PRECAT: OM25

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Data Structures

Introduction:

- What is data structure & its classification?

- What is an algorithm?

Array:

- **Searching Algorithms:** Linear Search & Binary Search

- **Sorting Algorithms:**

-   Selection Sort, Bubble Sort & Insertion Sort: Algorithms & Implementation

- Merge Sort & Quick Sort: Only Algorithms.

- Limitations of an Array data structure

Data Structures

Linked List:

- Concept & Definition

-Implementation of Singly Linear Linked List Operations: Addition & Deletion.

- Concepts:

- Singly Circular Linked List

- Doubly Linear Linked List

- Doubly Circular Linked List.

- Difference between Array and Linked List

Data Structures

Stack:

- Concept & Definition

- Implementation of Stack by using an array

+ Stack Application Algorithms:

 - Conversion of infix expression into its equivalent postfix

expression.

- Conversion of infix expression into its equivalent prefix expression.

-Conversion of prefix expression into its equivalent postfix expression.

- Evaluation of postfix expression

Data Structures

 # Queue:

- Concept & Definition

- Types of Queue

- Implementation of Linear Queue & Circular Queue

Tree terminologies

Graph terminologies

Data Structures: Introduction

Q. What is Data Structure?

Data Structure is a way to store data elements into the memory (i.e. into the main memory) in an organized manner so that operations like addition, deletion, traversal, searching, sorting etc... can be performed on it efficiently.
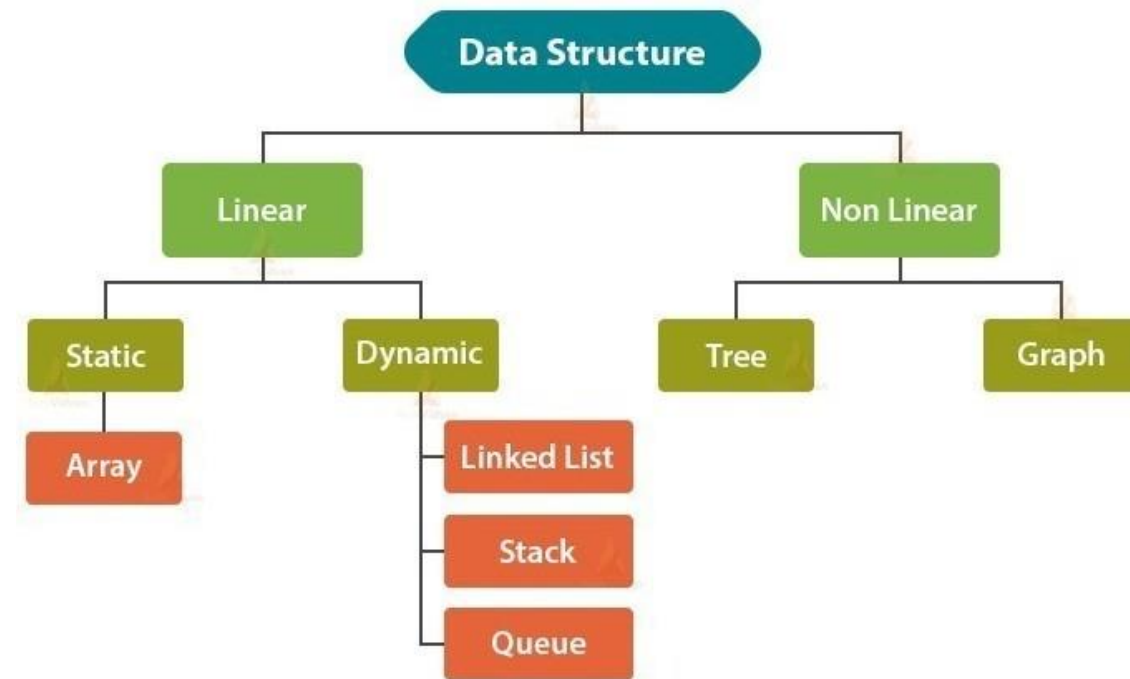
Data Structures: Introduction

Two types of **Data Structures** are there:

1. **Linear/Basic:** data elements gets stored into the memory in a linear manner and hence can be accessed linearly.

- Array

- Structure & Union

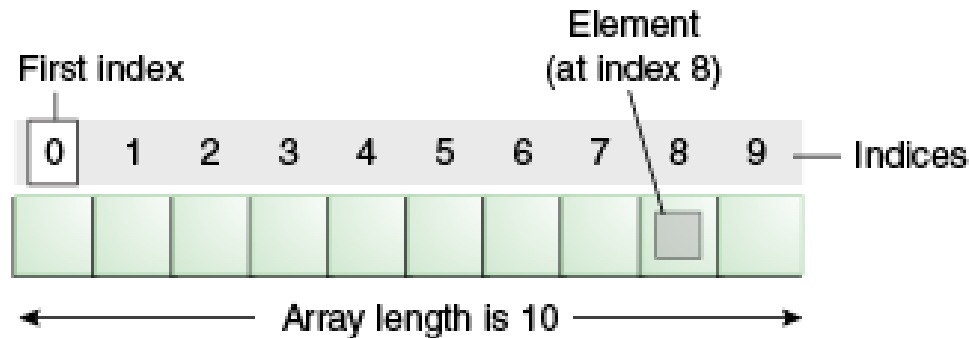- Class

- Linked List

- Stack

- Queue

2.**Non-linear/Advanced:** data elements gets stored into the memory in a non-linear manner and hence can be accessed non-linearly.

- Tree (Hierarchical)

- Graph

Data Structures: Introduction

Array: It is a collection of logically related similar type of elements in which data elements gets stored into the memory at contiguos locations.

First index

Element (at index 8)

| 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | — Indices |

Array length is 10

Structure: It is a collection of logically related similar and disimmilar type of elements gets stored into the memory collectively (as a single entity/record).

Sizeof of structure is sum of size of all its members.

Union: Union is same like structure, except, memory allocation i.e. size of union is the size of max size member defined in it and that memory gets shared among all its members for effective memory utilization (can be used in a special case only).

Data Structures: Introduction

Q. What is a Program?

- A program is a set of instructions written in any programming language (like C, C++, Java, Python, Assembly etc...) given to the machine to do specific task.

- An algorithm is a template whereas a program is an implementation of an algorithm.

Q. What is an Algorithm?

- An algorithm is a finite set of instructions written in human understandable language (like english), if followed, acomplishesh a given task.

- An algorithm is a finite set of instructions written in human understandable language (like english) **with some programming constraints**, if followed, acomplishesh a given task, such an algorithm also called as **pseudocode.**

Data Structures: Introduction

Example: An algorithm to do sum of all array elements

```
Algorithm ArraySum(A, n)//whereas A is an array of size n
{

    sum=0;//initially sum is 0

    for( index = 1 ; index <= size ; index++ ) {

    sum += A[ index ];//add each array element into the sum

    }

    return sum;

}
```

- In this algorithm, **traversal/scanning** operation is applied on an array. Initially sum is 0, each array element gets added into to the sum by traversing array sequentially from the first element till last element and final result is returned as an output.

Data Structures: Introduction

-**Analysis of an algorithm** is a work of determining how much **time** i.e. computer time and **space** i.e. computer memory it needs to run to completion.

- There are two measures of an analysis of an algorithms:

1.Time Complexity: It is the amount of time i.e. computer time required for an algorithm to run to completion.

2.Space Complexity: It is the amount of space i.e. computer memory required for an algorithm to run to completion.

Asymptotic Analysis: It is a **mathematical** way to calculate time complexity and space complexity of an algorithm **without implementing it in any programming language.**

- In this type of analysis, analysis can be done on the basis of **basic operation** in that algorithm.

e.g. in searching & sorting algorithms comparison is the basic operation and hence analysis gets done on the basis of no. of comparisons, in addition of matrices algorithms addition is the basic operation and hence on the basis of addition operation.

Data Structures: Introduction

"Best case time complexity": if an algo takes min amount of time to complete its execution then it is referred as best case time complexity.

"Worst case time complexity": if an algo takes max amount of time to complete its execution then it is referred as worst case time complexity.

"Average case time complexity": if an algo takes neither min nor max amount of time to complete its execution then it is referred as an average case time complexity.

"Asympotic Notations":

1.Big Omega (Ω): this notation is used to denote best case time complexity

2. Big Oh (O): this notation is used to denote worst case time complexity

3.Big Theta (θ): this notation is used to denote an average case time complexity

Data Structures: Searching Algorithms

1. Linear Search/Sequential Search:

- In this algorithm, key element gets compared sequentially with each array element by traversing it from first element till either match is found or maximum till the last element.

```
Algorithm LinearSearch(A, size, key)
{
    for( index = 1        ; index <= size ; index++ ){  if(
    key == A[ index ] )
    return true;
    }
    return false;
}
```

arr	10	20	30	40	50	60	70	80
	0	1	2	3	4	5	6	7

Data Structures: Searching Algorithms

Best Case: If key is found at very first position in only 1 no. of comparison then it is considered as a best case and running time of an algorithm in this case is O(1) **= Ω(1)**

Worst Case: If either key is found at last position or key does not exists, maximum **n** no. of comparisons takes place, it is considered as a worst case and running time of an algorithm in this case is O(n) **= O(n)**

Average Case: If key is found at any in between position it is considered as an average case and running time of an algorithm in this case is O(n/2) **= θ(n)**

Data Structures: Searching Algorithms

2. Binary Search/Logarithmic Search:

- This algorithm follows **divide-and-conquer** approach.

- To apply binary search on an array prerequisite is that array elements must be in a sorted manner.

- In this algorithm, in first iteration, by means of calculating mid position big size array gets divided into two subarray's, **left subarray** and **right subarray**, key element gets compared with element which is at mid position, if key is found at mid position in very first iteration in only 1 no. of comparison, then it is considerd as a best case and in this case an algortihm takes O(1) time.

- If key is not found in the first iteration then either it will get searched into left subarray or into the right subarray by applying same logic repeatedly till either key is not found or till max the size of any subarray is valid i.e. size of subarray is greater or equal to 1.

Data Structures: Searching Algorithms

```
Algorithm BinarySearch(A, n, key)//A is an array of size "n", and key to be search
{
  left = 1;
  right = n;

  while( left <= right )
  {
    //calculate mid position
    mid = (left+right)/2;
    //compare key with an ele which is at mid position
    if( key == A[ mid ] )//if found return true
      return true;

    //if key is less than mid position element
    if( key < A[ mid ] )
    {
      right = mid-1;//search key only in a left subarray
    }
    else//if key is greater than mid position element
    {
      left = mid+1;//search key only in a right subarray
    }
  }//repeat the above steps either key is not found or max any subarray is valid
  return false;
}
```

Data Structures: Searching Algorithms

Best Case: if the key is found in very first iteration at mid position in only 1 no. of comparison it is considered as a best case and running time of an algorithm in this case is O(1) = $\Omega(1)$.

Worst Case: if either key is not found or key is found at leaf position it is considered as a worst case and running time of an algorithm in this case is O(log n) = **O(log n).**

Average Case: if key is not found in the first iteration and it is found at non-leaf position it is considered as an average case and running time of an algorithm in this case is O(log n) = $\theta(\log n)$.

Data Structures: Sorting Algorithms

1. Selection Sort:

-In this algorithm, in first iteration, first position gets selected and element which is at selected position gets compared with all its next position elements, if selected position element found greater than any other position element then swapping takes place and in first iteration smallest element gets setteled at first position.

-In the second iteration, second position gets selected and element which is at selected position gets compared with all its next position elements, if selected position element found greater than any other position element then swapping takes place and in second iteration second smallest element gets setteled at second position, and so on in maximum **(n-1)** no. of iterations all array elements gets arranged in a sorted manner.

Data Structures: Sorting Algorithms

Data Structures: Sorting Algorithms

Best Case   : $\Omega(n^2)$

Worst Case   : $O(n^2)$

Average Case   : $\theta(n^2)$

2. Bubble Sort:

- In this algorithm, in every iteration elements which are at two consecutive positions gets compared, if they are already in order then no need of swapping between them, but if they are not in order i.e. if prev position element is greater than its next position element then swapping takes place, and by this logic in first iteration largest element gets setteled at last position, in second iteration second largest element gets setteled at second last position and so on, in max **(n-1)** no. of iterations all elements gets arranged in a sorted manner.

Data Structures: Sorting Algorithms

Iteration-1	Iteration-2	Iteration-3	Iteration-4	Iteration-5

Iteration-1

(30) (20) 60 50 10 40
0   1   2 3 4 5
pos pos+1

20 (30) (60) 50 10 40
0   1   2   3 4 5
   pos pos+1

20 30 (60) (50) 10 40
0 1 2   3   4 5
      pos pos+1

20 30 50 (60) (10) 40
0 1 2 3   4   5
         pos pos+1

20 30 50 10 (60) (40)
0 1 2 3 4   5
            pos pos+1

20 30 50 10 40 [60]
0 1 2 3 4 5

Iteration-2

(20) (30) 50 10 40 [60]
0   1   2 3 4 5
pos pos+1

20 (30) (50) 10 40 [60]
0   1   2   3 4 5
   pos pos+1

20 30 (50) (10) 40 [60]
0 1 2   3   4 5
      pos pos+1

20 30 10 (50) (40) [60]
0 1 2 3   4   5
         pos pos+1

20 30 10 40 [50 60]
0 1 2 3 4 5

Iteration-3

(20) (30) 10 40 [50 60]
0   1   2 3 4 5
pos pos+1

20 (30) (10) 40 [50 60]
0   1   2   3 4 5
   pos pos+1

20 10 (30) (40) [50 60]
0 1 2   3   4 5
      pos pos+1

20 10 30 [40 50 60]
0 1 2 3 4 5

Iteration-4

(20) (10) 30 [40 50 60]
0   1   2 3 4 5
pos pos+1

10 (20) (30) [40 50 60]
0   1   2   3 4 5
   pos pos+1

10 20 [30 40 50 60]
0 1 2 3 4 5

Iteration-5

(10) (20) [30 40 50 60]
0   1   2 3 4 5
pos pos+1

10 [20 30 40 50 60]
0 1 2 3 4 5

Data Structures: Sorting Algorithms

Best Case : $\Omega(n)$ – if array elements are already arranged in a sorted manner.

Worst Case : $O(n^2)$

Average Case : $\theta(n^2)$

3. Insertion Sort:

-In this algorithm, in every iteration one element gets selected as a **key element** and key element gets inserted into an array at its appropriate position towards its left hand side elements in a such a way that elements which are at left side are arranged in a sorted manner, and so on, in max **(n-1)** no. of iterations all array elements gets arranged in a sorted manner.

- This algorithm works efficiently for already sorted input sequence by design and hence running time of an algorithm is $O(n)$ and it is considered as a best case.

Data Structures: Sorting Algorithms

Best Case **: Ω(n)** – if array elements are already arranged in a sorted manner.

Worst Case **: O(n^2)**

Average Case: θ(n^2)

- Insertion sort algortihm is an efficient algorithm for smaller input size array.

4. Merge Sort:

- This algorithm follows **divide-and-conquer** approach.

-In this algorithm, big size array is divided logically into smallest size (i.e. having size 1) subarrays, as if size of subarray is 1 it is sorted, after dividing array into sorted smallest size subarray's, subarrays gets merged into one array step by step in a sorted manner and finally all array elements gets arranged in a sorted manner.

- This algorithm works fine for **even** as well **odd** input size array.

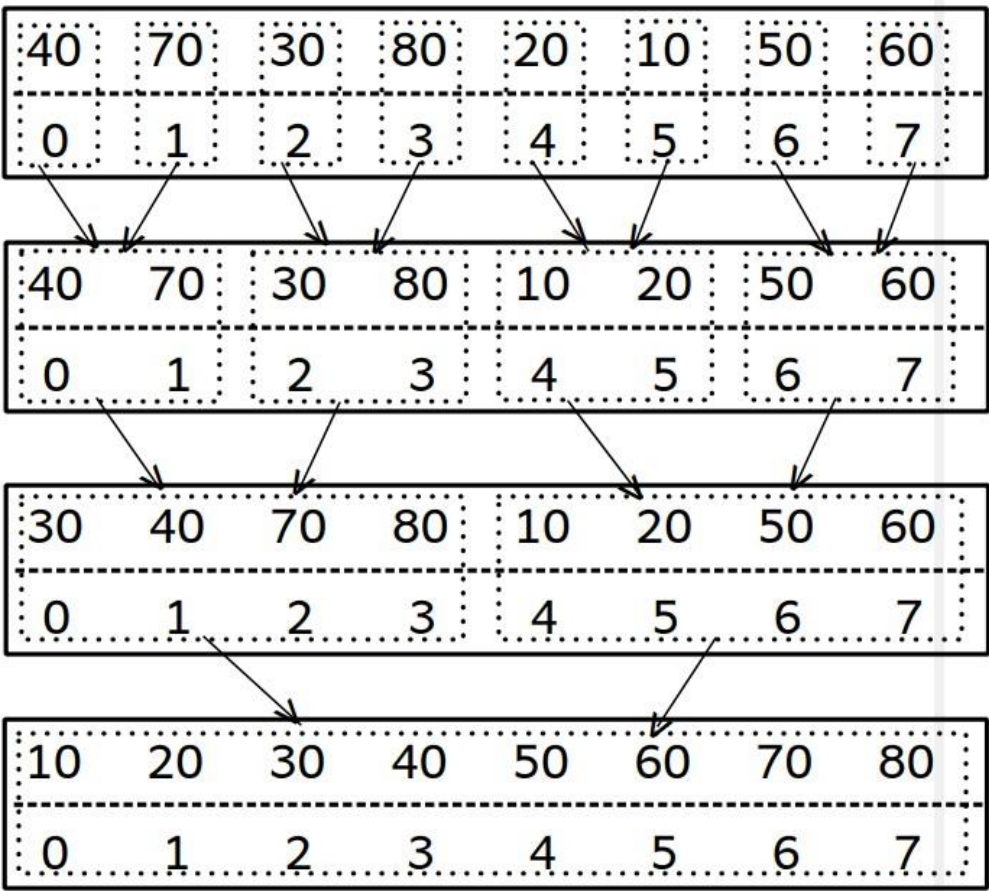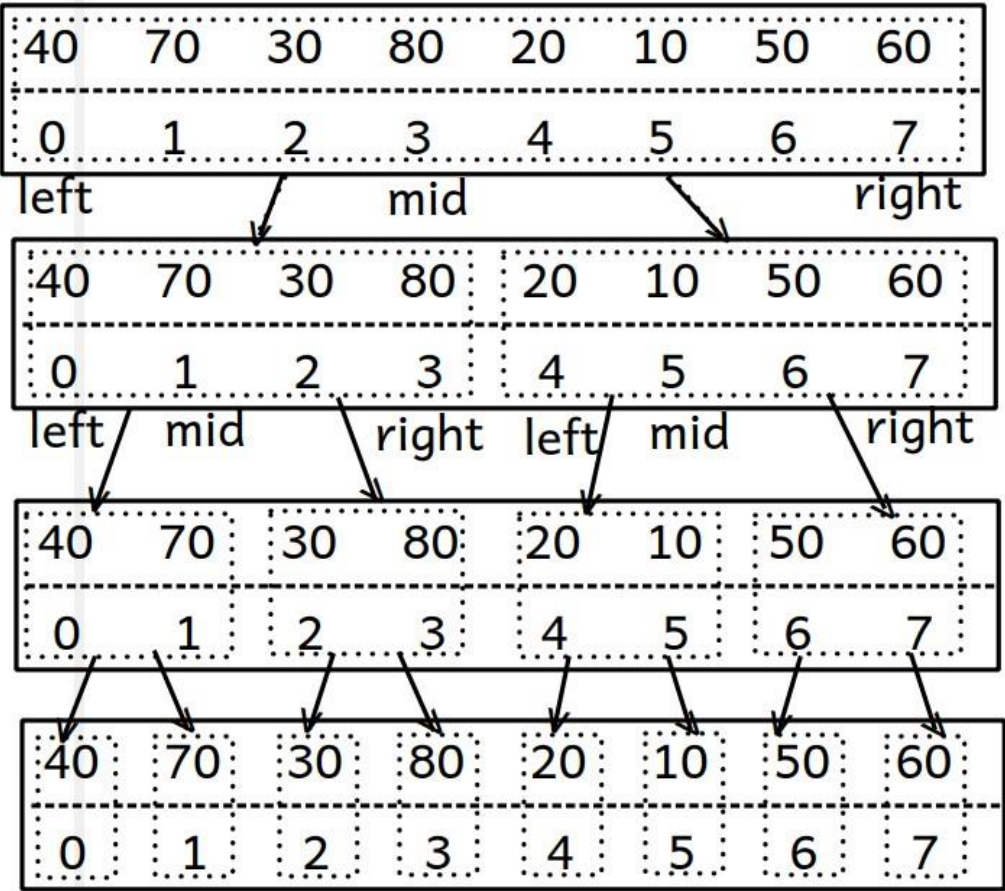-This algorithm takes extra space to sort array elements, and hence its space complexity is more.

Data Structures: Sorting Algorithms

Merge Sort

Dividing big size array into smallest size subarrays   Merge already sorted arrays

Data Structures: Sorting Algorithms

Best Case	: Ω(nlog n)
Worst Case	: O(n log n)
Average Case	: θ(nlog n)

5. Quick Sort:

- This algorithm follows **divide-and-conquer** approach.
- In this algorithm the basic logic is a **partitioning.**
- **Partitioning:** in parititioning, pivot element gets selected first (it may be either leftmost or rightmost or middle most element in an array), after selection of pivot element all the elements which are smaller than pivot gets arranged towards as its left as possible and elements which are greater than pivot gets arranged as its right as possible, and big size array is divided into two subarray's, so after first pass pivot element gets settled at its appropriate position, elements which are at left of pivot is referred as **left partition** and elements which are at its right referred as a **right partition.**

Data Structures: Sorting Algorithms

Best Case   : Ω(nlog n)

Worst Case   : $O(n^2)$ – worst case rarely occures

Average Case : θ(nlog n)

- Quick sort algortihm is an efficient sorting algorithm for larger input size array.

Data Structures: Linked List

- **Limitations of an array data structure:**

1.Array is static, i.e. size of an array is fixed, its size cannot be either grow or shrink during runtime.

2.Addition and deletion operations on an array are not efficient as it takes O(n) time, and hence to overcome these two limitations of an Array **Linked List** data structure has been designed.

Linked List: It is a collection/list of logically related similar type of elements in which,

-an address of first element in a collection/list is stored into a pointer variable referred as a head pointer.

-each element contains data and an address of its next (as well as its previous element).

- An element in a Linked List is also called as a **Node.**

-Four types of linked lists are there: **Singly Linear Linked List, Singly Circular Linked List, Doubly Linear Linked List and Doubly Circular Linked List.**

Data Structures: Linked List

-Basically we can perform **addition, deletion, traversal** etc... operations on linked list data structure.

-We can add and delete node by three ways: we can add node into the linked list at last position, at first position and at any specific position, simillarly we can delete node from linked list which is at first position, last position and at any specific position.

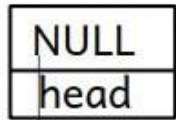**1. Singly Linear Linked List:** It is a linked list in which

- head always contains an address of first element, if list is not empty.

- each node has two parts:

i. data part: contains data of any primitive/non-primitive type.

ii. pointer part(next): contains an address of its next element/node.

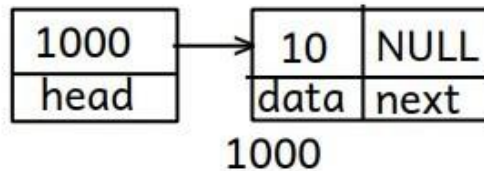- last node points to NULL, i.e. next part of last node contains NULL.

Data Structures: Linked List

SINGLY LINEAR LINKED LIST

1) singly linear linked list --> list is empty

```
NULL
head
```

2) singly linear linked list --> list contains only one node

```
1000  -->  10    NULL
head       data  next
           1000
```

3) singly linear linked list --> list contains more than one nodes

```
1000  -->  10    2000 -->  20    3000 -->  30    4000 -->  40    5000 -->  50    NULL
head       data  next      data  next      data  next      data  next      data  next
           1000            2000            3000            4000            5000
```
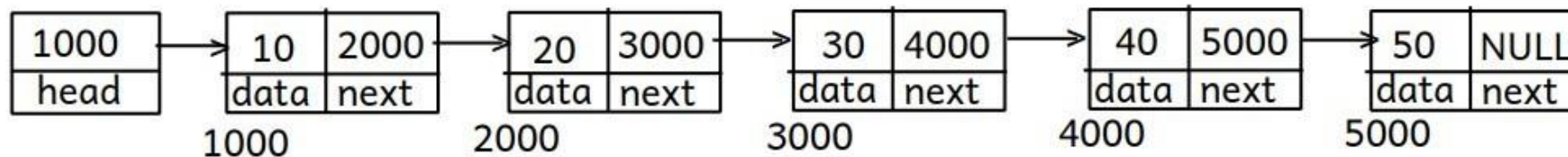
Data Structures: Linked List

Limitations of Singly Linear Linked List:

-Add node at last position & delete node at last position operations are not efficient as it takes O(n) time.

-We can starts traversal only from first node and can traverse the SLLL only in a forward direction.

- Previous node of any node cannot be accesed from it.

- **Any node cannot be revisited** – to overcome this limitation Singly Circular Linked List has been designed.

2. Singly Circular Linked List: It is a linked list in which

- head always contains an address of first element, if list is not empty.

- each node has two parts:

i. data part: contains data of any primitive/non-primitive type.

ii. pointer part(next): contains an address of its next element/node.

- last node point to first node, i.e. next part of last node contains an address of first node.
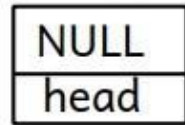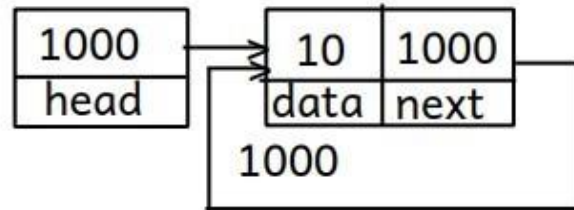
Data Structures: Linked List

SINGLY CIRCULAR LINKED LIST

1) singly circular linked list --> list is empty

```
| NULL |
| head |
```

2) singly circular linked list --> list contains only one node

```
| 1000 |  ---->  | 10   | 1000 |
| head |         | data | next |
                 1000
```

3) singly circular linked list --> list contains more than one nodes

```
| 1000 | ---> | 10   | 2000 | --> | 20   | 3000 | --> | 30   | 4000 | --> | 40   | 5000 | --> | 50   | 1000 |
| head |      | data | next |     | data | next |     | data | next |     | data | next |     | data | next |
             1000                2000                3000                4000                5000
```
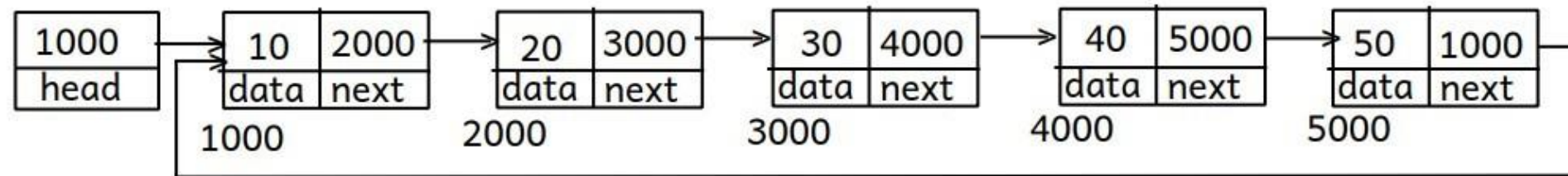
Data Structures: Linked List

Limitations of Singly Circular Linked List:

-Add last, delete last & add first, delete first operations are not efficient as it takes O(n) time.

-We can starts traversal only from first node and can traverse the SCLL only in a forward direction.

-Previous node of any node cannot be accesed from it – to overcome this limitation Doubly Linear Linked List has been designed.

3. Doubly Linear Linked List: It is a linked list in which

- head always contains an address of first element, if list is not empty.

- each node has three parts:

i. data part: contains data of any primitive/non-primitive type.

ii. pointer part(next): contains an address of its next element/node.

iii .pointer part(prev): contains an address of its previous element/node.

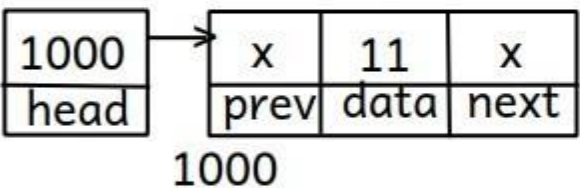- next part of last node & prev part of first node point to NULL.

Data Structures: Linked List

DOUBLY LINEAR LINKED LIST

1. doubly linear linked list --> list is empty

```
NULL
head
```

2. doubly linear linked list --> list is contains only one node

```
1000  ->  x    11    x
head     prev data next
          1000
```

3. doubly linear linked list --> list is contains more than one nodes

```
1000 ->  x    11   2000 <-> 1000  22  3000 <-> 2000  33  4000 <-> 3000  44    x
head    prev data next     prev data next     prev data next     prev data next
         1000                2000                3000                4000
```
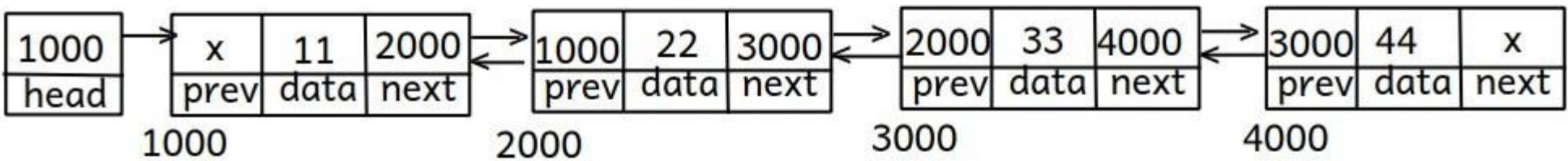
Data Structures: Linked List

Limitations of Doubly Linear Linked List:

- Add last and delete last operations are not efficient as it takes O(n) time.

-We can starts traversal only from first node, and hence to overcome these limitations Doubly Circular Linked List has been designed.

4. Doubly Circular Linked List: It is a linked list in which

- head always contains an address of first node, if list is not empty.

- each node has three parts:

i. data part: contains data of any primitive/non-primitive type.

ii. pointer part(next): contains an address of its next element/node.

iii .pointer part(prev): contains an address of its previous element/node.

- next part of last node contains an address of first node & prev part of first node contains an address of last node.
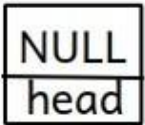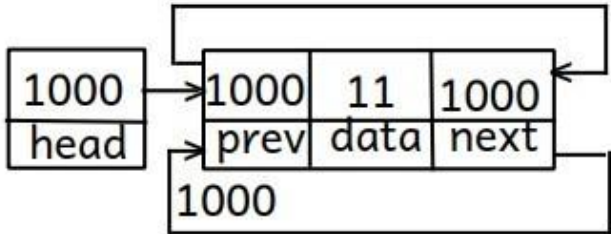
Data Structures: Linked List

DOUBLY CIRCULAR LINKED LIST

1. doubly circular linked list --> list is empty

```
NULL
head
```

2. doubly circular linked list -> list is contains only one node

| 1000 | → | 1000 | 11 | 1000 |
| head | | prev | data | next |

1000

3. doubly circular linked list --> list is contains more than one nodes

| 1000 | → | 4000 | 11 | 2000 | → | 1000 | 22 | 3000 | → | 2000 | 33 | 4000 | → | 3000 | 44 | 1000 |
| head | | prev | data | next | | prev | data | next | | prev | data | next | | prev | data | next |

1000   2000   3000   4000
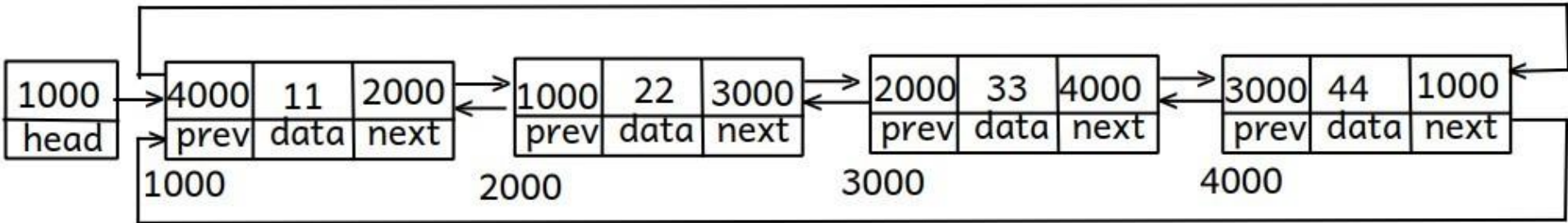
Data Structures: Linked List

Advantages of Doubly Circular Linked List:

- DCLL can be traverse in forward as well as in a backward direction.

-Add last, add first, delete last & delete first operations are efficient as it takes O(1) time and are convenient as well.

- Traversal can be start either from first node or from last node.

- Any node can be revisited.

- Previous node of any node can be accessed from it

Array v/s Linked List:

- Array is **static** data structure whereas linked list is dynamic data structure.

-Array elements can be accessed by using **random access** method which is efficient than linked list elements which can be accessed by **sequential access** method.

- Addition & Deletion operations are efficient on linked list than on an array.

- Array elements gets stored into the **stack section**, whereas linked list elements gets stored into **heap section.**

-In a linked list extra space is required to maintain link between elements, whereas in an array to maintain link between elements is the job of **compiler**.

Data Structures: Stack

Stack: It is a collection/list of logically related similar type elements into which data elements can be added as well as deleted from only one end referred **top** end.

-In this collection/list, element which was inserted last only can be deleted first, so this list works in **last in first out/first in last out** manner, and hence it is also called as **LIFO list**/FILO list.

- We can perform basic three operations on stack in **O(1)** time: **Push, Pop & Peek.**

1. **Push** : **to insert/add an element onto the stack at top position**

     step1: check stack is not full

     step2: increment the value of top by 1

     step3: insert an element onto the stack at top position.

2. **Pop   : to delete/remove an element from the stack which is at top position**

     step1: check stack is not empty

     step2: decrement the value of top by 1.

Data Structures: Stack

3. Peek   : to get the value of an element which is at top position without push & pop.

　　step1: check stack is not empty

　　step2: return the value of an element which is at top position

Stack Empty　　　**: top == -1**

Stack Full　　　　**: top == SIZE-1**

 # Applications of Stack:

- Stack is used by an OS to control of flow of an execution of program.

- In recursion internally an OS uses a stack.

- undo & redo functionalities of an OS are implemented by using stack.

- Stack is used to implement advanced data structure algorithm like **DFS: Depth First Search** traversal in tree & graph.

-Stack is used in an algorithms to covert given infix expression into its equivalent postfix and prefix, and for postfix expression evaluation.

Data Structures: Stack

- Algorithm to convert given infix expession into its equivalent postfix expression:

Initially we have, an Infix expression, an empty Postfix expression & empty Stack.

```
# algorithm to convert given infix expression into its equivalent postfix expression
step1: start scanning infix expression from left to right
step2:
    if( cur ele is an operand )
        append it into the postfix expression
    else//if( cur ele is an operator )
    {
        while( !is_stack_empty(&s) && priority(topmost ele) >= priority(cur ele) )
        {
            pop an ele from the stack and append it into the postfix expression
        }

        push cur ele onto the stack
    }
step3: repeat step1 & step2 till the end of infix expression
step4: pop all remaining ele's one by one from the stack and append them into the
postfix expression.
```

Data Structures: Stack

- Algorithm to convert given infix expession into its equivalent prefix expession:

Initially we have, an Infix expression, an empty Prefix expression & empty Stack.

```
# algorithm to convert given infix expression into its equivalent prefix:
step1: start scanning infix expression from right to left
step2:
    if( cur ele is an operand )
        append it into the prefix expression
    else//if( cur ele is an operator )
    {
        while( !is_stack_empty(&s) && priority(topmost ele) > priority(cur ele) )
        {
            pop an ele from the stack and append it into the prefix expression
        }

        push cur ele onto the stack
    }
step3: repeat step1 & step2 till the end of infix expression
step4: pop all remaining ele's one by one from the stack and append them into the
prefix expression.
step5: reverse prefix expression - equivalent prefix expression.
```