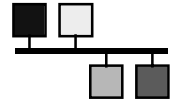




EPICS



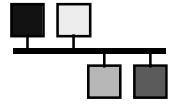
Writing Channel Access Clients

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Observatory Sciences Limited



Outline

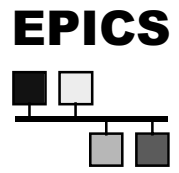
EPICS



- ◆ EPICS Communication Protocol
 - ◆ Client/Server Architecture
- ◆ Server is part of iocCore
- ◆ Basic Principles of Client Operation
- ◆ Clients are written using the CA Client Library – Basic Functions:
 - ◆ Initialize CA
 - ◆ Search
 - ◆ Put
 - ◆ Get
 - ◆ Monitors
 - ◆ Flush Send Buffer
 - ◆ Error reporting
- ◆ Explain 6 example clients
- ◆ See EPICS 3.12 Channel Access Reference Manual for full details of functions and macros (not changed for 3.13)
- ◆ Channel Access Performance Figures



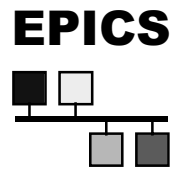
Basic Principles of Client Operation



- ◆ CA library calls are buffered until either:
 - ◆ send buffer is full
 - ◆ a special CA library call is made
 - ◆ allows efficient operation over a network
- ◆ Error codes returned from CA library calls only check the validity of the request NOT the success of the operation.
- ◆ When the server detects an error, an exception handler is executed in the client. Default is to print a message to the screen.



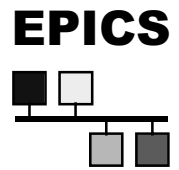
Initialize



- ◆ `ca_task_initialize()`
- ◆ Should be called prior to making any other CA calls.
- ◆ If you forget, it will be called from the first call to any `ca_xxx` function.
- ◆ Registers this client with the CA repeater.
 - ◆ This is a daemon (under Unix) which fans out UDP broadcasts received on the CA UDP port to all CA processes running on the machine. Solves the problem of the O/S only allowing one process to have access to the port.



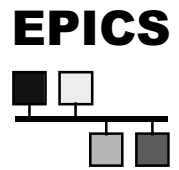
Search



- ◆ `ca_search("name", &channelId)`
 - ◆ Causes a UDP broadcast to be sent to each IOC on the subnet.
 - ◆ A TCP connection is then established with the IOC that contains this record.
 - ◆ Using the channel identifier, a client can retrieve lots of useful information.



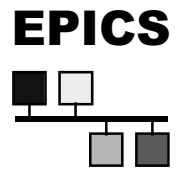
Put



- ◆ There are many CA PUT functions:
 - ◆ `ca_put(field_type, channelId, &val)`
 - ◆ `ca_put_callback`
(`field_type`, `channelId`, `&val`, `usrFunc`, `usrArg`)
- ◆ “`field_type`” is one of `DBR_DOUBLE` etc. See:
`base/include/db_access.h`.
- ◆ Conversion between types are done in the server so ask for native types for better performance at the real-time end!
- ◆ All use “channel ID” from Search to communicate with record field
- ◆ `usrFunc` is called after all records in the processing chain in the database have been processed.



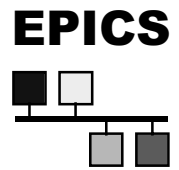
Get



- ◆ There are many CA GET functions:
 - ◆ `ca_get(field_type, channelId, &val)`
 - ◆ `ca_get_callback`
`(field_type, channelId, usrFunc, usrArg)`
- ◆ Arguments similar to the PUT functions.
- ◆ Notice that `ca_get_callback` does not get the value directly. It is available to the user defined function (see example).



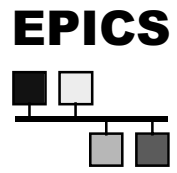
Monitors



- ◆ How can we write a client which will react to monitors raised in the database?
- ◆ Use:
`ca_add_event(field_type, channelId,
usrFunc, usrArg, eventId
)`
- ◆ `usrFunc` will be called when the channel's value changes by more than the dead band or when the channel's alarm state changes.
- ◆ `eventId` is a pointer to a user defined event ID. Often omitted by setting as `NULL`.



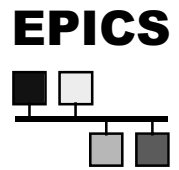
Flushing the Send Buffer



- ◆ Vital for the CA client to work!!
- ◆ All CA client calls are buffered until either the send buffer is full or one of these is explicitly called:
 - ◆ `ca_pend_io(timeout)`
Flushes the send buffer and waits until the shorter of:
 - ◆ All outstanding calls to `ca_get` complete
 - ◆ The timeout expires(Note a timeout of 0 means wait forever)
 - ◆ `ca_pend_event(timeout)`
Flushes the send buffer and always waits "timeout" seconds for asynchronous events (timeout of 0 means wait forever)



Error Reporting



- ◆ For portability reasons CA functions do not return status following the UNIX convention.
- ◆ Do not test return status against “0”.
- ◆ Useful macro for testing return status:

SEVCHK(status, “user string”);

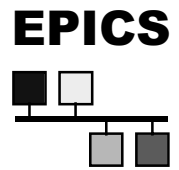
but CANNOT do: “if(SEVCHK())”

So in the following examples, I have defined this:

```
#define MY_SEVCHK(status)           \  
{                                   \  
    if( status != ECA_NORMAL )     \  
    {                               \  
        SEVCHK(status, NULL);      \  
        exit(status);              \  
    }                               \  
}
```



Example Client caPut1.c



```
#include <stdio.h>
#include <stdlib.h>
#include <cadef.h>    /* Structures and data types used by CA */

int main( int argc, char *argv[] )
{
    int      status;
    chid     channelld;
    double val;

    val = atof( argv[1] );

    status = ca_task_initialize();
    MY_SEVCHK(status);

    status = ca_search( "test:ai", &channelld );
    MY_SEVCHK(status);

    status = ca_pend_io(0.0);
    MY_SEVCHK(status);

    status = ca_put( DBR_DOUBLE, channelld, &val );
    MY_SEVCHK(status);

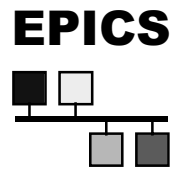
    status = ca_pend_io(0.0);
    MY_SEVCHK(status);

    return(0);
}
```

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Example Client caGet1.c



```
#include <stdio.h>
#include <stdlib.h>
#include <cadef.h>

int main( int argc, char *argv[] )
{
    int      status;
    chid     channelId;
    double val;

    status = ca_task_initialize();
    MY_SEVCHK(status);

    status = ca_search( "test:ai", &channelId );
    MY_SEVCHK(status);

    status = ca_pend_io(0.0);
    MY_SEVCHK(status);

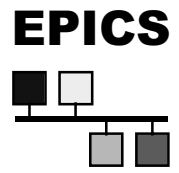
    status = ca_get( DBR_DOUBLE, channelId, &val );
    MY_SEVCHK(status);

    status = ca_pend_io(0.0);
    MY_SEVCHK(status);

    printf("Value is %f\n", val);
    return(0);
}
```



Example Client caPut2.c (main)



```
int main( int argc, char *argv[] )
{
    int      status;
    chid     channelId;
    double val;
    info_t   info;

    info.project = "Diamond";
    info.numloc = 167;
    info.current = 3.45;
    val          = atof( argv[1] );

    status = ca_task_initialize();
    MY_SEVCHK(status);

    status = ca_search( "test:ai", &channelId );
    MY_SEVCHK(status);

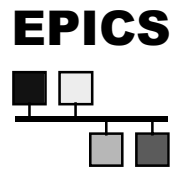
    status = ca_pend_io(0.0);
    MY_SEVCHK(status);

    status = ca_put_callback( DBR_DOUBLE, channelId, &val,
                             (void (*)( ))usrFunc, &info );
    MY_SEVCHK(status);

    status = ca_pend_event(0.1); /* This is different! */
    MY_SEVCHK(status);
    return(0);
}
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```



Example Client caPut2.c (the rest)



```
#include <stdio.h>
#include <stdlib.h>
#include <cadef.h>
```

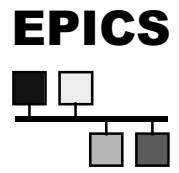
```
typedef struct info
{
    char    *project;
    int     numloc;
    double  current;
} info_t;
```

```
void usrFunc( struct event_handler_args args )  /* cadef.h */
{
    info_t *t = (info_t *)args.usr;

    printf("UsrFunc called:\n");
    printf("User Argument Name    = %s\n", t->project);
    printf("User Argument Numloc = %d\n", t->numloc);
    printf("User Argument Current = %f\n", t->current);
    printf("Channel Name            = %s\n", ca_name(args.chid) );
    printf("Number of Elements      = %d\n",
        ca_element_count(args.chid) );
    printf("Host Name                = %s\n",
        ca_host_name(args.chid) );
}
```



Example Client caGet2.c (main)



```
int main( int argc, char *argv[] )
{
    int      status;
    chid     channelId;
    info_t   info;

    info.project = "Diamond";
    info.numloc = 167;
    info.current = 3.45;

    status = ca_task_initialize();
    MY_SEVCHK(status);

    status = ca_search( "test:ai", &channelId );
    MY_SEVCHK(status);

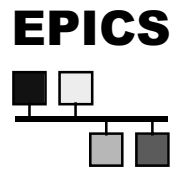
    status = ca_pend_io(0.0);
    MY_SEVCHK(status);

    status = ca_get_callback( DBR_DOUBLE, channelId,
                             (void (*)())usrFunc, &info );
    MY_SEVCHK(status);

    status = ca_pend_event(0.1); /* This is different! */
    MY_SEVCHK(status);
    return(0);
}
```



Example Client caGet2.c (the rest)



```
#include <stdio.h>
#include <stdlib.h>
#include <cadef.h>
```

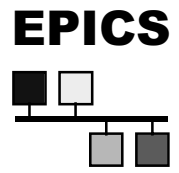
```
typedef struct info
{
    char    *project;
    int     numloc;
    double  current;
} info_t;
```

```
void usrFunc( struct event_handler_args args ) /* cadef.h */
{
    info_t *t = (info_t *)args.usr;

    printf("UsrFunc called: Value      = %f\n", *(double *)args.dbr);
    printf("User Argument Name      = %s\n", t->project);
    printf("User Argument Numloc = %d\n", t->numloc);
    printf("User Argument Current = %f\n", t->current);
    printf("Channel Name              = %s\n", ca_name(args.chid) );
    printf("Number of Elements      = %d\n",
        ca_element_count(args.chid) );
    printf("Host Name                = %s\n",
        ca_host_name(args.chid) );
}
```




Example Client caMonitor.c (main)



```
int main( int argc, char *argv[] )
{
    int      status;
    chid     channelId;

    status = ca_task_initialize();
    MY_SEVCHK(status);

    /* Note new type of search call */
    status = ca_search_and_connect( "test:ai", &channelId,
                                   (void (*)())connectFunc, NULL );

    MY_SEVCHK(status);

    status = ca_pend_io(0.0);
    MY_SEVCHK(status);

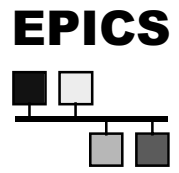
    status = ca_add_event( DBR_DOUBLE, channelId,
                           (void (*)())monitorFunc, NULL, NULL );

    MY_SEVCHK(status);

    status = ca_pend_event(0.0); /* Wait forever */
    MY_SEVCHK(status);
    return(0);
}
```



Example Client caMonitor.c (the rest)



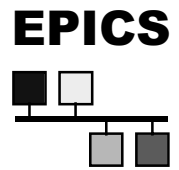
```
#include <stdio.h>
#include <stdlib.h>
#include <cadef.h>
```

```
void connectFunc( struct connection_handler_args args )
{
    if( ca_state(args.chid) != cs_conn )
        printf("%s" has just Disconnected\n",
            ca_name(args.chid));
    else
        printf("%s" has just Connected\n", ca_name(args.chid));
}
```

```
void monitorFunc( struct event_handler_args args )
{
    printf("Monitor on %s, new value = %f\n",
        ca_name(args.chid), *(double *)args.dbr);
}
```



Composite Data Structures

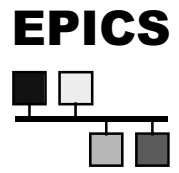


- ◆ Requests can be made for data related to the value field e.g.
 - ◆ Alarm Status
 - ◆ Alarm Severity
 - ◆ Precision
 - ◆ Engineering units
 - ◆ Time Stamp
 - ◆ Display Limits
 - ◆ Alarm Limits

- ◆ Many fields are fetched from the database in one access



Example Client caGet3.c (main)



```
int main( int argc, char *argv[] )
{
    int                status;
    chid               channelId;
    struct dbr_ctrl_double  data;
    struct dbr_time_double tdata;
    struct tsDetail      T;

    status = ca_task_initialize();
    MY_SEVCHK(status);

    status = ca_search( "test:ai", &channelId );
    MY_SEVCHK(status);

    status = ca_pend_io(0.0);
    MY_SEVCHK(status);

    status = ca_get( DBR_CTRL_DOUBLE, channelId, &data );
    MY_SEVCHK(status);

    status = ca_get( DBR_TIME_DOUBLE, channelId, &tdata );

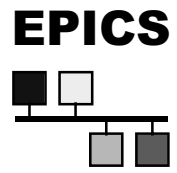
    status = ca_pend_io(0.0);
    MY_SEVCHK(status);

    tsStampToLocal( tdata.stamp, &T );
    printResults( data, T );
    return(0);
}
```

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Example Client caGet3.c (the rest)

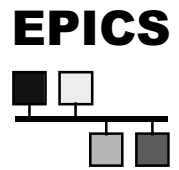


```
#include <stdio.h>
#include <stdlib.h>
#include <cadef.h>

void printResults( struct dbr_ctrl_double data, struct tsDetail T )
{
    printf("Channel Value          = %f\n", data.value);
    printf("Alarm Status            = %d\n", data.status);    /* see alarm.h */
    printf("Alarm Severity             = %d\n", data.severity); /* see alarm.h */
    printf("Precision                  = %d\n", data.precision);
    printf("Engineering Units          = %s\n", data.units);
    printf("Upper Display Limit = %d\n",
                                data.upper_disp_limit);
    printf("Lower Display Limit = %d\n",
                                data.lower_disp_limit);
    printf("Upper Alarm Limit = %d\n",
                                data.upper_alarm_limit);
    printf("Lower Alarm Limit = %d\n",
                                data.lower_alarm_limit);
    printf("Upper Warning Limit = %d\n",
                                data.upper_warning_limit);
    printf("Lower Warning Limit = %d\n",
                                data.lower_warning_limit);
    printf("Last Processed on: %d/%d/%d %d:%d:%d\n",
            T.dayMonth+1, T.monthNum+1, T.year,
            T.hours, T.minutes, T.seconds);
}
```



Channel Access Performance



Figures

- ◆ External factors should be taken into account such as the network loading during the test

	PowerPC	68040
ca_search	1050/sec	840/sec
ca_put	43,500/sec	9200/sec
ca_get	17,300/sec	8500/sec

- ◆ Based on measurements at the KEK Accelerator. See:

www.aps.anl.gov/icalepcs97/paper97/p077.pdf
for the full story