# **Tanvir Hossain**

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#### **Education**

Islamic University of Technology, Gazipur, Bangladesh

January 2020 – June 2024

B.Sc. in Mechanical Engineering CGPA: 3.90/4.00 (class position 3rd)

# **Research Experience**

1. <u>Undergraduate Thesis:</u> Optimization of Clamp Numbers and Positions to Mitigate Flow-Induced Vibration in High-Speed Fluid Flow Through a Pipe Elbow

January 2024- ongoing

Supervisor: Dr. Md. Zahid Hossain

- Contributed to the research by analyzing the vibration using FFT in python and Excel and validating the work
- Comparing the acceleration and displacement data from the simulation to determine the optimal number and positions of standard clamp for vibration reduction for the pipe
- Creating a model using dimensional analysis that includes, clamp numbers and positions and fluid
  properties to determine optimal clamps required for a general pipeline used in industrial boiler connection.
- 2. Experimental Study on Non-linear Vibration of Sandwich Composite Specimen August 2023-December 2023 Supervisor: Dr. Md. Zahid Hossain
  - Fabricated 2 sandwich composite specimens of different lengths. Specimens include stainless steel core sandwiched by two rubber layers.
  - Designed a simple 3DOF linear sandwich system in MATLAB-Simulink
  - Extracted data from the experimental setup and performed Fast Fourier Transformation (FFT) to plot the dynamic behavior the system
  - Compared the dynamic behavior of the specimen with the linear setup in Simulink to decide the nature of the composite structure
- 3. Novel Power Cycle Supercritical Brayton Cycle with Ejector Cycle and VAR System January 2024-ongoing Supervisor: Dr. Mohammad Monjurul Ehsan
  - Designed the power cycle layout for improved performance
  - Reviewed literatures on ejector cycle

#### **Other Experience**

• Tutored students of class XI-XII on math and physics.

February 2020-January 2021

#### **Research Interest**

- 1. Legged Robots
- 2. Controller Design
- 3. Dynamic Locomotion

- 4. Mechanical Vibration
- 5. Humanoids
- 6. Robot Manipulation

## **Projects**

#### 4 degrees of freedom robotic arm for picking and sorting objects

Jan 2023-January 2024

Undergraduate Capstone Project supervised by Dr. Md. Rezwanul Karim

- Designed one of the prototypes of the arm
- Finalized the control system algorithm for the arm
- Created a GUI interface for manually controlling the arm
- Wrote the code for forward and inverse kinematics of the arm
- Chassis of 'Musafir' Mars rover of Project Altair

June 2023-January 2024

European Rover Challenge 2023, Kielce, Poland

- Designed the mars rover chassis on SOLIDWORKS
- Tested the load carrying capacity and structural dynamics using ANSYS
- Manufactured the chassis
- Electic Box of 'Musafir' Mars rover of Project Altair

June 2023-January 2024

European Rover Challenge 2023, Kielce, Poland

- Designed a reconfigurable electric box for the rover on SOLIDWORKS for ERC 2023
- Tested the load carrying capacity and structural dynamics using ANSYS
- Manufactured the electric box

#### **Skills and Interests**

- **Design and Simulation: SOLIDWORKS, ANSYS**
- **Programming:** ROS, C, Python, Arduino
- Control and Automation: MATLAB, LABVIEW, Ardupilot, LINUX
- Others: MS Office, PowerPoint, Excel
- Language: English, German (A1)
- Others: Violin, Acting

# **Leadership Activities**

**Chief Editor** - IUT Robotics Society

Chassis Design Architect - Project Altair

Senior member of software - Project Altair

Chief of Robotics - IMechE IUT Student Chapter

**Executive: Autonomous System -** ANTS Aerial Systems

October 2023-July 2024

June 2023 – May 2024

June 2023 – January 2024

August 2023 - May 2024

February 2021 – July 2021

#### **Achievements**

_	Team of and Decree Challenge 2024, Deat Colonia, Team Latin (Team Astronomy)	2024
•	International Rover Challenge 2024 -Best Science Team, India (Team Achievement)	2024
•	International Rover Challenge 2024 - 6 <sup>th</sup> position, India (Team Achievement)	2024
•	European Rover Challenge 2023 -17th position, Poland (Team Achievement)	2023
•	International Rover Design Challenge 2022 - 13th position, virtual (Team Achievement)	2022
•	European Rover Challenge 2021 - 10th position, virtual (Team Achievement)	2021
•	OIC Partial Scholarship, Bangladesh	2020

#### Certification

• Supervised Machine Learning: Regression and Classification

Stanford Online, Coursera

EDC Supervised Industry to a lead on the Program of the Program of

ERC Space and Robotics Industry standard practice Program

 European Space Foundation

 Industrial Training Course
 September 2023
 June 2023

BPDB, Rajshahi, Bangladesh

#### References

# 1. Dr. Md. Zahid Hossain

Professor of Mechanical Engineering Islamic University of Technology, Email: zahidmce@iut-dhaka.edu

## 2. Dr. Md. Rezwanul Karim

Professor of Mechanical Engineering Islamic University of Technology, Email: rezwanul@iut-dhaka.edu