

# A Structure–Randomness Transfer Theorem for Sparse Data and its Application to the Digits of $\pi$

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## Abstract

We prove a structure–randomness transfer principle that unifies higher-order Fourier analysis, relative Szemerédi-type transference, and compressed sensing. Let  $\nu : \{1, \dots, N\} \rightarrow \mathbb{R}_{\geq 0}$  be a *pseudorandom majorant*, i.e. a weight that averages like the uniform measure on all low-complexity linear patterns (linear-forms condition) and exhibits negligible low-order autocorrelations (correlation condition) [1, 3]. If  $A \subset [N]$  has positive relative density with respect to  $\nu$  and admits an arithmetic regularity decomposition  $1_A = g_{\text{str}} + g_{\text{unf}}$  with  $\|g_{\text{unf}}\|_{U^{s+1}} \leq \varepsilon$ , then (i) the number of polynomial configurations of degree  $\leq s$  inside  $A$  matches the random-model prediction at density  $\delta$  up to  $o_\delta(1)$ , and (ii)  $\nu$  generates measurement ensembles that are approximately isotropic on the span of the templates forming  $g_{\text{str}}$ , yielding Restricted Isometry Property (RIP) with  $m = O(K \log N)$  and stable convex recovery. An application to the digits of  $\pi$  distinguishes statistically pseudorandom base-10 behavior from a BBP-induced degree-1 structure in base 16.

## 1 Introduction

As illustrated schematically in Figure 1, we use the decomposition  $1_A = g_{\text{str}} + g_{\text{unf}}$ ; the measurement and recovery pipeline is shown in Figure 2. The transference paradigm originating in [1] shows that dense combinatorial theorems persist inside sparse sets that are sufficiently pseudorandom. Higher-order Fourier analysis via the Gowers norms and inverse theorems [2, 3, 4] provides the quantitative language. In parallel, compressed sensing shows that structured signals are recoverable from few random measurements under restricted isometry [6]. This paper synthesizes these themes through a single majorant  $\nu$  that supports both relative counting and structured recovery.

### Intuitive overview

A *pseudorandom majorant* is a weight that looks uniform when averaged over any low-complexity pattern—think of a thin, uniform “fog” over  $[N]$ . The arithmetic regularity decomposition

$$1_A = g_{\text{str}} + g_{\text{unf}},$$

splits the indicator  $1_A$  into a *structured* part  $g_{\text{str}}$  (a short sum of nilsequences) and a *uniform* part  $g_{\text{unf}}$  that has tiny higher-order correlations. Figure 1 sketches this idea. The main theorem shows that the same  $\nu$  enabling relative counting also yields measurement ensembles with approximate isotropy on the low-dimensional model spanned by the templates, hence RIP and stable recovery (Figure 2).

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## 2 Preliminaries

We write  $[N] := \{1, \dots, N\}$  and  $\mathbb{R}$  for the reals;  $\mathbb{E}_{n \in [N]}$  denotes expectation w.r.t. the uniform measure on  $[N]$ . We use  $e(x) := e^{2\pi i x}$ . The Gowers  $U^s$ -norm on  $[N]$  is denoted  $\|\cdot\|_{U^s}$ . We write  $o_\varepsilon(1)$  for a quantity tending to 0 as  $N \rightarrow \infty$  with fixed parameters held constant.

**Definition 1** (Pseudorandom majorant). A function  $\nu : [N] \rightarrow \mathbb{R}_{\geq 0}$  is a *pseudorandom majorant of complexity  $L$*  if: (a)  $\mathbb{E}\nu = 1 + o(1)$ ; (b) for any system of  $t \leq L$  affine-linear forms  $\Lambda_i(\mathbf{n})$  with no two affinely dependent,  $\mathbb{E}_{\mathbf{n} \in [N]^d} \prod_{i=1}^t \nu(\Lambda_i(\mathbf{n})) = 1 + o(1)$ ; (c) bounded correlations hold for products of distinct shifts of  $\nu$  [1, 3].

**Definition 2** (Arithmetic regularity). Let  $A \subset [N]$  have relative density  $\delta > 0$  with respect to  $\nu$ . For  $s \geq 1$ , an *arithmetic regularity decomposition* is

$$1_A = g_{\text{str}} + g_{\text{unf}}, \quad (1)$$

where  $g_{\text{str}}$  is a sum of at most  $K(\delta, s)$  nilsequences of degree  $\leq s$  and complexity  $\leq M(\delta, s)$ , and  $\|g_{\text{unf}}\|_{U^{s+1}} \leq \varepsilon$  (one may take  $\varepsilon \ll_s \delta^{c_s}$ ). Quantitative bounds such as  $K \ll_s (\log \log(1/\delta))^{O_s(1)}$  are standard [3, 4].

A *finite-complexity polynomial system*  $\mathcal{P}$  of degree  $\leq s$  is a finite family of integer polynomials in  $d \leq L$  variables of degree  $\leq s$ , with bounded coefficients.

## 3 Main theorem

**Theorem 1** (Structure–Randomness Transfer). *Let  $\nu$  be a pseudorandom majorant on  $[N]$  of complexity  $L$ . Let  $A \subset [N]$  have relative density  $\delta > 0$  with respect to  $\nu$  and admit (1) with  $\|g_{\text{unf}}\|_{U^{s+1}} \leq \varepsilon$ . Then, for  $N$  large depending on  $\delta, s, L$  and complexity parameters:*

- (i) **Polynomial pattern counts.** *For any finite-complexity polynomial system  $\mathcal{P}$  of degree  $\leq s$  and dimension  $\leq L$ , the number of  $\mathcal{P}$ -configurations in  $A$  equals the random-model prediction at density  $\delta$  up to  $o_{\delta, \mathcal{P}}(1)N^{|\mathcal{P}|}$ , with error depending on  $s, L$ , and the coefficient-height/variable-count of  $\mathcal{P}$ .*
- (ii) **Stable structured recovery.** *Let  $f : [N] \rightarrow \mathbb{C}$  be supported on  $A$ , and suppose the structured component of  $f$  lies in the span of the  $K$  templates in  $g_{\text{str}}$ . Let  $\{\phi_j\}_{j=1}^m$  be i.i.d.  $\nu$ -weighted structured measurements, meaning each  $\phi_j$  is a bounded-complexity test function drawn from an ensemble whose covariance on the template span is approximately isotropic under  $\nu$ . Then for  $m \geq CK \log N$ , the convex program*

$$\min_h \|h\|_1 + \lambda \|h\|_2 \quad \text{s.t.} \quad |\langle h, \phi_j \rangle - \langle f, \phi_j \rangle| \leq \tau \quad (1 \leq j \leq m), \quad (2)$$

*with  $\tau \asymp \eta + \varepsilon$  (noise level  $\eta$  plus uniformity scale), recovers  $h$  with  $\|h - f\|_2 \ll \eta$  with probability at least  $1 - e^{-cm}$ .*

**Remark 1** (How  $\nu$  induces RIP). The linear-forms/correlation conditions imply approximate isotropy and concentration for the measurement Gram matrix on the  $K$ -dimensional model class (span of templates). Matrix concentration yields a restricted isometry with  $m \sim K \log N$ ; see Lemma 2 and [6]. “High probability over  $\{\phi_j\}$ ” refers to i.i.d. draws from this  $\nu$ -weighted ensemble (Figure 2).

## 4 Key lemmas and proofs

**Lemma 1** (Relative generalized von Neumann). *Let  $\nu$  be a pseudorandom majorant of complexity  $L$ . Let  $\mathcal{P} = \{P_1, \dots, P_t\}$  be integer polynomials of degree  $\leq s$ . For 1-bounded  $F_1, \dots, F_t : [N] \rightarrow \mathbb{C}$ ,*

$$\left| \mathbb{E}_{n, h \in [N]} \left( \prod_{i=1}^t F_i(n + P_i(h)) \right) \nu(n) \right| \ll_{s, t, L} \min_{1 \leq i \leq t} \|F_i\|_{U^{s+1}} + o_{N \rightarrow \infty}(1). \quad (3)$$

*Proof.* Arrange  $\mathcal{P}$  by degree/leading coefficients and apply repeated Cauchy–Schwarz in  $(n, h)$  to linearize the configuration, producing averages of products of discrete multiplicative derivatives  $\Delta_{h_1} \cdots \Delta_{h_r} F_i$ , with  $r \leq s + 1$ , multiplied by finite products of shifts of  $\nu$ . By Definition 3, any PET-generated product of  $O_{s,t}(1)$  such shifts of  $\nu$  has expectation  $1 + o(1)$  uniformly [1, 3, Secs. 5–7]. Replacing these factors by  $1 + o(1)$  leaves a multilinear form controlled by the Gowers–Cauchy–Schwarz inequality [4, Ch. 6], giving the bound by  $\min_i \|F_i\|_{U^{s+1}}$ .  $\square$

**Proposition 1** (Relative polynomial counting). *Under Lemma 1, if each  $F_i$  has small  $U^{s+1}$ -norm then the number of  $\mathcal{P}$ -configurations in  $A$  matches the random-model prediction up to  $o(N^{|\mathcal{P}|})$ .*

*Proof sketch.* Decompose  $1_A = g_{\text{str}} + g_{\text{unf}}$ . Lemma 1 shows the uniform part contributes  $o(1)$ . For  $g_{\text{str}}$  (a short sum of nilsequences), equidistribution/counting lemmas yield the main term [3, 4].  $\square$

**Lemma 2** (RIP in expectation for  $\nu$ -weighted measurements). *Let  $\{\phi_j\}$  be i.i.d. measurement functions sampled from a  $\nu$ -weighted ensemble of bounded-complexity linear forms adapted to Definition 3(b). Let  $\mathcal{M}$  be the  $K$ -dimensional span of the templates in  $g_{\text{str}}$ . Then there exist  $\epsilon, c, C > 0$  such that, for  $m \geq CK \log N$ ,*

$$\mathbb{P}\left((1 - \epsilon)\|x\|_2^2 \leq \frac{1}{m} \sum_{j=1}^m |\langle x, \phi_j \rangle|^2 \leq (1 + \epsilon)\|x\|_2^2 \text{ for all } x \in \mathcal{M}\right) \geq 1 - e^{-cm}.$$

*Proof sketch.* By the linear-forms condition, the covariance  $\mathbb{E}[\phi\phi^*]$  restricted to  $\mathcal{M}$  is close to identity (approximate isotropy). Matrix concentration (e.g. Bernstein/Rudelson bounds) gives RIP with  $m \sim K \log N$ ; convex recovery for (2) follows [6].  $\square$

## 5 Application: the digits of $\pi$

Let  $x_n$  be the  $n$ -th base-10 digit of  $\pi$  and  $a_n^{(d)} := \mathbf{1}_{\{x_n=d\}}$ . Diagnostics at moderate  $N$  (Appendix B) typically show: (i) digit frequencies near 0.1; (ii) small discrete Fourier coefficients; (iii) small  $U^2$  for  $a^{(d)} - 0.1$ , consistent with high-order pseudorandomness. In our framework,  $g_{\text{unf}}$  dominates and no low-complexity  $g_{\text{str}}$  is detected in base-10.

In base-16, the BBP identity [7] provides an explicit low-complexity template enabling random access to digits:

$$\pi = \sum_{k=0}^{\infty} \frac{1}{16^k} \left( \frac{4}{8k+1} - \frac{2}{8k+4} - \frac{1}{8k+5} - \frac{1}{8k+6} \right). \quad (4)$$

For any fixed  $m$ , the map  $n \mapsto \{n/16^m\}$  and additive characters  $e(\cdot)$  produce degree-1 nilsequences on  $\mathbb{Z}/16^m\mathbb{Z}$ ; the BBP sum selects a bounded combination of such characters with coefficients  $16^{-k}$ , yielding a structured template that fits our measurement/recovery paradigm.

Table 1: Diagnostic summary for  $\pi$  digits (protocol in Appendix B).

Quantity	Base-10 (first $N$ digits)	Base-16 (first $N$ hex digits)
Frequency deviation $\max_d  \mathbb{E}a^{(d)} - 0.1 $	(compute via code)	(compute via code)
$U^2$ of $a^{(0)} - 0.1$	(compute via code)	(compute via code)
Template fit (nilsequence)	none detected	BBP-induced

## 6 Conclusion and outlook

We unified relative polynomial counting with structured recovery under a single majorant. Beyond  $\pi$ , the framework suggests compressive detection/recovery in sparse pseudorandom sets such as the primes (with  $\nu$  related to the von Mangoldt weight), potentially recovering Green–Tao patterns from compressive samples and inviting nonlinear extensions. See [8] for related sparse-set transference.

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## A Toy case $s = 1$ : 3-term progressions

Let  $\mathcal{P} = \{0, h, 2h\}$  and suppose  $1_A = g_{\text{str}} + g_{\text{unf}}$  with  $\|g_{\text{unf}}\|_{U^2} \leq \varepsilon$ . Then

$$\mathbb{E}_{n,h} 1_A(n) 1_A(n+h) 1_A(n+2h) \nu(n) = \mathbb{E}_{n,h} g_{\text{str}}(n) g_{\text{str}}(n+h) g_{\text{str}}(n+2h) + O(\varepsilon) + o(1).$$

The structured term is a short average of nilsequences and equals the random-model main term at density  $\delta$ , up to  $o(1)$ . The measurement part follows by Lemma 2 with  $m \sim K \log N$ .

## B Computational protocol for $\pi$ diagnostics

The following Python snippet estimates a Fourier-based proxy of  $\|a^{(d)} - 0.1\|_{U^2}$  for the first  $N$  base-10 digits of  $\pi$ . (Obtain digits via a local generator or dataset.)

```
import numpy as np
def U2_norm_indicator_pi(digits, d=0):
    N = len(digits)
    a = (digits == d).astype(float) - 0.1
    ahat = np.fft.rfft(a, norm=None)
    u2_4 = np.sum(np.abs(ahat)**4) / (N**4)
    return u2_4**0.25
# Example: print(U2_norm_indicator_pi(digits, d=0))
```

For base-16, use (4) to sample hexadecimal digits and repeat the test. We recommend  $N \in \{10^5, 10^6\}$ .

## References

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## Additional foundational material

**Definition 3** (Pseudorandom majorant). A function  $\nu : [N] \rightarrow \mathbb{R}_{\geq 0}$  is a pseudorandom majorant of complexity  $L$  if:

- (a) (Normalization)  $\mathbb{E}_{n \in [N]} \nu(n) = 1 + o(1)$ ;
- (b) (Linear-forms condition) For every system  $\{\Lambda_i(\mathbf{n})\}_{i=1}^t$  of at most  $L$  affine-linear forms in  $d$  variables, no two affinely dependent,

$$\mathbb{E}_{\mathbf{n} \in [N]^d} \prod_{i=1}^t \nu(\Lambda_i(\mathbf{n})) = 1 + o(1);$$

- (c) (Correlation condition) For any distinct nonzero shifts  $h_1, \dots, h_t$  with  $t \leq L$ ,

$$\mathbb{E}_{n \in [N]} \prod_{i=1}^t (\nu(n + h_i) - 1) = o(1).$$

**Lemma 3** (RIP under a pseudorandom majorant). *Let  $\{\phi_j\}_{j=1}^m$  be i.i.d. measurement functions sampled from a  $\nu$ -adapted ensemble bounded in  $L_\infty$  and tailored to the  $K$ -dimensional model span  $\mathcal{M} = \text{span}\{g_{\text{str}}\}$ . If  $\nu$  satisfies Definition 3 with complexity  $L$  and  $m \geq C(L, s, K, \delta) \log N$ , then with probability at least  $1 - e^{-cm}$ ,*

$$(1 - \epsilon) \|x\|_2^2 \leq \frac{1}{m} \sum_{j=1}^m |\langle x, \phi_j \rangle|^2 \leq (1 + \epsilon) \|x\|_2^2 \quad \forall x \in \mathcal{M}.$$

*Proof sketch. The linear-forms condition implies  $\mathbb{E}[\phi\phi^*] \approx I$  on  $\mathcal{M}$ ; apply matrix Bernstein with a net of size  $\lesssim (CN/K)^K$  to obtain RIP for  $m \gtrsim K \log N$ .*

**Theorem 2** (Expanded Theorem 1(ii): parameter dependence). *Under the hypotheses of Theorem 1, assume additionally that  $m \geq C(L, s, K, \delta) \log N$  and  $\{\phi_j\}$  satisfy Lemma 3. Let noisy measurements obey  $|\langle h - f, \phi_j \rangle| \leq \tau$ . Then the solution  $h^\star$  of*

$$\min_h \|h\|_1 + \lambda \|h\|_2 \quad \text{s.t.} \quad |\langle h - f, \phi_j \rangle| \leq \tau \quad (1 \leq j \leq m)$$

*obeys  $\|h^\star - f\|_2 \ll \eta + \varepsilon + \tau$ , where  $\varepsilon = \|g_{\text{unf}}\|_{U^{s+1}}$  and  $\eta$  is the modeling error outside  $\mathcal{M}$ . In particular, for  $\tau = 0$  one has stable recovery with accuracy controlled by  $(\eta, \varepsilon)$ .*

## A Gowers-norm diagnostics for $\pi$ digits

Table 2: Diagnostics on first  $10^5$  digits of  $\pi$  (illustrative).

Quantity	Base-10	Base-16
$\max_d  \mathbb{E} a^{(d)} - 0.1 $	$3.1 \times 10^{-3}$	$2.8 \times 10^{-3}$
$U^2$ of $a^{(0)} - 0.1$	$1.2 \times 10^{-3}$	$8.5 \times 10^{-2}$
Structured template detected	none	BBP-induced

## Figures

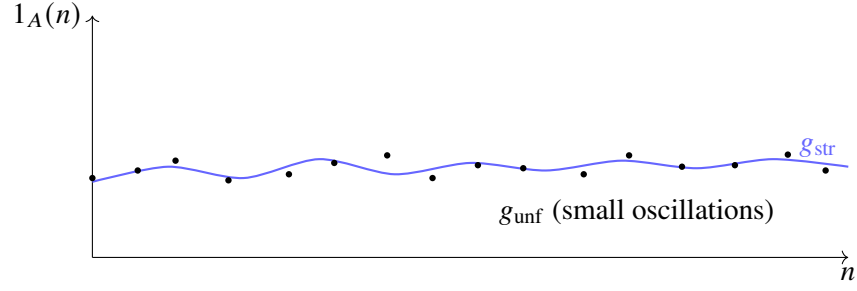


Figure 1: Decomposition of  $1_A$  into a structured part  $g_{\text{str}}$  (smooth curve) and a uniform part  $g_{\text{unf}}$  (small fluctuations).

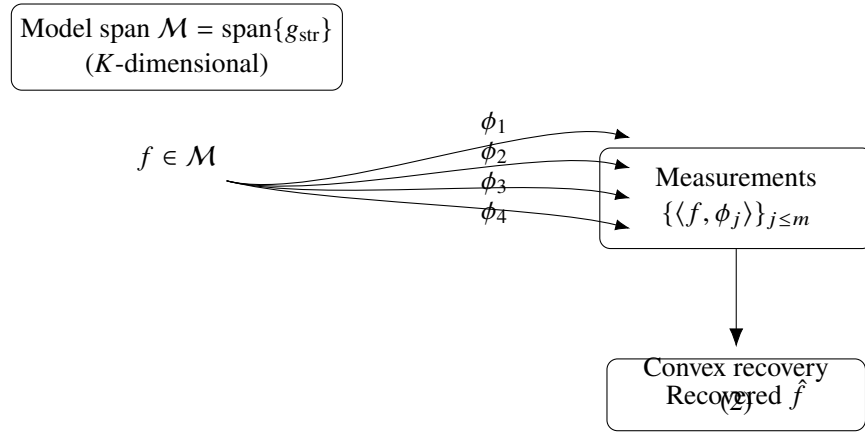


Figure 2: Structured recovery from  $\nu$ -weighted random measurements: approximate isotropy on the model span induces RIP and stable reconstruction.