

metrics for
search analysis

19 sept
2022

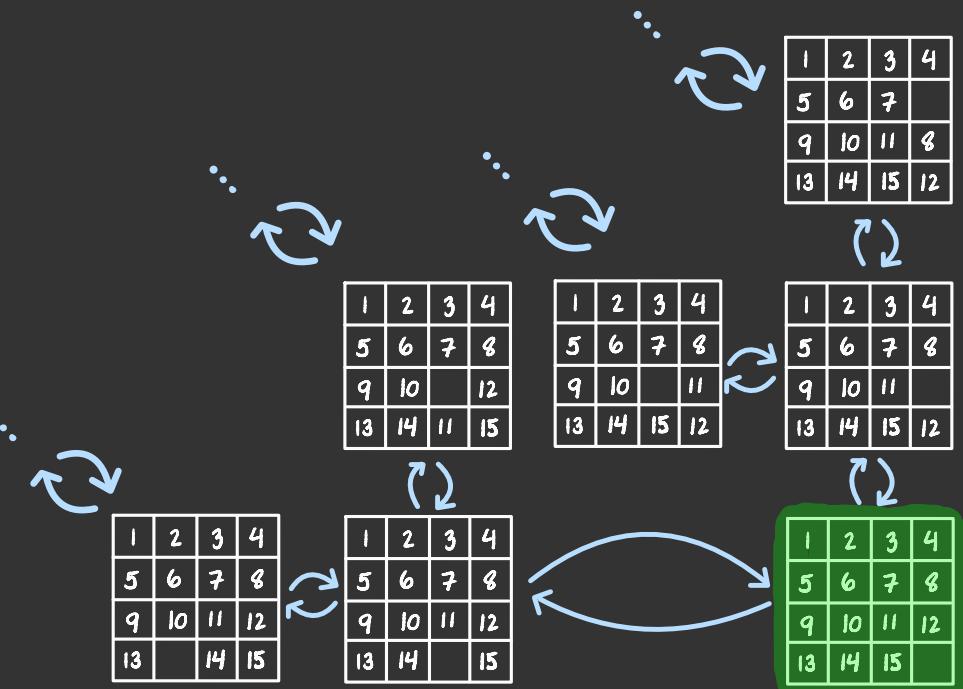
CSCI
373

from the wikipedia article on depth-first search

Properties [edit]

The time and space analysis of DFS differs according to its application area. In theoretical computer science, DFS is typically used to traverse an entire graph, and takes time $O(|V| + |E|)$,^[4] linear in the size of the graph. In these applications it also uses space $O(|V|)$ in the worst case to store the stack of vertices on the current search path as well as the set of already-visited vertices. Thus, in this setting, the time and space bounds are the same as for breadth-first search and the choice of which of these two algorithms to use depends less on their complexity and more on the different

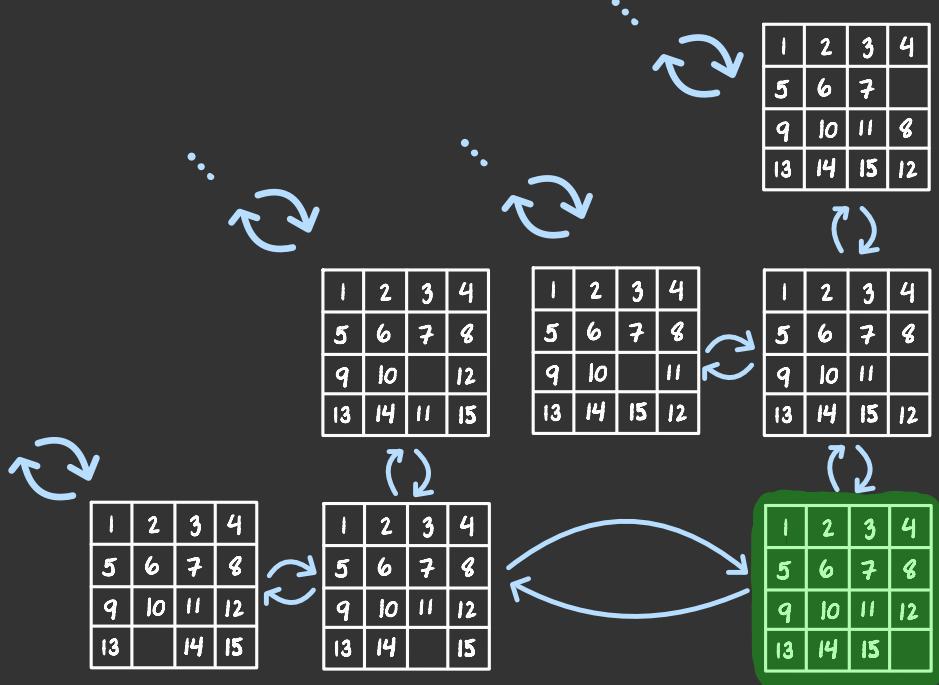
how many states
are there for this
sliding tile
puzzle?



your answer
here

how many states
are there for this
sliding tile
puzzle?

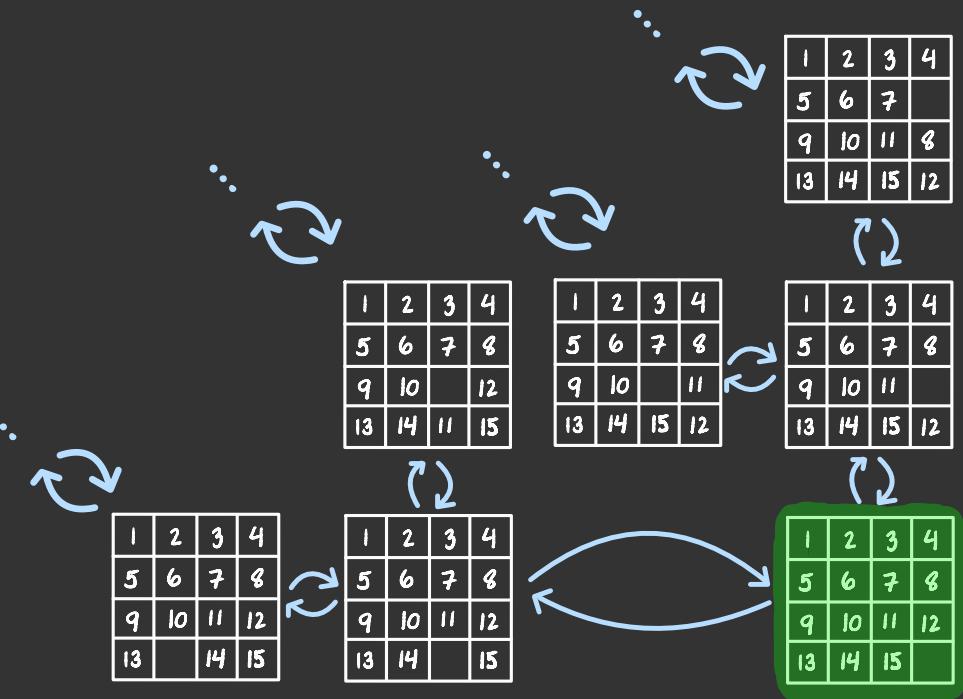
16!



how many states
are there for this
sliding tile
puzzle?

16!

= 20,922,789,888,000
(over twenty trillion)



Properties [edit]

The time and space analysis of DFS differs according to its application area. In theoretical computer science, DFS is typically used to traverse an entire graph, and takes time $O(|V| + |E|)$,^[4] linear in the size of the graph. In these applications it also uses space $O(|V|)$ in the worst case to store the stack of vertices on the current search path as well as the set of already-visited vertices. Thus, in this setting, the time and space bounds are the same as for breadth-first search and the choice of which of these two algorithms to use depends less on their complexity and more on the different

how many states
are there for this
sliding tile
puzzle?

16!

= 20,922,789,888,000
(over twenty trillion)

so dfs is linear... in twenty
trillion vertices



and what about
this
sliding tile puzzle?

how many
States?



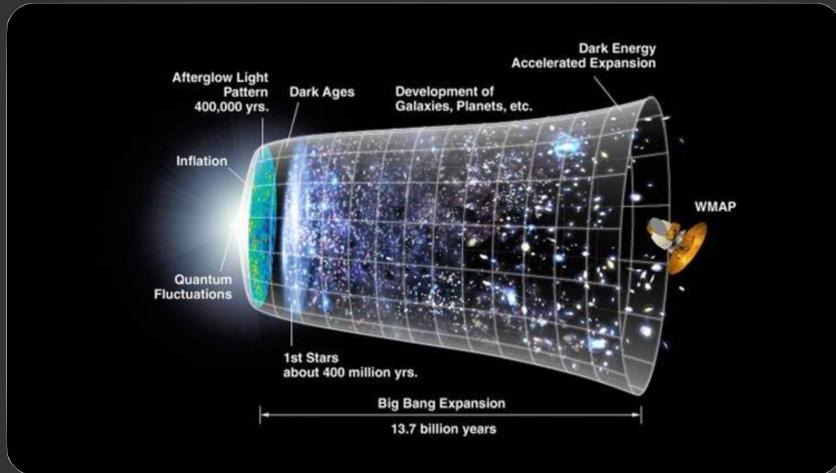
and what about
this
sliding tile puzzle?

36!

$\approx 3.72 \times 10^{41}$

(over three hundred duodecillion)

the 64-puzzle has
more states than
atoms
in the observable universe



from the wikipedia article on depth-first search

Properties [edit]

The time and space analysis of DFS differs according to its application area. In theoretical computer science, DFS is typically used to traverse an entire graph, and takes time $O(|V| + |E|)$,^[4] linear in the size of the graph. In these applications it also uses space $O(|V|)$ in the worst case to store the stack of vertices on the current search path as well as the set of already-visited vertices. Thus, in this setting, the time and space bounds are the same as for breadth-first search and the choice of which of these two algorithms to use depends less on their complexity and more on the different

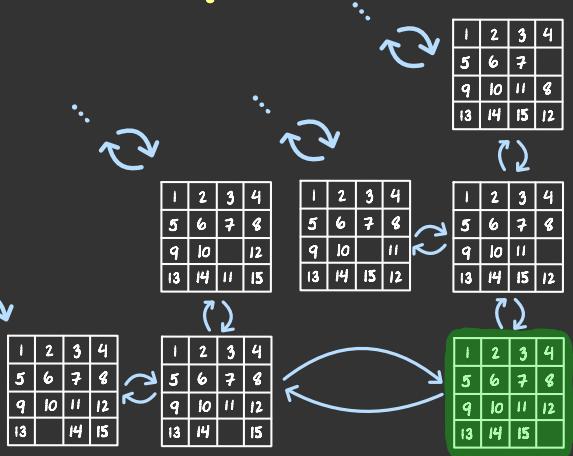
the number of states (i.e. $|V|$) doesn't provide much insight into the performance of search algorithms for most AI applications

solution depth : the length of the shortest search path that leads to a final state

maximum depth: the length of the longest search path

branching factor: the maximum number of successors of a search node

15-puzzle



solution depth = your answer here

the length of the shortest search path that leads to a final state

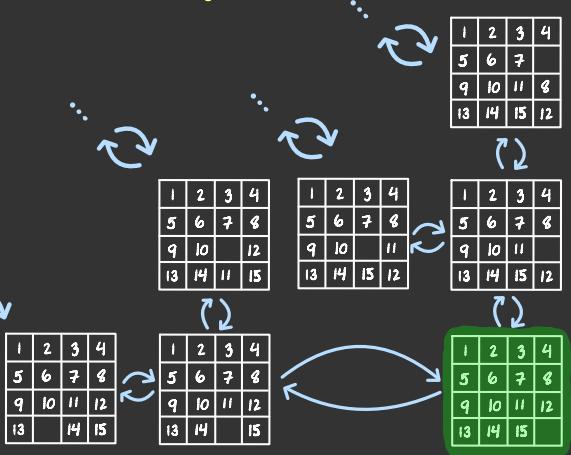
maximum depth = your answer here

the length of the longest search path

branching factor = your answer here

the maximum number of successors of a search node

15-puzzle



solution depth = depends on initial state

the length of the shortest search path that leads to a final state

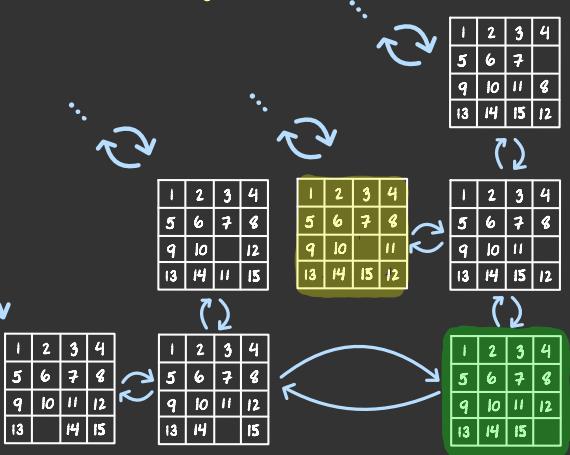
maximum depth = ∞

the length of the longest search path

branching factor = 4

the maximum number of successors of a search node

15-puzzle



solution depth = 2

the length of the shortest search path that leads to a final state

maximum depth = ∞

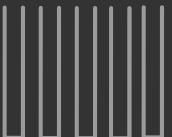
the length of the longest search path

branching factor = 4

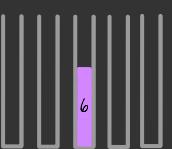
the maximum number of successors of a search node

bin packing (formulation 1)

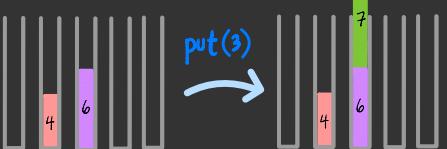
initial state:



action:



$\xrightarrow{\text{put}(2)}$



$\xrightarrow{\text{put}(3)}$



put next block into i^{th} bin

solution depth = your answer here

the length of the shortest search path that leads to a final state

maximum depth = your answer here

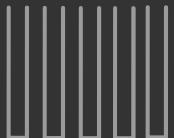
the length of the longest search path

branching factor = your answer here

the maximum number of successors of a search node

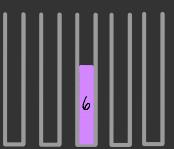
bin packing (formulation 1)

initial state:

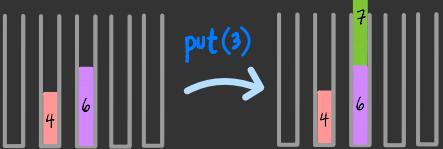


n empty bins

action:



$\text{put}(2)$



$\text{put}(3)$



solution depth = n

the length of the shortest search path that leads to a final state

maximum depth = n

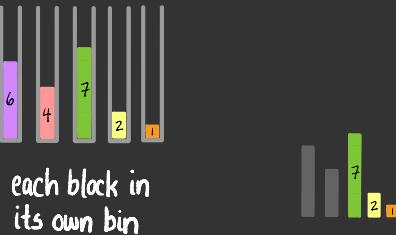
the length of the longest search path

branching factor = n

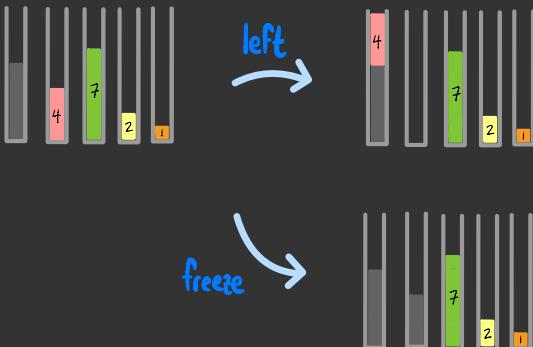
the maximum number of successors of a search node

bin packing (formulation 2)

initial state:



actions:



freeze leftmost block

solution depth = your answer here

the length of the shortest search path that leads to a final state

maximum depth = your answer here

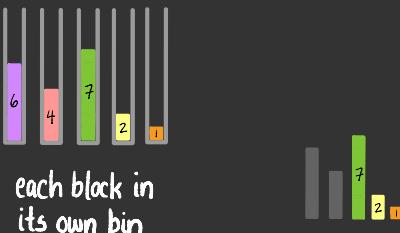
the length of the longest search path

branching factor = your answer here

the maximum number of successors of a search node

bin packing (formulation 2)

initial state:



actions:



freeze leftmost block

solution depth = depends on initial state

the length of the shortest search path that leads to a final state

$$\begin{aligned}\text{maximum depth} &= n + \sum_{i=0}^{n-1} i \\ &= n + \frac{n(n-1)}{2}\end{aligned}$$

branching factor = 2

the maximum number of successors of a search node