

SIMULATION & PHYSICS – PRACTICAL 5

Write a report (pdf or word) in which you **explain** your solution to the assignments below.

For each assignment:

1. repeat the assignment you are implementing;
2. explain your approach;
3. describe your code;
4. show (relevant) code snippets;
5. include a screenshot of your program.

Once your report is finished, make sure your name and student number is on the title page, and upload it to the corresponding Assignment in your **VLO group** before June 11th, 23:00.

Assignments are graded with a V (sufficient) or O (insufficient).

You can work in pairs, but you each have to write your own explanations!

(Code snippets and screenshots may be identical.)

Continue the source solution from your finished assignment 4 “Collision”. It's advisable to make a copy of your previous project before you start implementing the assignments below.

Assignment 1: Collision with inelastic bounce & mass

Adjust the collision method `ResolveCollisionWith` in the `Ball` class so that the collision of all the balls is affected by an inelastic bounce and by mass as explained in the slides from practical 5:

- Randomize the radii of the balls in the `PlayingState` from 8 to 23.
- Create a variable for `inverseMass`. $inverseMass = 1/(radius * radius)$;
- Implement collision influenced by the mass of the Balls according to the final collision algorithm from the slides of practical 5.
- *Note: `bounceFactor` is named `inelastic` in the solution of assignment 4