MTX - 3.4

C ANSI/C++ BLAS-3 API

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Macro/Function/Keyword	Description	MATLAB Eq.
Generation		
`matrix VAR=NULL` `mtxdef(VAR)`	Matrix MTX type definition Keyword. `matrix` keyword, defines unallocated variables. Always initialize matrix-type MTX variables to NULL Use `mtxdef` to define an allocated empty MATRIX by default.	`VAR=[];`
`M=mtx_new(n,m)`	Returns a matrix M of mxn dimensions (initialized on 0)	`M=zeros(n,m)`
`M=mtx_init(n,m,initval)`	Returns a matrix M of mxn dimensions initialized on *initval*	`M=initval*ones(n,m)`
`M=mtx_rand(n,m)`	Returns a matrix M of mxn dimensions containing pseudorandom values drawn from the standard uniform distribution on the open interval (0,1)	`M=rand(n,m)`
`M=mtx_1dtomtx(A)`	Allocates a MTX matrix from the 1D array A	
`M=mtx_2dtomtx(A)`	Allocates a MTX matrix from the 2D array A	
`M=mtx_eye(n,alpha)`	Returns the nxn identity matrix $M = \alpha I$. α is scalar and I represents the identity matrix	`M=alpha*eye(n)`
`mtx_del(M)`	Releases the specified block of memory generated by M, back to the heap	`clear M`
`M=mtx_cpy(A)`	Generates a copy of matrix A into M.	`M=A`
`mtx_memcpy(M,A)`	Generates a copy of matrix A into M. (M is allocated, and has the same dimensions of A)	`M=A`
Indexing		
`x=A->pos[r][c]`	Get the element at index *row-r* and *column-c*	`x=A(r,c)`
`A->pos[r][c] = value`	Set a single element at index *row-r* and *column-c*	`A(r,c)=value`
`M=mtx_submatget(A,r1,r2,c1,c2)`	Get submatrix $M \leftarrow A$ (M from A), from rows *r1* to *r2* and columns *c1* to *c2*	`A(r1:r2,c1:c2)`
`M=mtx_getrow(A,r)`	Get the *r-row* from matrix A	`M=A(r,:)`
`M=mtx_getcol(A,c)`	Get the *c-column* from matrix A	`M=A(:,c)`
`M=mtx_getrows(A,r1,r2)`	Get rows from matrix A. From rows *r1* to *r2*	`M=A(r1:r2,:)`
`M=mtx_getcols(A,c1,c2)`	Get columns from matrix A. From columns *c1* to c*2*	`M=A(:,c1:c2)`
`mxt_submatset(M,A,r1,r2,c1,c2)`	Put submatrix A into M from row *f1* to row *f2* and cols *c1* to col *c2*	`M(r1:r2,c1:c2)=A`

mtx_setrow(M,A,r)	Set the *r-row* from matrix *M*, with the row vector *A*	`M(r,:)=A`
mtx_setcol(M,A,c)	Set the *c-column* from matrix *M*, with the column vector *A*	`M(:,c)=A`
Basic information		
x=mtx_isempty(M)	TRUE if *M* is an empty matrix	`isempty(M)`
x=mtx_isrow(M)	TRUE if *M* is a row vector	`isrow(M)`
x=mtx_iscolumn(M)	TRUE if *M* is a column vector	`iscolumn(M)`
x=mtx_isvector(M)	TRUE if *M* is vector	`isvector(M)`
x=mtx_numel(M)	Number of elements in matrix *M*	`x=numel(M)`
x=mtx_length(M)	Largest matrix dimension of *M*	`x=length(M)`
x=mtx_det(M)	Determinant of matrix *M*	`x=det(M)`
x=mtx_trace(M)	Trace of matrix *M*	`x=trace(M)`
D=mtx_diag(M)	Returns a column vector with all diagonal elements of *M*	`D=diag(M)`
M=mtx_produ(A)	Product of matrix elements - by columns	`M=prod(A)`
x=mtx_cumprod(A)	Total product of matrix elements	`x=prod(A(:))`
M=mtx_sum(A)	Sum of matrix elements - by columns	`M=sum(A)`
x=mtx_cumsum(A)	Total sum of matrix elements	`x=sum(A(:))`
M=mtx_mean(A)	Mean of matrix elements – by columns	`M=mean(A)`
M=mtx_max(A)	If *A* is a vector, returns the largest element in *A*. If *A* is a matrix, treats the columns of *A* as vectors, returning a row vector containing the maximum element from each column.	`M=max(A)`
x=mtx_cummax(A)	Largest element in matrix	`x=max(A(:))`
M=mtx_min(A)	If *A* is a vector, returns the smallest element in *A*. If *A* is a matrix, treats the columns of *A* as vectors, returning a row vector containing the smallest element from each column.	`M=min(A)`
x=mtx_cummin(A)	Smallest element in matrix	`x=min(A(:))`
BLAS-Operations		
M=mtx_t(A)	Returns the transpose of *A*	`M=A'`
M=mtx_gadd(alpha,A,beta,B)	Returns $M=\alpha A + \beta B$ α and β are scalars, and *A* and *B* matrices.	`M=alpha*A+beta*B`
M=mtx_prod(alpha,A,B)	Returns matrix Multiplication $M=\alpha AB$	`M=alpha*A*B`

	α is scalar, A and B matrices.	

ret=mtx_dgemm(alpha,A,TA,B,TB,beta,C)	Computes $C = \alpha AB + \beta C$ and related operations.
	α and β are scalars, and A, B and C are matrices.
	TA = 'T' or 't' → A is considered transposed (A^T).
	TB = 'T' or 't' → B is considered transposed (B^T).
	On success, returns (0) and matrix C is overwritten, otherwise returns (-1).
		`C = alpha*A*B + beta*C`
		`C = alpha*A'*B + beta*C`
		`C = alpha*A*B' + beta*C`
		`C = alpha*A'*B' + beta*C`

M=mtx_powui(A,n)	Returns A^n (Matrix power - n must be an unsigned int and A an square matrix)	`M=A^n`
M=mtx_ptpprod(A,B)	Returns $A.B$ (point by point product) (A and B must have the same dimensions)	`M=A.*B`

M=mtx_koper(A,Op,beta)	Returns standard scalar matrix operations.
	$C = A(Op)\beta$
	Related operations (Op) = '+' , '-' , '*', '/' and '^' (power)
	Example:
	`M=mtx_koper(A,'+',beta);`
		`M=A+beta`
		`M=A-beta`
		`M=A*beta`
		`M=A/beta`
		`M=A^beta`

M=mtx_inv(A)	Returns A^{-1} (Matrix inverse)	`M=inv(A)`
M=mtx_linsolve(A,B)	Returns $M = A^{-1}B$	`M=inv(A)*B` `M=A\B`
mtx_lu(L,U,A)	Expresses the matrix A, as the product of two essentially triangular matrices, one of them, a permutation of a lower triangular matrix and the other an upper triangular matrix. (L and U, must be allocated previously and must have the same dimensions of A)	`[L,U] = lu(A)`
Q=mtx_qr(A,R)	Orthogonal-triangular decomposition. (R is allocated previously and must have the same dimensions of A)	`[Q,R]=qr(A)`
M=mtx_rpinv(A)	Returns the Moore-Penrose right pseudoinverse	
M=mtx_lpinv(A)	Returns the Moore-Penrose left pseudoinverse	
M=mtx_expm(A, alpha)	Returns matrix exponential $e^{\alpha A}$. `mtx_expm` uses the Padé approximation with scaling and squaring.	`M=expm(alpha*A)`
M=mtx_fxptp(A, fx)	Returns function fx evaluated for each element of matrix A Examples: `M=mtx_fxptp(A, sin);` → Element-wise sine `M=mtx_fxptp(A, fabs);` → Element-wise absolute value	`M=fx(A)`
Manipulation		
M=mtx_vcat(A,B)	Returns $[A ; B]$ (Vertical concatenation - append by columns)	`M=[A;B]`

M=mtx_hcat(A,B)	Returns *[A , B]* (Horizontal concatenation - append by rows)	`M=[A,B]`
M=mtx_vcatn(A,B,C,…,X,Y,Z,NULL)	Return *[A ; B ; C; … , X ; Y ; Z]* (Vertical concatenation - append by columns)	`M=[A;B;C;…;X;Y;Z]`
M=mtx_hcatn(A,B,C,…,X,Y,Z,NULL)	Return *[A , B , C, … , X , Y , Z]* (Horizontal concatenation - append by rows)	`M=[A,B,C,…,X,Y,Z]`
Visualization		
mtx_disp(A)	Display matrix A	`disp(A)`
mtx_show(A)	Display matrix with variable name	