1 Algorithmus

```
Input: loss function E, learning rate \eta, dataset X,y und das Modell F(\theta,x)

Output: Optimum \theta which minimizes \epsilon

1 while converge do

2 | \tilde{y} = F(\theta,x)

3 | \theta = \theta - \eta \cdot \frac{1}{N} \sum_{i=1}^{N} \frac{\delta \epsilon(y,\tilde{y})}{\delta \theta}

4 end
```

Algorithm 1: Gradient descent

```
Input: loss function E, learning rate \eta, dataset X,y und das Modell F(\theta,x)

Output: Optimum \theta which minimizes \epsilon

1 while converge do

2 | Shuffle X, y

3 | for x_i, y_i in X, y do

4 | \tilde{y} = F(\theta, x_i)

5 | \theta = \theta - \eta \cdot \frac{1}{N} \sum_{i=1}^{N} \frac{\delta \epsilon(y_i, \tilde{y_i})}{\delta \theta}

6 | end

7 end
```

Algorithm 2: Stochastic Gradient descent(SGD)

```
Input: loss function E, learning rate \eta, dataset X,y und das Modell F(\theta,x)

Output: Optimum \theta which minimizes E

1 while converge do

2 | Shuffle X, y

3 | for each batch of x_i, y_i in X, y do

4 | \tilde{y} = F(\theta, x_i)

5 | \theta = \theta - \eta \cdot \frac{1}{N} \sum_{i=1}^{N} \frac{\delta E(y_i, \tilde{y_i})}{\delta E}

6 | end

7 end
```

Algorithm 3: Mini-Batch Stochastic Gradient descent(MSGD)

```
Input: Netzwerk mit l layers, Aktivirungsfunktion \sigma_l, Output von der verstekten Schicht h_l = \sigma_l(W_l^T h_{l-1} + b_l) und die Netzwerkausgabe \tilde{y} = h_l

1 Berechnen der Gradient: \delta \leftarrow \frac{\partial E(y_i, \tilde{y}_i)}{\partial y}

2 for i \leftarrow l bis 0 do

3 Berechnen der Gradient für die Aktuelle Schicht

4 \frac{\partial E(y, \tilde{y})}{\partial W_l} = \frac{\partial E(y, \tilde{y})}{\partial h_l} \frac{\partial h_l}{\partial W_l} = \delta \frac{\partial h_l}{\partial W_l}

5 \frac{\partial E(y, \tilde{y})}{\partial b_l} = \frac{\partial E(y, \tilde{y})}{\partial h_l} \frac{\partial h_l}{\partial b_l} = \delta \frac{\partial h_l}{\partial b_l}

6 Gradientabstiegverfahren mit \frac{\partial E(y, \tilde{y})}{\partial W_l} und \frac{\partial E(y, \tilde{y})}{\partial b_l}

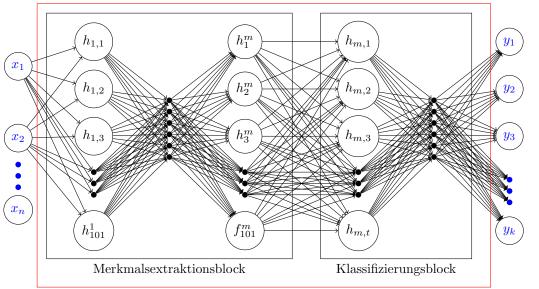
7 Propagiere den Gradienten zu den unteren Schichten.

8 \delta \leftarrow \frac{\partial E(y, \tilde{y})}{\partial h_l} \frac{\partial h_l}{\partial h_{l-1}} = \delta \frac{\partial h_l}{\partial h_{l-1}}

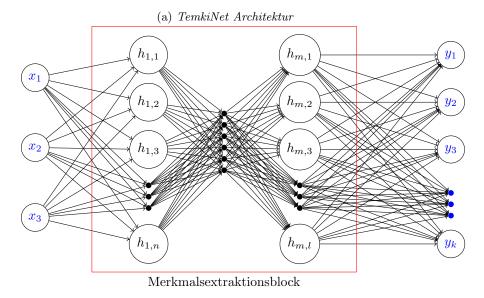
9 end
```

Algorithm 4: Back-Propagation

2 Neuronale Netzwerk



Input Layer Hidden Layer Output Layer



 ${\color{red} {\bf Hidden~Layer}}$ (b) Allgemeine CNN-Architektur

Output Layer

Input Layer