# Curriculum Vitae Tanvir Hossain

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#### Education

Islamic University of Technology — Gazipur, Bangladesh BSc in Mechanical Engineering

Jan 2020 – June 2024

bbe in Mechanical Dugineering

• <u>GPA</u>: **3.9**/4.0; <u>Class Rank</u>: **3**/36

<u>Relevant Coursework</u>: 3D Solid Modelling and Assembly, Mechanics of Materials, Measurement, Instrumentation and Control, Manufacturing Processes, Industrial Management, Machine Design I & II, Capstone Design I & II, Mechanics of Machines, Project and Environmental Management, Machine Tools, Mechanical Vibration, Control System and Industrial Automation, Operations Research

### **Publications**

- o Ahmed, H., **Hossain, T.**, Ahmed, A., Hossain, Z. Investigation of Clamp Numbers and Positions to Mitigate Flow-Induced Vibration in High-Speed Superheated Steam Flow Through a Pipe Elbow. *International Mechanical Engineering and Congress Exhibition* (Abstract Submitted)
- Khan, T.E., Sakib, S.H., Sakib, N. Hossain, T., Ehsan, M.. Thermal Analysis and Multi-objective Optimization of Supercritical CO2 Brayton Cycle Cascaded with Ejector Enhanced Transcritical CO2 Refrigeration Cycle and Flash Tank Enhanced Compression-absorption Refrigeration Cycle. Energy Conversion and Management: X (under review)

#### Research Experience (click the link to read the full PDF)

1. Investigation of Clamp Numbers and Positions to Mitigate Flow-Induced Vibration in High-Speed Superheated Steam Flow Through a Pipe Elbow Jan 2024 - May 2024

Undergraduate Thesis — Supervisor: Dr. Md. Zahid Hossain

- Modelled the methodology for testing clamp location and numbers in bent pipe section from a boiler outlet.
- Wrote a Python code using the FFT algorithm to test the dynamic behaviour in the frequency domain.
- Resulted in a 33% reduction in acceleration and a 35% reduction in displacement using just two clamps.

Aug 2023 – Dec 2023

Research Project — Supervisor: Dr. Md. Zahid Hossain

- Fabricated two sandwich composite specimens of different lengths, each with a Butyl Rubber core sandwiched between two stainless steel plates.
- Designed a simple 3DOF spring mass damper system in MATLAB-Simulink and compared the simulation plot with the experimental setup result.
- Wrote a Python code using the FFT algorithm to extract the experimental setup data and test the frequency domain's dynamic behaviour to detect non-linearity.
- 3. Supercritical CO2 Recompression Brayton Power Cycle cascaded with Transcritical CO2 Ejector Refrigeration Cycle and Flash Tank Enhanced VAR system

Jan 2024 – May 2024

Research Project — Supervisor: Dr. Mohammad Monjurul Ehsan

- Analyzed the exergy destruction across the components using CoolProp library in Python.
- Illustrated the Ph diagram, integrated power and cooling cycle, and exergy analysis using Adobe Illustrator.
- $\circ$  The Final cascaded model resulted in a **4.4%** reduction in overall exergy destruction compared to the standalone system.

#### Research Interests

- o Multi-Robot System
- o Predictive Control
- Aerial Manipulation

- Human-Computer Interaction
- Dynamic Locomotion
- Nonlinear Vibration

#### Skills

o Design and Simulation: SOLIDWORKS, ANSYS

o **Programming**: ROS, Python, Arduino

o Control and Automation: MATLAB, LABVIEW, Ardupilot

# Projects (click the link to read the full PDF)

# 4 Degrees of Freedom Robotic Arm for Picking and Sorting Objects Report ☑

 $Jan\ 2023 - Jan\ 2024$ 

Undergraduate Capstone Project

Supervised by Dr. Md. Rezwanul Karim

- Finalized the control system architecture for the robotic arm using a laptop as the power source and Arduino Mega as the Microcontroller.
- Built a GUI interface in Python using the Tkinter library to test the actuators.
- Wrote the arm manipulation code in Python using Numpy based on Forward Kinematics.

#### Chassis of Project Altair Mars Rover - Musafir

June 2023 – Jan 2024

European Rover Challenge 2023, Kielce, Poland

- o Designed a 6kg Mars rover chassis frame on SOLIDWORKS using Stainless Steel.
- $\circ\,$  Tested load-carrying capacity and structural dynamics using ANSYS to maintain it under 75kg.
- $\circ\,$  Designed the placement for electric box and the science module.

# Electric Box of Project Altair Mars Rover

June 2023 – Jan 2024

European Rover Challenge 2023, Kielce, Poland

- Designed a vertical electric box SOLIDWORKS using 12mm thick plywood for ease of access.
- Tested load-carrying capacity and structural dynamics using ANSYS.
- Created a custom conduit system for wire access through and across the chassis length.

# Teaching Experience

∘ IELTS Instructor – <b>Mentors</b>	Feb 2025 – Ongoing
$\circ$ Tutored Higher Maths, General Maths and Physics – $\mathbf{Grades:}$ $\mathbf{XI-XII}$	Feb $2020 - Dec 2023$

# Language Proficiency

• English – **IELTS - 8.5** (Listening: 9, Reading: 9, Writing: 7, Speaking: 8)

29 Sept 2024

# Leadership Activities

 $\circ$  Chief Editor - *IUT Robotics Society* Oct 2023 – July 2024 Led the magazine team for the publication of a brand new robotics magazine - *Genesis* 

• Chassis Design Architect - Project Altair

Led the chassis subteam of Project Altair for the European Rover Challenge, 2023, onsite

Chief of Robotics - IMechE IUT Student Chapter
 Organized robotics competitions and took workshops

Aug 2023 - May 2024

#### Achievements

o International Rover Challenge 2024 - Best Science Team, India (Team Achievement)	2024
o International Rover Challenge 2024 - 6th Position, India (Team Achievement)	2024
o European Rover Challenge 2023 - 17th Position, Poland (Team Achievement)	2023
o International Rover Design Challenge 2022 - 13th Position, Virtual (Team Achievement)	2022
o European Rover Challenge 2021 - 10th Position, Virtual (Team Achievement)	2021
o IMechE UAS Challenge 2021, Design Challenge Award (Team Achievement)	2021
o OIC Partial Scholarship, Bangladesh	2020

# Certifications

# Reference

#### Dr. Md. Zahid Hossain

Professor

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#### Dr. Md. Rezwanul Karim

Professor

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