

# Introduction to Machine learning

## **SUPPORT VECTOR MACHINES**

1962, Vapnik, Alexey et al.

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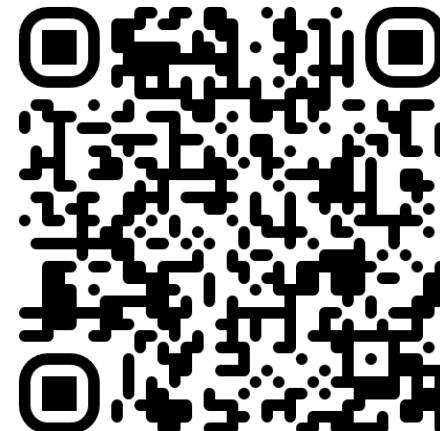
# QR Code



[Presentation slide](#)



[Implementation](#)



[Github Resources](#)

# Outline

1. Introduction & General Idea
2. Architecture
3. Challenges & improvements
4. Applications
5. Demo / Visualization

# 1. Introduction & General Idea

## What is SVM ?

A supervised machine learning algorithm primarily used for classification (and also regression).

### SVC

```
class sklearn.svm.SVC(*, C=1.0, kernel='rbf', degree=3,  
coef0=0.0, shrinking=True, probability=False, tol=0.01,  
class_weight=None, verbose=False, max_iter=-1, decision_function_shape='ovo',  
break_ties=False, random_state=None)
```

C-Support Vector Classification.

The implementation is based on libsvm. The fit time scales at least quadratically with the number of samples and may be impractical beyond tens of thousands of samples. For large datasets consider using [LinearSVC](#) or [SGDClassifier](#) instead, possibly after a [Nyström Approximation](#).

The multiclass support is handled according to a one-vs-one scheme.

### SVR

```
class sklearn.svm.SVR(*, kernel='rbf', degree=3, gamma='scale',  
C=1.0, epsilon=0.1, shrinking=True, cache_size=200,  
tol=0.001, max_iter=-1)
```

Epsilon-Support Vector Regression.

The free parameters in the model are C and epsilon.

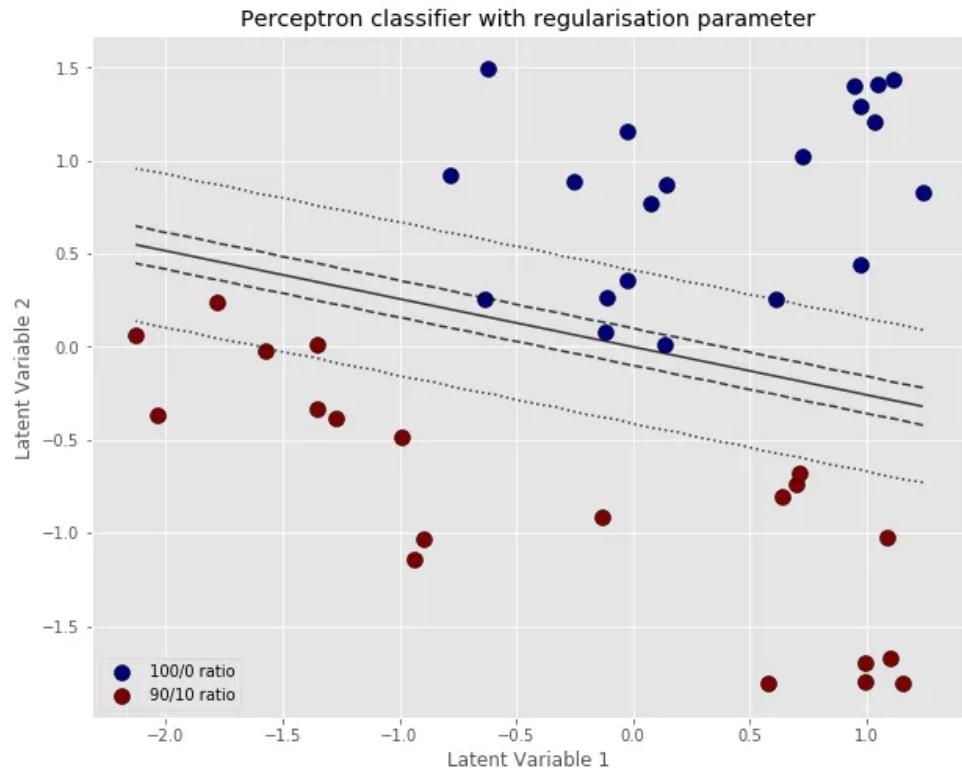
The implementation is based on libsvm. The fit time complexity is more than quadratic with the number of samples which makes it hard to scale to datasets with more than a few thousand samples. For large datasets consider using [LinearSVR](#) or [SGDRegressor](#) instead, or a [kernel approximation](#).

Read more in the [User Guide](#).

# 1. Introduction & General Idea

## Early Algorithms (Pre-1980s)

The Perceptron algorithm guaranteed convergence for linearly separable data but failed to provide an optimal solution.



# 1. Introduction & General Idea

## Philosophy of SVM

Based on the principle of Structural Risk Minimization (SRM) - **General Model**

$$\min_{\mathbf{w}} \mathcal{L}(\mathbf{w}) = \min_{\mathbf{w}} \underbrace{\frac{1}{n} \sum_{i=1}^n l(h_{\mathbf{w}}(\mathbf{x}_i), y_i)}_{\text{training loss}} + \lambda \underbrace{r(\mathbf{w})}_{\text{regularizer}}$$

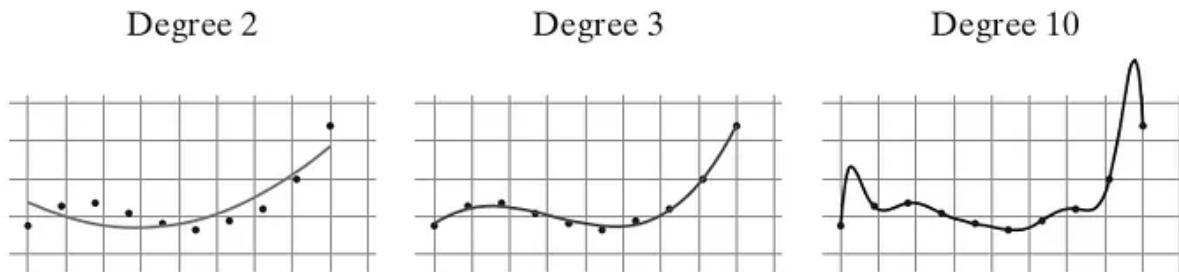
not Empirical Risk Minimization (ERM) - **Overfitting Model**

$$\min_h R_{emp}[h] = \min_h \frac{1}{n} \sum_{i=1}^n l(h(\mathbf{x}_i), y_i)$$

# 1. Introduction & General Idea

## Philosophy of SVM

Let the hypothesis space is the class of polynomials of degree up to 10

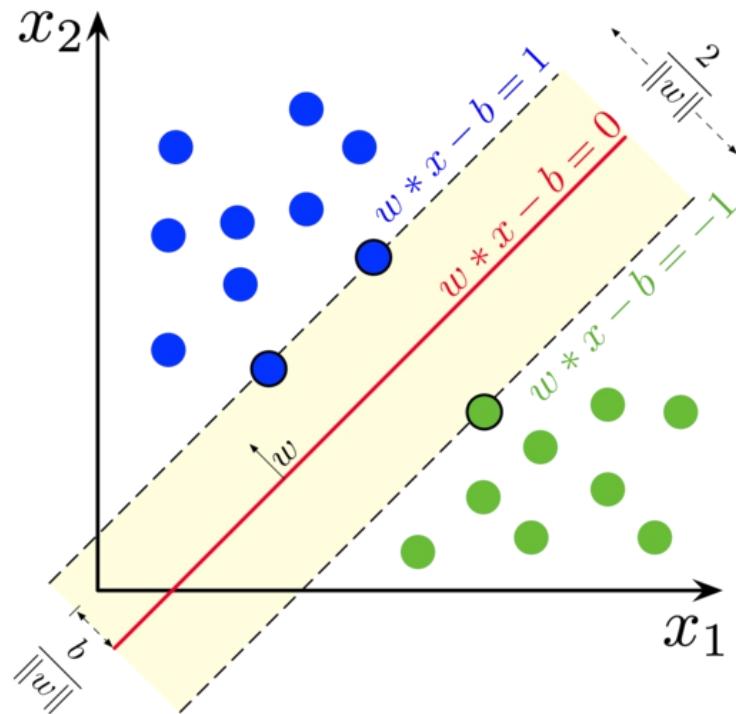


- ERM will choose a polynomial of degree 10. But that will overfit the data.
- Define the weight function by the 1/degree of the polynomials, then SRM will balance between training loss and polynomial degree.

# 1. Introduction & General Idea

## Idea of SVM Hyperplanes & Margin

- Finds an optimal separating hyperplane that divides the data into classes.
- The optimal hyperplane is the one that maximizes the margin, the distance between the hyperplane and the nearest data points (the Support Vectors).



## 2. Architectures

### Mathematical Architecture

In an n-dimensional, a hyperplane is defined as:

$$w^T x + b = 0 \quad \text{with} \quad x \in \mathcal{X}, \mathcal{X} = \mathbb{R}^n$$

- Orientation of the surface:

$$y(x) = w \cdot x + b, \quad y(x) \in \mathbb{R}$$

$$x_1, x_2 \in \{x \mid y(x) = 0\}$$

$$\implies w \cdot x_1 + b = 0, \quad w \cdot x_2 + b = 0 \mid v = x_2 - x_1, \quad v \in y$$

$$y(x_2) - y(x_1) = w \cdot (x_2 - x_1) = w \cdot v = 0$$

$$\implies w \perp v \implies w \perp y$$

## 2. Architectures

### Mathematical Architecture

In an n-dimensional, a hyperplane is defined as:

$$w^T x + b = 0 \quad \text{with} \quad x \in \mathcal{X}, \mathcal{X} = \mathbb{R}^n$$

- Distance of the hyperplane from the origin:

$$d = \frac{|w \cdot x_0 + b|}{\|w\|}$$

$$\text{with } x_0 = 0 \implies d = \frac{b}{\|w\|}$$

## 2. Architectures

### Mathematical Architecture

Distance between 2 points

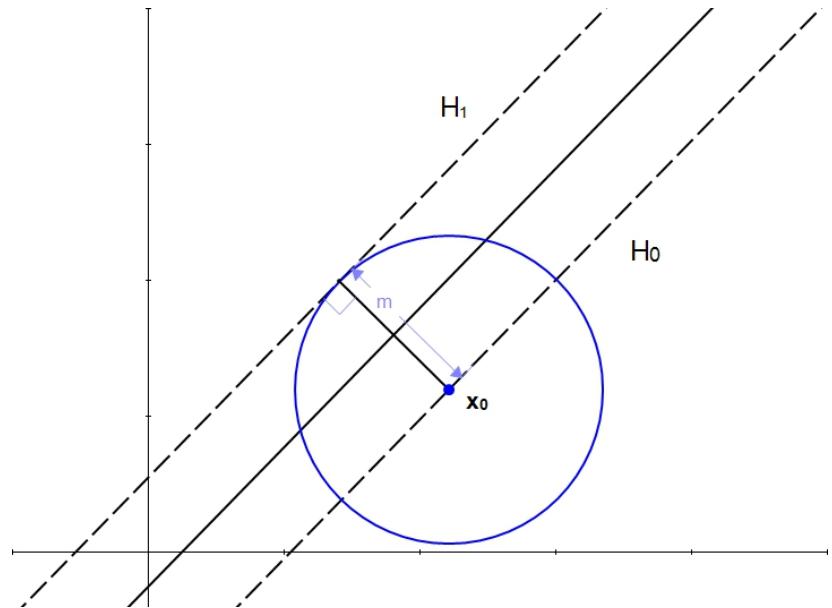
$$w \cdot x + b = 0, \quad x_0 \in \mathbb{R}^n, \quad x_p \in \mathbb{R}^n$$

$$x_0 - x_p = \lambda w$$

$$w \cdot x_p + b = 0 \implies w \cdot (x_0 - \lambda w) + b = 0$$

$$w \cdot x_0 - \lambda \|w\|^2 + b = 0 \implies \lambda = \frac{w \cdot x_0 + b}{\|w\|^2}$$

$$r = \|x_0 - x_p\| = \|\lambda w\| = |\lambda| \|w\| = \frac{|w \cdot x_0 + b|}{\|w\|}$$



## 2. Architectures

**Mathematical Architecture Functional margin**  $(x_i, y_i) \in \mathbb{R}$ ,  $w \cdot x + b = 0$

$$\hat{\gamma}_i = y_i(w \cdot x_i + b)$$

- Tells whether the hyperplane is correct in classification and how “strong” it is:
  - gamma > 0 : Correct classified  
 $y = ax + b$ , A = (3, -1)  
If  $y^A(3) = -3 \rightarrow \text{Gamma} = (-1) \times (-3) = 3$
  - gamma < 0 : Wrong classified  
 $y = ax + b$ , B = (1, 4)  
If  $y^B(1) = -2 \rightarrow \text{Gamma} = 4 \times (-2) = -8$
- Does not reflect actual distance.

## 2. Architectures

### Mathematical Architecture Geometric margin

$$\gamma_i = \frac{\hat{\gamma}_i}{\|w\|} = \frac{y_i(w \cdot x_i + b)}{\|w\|}$$

- Perpendicular distance from point  $x_i$  to hyperplane.
- The hard-margin SVM problem is to maximize the geometric margin.

## 2. Architectures

### Mathematical Architecture

$$y = 2x - 1$$

$$\gamma^{(g)}(1) = \frac{1 \cdot (2 \cdot 1 - 1)}{||2||} = 0.5$$

$$\gamma^{(f)}(1) = 1 \cdot (2 \cdot 1 - 1) = 1$$

$$\gamma^{(g)}(20) = \frac{1 \cdot (20 \cdot 1 - 10)}{||20||} = 0.5$$

$$\gamma^{(f)}(20) = 1 \cdot (20 \cdot 1 - 10) = 10$$

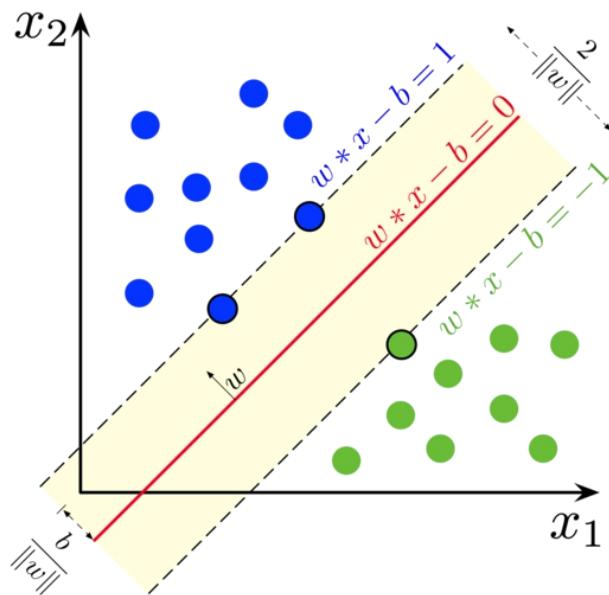
## 2. Architectures

### Mathematical Architecture

#### Canonical Form to Geometric Margin

- Rescale the parameters  $w$  and  $b$  such that the functional margin of the closest data point(s) to the decision boundary is exactly 1.

$$\gamma_i = \frac{1}{\|w\|} y_i (w \cdot x_i + b) = \frac{\pm 1}{\|w\|}$$



## 2. Architectures

### Mathematical Architecture Primal Formulation

- Goal

$$\max \frac{1}{\|w\|} \quad \text{or} \quad \min \frac{1}{2} \|w\|^2$$

$$y_i(w \cdot x_i + b) \geq 1$$

$$\left( \frac{1}{\|w\|} \right)' = \frac{\|w\|'}{\|w\|}$$

$$= \frac{(w_1^2 + w_2^2 + \dots + w_n^2)'}{2 \cdot (w_1^2 + w_2^2 + \dots + w_n^2)} \cdot \|w\| \neq 0$$

$$\gamma = \frac{2}{\|w\|} \quad \forall w \models w^T x + b = \pm 1$$

$$\max_{w,b} \gamma \Leftrightarrow \max_{w,b} \frac{2}{\|w\|} \Leftrightarrow \max_{w,b} \frac{1}{\|w\|}$$

$$\Leftrightarrow \min_{w,b} \|w\| \Leftrightarrow \min_{w,b} \|w\|^2 \Leftrightarrow \min_{w,b} \frac{1}{2} \|w\|^2$$

## 2. Architectures

**Mathematical Architecture Why not derivative directly**

$$\max \frac{1}{\|w\|} \quad \text{or} \quad \min \frac{1}{2} \|w\|^2$$

$$3x_1 - 1x_2 + 3 = 0$$

$$w = (3, -1) \implies \|w\|^2 = 3^2 + (-1)^2 = 10$$

$$\left( \frac{1}{2} \|w\|^2 \right)' = \|w\| = 0 \implies w = (0, 0)$$

$$w = (0, 0) \implies 3 \cdot 0 - 1 \cdot 0 + 3 = 0$$

**Hyperplane disappear (Without constraint)**

## 2. Architectures

### Mathematical Architecture Lagrangian Function and KKT Conditions.

- Lagrangian  $\mathcal{L}(w, b, \alpha) = \frac{1}{2}||w||^2 - \sum_{i=1}^n \alpha_i(y_i(w^T x_i + b) - 1) \quad \alpha_i \geq 0$

- KTT  $\frac{\partial \mathcal{L}}{\partial w} = 0 \implies w = \sum_{i=1}^n \alpha_i y_i x_i$

$$\frac{\partial \mathcal{L}}{\partial b} = 0 \implies \sum_{i=1}^n \alpha_i y_i = 0$$

## 2. Architectures

### Mathematical Architecture Dual Formulation

$$\begin{aligned}\mathcal{L}(w, b, \alpha) &= \frac{1}{2} w^\top w - \sum_{i=1}^n \alpha_i y_i w^\top x_i - b \sum_{i=1}^n \alpha_i y_i + \sum_{i=1}^n \alpha_i \\ \mathcal{L}(\alpha) &= \frac{1}{2} \left( \sum_k \alpha_k y_k x_k \right)^\top \left( \sum_\ell \alpha_\ell y_\ell x_\ell \right) * \sum_i \alpha_i y_i \left( \sum_k \alpha_k y_k x_k \right)^\top x_i - \sum_i \alpha_i \\ &= \frac{1}{2} \sum_{k, \ell} \alpha_k \alpha_\ell y_k y_\ell x_k^\top x_\ell * \sum_{i, k} \alpha_i \alpha_k y_i y_k x_k^\top x_i - \sum_i \alpha_i. \\ \frac{1}{2} A - A &= -\frac{1}{2} A. \\ \mathcal{L}(\alpha) &= -\frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j x_i^\top x_j + \sum_{i=1}^n \alpha_i.\end{aligned}$$

## 2. Architectures

### Mathematical Architecture Dual Formulation

- Standard Form

$$\max_{\alpha} \sum_{i=1}^m \alpha_i - \frac{1}{2} \sum_{i=1}^m \sum_{j=1}^m \alpha_i \alpha_j y_i y_j (x_i^T x_j)$$

subject to  $\alpha_i \geq 0$  and  $\sum_{i=1}^m \alpha_i y_i = 0$

- Decision Function

$$f(x) = sign \left( \sum_{i=1}^n \alpha_i y_i x_i^T x + b \right)$$

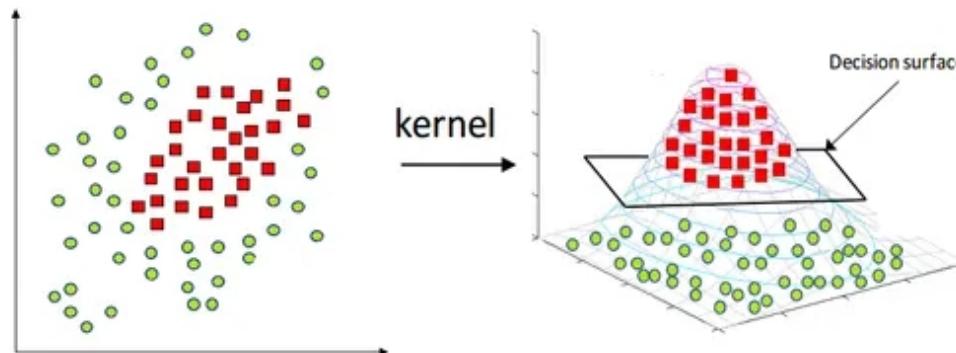
## 2. Architectures

### Mathematical Architecture Kernel Trick

- A technique to map non-linearly separable data into a higher-dimensional Feature Space where a linear separation is possible.

$$\Phi : \mathcal{X} \rightarrow \mathcal{F}$$

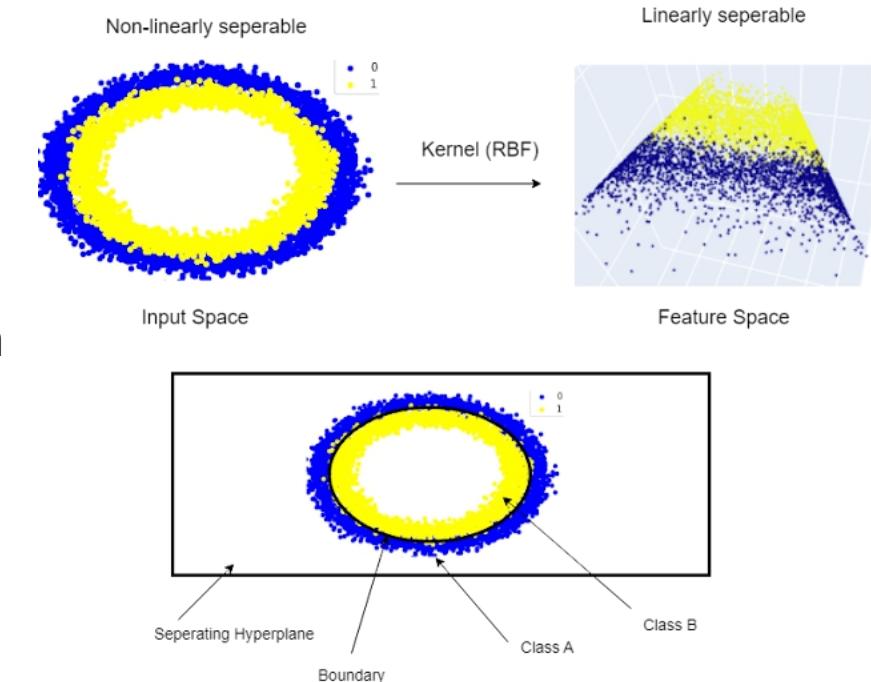
$$x = [x_1, x_2]^T \rightarrow \Phi(x) = [x_1^2, \sqrt{2}x_1x_2, x_2^2]^T$$



## 2. Architectures

### Mathematical Architecture RBF Kernel

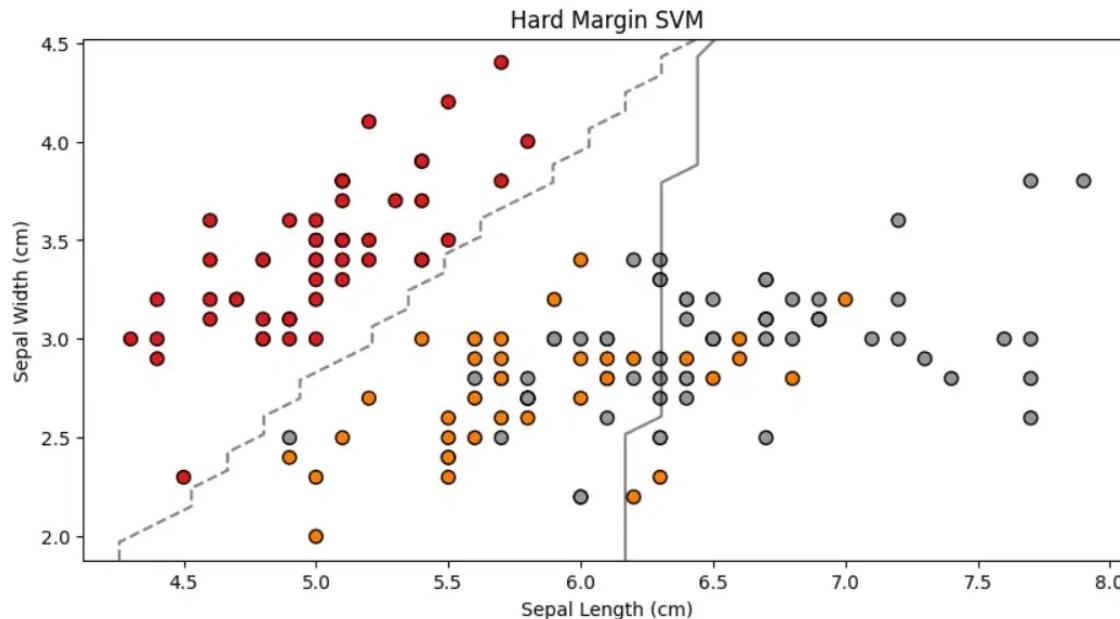
- The Kernel Trick replaces the expensive calculation of the dot product in the high-dimensional space with a fast, pre-defined Kernel Function in the low-dimensional space.



### 3. Challenges & Improvement

#### Hard Margin Challenge

- The Hard Margin SVM fails if the data is not perfectly linearly separable.



### 3. Challenges & Improvement

#### Soft Margin Solution

- Introduces Slack Variables to allow some data points to violate the margin constraint or even be misclassified.

$$y_i(w^T x_i + b) \geq 1 - \xi_i \quad \forall (x_i, y_i)$$

- On the boundary  $\xi_i = 0$
- Margin Violation  $0 < \xi_i < 1$
- Wrong classifier  $\xi_i \geq 1$

### 3. Challenges & Improvement

#### Regularization Parameter

$$\min \sum \xi_i$$

A hyperparameter that controls the trade-off:

- **High C:** Penalizes classification errors/slack heavily (stricter, narrower margin, higher risk of overfitting).
- **Low C:** Allows more errors/slack (looser fit, wider margin, higher risk of underfitting).

$$\min_{w,b,\xi} \frac{1}{2} \|w\|^2 + C \sum_{i=1}^m \xi_i$$

$$subject\ to \quad y_i(w^T x_i + b) \geq 1 - \xi_i, \quad \xi_i \geq 0$$

### 3. Challenges & Improvement

#### Loss Function

- The objective function incorporates the Hinge Loss, which penalizes points that are inside the margin or on the wrong side.

$$\min_{w,b} \underbrace{\frac{1}{2} \|w\|^2}_{\text{Regularization}} + C \sum_{i=1}^m \underbrace{\max(0, 1 - y_i(w^T x_i + b))}_{\text{Hinge Loss}}$$

- Correctly classified  $y \cdot f(x) \geq 1$
- Within margin  $0 < y \cdot f(x) < 1$
- Misclassified  $y \cdot f(x) < 0$

### 3. Challenges & Improvement

#### Sequential Minimal Optimization (SMO)

The Dual Optimization problem for SVM is a complex, large-scale Quadratic Programming (QP) problem. Solving it using general QP solvers is very slow, especially for large datasets.

$$\max_{\alpha} \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n y_i y_j K(x_i, x_j) \alpha_i \alpha_j$$

1. Select a couple of Lagrange multipliers by Heuristics
2. Freezing other ...
3. The original complex QP optimization problem is reduced to a simple quadratic function of one variable.

## 4. Manual calculation

$$\mathbf{x}_i \in \mathbb{R}^n$$

$$G_{ij} = \mathbf{x}_i \cdot \mathbf{x}_j$$

$$\max_{\boldsymbol{\alpha}} W(\boldsymbol{\alpha}) = \sum_{i=1}^m \alpha_i - \frac{1}{2} \sum_{i=1}^m \sum_{j=1}^m \alpha_i \alpha_j y_i y_j (\mathbf{x}_i \cdot \mathbf{x}_j)$$

We define a linearly separable dataset with 3 points ( $m=3$ ).

Negative Class ( $y = -I$ ):

$$x_1 = [1, 1]^T$$

Positive Class ( $y = +I$ ):

$$x_2 = [3, 3]^T$$

$$x_3 = [3, 1]^T$$

## 4. Manual calculation

First, we compute the Gram Matrix  $G$ , where  $G_{i,j} = x_i^T x_j$  (Linear Kernel) We want to maximize the Dual Objective function:

$$x_1^T x_1 = 1 \cdot 1 + 1 \cdot 1 = 2$$

$$x_2^T x_2 = 3 \cdot 3 + 3 \cdot 3 = 18$$

$$x_3^T x_3 = 3 \cdot 3 + 1 \cdot 1 = 10$$

$$x_1^T x_2 = 1 \cdot 3 + 1 \cdot 3 = 6$$

$$x_1^T x_3 = 1 \cdot 3 + 1 \cdot 1 = 4$$

$$x_2^T x_3 = 3 \cdot 3 + 3 \cdot 1 = 12$$

The Gram Matrix is:

$$G = \begin{pmatrix} 2 & 6 & 4 \\ 6 & 18 & 12 \\ 4 & 12 & 10 \end{pmatrix}$$

$$W(\alpha) = \sum_{i=1}^3 \alpha_i - \frac{1}{2} \sum_{i=1}^3 \sum_{j=1}^3 \alpha_i \alpha_j y_i y_j (\mathbf{x}_i^\top \mathbf{x}_j)$$

$$\alpha_i \geq 0$$

$$\sum \alpha_i y_i = 0 \implies -\alpha_1 + \alpha_2 + \alpha_3 = 0 \implies \alpha_1 = \alpha_2 + \alpha_3$$

$$W = (\alpha_1 + \alpha_2 + \alpha_3) - \frac{1}{2} \begin{bmatrix} \alpha_1^2(2) + \alpha_2^2(18) + \alpha_3^2(10) \\ + 2\alpha_1\alpha_2(-1)(1)(6) \\ + 2\alpha_1\alpha_3(-1)(1)(4) \\ + 2\alpha_2\alpha_3(1)(1)(12) \end{bmatrix}$$

Simplifying the quadratic part:

$$W = (\alpha_1 + \alpha_2 + \alpha_3) - [\alpha_1^2 + 9\alpha_2^2 + 5\alpha_3^2 - 6\alpha_1\alpha_2 - 4\alpha_1\alpha_3 + 12\alpha_2\alpha_3]$$

## 4. Manual calculation

To solve this, we substitute the constraint  $\alpha_1 = \alpha_2 + \alpha_3$  into the equation to eliminate  $\alpha_1$ . By geometric inspection, point  $x_2$  is farther from the boundary than  $x_3$ . Thus, we hypothesize that  $x_2$  is not a support vector, meaning  $\alpha_2 = 0$ . Let's test this hypothesis. If  $\alpha_2 = 0$ , then  $\alpha_1 = \alpha_3$ .

Substituting  $\alpha_2 = 0$  and  $\alpha_1 = \alpha_3$  into  $W$ :

$$\begin{aligned} W &= (2\alpha_3) - [\alpha_3^2 + 0 + 5\alpha_3^2 - 0 - 4\alpha_3^2 + 0] \\ W &= 2\alpha_3 - 2\alpha_3^2 \end{aligned}$$

To find the maximum, we take the derivative with respect to  $\alpha_3$  and set to 0:

$$\frac{dW}{d\alpha_3} = 2 - 4\alpha_3 = 0 \implies \alpha_3 = 0.5$$

## 4. Manual calculation

- Recover the weight vector  $w$  using the formula

$$\begin{aligned}w &= \sum \alpha_i y_i x_i \\w &= 0.5(-1) \begin{pmatrix} 1 \\ 1 \end{pmatrix} + 0(1) \begin{pmatrix} 3 \\ 3 \end{pmatrix} + 0.5(1) \begin{pmatrix} 3 \\ 1 \end{pmatrix} \\w &= \begin{pmatrix} -0.5 \\ -0.5 \end{pmatrix} + \begin{pmatrix} 1.5 \\ 0.5 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}\end{aligned}$$

- Computing the bias  $b$ : We use a support vector (e.g.,  $x_3$ ) and the support vector equation

$$\begin{aligned}y_3(w^T x_3 + b) &= 1 \\1 \cdot ([1, 0] \begin{pmatrix} 3 \\ 1 \end{pmatrix} + b) &= 1 \\1 \cdot (3 + b) = 1 &\implies b = -2\end{aligned}$$

## 4. Manual calculation

Final Model: The optimal hyperplane is defined by

$$w = [1, 0]^T$$

and

$$b = -2$$

The decision boundary equation is:

$$x_1 - 2 = 0 \implies x_1 = 2$$

This is a vertical line passing through  $x=2$ , which perfectly separates  $x=1$  (Negative) and  $x=3$  (Positive).

## 5. Demonstration

### The Iris Case Study

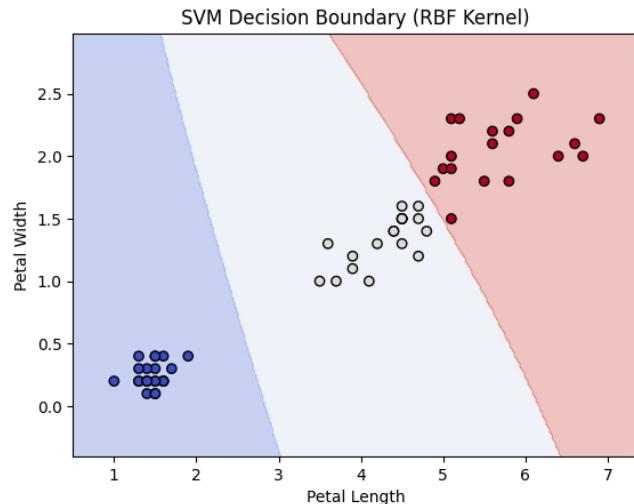
#### Flower classification

- Samples: 150 Flower samples (50 per class).
- Features ( $n = 4$ ): Sepal length, Sepal width, Petal length, Petal width (all in cm).
- Classes ( $K=3$ ): Iris setosa, Iris versicolor, and Iris virginica.
- RBF Kernel.
- Regularization Hyperparameter ( $C$ ) = 1

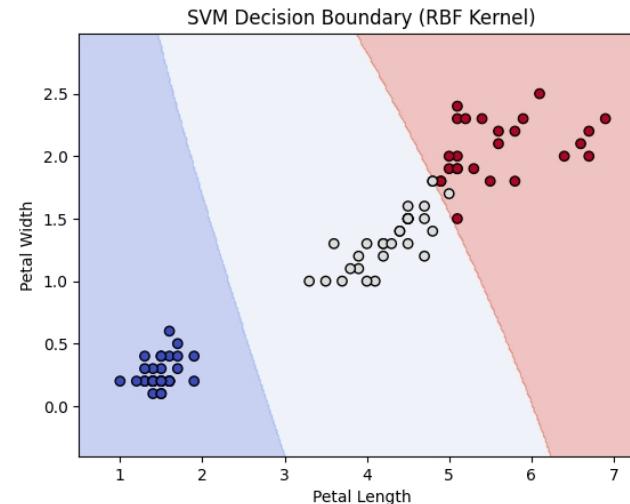
## 5. Demonstration

### The Iris Case Study

#### Flower classification



Train : Test = 6:4 - Accuracy = 100%  
 $C = 1$

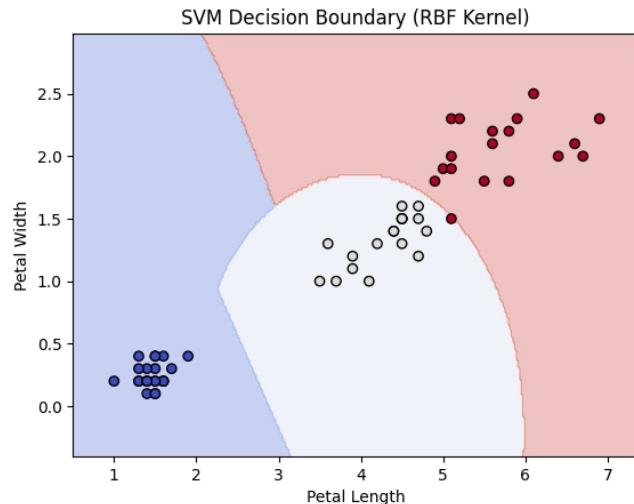


Train : Test = 4:6 - Accuracy = 97,78%  
 $C = 1$

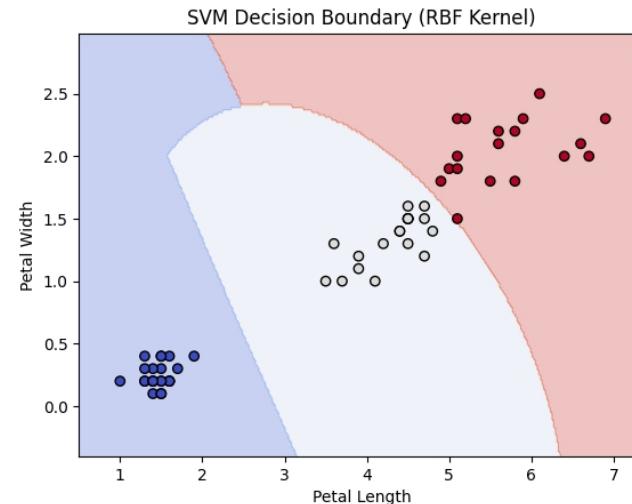
## 5. Demonstration

### The Iris Case Study

#### Flower classification



Train : Test = 6:4 - Accuracy = 98.33%  
C = 30



Train : Test = 6:4 - Accuracy = 100%  
C = 10

# References

- [PyTorch implementations of GANs](#)
- [A list of all named GANs](#)
- [Vanilla GANs paper](#)
- [WGAN paper](#)
- [Fréchet Inception Distance](#)
- [A mix of GAN implementations including progressive growing](#)
- [GAN-play](#)
- [Style GAN](#)