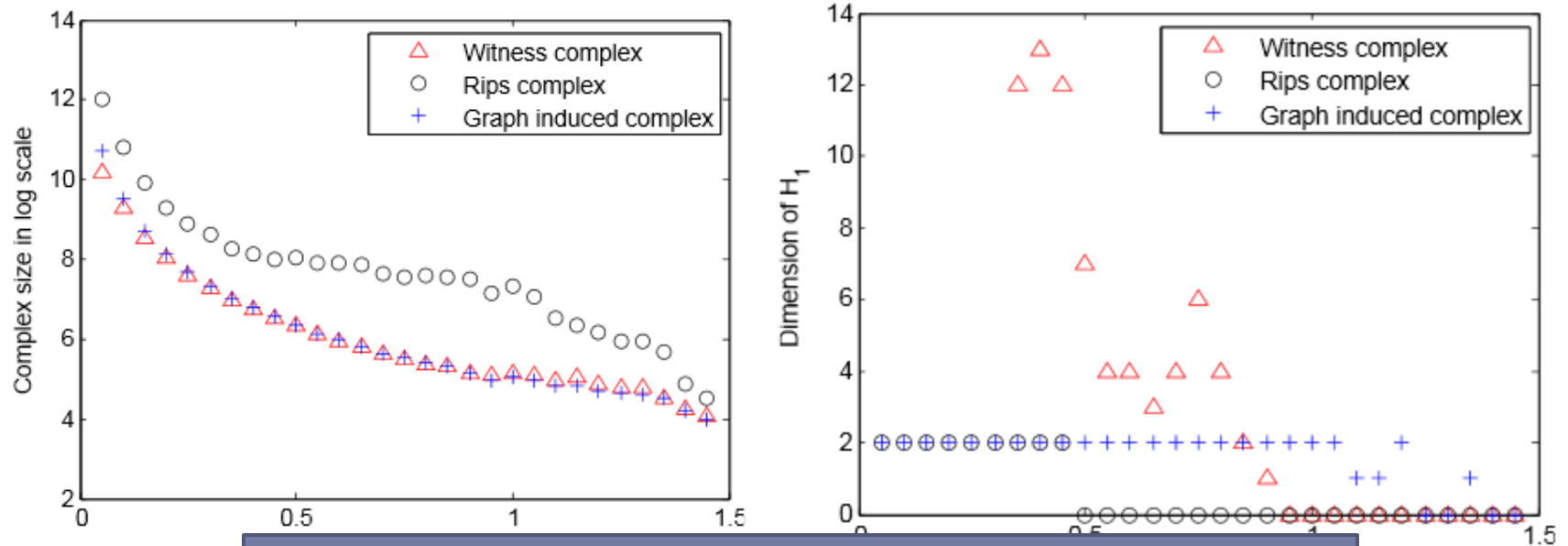


- ▶ Graph induced complex depends on the metric  $d$ :
  - ▶ Euclidean metric
  - ▶ Graph based distance  $d_G$



# Graph Induced Complex

- ▶ Small size, but with homology inference guarantees
- ▶ In particular:
  - ▶  $H_1$  inference from a lean sample

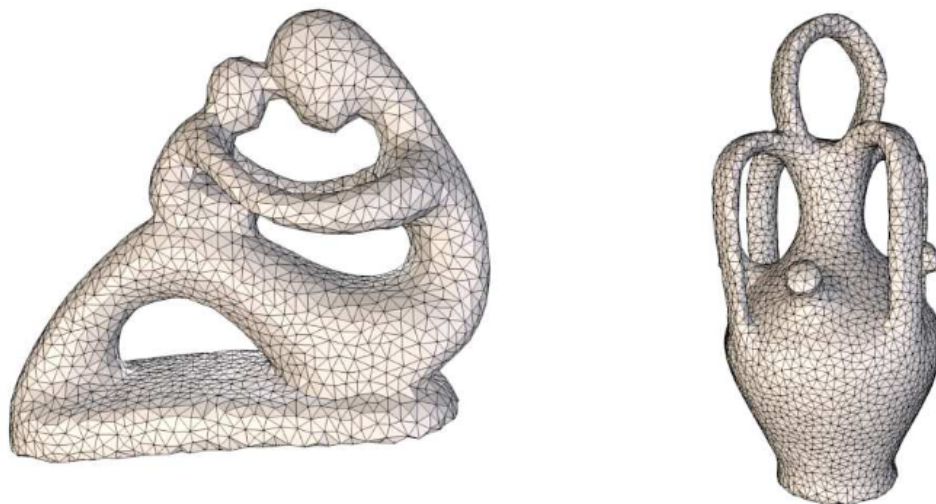


GIC can also be used as a way to sparsify graphs while maintaining global structure.

# Graph Induced Complex

---

- ▶ Small size, but with homology inference guarantees
- ▶ In particular:
  - ▶  $H_1$  inference from a lean sample
  - ▶ Surface reconstruction in  $R^3$



- ▶ Topological inference for compact sets in  $R^d$  using persistence

