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Chapter 1

Vector Spaces, Algebras, and Normed Spaces

For the entirety of this chapter assume F to be \mathbf{R} or \mathbf{C} .

§ 1.1. Vector Spaces

Definition 1.1.1. A vector space (or linear space) over F is a nonempty set V equipped with two operations:

$$V \times V \xrightarrow{+} V$$
 defined by $(v, w) \mapsto v + w$
 $F \times V \to V$ defined by $(\alpha, v) \mapsto \alpha v$

satisfying:

- (1) (V, +) is an abelian group:
 - (i) u + (v + w) = (u + v) + w for all $u, v, w \in V$;
 - (ii) there exists 0_V such that $v + 0_V = 0_V + v = v$ for all $v \in V$;
 - (iii) for all $v \in V$, there exists $w \in V$ satisfying $v + w = w + v = 0_V$;
 - (iv) v + w = w + v for all $v, w \in V$;
- (2) $\alpha(v+w) = \alpha v + \alpha w$ for all $\alpha \in F$, $v, w \in V$;
- (3) $\alpha(\beta v) = (\alpha \beta)v$ for all $\alpha, \beta \in F, v \in V$;
- (4) $1_F v = v$ for all $v \in V$.

It can be shown that the vector 0_V is unique, the additive inverse in (iii) is unique (which we denote as -v), that $0v = 0_V$, and (-1)v = -v.

Exercise 1.1.1. Show (iv) follows from the other axioms.

Exercise 1.1.2. Show
$$nv = \underbrace{v + v + ... + v}_{n \text{ times}}$$
 for $n \in \mathbb{Z}_{\geqslant 1}$.

It can be shown that a subspace is a vector space in its own right.

Example 1.1.1. Let $\{W_i\}_{i\in I}$ be a family of vector spaces. Then $\bigcap_{i\in I} W_i$ is also a vector space.

Example 1.1.2. Planes and lines through the origin are subspaces of \mathbb{R}^3 .

Definition 1.1.2. Let V be a vector space and $S \subseteq V$ a subset.

- (1) A linear combination from S is a finite sum $\sum_{j=1}^{n} \alpha_j v_j$ with $\alpha_j \in F$, $v_j \in S$.
- (2) The linear span of S is:

$$\operatorname{span}(S) := \left\{ \sum_{j=1}^{n} \alpha_{j} v_{j} \mid n \in \mathbb{N}, \alpha_{j} \in F, v_{j} \in S \right\}.$$

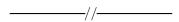
Exercise 1.1.3. Show that $span(S) \subseteq V$ is a subspace and:

$$\operatorname{span}(S) = \bigcap \{ W \mid S \subseteq W, W \text{ is a subspace } \},$$

that is, $\operatorname{span}(S)$ is the smallest subspace of V containing S.

Definition 1.1.3. Let V be a vector space and $S \subseteq V$ a subset.

- (1) S is spanning for V if span(S) = V.
- (2) S is independent if, given $n \in \mathbb{N}$, $\alpha_1, ..., \alpha_n \in F$, $v_1, ..., v_n \in S$, then $\sum_{j=1}^n \alpha_j v_j = 0$ implies $\alpha_j = 0$ for all j.



Our goal is to show that every vector space admits a basis. As such, recall the following definitions from a standard course in Real Analysis.

Definition 1.1.4. An ordering on a set X is a relation $R \subseteq X \times X$ on X that is reflexive, transitive, and antisymmetric. We write xRy as $x \leq_R y$. The pair (X, \leq_R) is called an ordered set. An ordering \leq on X is called total (or linear) if for all $x, y \in X$, $x \leq y$ or $y \leq x$.

Note that if (X, \leq) is an ordered set and $Y \subseteq X$ is a subset, then (Y, \leq) is an ordered set as well.

Definition 1.1.5. Let (X, \leq) be an ordered set and $Y \subseteq X$. An *upper bound* for Y is an element $u \in X$ with $u \geq y$ for all $y \in Y$. An element $m \in X$ is called *maximal* if $x \in X$, $x \geq m$ implies x = m.

Lemma 1.1.1 (Zorn's Lemma). Let (X, \leq_X) be an ordered set. Suppose every subset $Y \subseteq X$ for which (Y, \leq_X) is totally ordered has an upper bound in X. Then X admits a maximal element

The proof of Zorn's Lemma is outside the interest of this text.

Theorem 1.1.2. Every vector space admits a basis. Moreover, every independent set is contained in a basis.

Proof. Let $S \subseteq V$ be linearly independent. Define:

$$\mathfrak{T}(S) = \{ T \subseteq V \mid S \subseteq T, T \text{ linearly independent } \}.$$

Let $\mathfrak{C} \subseteq \mathfrak{T}(S)$ be a totally ordered subset. Set $R = \bigcup_{T \in \mathfrak{C}} T$. Clearly $R \supseteq S$. Assume $\sum_{j=1}^n \alpha_j v_j = 0$, where $\alpha_j \in F$ and $v_j \in R$. Since \mathfrak{C} is totally ordered, there exists $T_0 \in \mathfrak{C}$ with $v_j \in T_0$ for all j = 1, ..., n. Since T_0 is independent, T_0 for all T_0 is independent as well. Whence T_0 is an upper bound for T_0 . By Zorn's Lemma, T_0 admits a maximal element, call it T_0 .

Claim: B is a basis for V. Suppose towards contradiction it's not, then there exists $v_0 \in V \setminus \operatorname{span}(B)$. Consider $B \cup \{v_0\}$ and let $\alpha_0 v_0 + \sum_{j=1}^n \alpha_j v_j = 0_V$. If $\alpha_0 \neq 0$, then $\sum_{j=1}^n \alpha_j v_j = -\alpha_0 v_0$, giving $v_0 \in \operatorname{span}(B)$ which is a contradiction. If $\alpha_0 = 0$, then $\sum_{j=1}^n \alpha_j v_j = 0_V$. Since B is independent, $\alpha_j = 0$ for all j = 1, ..., n. Thus $B \cup \{v_0\}$ is independent, contradicting the maximality of B. Whence B is a basis for V.

Theorem 1.1.3. If B_1 and B_2 are bases for V, then $card(B_1) = card(B_2)$.

Definition 1.1.6. If V is a vector space, its *dimension* is the cardinality of any of its bases.

Corollary 1.1.4. If B is a basis for V, then every $v \in V$ can be written $v = \sum_{j=1}^{n} \alpha_k \beta_k$, $\alpha_k \in F$, $b_k \in B$ in a unique way.

Theorem 1.1.5. Let V be a linear space and $B \subseteq V$ a subset. The following are equivalent:

- (1) B is a basis for V;
- (2) B is a maximal element in $\mathfrak{T} = \{T \subseteq V \mid T \text{ independent}\};$
- (3) B is a minimal element in $\mathfrak{S} = \{ S \subseteq V \mid S \text{ spans } V \};$

Definition 1.1.7. Let $\{V_i\}_{i\in I}$ be a family of vector spaces over a field F.

(1) The product of $\{V_i\}_{i\in I}$ is denoted:

$$\prod_{i \in I} V_i := \{ (v_i)_{i \in I} \mid v_i \in V_i \}.$$

(2) The co-product (or sum) is denoted

$$\bigoplus_{i \in I} V_i := \left\{ (v_i)_{i \in I} \mid v_i \in V_i, \operatorname{supp}((v_i)_{i \in I}) < \infty \right\}.$$

Exercise 1.1.4.

(1) Show that $\prod_{i \in I} V_i$ equipped with pointwise operations:

$$(v_i)_{i \in I} + (w_i)_{i \in I} = (v_i + w_i)_{i \in I}$$
$$\alpha(v_i)_{i \in I} = (\alpha v_i)_{i \in I}$$

is a linear space.

(2) Show that $\bigoplus_{i \in I} V_i$ is a subspace of $\prod_{i \in I} V_i$.

Proposition 1.1.6. Let V be a vector space over F and $W \subseteq V$. The (additive, abelian) quotient group V/W can be made into a vector space by defining multiplication by scalars as $\alpha(v+W) = \alpha v + W$ for all $\alpha \in F$, $v+W \in V/W$.

Example 1.1.3.

- (1) The set $F^n = \{(x_1, ..., x_n) \mid x_j \in F\}$ with component-wise operations is a vector space.
- (2) The set $M_{n,m}(F) = \{(a_{ij}) \mid a_{ij} \in F\}$ with linear operations is a vector space.
- (3) Let Ω be a nonempty set. Then $\mathcal{F}(\Omega, F) = \{f \mid f : \Omega \to F\}$ with pointwise operations is a vector space.
- (4) The set $\ell_{\infty}(\Omega, F) = \{ f \in \mathcal{F}(\Omega, F) \mid ||f||_{u} < \infty \}$ with pointwise operations is a vector space.

Exercise 1.1.5. Show $\ell_{\infty}(\Omega, F) \subseteq \mathcal{F}(\Omega, F)$ is a subspace.

(5) Let $f : [a, b] \to \mathbf{R}$ be any function. Let $\mathcal{P} = \{a = x_0 < x_1 < ... < x_{n-1} < x_n = b\}$ be a partition of [a, b]. The variation of f on \mathcal{P} is defined as:

$$Var(f; \mathcal{P}) = \sum_{k=1}^{n} |f(x_k) - f(x_{k-1})|.$$

We say f is a bounded variation if:

$$\operatorname{Var}(f) := \sup_{\mathcal{P}} \operatorname{Var}(f; \mathcal{P}) < \infty.$$

The set of all functions of bounded variation is defined:

$$BV([a,b]) = \{ f : [a,b] \to \mathbf{R} \mid Var(f) < \infty \}.$$

This is a vector space by defining addition and scalar multiplication componentwise.

Exercise 1.1.6. Show that $BV([a,b]) \subseteq \ell_{\infty}([a,b], \mathbf{R})$ is a subspace.

(6) Let $K \subseteq V$ be a convex subset of a vector space V, that is, for all $v, w \in K$ and $t \in [0,1]$, then $(1-t)v+tw \in K$. A function $f: K \to F$ is said to be affine if $x, y \in K$ and $t \in [0,1]$ implies f((1-t)x+ty)=(1-t)f(x)+tf(y). The set $Aff(K,F)=\{f \in \mathcal{F}(\Omega,F) \mid f \text{ affine}\}\$ with pointwise operations is a vector space.

Exercise 1.1.7. Show $Aff(\Omega, F) \subseteq \mathcal{F}(\Omega, F)$ is a subspace.

(7) The set $C([a,b],F)=\{f:[a,b]\to F\mid f \text{ continuous}\}$ with pointwise operations is a vector space.

Exercise 1.1.8. Explain why $C([a,b],F) \subseteq \ell_{\infty}([a,b],F)$ is a subspace.

- (8) Consider the following sequence spaces:
 - $s = \{(a_k)_k \mid a_k \in F\} = \mathcal{F}(\mathbf{N}, F);$
 - $\ell_{\infty} = \ell_{\infty}(\mathbf{N}, F) = \{(a_k)_k \mid \sup_{k \geqslant 1} |a_k| < \infty\};$
 - $c = \{(a_k)_k \mid (a_k)_k \text{ converges }\};$
 - $c_0 = \{(a_k)_k \mid (a_k)_k \to 0\};$
 - $c_{00} = \{(a_k)_k \mid \text{supp}((a_k)_k) < \infty\};$
 - $\ell_1 = \{(a_k)_k \mid \sum_{k=1}^{\infty} |a_k| < \infty\}.$

These are all vector spaces with pointwise operations. In fact, $c_{00} \subseteq c_0 \subseteq c \subseteq \ell_{\infty} \subseteq s$ are all subspaces.

Exercise 1.1.9. Show that $\ell_1 \subseteq c_0$ is a subspace.

- (9) Consider the following continuous function spaces on R:
 - $C(\mathbf{R}) = \{ f : \mathbf{R} \to F \mid f \text{ continuous } \};$
 - $C_b(\mathbf{R}) = C(\mathbf{R}) \cap \ell_\infty(\mathbf{R});$
 - $C_0(\mathbf{R}) = \{ f \in C(\mathbf{R}) \mid \lim_{x \to \pm \infty} f(x) = 0 \};$
 - Recall that a function is *compactly supported* if for all $\epsilon > 0$, there exists $\alpha > 0$ such that $|x| \ge \alpha$ implies f(x) = 0. The set of compactly supported functions is denoted $C_c(\mathbf{R}) = \{ f \in C(\mathbf{R}) \mid f \text{ compactly supported } \}$.

These are all vector spaces with pointwise operations, and $C_c(\mathbf{R}) \subseteq C_0(\mathbf{R}) \subseteq C_b(\mathbf{R}) \subseteq C(\mathbf{R})$ are all subspace inclusion.

Definition 1.1.8. If V and W are linear spaces over a common field F, a map $T: V \to W$ is called *linear* if $T(v_1 + \alpha v_2) = T(v_1) + \alpha T(v_2)$ for all $v_1, v_2 \in V$ and $\alpha \in F$.

Example 1.1.4. Let $A \in M_{m,n}(F)$. Then $T_A : F^n \to F^m$ defined by $T_A(v) = Av$ is linear. Let $\{e_1, ..., e_n\}$ be a basis for F^n . If $T : F^n \to F^m$ is linear, set:

$$[T] = \Big(T(e_1) \mid T(e_2) \mid \dots \mid T(e_n)\Big).$$

This gives T(v) = [T]v for all $v \in F^n$. In fact, we also have $[T_A] = A$ and $T_{[T]} = T$.

Example 1.1.5. The canonical projection is linear:

$$\pi_j: \prod_{i \in I} V_i \to V_j$$
 defined by $\pi_j \big((v_i)_i \big) = v_i$.

We also have that the *coordinate exclusions* are linear:

$$\iota_j: V_j \hookrightarrow \bigoplus_{i \in I} V_i$$
 defined by $\iota_j(v) = (v_i)_i$, where $v_i = \begin{cases} 0_v, & i \neq j \\ v_j, & \text{otherwise.} \end{cases}$

The evaluation map is linear as well. For $s \in S$, consider:

$$e_s: \mathcal{F}(S, F) \to F$$
 defined by $e_s(f) = f(s)$.

Proposition 1.1.7. Let V be a vector space with basis B. Let W be a vector space and suppose $\varphi: B \to W$ is a map. Then there exists a unique linear map $T_{\varphi}: V \to W$ with $T_{\varphi}(b) = \varphi(b)$ for all $b \in B$. We have the following diagram.

$$B \xrightarrow{\iota} V$$

$$V$$

$$W$$

Proof. Define $T_{\varphi}: V \to W$ by:

$$T_{\varphi}(v) = T_{\varphi} \left(\sum_{j=1}^{n} \alpha_{j} b_{j} \right)$$
$$= \sum_{j=1}^{n} \alpha_{j} \varphi(b_{j}).$$

Let $v_1, v_2 \in V$ and $c \in F$. We have that:

$$T_{\varphi}(v_1 + cv_2) = T_{\varphi} \left(\sum_{j=1}^n \alpha_j b_j + c \sum_{j=1}^n \beta_j b_j \right)$$

$$= T_{\varphi} \left(\sum_{j=1}^n (\alpha_j + c\beta_j) b_j \right)$$

$$= \sum_{j=1}^n (\alpha_j + c\beta_j) \varphi(b_j)$$

$$= \sum_{j=1}^n \alpha_j \varphi(b_j) + c \sum_{j=1}^n \beta_j \varphi(b_j)$$

$$= T_{\varphi}(v_1) + c T_{\varphi}(v_2).$$

Thus T_{φ} is linear. Chasing the above diagram makes it clear that $T_{\varphi}(b) = \varphi(b)$. It remains to show that T_{φ} is unique. Let T be another linear transformation satisfying $T(b) = \varphi(b)$ for all $b \in B$. Then:

$$T(v) = T\left(\sum_{j=1}^{n} \alpha_j b_j\right)$$
$$= \sum_{j=1}^{n} \alpha_j \varphi(b_j)$$
$$= T_{\varphi}\left(\sum_{j=1}^{n} \alpha_j b_j\right)$$
$$= T_{\varphi}(v).$$

Thus T_{φ} is unique.

Proposition 1.1.8. Let $T: V \to W$ be linear.

- (1) $\ker(T) = \{v \in V \mid T(v) = 0_W\}$ is a linear subspace of V.
- (2) $\operatorname{im}(T) = \{T(v) \mid v \in V\}$ is a linear subspace of W.
- (3) $ker(T) = \{0_V\}$ if and only if T is injective.
- (4) im(T) = W if and only if T is surjective.

Proof. (1) Let $v_1, v_2 \in \ker(T)$ and $\alpha \in F$. Observe that:

$$T(v_1 + cv_2) = T(v_1) + cT(v_2)$$

= 0.

Thus $v_1 + cv_2 \in \ker(T)$, giving $\ker(T)$ as a linear subspace of V.

(2) Let $w_1, w_2 \in \text{im}(T)$. Then there exists $v_1.v_2 \in V$ with $T(v_1) = w_1$ and $T(v_2) = w_2$. We have:

$$w_1 + cw_2 = T(v_1) + cT(v_2)$$

= $T(v_1 + cv_2)$.

Whence $w_1 + cw_2 \in \text{im}(T)$, giving im(T) as a linear subspace of W.

- (3) Let $\ker(T) = \{0\}$. Suppose $T(v_1) = T(v_2)$. Then $T(v_1) T(v_2) = T(v_1 v_2) = 0_W$. It must be that $v_1 v_2 = 0_W$, giving $v_1 = v_2$. Thus T is injective. Conversely, suppose T is injective and let $v \in \ker(T)$. Then $T(v) = 0_W = T(0_V)$. Hence $v = 0_V$, establishing $\ker(T) = \{0\}$.
 - (4) This is by definition of surjectivity.

Proposition 1.1.9. If $T: V \to W$ is linear and bijective, then the inverse map $T^{-1}: W \to V$ is linear.

Proof. We have that:

$$T(T^{-1}(w_1) + \alpha T^{-1}(w_2)) = w_1 + \alpha w_2 = T \circ T^{-1}(w_1 + \alpha w_2).$$

Applying T^{-1} to both sides gives the desired result.

Proposition 1.1.10 (Vector Spaces are Injective). Let U, V, W be vector spaces and $0 \to U \xrightarrow{j} V$ be exact (that is, j is injective). Let $\varphi : U \to W$ be linear. There exists a linear map $\Psi : V \to W$ such that $\varphi = \Psi \circ j$; i.e., the following diagram commutes:

Proof. Let $\{u_i\}_{i\in I}$ be a basis for U. We must first show that $\{j(u_i)\}_{i\in I}$ is linearly independent. Notice that:

$$0_V = \sum_{i \in I} \alpha_i j(u_i)$$
$$= j \left(\sum_{i \in I} \alpha_i u_i \right).$$

By the injectivity of j, we have that $\sum_{i \in I} \alpha_i u_i = 0_U$. Thus $\alpha_i = 0$ for all $i \in I$, giving $\{j(u_i)\}_{i \in I}$ as linearly independent.

Since $\{j(u_i)\}_{i\in I}$ is linearly independent in V, we can extend it to a basis $B=\{v_i\}_{i\in J}$ where $I\subseteq J$ and $v_i=j(u_i)$ whenever $i\in I$. Now define $\psi:B\to W$ by:

$$\psi(v_i) = \begin{cases} \varphi(u_i), & i \in I \\ w, & i \in J \setminus I \end{cases}$$

where $w \in W$ is arbitrary. Since this is a map of basis elements, there exists a unique linear map $\Psi: V \to W$ with $\Psi(v_i) = \psi(v_i)$ for all $v_i \in B$. We can finally see that:

$$\varphi(u_i) = \psi(v_i)$$

$$= \Psi(v_i)$$

$$= \Psi(j(u_i)).$$

This establishes that $\varphi = \Psi \circ j$.

Proposition 1.1.11 (Vector Spaces are Projective). Let U, V, W be vector spaces and $V \xrightarrow{\pi} U \to 0$ be exact (that is, π is onto). Let $\varphi : W \to U$ be linear. There exists a linear map $\Psi : V \to W$ such that $\varphi = \pi \circ \Psi$; i.e., the following diagram commutes:

$$V \xrightarrow{\Psi} V \xrightarrow{\pi} U \longrightarrow 0$$

Proof. Let $B = \{w_i\}_{i \in I}$ be a basis for W. Define $\psi : B \to V$ by $\psi(w_i) = \pi^{-1}(\varphi(w_i))$. Since this is a map of basis elements, it extends to a unique (dependent on π^{-1}) linear map $\Psi : W \to V$ with $\Psi(w_i) = \psi(w_i)$ for all $w_i \in B$. Moreover, we have that:

$$(\pi \circ \Psi)(w_i) = (\pi \circ \psi)(w_i)$$

$$= (\pi \circ (\pi^{-1} \circ \varphi))(w_i)$$

$$= \varphi(w_i).$$

Definition 1.1.9. Let V and W be vector spaces over F. A linear isomorphism between V and W is a bijective linear map $T:V\to W$. If such a T exists, we say V and W are linearly isomorphic, and write $V\cong W$.

Finite dimensional vector spaces are boring. This is illustrated through the following theorem.

Theorem 1.1.12. Let V and W be finite-dimensional vector spaces over F. Then $V \cong W$ if and only if $\dim(V) = \dim(W)$.

Proof. Suppose $V \cong W$. Then there is an isomorphism taking basis of V to a basis of W. Therefore they have the same dimension.

Conversely, if $\dim(V) = \dim(W) = n$, then they are each isomorphic to F^n , giving that they are isomorphic to each other.

Example 1.1.6. Let V be a vector space, $W \subseteq V$ a subspace. The natural projection:

$$\pi: V \to V/W$$
 defined by $\pi(v) = v + W$

is a linear surjective map.

Theorem 1.1.13 (First Isomorphism Theorem for Vector Spaces). Let $T: V \to V'$ be a linear map and $W \subseteq V$ a subspace.

(1) If T "kills" W (that is, $W \subseteq \ker(T)$), then there exists a linear map $\widetilde{T}: V/W \to V'$ with $\widetilde{T} \circ \pi = T$; i.e., the following diagram commutes.

$$V \xrightarrow{T} V'$$

$$\pi \qquad \qquad V/W$$

- (2) If ker(T) = W, then \widetilde{T} is injective.
- (3) If ker(T) = W and im(T) = V', then $V/W \cong V'$.

Proof. (1) As stipulated, define $\widetilde{T}(v+W)=T(v)$. We must show that \widetilde{T} is well-defined: suppose $v_1+W=v_2+W$ for some $v_1,v_2\in V$. Then $v_1=v_2+w$ for some $w\in W$. This gives:

$$\widetilde{T}(v_1 + W) = \widetilde{T}(v_2 + w + W)$$

= $\widetilde{T}(v_2 + W)$.

Whence \widetilde{T} is well-defined. Now given $v_1 + W, v_2 + W \in V/W$ and $\alpha \in F$, observe that:

$$\widetilde{T}((v_1 + W) + c(v_2 + W)) = \widetilde{T}((v_1 + cv_2) + W)$$

= $T(v_1 + cv_2)$
= $T(v_1) + cT(v_2)$
= $\widetilde{T}(v_1 + W) + c\widetilde{T}(v_2 + W)$.

Thus \widetilde{T} is linear.

(2) If ker(T) = W, then:

$$\begin{aligned} \ker(\widetilde{T}) &= \{ v + W \mid \widetilde{T}(v + W) = 0_{V'} \} \\ &= \{ v + W \mid T(v) = 0_{V'} \} \\ &= \{ v + W \mid v \in \ker(T) \} \\ &= \{ v + W \mid v \in W \} \\ &= \{ 0 \}. \end{aligned}$$

Thus \widetilde{T} is injective.

(3) It remains to show that $\operatorname{im}(T) = V'$ implies \widetilde{T} is surjective. Observe that:

$$\begin{split} \operatorname{im}(\widetilde{T}) &= \{\widetilde{T}(v+W) \mid v+W \in V/W\} \\ &= \{\widetilde{T}(\pi(v)) \mid v \in V\} \\ &= \{T(v) \mid v \in V\} \\ &= \operatorname{im}(T) \\ &= V'. \end{split}$$

Thus \widetilde{T} is surjective, which establishes it as a bijection. This gives $V/W \cong V'$.

Definition 1.1.10. Let S be a nonempty set. The free vector space of S is:

$$\mathbf{F}(S) = \{ f : S \to F \mid \text{supp}(f) < \infty \}.$$

Exercise 1.1.10. Show $\mathbf{F}(S) \subseteq \mathcal{F}(S,F)$ is a subspace.

Proposition 1.1.14. The set $\{\delta_s \mid s \in S\}$ is a basis for $\mathbf{F}(S)$, where $\delta_s : S \to F$ is defined by:

$$\delta_s(t) = \begin{cases} 1, & t = 0 \\ 0, & otherwise. \end{cases}$$

Proof. If
$$f \in \mathbf{F}(S)$$
 with $\text{supp}(f) = \{s_1, ..., s_n\}$, then $f = \sum_{k=1}^n f(s_k) \delta_{s_k}$. If $\sum_{k=1}^n \alpha_k \delta_{s_k} = 0$, then for $j = 1, ..., n$ we have $0 = (\sum_{k=1}^n \alpha_k \delta_{s_k}) (s_j) = \alpha_j$.

Theorem 1.1.15. Given any vector space V and a map (of sets) $\varphi: S \to V$, there exists a unique linear map $T_{\varphi}: \mathbf{F}(S) \to V$ with $T_{\varphi} \circ \iota = \varphi$, where $\iota: S \to \mathbf{F}(S)$ is defined by $\iota(s) = \delta_s$ for all $s \in S$. The following diagram commutes:

$$S \xrightarrow{\iota} \mathbf{F}(S)$$

$$\downarrow^{T_{\varphi}}$$

$$V$$

Proof. By the previous proposition, we have that $B = \{\delta_s \mid s \in S\}$ is a basis for $\mathbf{F}(S)$. Define $T: B \to V$ by $T(\delta_s) = \varphi(s)$. Since this is a map of basis elements, there exists

a unique linear map $T_{\varphi}: \mathbf{F}(S) \to V$ with $T_{\varphi}(\delta_s) = T(\delta_s)$ for all $\delta_s \in B$. The diagram commutes because:

$$\varphi(s) = T(\delta_s)$$

$$= T_{\varphi}(\delta_s)$$

$$= T_{\varphi}(\iota(s)).$$

Moreover, if T' satisfies $\varphi = T' \circ \iota$, then:

$$T'(\delta_s) = T'(\iota(s))$$

$$= \varphi(s)$$

$$= T_{\varphi}(\iota(s))$$

$$= T_{\varphi}(\delta_s).$$

Thus T_{φ} is unique.

Definition 1.1.11. Let V and W be vector spaces. The set of linear transformations between V and W is $\mathcal{L}(V,W) = \{T \mid T : V \to W \text{ linear } \}$. The set of linear functionals is $V' := \mathcal{L}(V,F)$.

Exercise 1.1.11. Show $\mathcal{L}(V, W)$ is a vector space.

Exercise 1.1.12. Show $M_{m,n}(F) \cong \mathcal{L}(F^m, F^n)$ by $a \mapsto T_a : (v \mapsto av)$.

§ 1.2. Algebras

Definition 1.2.1. An algebra over F is a linear space A over F equipped with a multiplication operation:

$$A \times A \to A$$
 defined by $(a, b) \mapsto ab$

satisfying:

- (1) (ab)c = a(bc) for all $a, b, c \in A$;
- (2) $(\alpha a)b = \alpha(ab) = a(\alpha b)$ for all $a, b \in A, \alpha \in F$;
- (3) a(b+c) = ab + ac for all $a, b, c \in A$;
- (4) (a+b)c = ac + bc for all $a, b, c \in A$.

If ab = ba for all $a, b \in A$ we say that A is *commutative*. If there exists $1_A \in A$ with $1_A a = a 1_A = a$ for all $a \in A$ we say A is *unital*.

Example 1.2.1.

- (1) $M_n(F)$ is a noncommutative unital algebra over F under the usual matrix multiplication.
- (2) If V is a vector space over F, $\mathcal{L}(V)$ is a unital algebra over F. It is noncommutative provided $\dim(V) > 1$.
- (3) $\mathcal{F}(S,F)$ is a unital commutative algebra over F.

Definition 1.2.2. Let B be a (unital) algebra over F.

- (1) A (unital) subalgebra of B is a subspace $A \subseteq B$ ($1_B \in A$) satisfying the property that if $a, a' \in A$, then $aa' \in A$.
- (2) An *ideal* of B is a subspace $I \subseteq B$ with $b \in B$, $a \in I$ implying $ba, ab \in I$.

Example 1.2.2.

- (1) $\ell_{\infty}(\Omega, F) \subseteq \mathcal{F}(\Omega, F)$ is a unital subalgebra.
- (2) $c_{00} \subseteq c_0 \subseteq c \subseteq \ell_{\infty} \subseteq s$ are all subalgebras. In particular, $c_0 \subseteq \ell_{\infty}$ and $c_{00} \subseteq s$ are ideals.
- (3) $C([a,b]) \subseteq \ell_{\infty}([a,b])$ is a unital subalgebra.
- (4) $C_c(\mathbf{R}) \subseteq C_0(\mathbf{R}) \subseteq C_b(\mathbf{R}) \subseteq \ell_\infty(\mathbf{R})$ are all subalgebras. In fact, $C_b(\mathbf{R}) \subseteq C(\mathbf{R})$ and $C_b(\mathbf{R}) \subseteq \ell_\infty(\mathbf{R})$ are unital, whereas $C_0(\mathbf{R}) \subseteq C_b(\mathbf{R})$ and $C_c(\mathbf{R}) \subseteq C(\mathbf{R})$ are ideals.
- (5) The set $T_n(F) = \{(a_{ij}) \in M_n(F) \mid a_{ij} = 0, i > j\}$ is a unital subalgebra of $M_n(F)$.

Example 1.2.3 (Group Algebra). Let Γ denote a group (not necessarily abelian). Take the free vector space $\mathbf{F}(\Gamma)$ and define multiplication as *convolution*: given $f, g \in \mathbf{F}(\Gamma)$ let:

$$(f * g)(r) = \sum_{\substack{\{(s,t) \mid s \in \text{supp}(f), \\ t \in \text{supp}(g), \\ st = r\}}} f(s)g(t).$$

Since $\operatorname{supp}(f)$ and $\operatorname{supp}(g)$ are finite, this is a finite sum. We often suppress this notation and write $(f*g)(r) = \sum_{st=r} f(s)g(t)$.

We can also make substitutions:

$$\begin{split} (f*g)(r) &= \sum_{st=r} f(s)g(t) \\ &= \sum_{t \in \Gamma} f(rt^{-1})g(t) \\ &= \sum_{s \in \Gamma} f(s)g(s^{-1}r). \end{split}$$

It is clear that:

$$(f+g)*h = f*h+g*h$$
$$g*(g+h) = f*g+f*h$$
$$\alpha(f*g) = (\alpha f)*g = f*(\alpha g)$$

for $f, g, h \in \mathbf{F}(\Gamma)$, $\alpha \in F$. Associativity can be similarly shown using the above definition. Rather, we will prove associativity by first show that $\delta_s * \delta_t = \delta_{st}$. Given:

$$(\delta_s * \delta_t)(r) = \sum_{q \in \Gamma} \delta_s(rq^{-1})\delta_t(q),$$

notice that:

$$\delta_s(rt^{-1}) = \begin{cases} 1, & s = rt^{-1} \\ 0, & \text{otherwise} \end{cases} = \begin{cases} 1, & r = st \\ 0, & \text{otherwise} \end{cases} = \delta_{st}(r).$$

Since $\{\delta_t \mid t \in \Gamma\}$ is a basis for $\mathbf{F}(\Gamma)$, every $f \in \mathbf{F}(\Gamma)$ looks like:

$$f = \sum_{t \in I} \alpha_t \delta_t, \ J \subseteq T$$
 finite.

Using distributivity we get:

$$\begin{split} \delta_r * (\delta_s * \delta_t) &= \delta_r * \delta_{st} \\ &= \delta_{rst} \\ &= \delta_{rs} * \delta_t \\ &= (\delta_r * \delta_s) * \delta_t. \end{split}$$

Whence convolution is associative.

Exercise 1.2.1. Let $\{A_i\}_{i\in I}$ be a family of algebras over F.

- (1) $\prod_{i \in I} A_i$ is an algebra under $(a_i)_i(b_i)_i = (a_i b_i)_i$.
- (2) $\bigoplus_{i \in I} A_i \subseteq \prod_{i \in I} A_i$ is an ideal.

Exercise 1.2.2. Let A be an algebra over F and $I \subseteq A$ an ideal. Then A/I is an algebra under (a+I)(b+I) = ab+I.

§ 1.3. Normed Vector Spaces

To each vector v in a vector space V, we want to assign a "length", denoted ||v||.

Definition 1.3.1. A *norm* on a vector space V is a map:

$$\|\cdot\|: V \to [0,\infty), \ v \mapsto \|v\|$$

satisfying:

- (1) $\|\alpha v\| = |\alpha| \|v\|$ for all $\alpha \in F$, $v \in V$ (homogeneity);
- (2) $||v+w|| \leq ||v|| + ||w||$ (triangle inequality);
- (3) If ||v|| = 0, then $v = 0_V$ (positive-definite).

If $\|\cdot\|$ satisfies (1) and (2), it is called a *seminorm*. The pair $(V, \|\cdot\|)$ is called a *normed space*.

Definition 1.3.2. Two norms $\|\cdot\|$ and $\|\cdot\|'$ on a vector space V are called *equivalent* if there exists $c_1 \ge 0$ and $c_2 \ge 0$ with $\|v\| \le c_1 \|v\|'$ and $\|v\|' \le c_2 \|v\|$ for all $v \in V$.

Exercise 1.3.1. If p is a seminorm on V, show that $|p(v) - p(w)| \leq p(v - w)$.

Definition 1.3.3. Let (V, ||v||) be a normed space.

(1) The closed unit ball is denoted $B_V = \{v \in V \mid ||v|| \le 1\}.$

- (2) The open unit ball is denoted $U_V = \{v \in V \mid ||v|| < 1\}.$
- (3) The unit sphere is denoted $S_V = \{v \in V \mid ||v|| = 1\}.$

Example 1.3.1. Let $V = F^n$ and $x = (x_1, ..., x_n)$. We define:

$$||x||_1 = \sum_{j=1}^n |x_j|;$$

$$||x||_{\infty} = \max_{j=1}^n |x_j|;$$

$$||x||_2 = \left(\sum_{j=1}^n |x_j|^2\right)^{\frac{1}{2}}.$$

For $p \geqslant 1$:

$$||x||_p = \left(\sum_{j=1}^n |x_j|^p\right)^{\frac{1}{p}}.$$

Exercise 1.3.2. Show that $\|\cdot\|_1$ and $\|\cdot\|_{\infty}$ are norms

We aim to show that $\|\cdot\|_p$ is a norm for $p \in [0, \infty]$.

Lemma 1.3.1. Let $p, q \in [1, \infty]$ with $\frac{1}{p} + \frac{1}{q} = 1$. Let $f : [0, \infty) \to \mathbf{R}$ be defined by $f(t) = \frac{1}{p}t^p - t + \frac{1}{q}$. Then $f(t) \ge 0$ for $t \ge 0$.

Proof. Note that $f'(t) = t^{p-1} - 1$. Since:

$$f'(1) = 0$$

 $f'(t) > 0$ for $t > 1$
 $f'(t) < 0$ for $0 \le t < 1$,

we can see that $f(t) \ge 0$ for all $t \ge 0$.

Lemma 1.3.2 (Young's Inequality). Let $p,q \in [0,\infty]$ with $\frac{1}{p} + \frac{1}{q} = 1$. If $x,y \ge 0$, then $xy \le \frac{1}{p}x^p + \frac{1}{q}y^q$.

Proof. By Lemma 1.3.1, $t \leq \frac{1}{p}t^p + \frac{1}{q}$. Multiplying both sides by y^q gives:

$$ty^q \leqslant \frac{1}{p}t^p y^q + \frac{1}{q}y^q.$$

Let $t = xy^{1-q}$. Then:

$$xy^{1-q}y^{q} \leqslant \frac{1}{p}x^{p}y^{p-pq}y^{q} + \frac{1}{q}y^{q}.$$

Since $\frac{1}{p} + \frac{1}{q} = 1$, we have that p - pq = -q. Whence:

$$xy \leqslant \frac{1}{p}x^p + \frac{1}{q}y^q.$$

Lemma 1.3.3 (Hölders Inequality). Let $p, q \in [0, \infty]$ with $\frac{1}{p} + \frac{1}{q} = 1$. Then for $x, y \in F^n$:

$$\left| \sum_{j=1}^{n} x_j y_j \right| \leqslant ||x||_p ||y||_q.$$

Proof. We proceed by cases.

Case 1: p = 1. Then:

$$\left| \sum_{j=1}^{n} x_j y_j \right| \leqslant \sum_{j=1}^{n} |x_j| |y_j|$$

$$\leqslant \sum_{j=1}^{n} |x_j| ||y||_{\infty}$$

$$= ||x||_1 ||y||_{\infty}.$$

Case 2: $p = \infty$. This follows similarly to Case 1.

Case 3: $1 . Suppose <math>||x||_p = ||y||_q = 1$. Then:

$$\left| \sum_{j=1}^{n} x_{j} y_{j} \right| \leq \sum_{j=1}^{n} |x_{j}| |y_{j}|$$

$$\leq \sum_{j=1}^{n} \left(\frac{1}{p} |x_{j}|^{p} + \frac{1}{q} |y_{j}|^{q} \right)$$

$$= \frac{1}{p} \left(\sum_{j=1}^{n} |x_{j}|^{p} \right) + \frac{1}{q} \left(\sum_{j=1}^{n} |y_{j}|^{q} \right)$$

$$= \frac{1}{p} + \frac{1}{q}$$

$$= 1.$$

Whence the inequality holds. Now suppose $||x||_p = 0$ or $||y||_q = 0$. Then $x = 0_{F^n}$ or $y = 0_{F^n}$, whence the inequality holds. Suppose $||x||_p \neq 0$ and $||y||_p \neq 0$. Set:

$$x' = \frac{x}{\|x\|_p}$$
$$y' = \frac{y}{\|y\|_p}.$$

Then $||x'||_p = 1 = ||y'||_p$. Observe that:

$$1 \geqslant \left| \sum_{j=1}^{n} x_j' y_j' \right|$$
$$= \left| \sum_{j=1}^{n} \frac{x}{\|x\|_p} \frac{y}{\|y\|_p} \right|.$$

Multiplying both sides by $||x||_p ||y||_q$ gives the desired result.

Lemma 1.3.4 (Minkowski's Inequality). Let $p, q \in [1, \infty]$ with $\frac{1}{p} + \frac{1}{q} = 1$. For $x, y \in F^n$:

$$||x+y||_p \le ||x||_p + ||y||_p.$$

Proof. The only nontrivial case is for 1 . Observe that:

$$\begin{split} (\|x+y\|_p)^p &= \sum_{j=1}^n |x_j + y_j|^p \\ &= \sum_{j=1}^n |x_j + y_j| |x_j + y_j|^{p-1} \\ &\leq \sum_{j=1}^n |x_j| |x_j + y_j|^{p-1} + |y_j| |x_j + y_j|^{p-1} \\ &\leq \left(\sum_{j=1}^n |x_j|^p\right)^{\frac{1}{p}} \left(\sum_{j=1}^n |x_j + y_j|^{(p-1)q}\right)^{\frac{1}{q}} + \left(\sum_{j=1}^n |y_j|^p\right)^{\frac{1}{p}} \left(\sum_{j=1}^n |x_j + y_j|^{(p-1)q}\right)^{\frac{1}{q}} \\ &= \left(\sum_{j=1}^n |x_j|^p\right)^{\frac{1}{p}} \left(\sum_{j=1}^n |x_j + y_j|^{p-1\left(\frac{p}{p-1}\right)}\right)^{1-\frac{1}{p}} + \left(\sum_{j=1}^n |y_j|^p\right)^{\frac{1}{p}} \left(\sum_{j=1}^n |x_j + y_j|^{p-1\left(\frac{p}{p-1}\right)}\right)^{1-\frac{1}{p}} \\ &= \left(\sum_{j=1}^n |x_j|^p\right)^{\frac{1}{p}} \left(\sum_{j=1}^n |x_j + y_j|^p\right)^{1-\frac{1}{p}} + \left(\sum_{j=1}^n |y_j|^p\right)^{\frac{1}{p}} \left(\sum_{j=1}^n |x_j + y_j|^p\right)^{1-\frac{1}{p}} \\ &= (\|x\|_p + \|y\|_p) \frac{\|x + y\|_p}{\|x + y\|_p}. \end{split}$$

Multiplying boths sides by $\frac{\|x+y\|_p}{\|x+y\|_p^p}$ gives the desired inequality.

Theorem 1.3.5. Let $V = F^n$. Then $(F^n, \|\cdot\|_p)$ is a normed space.

Proof. Let $x = (x_1, ..., x_n) \in F^n$ and $\alpha \in F$. Observe that:

$$\|\alpha x\|_p = \left(\sum_{j=1}^n |\alpha x_j|^p\right)^{\frac{1}{p}}$$
$$= \left(\sum_{j=1}^n |\alpha|^p |x_j|^p\right)^{\frac{1}{p}}$$
$$= |\alpha| \|x\|_p.$$

This satisfies homogeneity. Moreover, Minkowski's Inequality satisfies the triangle inequality. It remains to show that $\|\cdot\|_p$ is positive-definite. If $\|x\|_p = 0$, then $x_j = 0$ for all $1 \le j \le n$. Thus $x = 0_{F^n}$.

Corollary 1.3.6. Let $p \in [1, \infty]$. Then $\ell_p = \{(a_k)_k \mid \sum_{k=1}^{\infty} |a_k|^p < \infty\}$ with norm $\|(a_k)_k\|_p = (\sum_{k=1}^{\infty} |a_k|^p)^{\frac{1}{p}}$ is a normed space.

Proof. Homogeneity and positive-definiteness are trivial to prove. Let $(x_k)_k, (y_k)_k \in \ell_p$. It is clear that:

$$\left(\sum_{k=1}^{n} |x_k + y_k|^p\right)^{\frac{1}{p}} \leqslant \left(\sum_{k=1}^{n} |x_k|^p\right)^{\frac{1}{p}} + \left(\sum_{k=1}^{n} |y_k|^p\right)^{\frac{1}{p}}$$

$$\leqslant \left(\sum_{k=1}^{\infty} |x_k|^p\right)^{\frac{1}{p}} + \left(\sum_{k=1}^{\infty} |y_k|^p\right)^{\frac{1}{p}}$$

$$= \|(x_k)_k\|_p + \|(y_k)_k\|_p.$$

We have that $\sum_{k=1}^{n} |x_k + y_k|^p$ is increasing and bounded above by $(\|(x_k)_k\|_p + \|(y_k)_k\|_p)^p$. By the Monotone Convergence Theorem $\lim_{n\to\infty} \sum_{k=1}^{n} |x_k + y_k|^p = \sum_{k=1}^{\infty} |x_k + y_k|^p$ exists. Whence $(\sum_{k=1}^{\infty} |x_k + y_k|^p)^{\frac{1}{p}} = \|(x_k)_k + (y_k)_k\|_p \leq \|(x_k)_k\|_p + \|(y_k)_k\|_p$

Example 1.3.2.

- (1) $(\ell_{\infty}(\Omega, F), \|\cdot\|_u)$ where $\|f\|_u = \sup_{x \in \Omega} |f(x)|$ is a normed space. This includes its subspaces, such as $C([a, b], F) \subseteq \ell_{\infty}([a, b], F)$ and $C_c(\mathbf{R}) \subseteq C_0(\mathbf{R}) \subseteq \ell_{\infty}(\mathbf{R})$, all with $\|\cdot\|_u$.
- (2) Take $\Omega = \mathbf{N}$ in the previous example. Then $(\ell_{\infty}, \|\cdot\|_{\infty})$ is a normed space. This includes its subspaces $c_{00} \subseteq c_0 \subseteq \ell_{\infty}$ with $\|\cdot\|_{\infty}$.
- (3) $(\ell_1, \|\cdot\|_1)$ is a normed space.
- (4) $(C([a,b]), \|\cdot\|_1)$ with $\|f\|_1 = \int_a^b |f(t)| dt$ is a normed space.
- (5) $(BV([a,b]), \|\cdot\|_{BV})$ where $\|f\|_{BV} = |f(a)| + Var(f)$ is a normed space.

- (6) Let $(V, \|\cdot\|_V)$ and $(W, \|\cdot\|_W)$ be normed spaces. Then $(B(V, W), \|\cdot\|_{\text{op}})$ is a normed space, where $B(V, W) = \{T \in \mathcal{L}(V, W) \mid \|T\|_{\text{op}} < \infty\}$ is the set of bounded linear maps and $\|T\|_{\text{op}} = \sup_{v \in B_V} \|T(v)\|_W$. Intuitively, $\|T\|_{\text{op}}$ measures the radius of the smallest ball which contains B_V .
 - **Exercise 1.3.3.** Show that $V^* := B(V, F)$ is a subspace of V'.
- (7) Let S be a nonempty set. Both $(\mathbf{F}(S), \|\cdot\|_1)$ and $(\mathbf{F}(S), \|\cdot\|_p)$ are normed spaces, where $\|f\|_1 = \sum_{s \in S} |f(s)|$ and $\|f\|_p = \left(\sum_{s \in S} |f(s)|^p\right)^{\frac{1}{p}}$. Note that since $f(s) \neq 0$ for finitely many $s \in S$, both $\|\cdot\|_1$ and $\|\cdot\|_p$ are well-defined.
 - **Exercise 1.3.4.** Show that $\|f\|_{\infty} := \sup_{s \in S} |f(s)|$ is a norm on $\mathbf{F}(S)$.

§ 1.4. Inner Product Spaces

Definition 1.4.1. Let V be a vector space over F and $\varphi: V \times V \to F$ a map.

- (1) The map φ is said to be a *bilinear form* if is is linear in the first and second variable separately; i.e., for all $v_1, v_2, v \in V$ and $c \in F$ we have:
 - (i) $\varphi(cv_1 + v_2, v) = c\varphi(v_1, v) + \varphi(v_2, v)$
 - (ii) $\varphi(v, cv_1 + v_2) = c\varphi(v, v_1) + \varphi(v, v_2).$
- (2) The map φ is said to be a *sesquilinear form* if it is linear in the first variable and conjugate linear in the second variable; i.e., for all $v_1, v_2, v \in V$ and $c \in F$ we have:
 - (i) $\varphi(cv_1 + v_2, v) = c\varphi(v_1, v) + \varphi(v_2, v)$
 - (ii) $\varphi(v, cv_1 + v_2) = \overline{c}\varphi(v, v_1) + \varphi(v, v_2).$

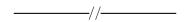
If we wish to keep track of a bilinear form on V we write (V, φ) .

Definition 1.4.2. Let V be a vector space over F.

- (1) A bilinear form φ on V is said to be symmetric if $\varphi(v, w) = \varphi(w, v)$ for all $v, w \in V$.
- (2) A sesquilinear form φ on V is said to be Hermitian if $\varphi(v,w) = \overline{\varphi(w,v)}$ for all $v,w \in V$.

Definition 1.4.3. Let (V, φ) be a vector space over F such that if φ is symmetric, then $F = \mathbf{R}$ or if φ is Hermitian, then $F = \mathbf{C}$. We say φ is positive-definite if for all nonzero $v \in V$ we have $\varphi(v, v) \neq 0$.

Definition 1.4.4. Let (V, φ) be a vector space over \mathbf{R} with φ a positive-definite symmetric bilinear form or over \mathbf{C} with φ a positive-definite Hermitian sesquilinear form. Then we say φ is an *inner product* on V and write φ as $\langle \cdot, \cdot \rangle$. We say $(V, \langle \cdot, \cdot \rangle)$ is an *inner product space*.



Definition 1.4.5. If V is an inner product space we define $||v||_2 = \langle v, v \rangle^{\frac{1}{2}}$.

Definition 1.4.6. Let V be an inner product space. Two vectors $v, w \in V$ are orthogonal if $\langle u, v \rangle = 0$. We denote this as $u \perp v$.

Theorem 1.4.1 (Pythagorean Theorem). Let $v_1, ..., v_n$ be mutually orthogonal. Then $\sum_{j=1}^n \|v_j\|_2^2 = \left\|\sum_{j=1}^n v_j\right\|_2^2$.

Proof. Because $v_i \perp v_j$ for $1 \leq i, j \leq n$, we have $\langle v_i, v_j \rangle = 0$. Observe that:

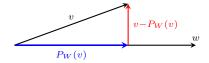
$$\left\| \sum_{j=1}^{n} v_j \right\|_2^2 = \left\langle \sum_{j=1}^{n} v_j, \sum_{j=1}^{n} v_j \right\rangle$$

$$= \sum_{j=1}^{n} \left(\sum_{i=1}^{n} \langle v_j, v_i \rangle \right)$$

$$= \sum_{j=1}^{n} \langle v_j, v_j \rangle$$

$$= \sum_{j=1}^{n} \|v_j\|_2^2.$$

Definition 1.4.7. Let V be an inner product space and $w \in V$ nonzero. The projection of a vector $v \in V$ onto w is a map $P_W : V \to V$ defined by $P_W(v) = \frac{\langle v, w \rangle}{\langle w, w \rangle} w$.



Proposition 1.4.2. *** Let V be an inner product space and $w \in V$ a nonzero vector. Then $P_w(v) \perp v - P_w(v)$.

Corollary 1.4.3. *** Let V be an inner product space and $w \in W$ a nonzero vector. Then $\|v\|_2^2 = \|P_w(v)\|_2^2 + \|v - P_w(v)\|_2^2$.

Lemma 1.4.4 (Cauchy-Schwartz Inequality). Let V be an inner product space and $v, w \in V$. Then $|\langle v, w \rangle| \leq ||v||_2 ||w||_2$.

Proof. The previous corollary gives $\|v\|_2 \geqslant \|P_w(v)\|_2$. We have that:

$$\begin{split} \|v\|_2 &\geqslant \left\| \frac{\langle v, w \rangle}{\langle w, w \rangle} w \right\|_2 \\ &= \frac{|\langle v, w \rangle|}{\|w\|_2^2} \|w\|_2 \\ &= \frac{\langle v, w \rangle}{\|w\|_2}. \end{split}$$

Multiplying both sides by $||w||_2$ gives the desired result.

Theorem 1.4.5. Let V be an inner product space. Then $(V, \|\cdot\|_2)$ is a normed space.

Proof. Let $v, w \in V$ and $\alpha \in F$. We have that:

$$\begin{split} \|\alpha v\|_2 &= \langle \alpha v, \alpha v \rangle^{\frac{1}{2}} \\ &= (\alpha \overline{\alpha} \langle v, v \rangle)^{\frac{1}{2}} \\ &= \left(|\alpha|^2 \langle v, v \rangle \right)^{\frac{1}{2}} \\ &= |\alpha| \, \|v\|_2 \, . \end{split}$$

Thus $\|\cdot\|_2$ satisfies homogeneity. It follows from the Cauchy-Schwartz Inequality that:

$$||v + w||_{2}^{2} = \langle v + w, v + w \rangle$$

$$= \langle v, v \rangle + \langle v, w \rangle + \langle w, v \rangle + \langle w, w \rangle$$

$$= ||v||_{2}^{2} + \langle v, w \rangle + \overline{\langle v, w \rangle} + ||w||_{2}^{2}$$

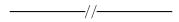
$$= ||v||_{2}^{2} + 2\Re(\langle v, w \rangle) + ||w||_{2}^{2}$$

$$\leq ||v||_{2}^{2} + 2|\langle v, w \rangle| + ||w||_{2}^{2}$$

$$\leq ||v||_{2}^{2} + 2||v||_{2}||w||_{2} + ||w||_{2}^{2}$$

$$= (||v||_{2} + ||w||_{2})^{2},$$

where we used the fact that $2\Re(\langle v,w\rangle)=2|\langle v,w\rangle|$. Squaring both sides proves that $\|\cdot\|_2$ satisfies the triangle inequality. It remains to show positive-definiteness. Suppose $\|v\|_2=0$. Then $\langle v,v\rangle=0$, but since the inner-product is by definition positive-definite, we get that $v=0_V$.



Example 1.4.1.

- (1) $\ell_2^n = F^n$ is an inner product space where $\langle (x_1,...,x_n),(y_1,...,y_n) \rangle := \sum_{j=1}^n x_j \overline{y_j}$.
- (2) ℓ_2 is an inner product space where $\langle (a_k)_k, (b_k)_k \rangle := \sum_{k=1}^{\infty} a_k \overline{b_k}$. Note that:

$$\begin{split} \sum_{k=1}^{n} \left| a_{k} \overline{b_{k}} \right| &= \sum_{k=1}^{n} |a_{k}| |b_{k}| \\ &\leqslant \left(\sum_{k=1}^{n} |a_{k}|^{2} \right)^{\frac{1}{2}} \left(\sum_{k=1}^{n} |b_{k}|^{2} \right)^{\frac{1}{2}} \\ &\leqslant \left(\sum_{k=1}^{\infty} |a_{k}|^{2} \right)^{\frac{1}{2}} \left(\sum_{k=1}^{\infty} |b_{k}|^{2} \right)^{\frac{1}{2}} \\ &= \|(a_{k})_{k}\|_{2} \|(b_{k})_{k}\|_{2} \\ &< \infty \qquad \qquad (\text{Because } (a_{k})_{k}, (b_{k})_{k} \in \ell_{2}). \end{split}$$

Since $\sum_{k=1}^{n}|a_{k}\overline{b_{k}}|$ is increasing and bounded above, the Monotone Convergence Theorem says $\sum_{k=1}^{\infty}|a_{k}\overline{b_{k}}|$ exists and is finite. Whence $\langle(a_{k})_{k},(b_{k})_{k}\rangle$ converges.

- (3) Recall that $\operatorname{Tr}: M_n(\mathbf{C}) \to \mathbf{C}$ is defined by $\operatorname{Tr}(a_{ij}) = \sum_{i=1}^n a_{ii}$. Then $M_n(\mathbf{C})$ is an inner product space where $\langle a_{ij}, b_{ij} \rangle := \operatorname{Tr}(b_{ij}^* a_{ij})$.
- (4) C([0,1]) is an inner product space where $\langle f,g\rangle := \int_0^1 f(x)\overline{g(x)}dx$.

§ 1.5. Normed Algebras

Definition 1.5.1. A normed algebra is an algebra A equipped with a norm $\|\cdot\|_A$ such that $\|ab\|_A \leq \|a\|_A \|b\|_A$. If A is unital, we require $\|1\|_A = 1$.

Example 1.5.1.

- (1) $\ell_{\infty}(\Omega)$ equipped with $\|\cdot\|_{u}$ is a normed algebra.
- (2) $C_c(\mathbf{R})$, $C_0(\mathbf{R})$, and C([0,1]) are all normed algebras when equipped with $\|\cdot\|_u$.
- (3) $M_n(F)$ equipped with $\|\cdot\|_{\text{op}}$ is a normed algebra.
- (4) If V is a normed space, then B(V, V) with $\|\cdot\|_{\text{op}}$ is a normed algebra: for $T, S \in B(V, V)$ and $v \in B_V$, we have that

$$\begin{aligned} \|(T \circ S)(v)\| &\leqslant \|T\|_{\mathrm{op}} \|S(v)\| \\ &\leqslant \|T\|_{\mathrm{op}} \|S\|_{\mathrm{op}}. \end{aligned}$$

Taking the supremum over all $v \in B_V$ gives $||T \circ S||_{\text{op}} \leq ||T||_{\text{op}} ||S||_{\text{op}}$.

(5) Let S be a group. Equip the algebra $\mathbf{F}(S)$ with $\|\cdot\|_1$. We get a normed algebra.

Exercise 1.5.1. For $a, b \in \ell_1(\mathbf{Z})$, define $a * b : \mathbf{Z} \to F$ by $(a * b)(n) = \sum_{k \in \mathbf{Z}} a(n - k)b(k)$. Show that $\ell_1(\mathbf{Z})$ with this multiplication is a normed algebra.

Chapter 2

Metric Spaces

§ 2.1. Basic Definitions and Examples

Definition 2.1.1. A *metric* on a nonempty set X is a map

$$d: X \times X \to [0, \infty)$$

satisfying for all $x, y, z \in X$:

- (1) d(x,y) = d(y,x) (symmetry);
- (2) $d(x,z) \leq d(x,y) + d(y,z)$ (triangle inequality);
- (3) d(x,x) = 0;
- (4) if d(x,y) = 0 then x = y (positivity).

If d satisfies all but (iv), then d is called a *semi-metric*. The pair (X, d) is called a *metric space*.

Definition 2.1.2.

- (1) Two metrics d, ρ on X are called *equivalent* if there exists constants c, c' with $d(x, y) \leq c\rho(x, y)$ and $\rho(x, y) \leq c'd(x, y)$.
- (2) Let $\{d_k\}_{k=1}^{\infty}$ be a family of metrics on X. If for all $x, y \in X$ and $k \in \mathbb{N}$ we have $d_k(x,y) \leq C$, then we say the family of metrics is uniformly bounded.

Example 2.1.1.

(1) The discrete metric on $X \neq \emptyset$ is:

$$d(x,y) = \begin{cases} 1, & x \neq y \\ 0, & x = y. \end{cases}$$

- (2) The hamming distance between two bit strings of equal length: given $X = \{0,1\}^n$, then $d_H: X \times X \to [0,\infty)$ is defined by $d_H((x_j)_{n\geqslant 1},(y_j)_{n\geqslant 1}) = |\{j \mid x_j \neq y_j\}|.$
- (3) If $(V, \|\cdot\|)$ is any normed space, then $d(v, w) = \|v w\|$ is a metric on V.

Exercise 2.1.1. If $\|\cdot\|$ and $\|\cdot\|'$ are norms on a linear space V, show they are equivalent if and only if their induced metrics are equivalent.

(4) If (X, d) is a metric and $Y \subseteq X$ is a subset, then (Y, d) is a metric space.

(5) Let (X, ρ) be a metric space. Fix $p \in X$. Then:

$$d(x,y) := \begin{cases} 0, & x = y \\ \rho(x,p) + \rho(p,y), & x \neq y \end{cases}$$

is a metric.

(6) It is often beneficial to work with metrics that are bounded. Let ρ be a (semi)-metric of X. Set:

$$d(x,y) = \frac{\rho(x,y)}{1 + \rho(x,y)}.$$

Defining d(x, y) as above gives $0 \le d(x, y) \le 1$. Although d and ρ are not equivalent metrics, they are topologically equivalent.

Clearly d is symmetric and d(x,x)=0. Moreover, if d(x,y)=0, then $\rho(x,y)=0$, giving x=y if ρ is a metric. For the triangle inequality, consider the function $g:[0,\infty)\to [0,1)$ given by $g(t)=\frac{t}{1+t}$. We have that $g'(t)=\frac{(1+t)-t}{(1+t)^2}=\frac{1}{(1+t)^2}>0$, whence g is strictly increasing. Since we know $\rho(x,z)\leqslant \rho(x,y)+\rho(y,z)$, observe that:

$$\begin{split} d(x,z) &= \frac{\rho(x,z)}{1 + \rho(x,z)} \\ &\leqslant \frac{\rho(x,y) + \rho(y,z)}{1 + \rho(x,y) + \rho(y,z)} \\ &= \frac{\rho(x,y)}{1 + \rho(x,y) + \rho(y,z)} + \frac{\rho(y,z)}{1 + \rho(x,y) + \rho(y,z)} \\ &\leqslant \frac{\rho(x,y)}{1 + \rho(x,y)} + \frac{\rho(y,z)}{1 + \rho(y,z)} \\ &= d(x,y) + d(y,z). \end{split}$$

(7) If $d_1, ..., d_n$ are metrics on X and $c_1, ..., c_n > 0$, then:

$$d(x,y) = \sum_{i=1}^{n} c_i d_i(x,y)$$

is a metric on X.

(8) Let $\{\rho_k\}_{k=1}^{\infty}$ be a family of semi-metrics on X. Assume that the family is *separating*: if $x,y\in X$ and $x\neq y$, then there exists k such that $\rho_k(x,y)\neq 0$. Let $d_k(x,y)=\frac{\rho_k(x,y)}{1+\rho_k(x,y)}$. Then:

$$d(x,y) = \sum_{k=1}^{\infty} 2^{-k} d_k(x,y)$$

is a metric on X. Since $0 \le d_k(x,y) \le 1$, by comparison d(x,y) will converge.

(9) Let $(X_k, \rho_k)_{k \ge 1}$ be a sequence of metric spaces. For each k let d_k be as above. Let $X = \prod_{k=1}^{\infty} X_k$. Then the map $D: X \times X \to [0, \infty)$ defined by

$$D(f,g) = \sum_{k=1}^{\infty} 2^{-k} d_k(f(k), g(k))$$

is a metric on X. Note that we need not make d_k from ρ_k if all the d_k are uniformly bounded.

(10) Let $X = \{0, 2\}$ with the discrete metric. The abstract Cantor set is $\Delta := \prod_{k \in \mathbb{N}} X$. Then the map $D : \Delta \times \Delta \to [0, \infty)$ defined by

$$D(f,g) = \sum_{k=1}^{\infty} 3^{-k} |f(k) - g(k)|$$

is a metric on Δ .

(11) Let $\langle \cdot, \cdot \rangle$ be the standard inner product on \mathbf{R}^3 (or \mathbf{R}^n). The unit sphere $S^2 = \{x \in \mathbf{R}^3 \mid ||x||_2 = 1\}$ paired with $d(x,y) := \arccos(\langle x,y \rangle)$ is a metric space.

Exercise 2.1.2. Show that (S^2, d) defined as above is indeed a metric space.

Definition 2.1.3.

- (1) Let (X,d) be a metric space with $E \subseteq X$. The diameter of E is diam $(E) = \sup_{x,y\in E} d(x,y)$. We say E is bounded (metrically) if diam $(E) < \infty$.
- (2) If Ω is any set and (Y,d) is a metric space, $f:\Omega\to Y$ is bounded if $\operatorname{diam}(f(\Omega))<\infty$. The set of bounded functions is $\operatorname{Bd}(\Omega,Y):=\{f:\Omega\to Y\mid f\text{ bounded}\}$.

Exercise 2.1.3. If $(V, \|\cdot\|)$ is a normed space and $E \subseteq V$, the following are equivalent:

- (1) E is bounded;
- $(2) \sup_{v \in E} ||v|| < \infty;$
- (3) there exists r > 0 such that $E \subseteq B(0, r)$.

Example 2.1.2. The set $\mathrm{Bd}(\Omega,Y)$ is a metric space with:

$$D_u(f,g) := \sup_{x \in \Omega} d(f(x), g(x)).$$

Clearly $D_u(f,g) = D_u(g,f)$ and $D_u(f,f) = 0$. If $D_u(f,g) = 0$, then f(x) = g(x) for all $x \in \Omega$, giving f = g. Moreover, for every $x \in \Omega$:

$$d(f(x), h(x)) \leq d(f(x), g(x)) + d(g(x), h(x))$$

$$\leq D_u(f, g) + D_u(g, h).$$

Whence $D_u(f,h) \leq D_u(f,g) + D_u(g,h)$. Note that if we take the normed space $(\ell_{\infty}(\Omega), \|\cdot\|_u)$, the induced metric is:

$$d(f,g) = \|f - g\|_u$$

$$= \sup_{x \in \Omega} |(f - g)(x)|$$

$$= \sup_{x \in \Omega} |f(x) - g(x)|$$

$$= D_u(f,g).$$

So as metric spaces, $\ell_{\infty}(\Omega) \cong \operatorname{Bd}(\Omega, F)$. Now consider the subset $E = \{ f \in \operatorname{Bd}(\Omega, F) \mid f(x) \in \{0, 1\} \}$. We get:

$$D_u(f,g) = \sup_{x \in \Omega} |f(x) - g(x)|$$
$$= \begin{cases} 0, & f = g \\ 1, & f \neq g \end{cases}.$$

So (E, D_u) is discrete.

§ 2.2. Topology of Metric Spaces

Unless otherwise stated, let (X, d) be a metric space.

Definition 2.2.1. Let X be a set. A collection T of subsets of X is called a *topology on* X if they satisfy:

- (1) $\emptyset, X \in T$;
- (2) arbitrary unions of elements in T are in T;
- (3) finite intersections of elements in T are in T.

Definition 2.2.2. Let (X, d) be a metric space.

- (1) Let $x_0 \in X$ and $\delta > 0$.
 - (i) The open ball centered at x_0 of radius δ is $U(x_0, \delta) = \{x \mid d(x, x_0) < \delta\}$.
 - (ii) The closed ball centered at x_0 of radius δ is $B(x_0, \delta) = \{x \mid d(x, x_0) \leq \delta\}$.
 - (iii) The sphere centered at x_0 of radius δ is $S(x_0, \delta) = \{x \mid d(x, x_0) = \delta\}$.
- (2) A subset $U \subseteq X$ is open in X if:

$$(\forall x \in U)(\exists \delta > 0) : U(x, \delta) \subseteq U.$$

The collection of open sets is denoted $\tau_X := \{U \subseteq X \mid U \text{ is open}\}.$

- (3) A subset $D \subseteq X$ is closed in X if $D^c \subseteq X$ is open in X.
- (4) If $x \in U \in \tau_X$, then U is called an *open neighborhood of* x. If $x \in U \in \tau_X$ and $U \subseteq N \subseteq X$, then N is called a *neighborhood of* x. The collection of neighborhoods of x is denoted $\mathcal{N}_x = \{N \mid N \text{ is a neighborhood of } x\}$.
- (5) Let $A \subseteq X$.
 - (i) The interior of A is:

$$A^o := \bigcup \{ V \in \tau_X \mid V \subseteq A \}.$$

(ii) The closure of A is:

$$\overline{A} := \bigcap \{C \mid C \supseteq A, C \text{ closed} \}.$$

(iii) The boundary of A is $\partial A := \overline{A} \setminus A^o$.

Exercise 2.2.1. Show that $\overline{A^c} = (A^o)^c$ and $\overline{A}^c = (A^c)^o$.

Proposition 2.2.1. Let (X,d) be a metric space. The open sets τ_X form a topology.

Proof. Both \emptyset and X are open by assumption. Let $\{V_i\}_{i\in I}$ be a family of open sets of X. Let $x\in\bigcup_{i\in I}V_i$. Then $x\in V_i$ for some i. Since V_i is open, there exists $\delta>0$ with $B(x,\delta)\subseteq V_i\subseteq\bigcup_{i\in I}V_i$. Whence the arbitrary union of open sets is open.

Now let $\{V_k\}_{k=1}^n$ be a family of open sets. Let $x \in \bigcap_{k=1}^n V_k$. Then $x \in V_k$ for all k. Since V_k is open, there exists $\delta_k > 0$ with $B(x, \delta_k) \subseteq V_k$. Pick $\delta = \min\{\delta_1, \delta_2, ..., \delta_k\}$. Then $B(x, \delta) \subseteq \bigcap_{k=1}^n V_k$. Whence $\bigcap_{k=1}^n V_k$ is open.

Note that an arbitrary intersection of open sets is not necessarily open. Consider the sequence of intervals $(I_n)_n = (-\frac{1}{n}, \frac{1}{n})$. Then $\bigcap_{n=1}^{\infty} I_n = \{0\}$, which is closed.

Exercise 2.2.2. Let (X,d) be a metric space and consider a collection \mathcal{C} of subsets of X with $\emptyset, X \in \mathcal{C}$. Show that:

- (1) if $\{C_i\}_{i\in I}$ is a family of closed sets, then $\bigcap_{i\in I} C_i$ is closed;
- (2) if $\{C_i\}_{i=1}^n$ is a family of closed sets then $\bigcup_{i=1}^n C_i$ is closed.

Proposition 2.2.2. Let (X,d) be a metric space and $x \in X$.

- (1) $N \in \mathcal{N}_x$ if and only if there exists $\delta > 0$ such that $U(x, \delta) \subseteq N$.
- (2) If $N \in \mathcal{N}_x$ and $N \subseteq M$, then $M \in \mathcal{N}_x$.
- (3) If $N_1, N_2 \in \mathcal{N}_x$, then $N_1 \cap N_2 \in \mathcal{N}_x$.

Proof. (1) Let $N \in \mathcal{N}_x$. Then there is an open set $x \in U$ with $U \subseteq N \subseteq X$. Since U is open, there exists $\delta > 0$ such that $U(x, \delta) \subseteq U \subseteq N$. Conversely, suppose there exists $\delta > 0$ such that $U(x, \delta) \subseteq N$. Clearly $U(x, \delta) \subseteq N \subseteq X$, whence $N \in \mathcal{N}_x$.

- (2) If $N \in \mathcal{N}_x$, then there is an open set U with $x \in U$ and $U \subseteq N \subseteq X$. So $U \subseteq N \subseteq M \subseteq X$. Whence $M \in \mathcal{N}_x$.
- (3) If $N_1, N_2 \in \mathcal{N}_x$, then there are open sets U_1, U_2 with $x \in U_1$, $x \in U_2$ and $U_1 \subseteq N_1 \subseteq X$, $U_2 \subseteq N_2 \subseteq X$. Whence $U_1 \cap U_2 \subseteq N_1 \cap N_2 \subseteq X$.

Proposition 2.2.3. *Let* $U \subseteq \mathbf{R}$ *be open. Then:*

$$U = \bigsqcup_{j \in J} I_j,$$

where J is countable and I_j are open intervals.

Proof. For each $x \in U$, define:

$$I_x := \bigcup \{I \mid x \in I \subseteq U, I \text{ open interval}\}.$$

Clearly $x \in I_x \subseteq U$. If $s,t \in I_x$ with s < t, then there exists open intervals I,I' with $x \in I \subseteq U$, $x \in I' \subseteq U$, and $s \in I$, $t \in I'$. Since $I \cap I' \neq \emptyset$, $I \cup I'$ is an open interval. Moreover, since $s,t \in I \cup I'$, we know $[s,t] \subseteq I \cup I' \subseteq I_x$. This shows I_x is an interval —in particular, since I_x is the union of open intervals, it must be open.

Now suppose $x, y \in U$ and $I_x \cap I_y \neq \emptyset$. Then there exists $z \in I_x \cap I_y$, but $z \in I_x$ implies $I_x \subseteq I_z$ and $z \in I_y$ implies $I_y \subseteq I_z$. But we also have $x \in I_x \subseteq I_z$ which gives $I_z \subseteq I_x$,

and similarly $y \in I_y \subseteq I_z$ gives $I_z \subseteq I_y$. Together, we have $I_x = I_y$, which means for any $x, y \in U$, then $I_x \cap I_y = \emptyset$ or $I_x = I_y$. Thus there exists $J \subseteq U$ with $U = \bigsqcup_{j \in J} I_j$.

It remains to show that J is countable. Define $J \to \mathbf{Q}$ by $x \mapsto q_x$, where $q_x \in \mathbf{Q} \cap I_x$. This map is injective, establishing the proposition.

Proposition 2.2.4. *Let* $A \subseteq X$.

- (1) $x \in A^{\circ}$ if and only if there exists $\delta > 0$ such that $U(x, \delta) \subseteq A$.
- (2) $x \in \overline{A}$ if and only if for all $\delta > 0$, $U(x, \delta) \cap A \neq \emptyset$.
- (3) $x \in \partial A$ if and only if for all $\delta > 0$, $U(x,\delta) \cap A \neq \emptyset$ and $U(x,\delta) \cap A^c \neq \emptyset$.

Proof. (1) $x \in A^o \iff$ there exists $V \in \tau_X$ with $x \in V \subseteq A \iff$ there exists $\delta > 0$ with $U(x,\delta) \subseteq V \subseteq A$.

- (2) The converse gives $x \notin \overline{A} \iff x \in (\overline{A})^c = (A^c)^o \iff$ there exists $\delta > 0$ such that $U(x,\delta) \subseteq (A^c)^o \subseteq A^c \iff U(x,\delta) \cap A = \emptyset$.
- (3) $x \in \partial A \iff x \in \overline{A} \setminus A^o \iff x \in \overline{A} \cap (A^o)^c \iff x \in \overline{A} \cap \overline{A^c} \iff \text{there exists}$ $\delta > 0 \text{ with } U(x,\delta) \cap A \neq \emptyset \text{ and } U(x,\delta) \cap A^c \neq \emptyset$

Exercise 2.2.3. Show that open balls are open, closed balls are closed, and spheres are closed.

Proposition 2.2.5. *** For any normed space:

- (1) $\overline{U(x,\delta)} = B(x,\delta)$
- (2) $B(x,\delta)^o = U(x,\delta)$
- (3) $\partial U(x,\delta) = \partial B(x,\delta) = S(x,\delta)$.

Proof. (1)

(2) Suppose $y \in B(x, \delta)^o \setminus U(x, \delta)$. Then there exists $\delta' > 0$ with $U(x, \delta') \subseteq B(x, \delta)$. But this means $d(x, y) < \delta$, which is a contradiction. Thus $B(x, \delta)^o \setminus U(x, \delta) = \emptyset$, establishing $B(x, \delta)^o = U(x, \delta)$.

Proposition 2.2.6. *** Let (X,d) be a metric space with $\{A_i\}_{i\in I}$ a family of subsets. Let $K\subseteq I$ be finite.

- (1) $\bigcup_{i \in I} A_i^o \subseteq \left(\bigcup_{i \in I} A_i\right)^o$ (Inclusion may be strict).
- (2) $\overline{\bigcap_{i \in I} A_i} \subseteq \bigcap_{i \in I} \overline{A_i}$ (Inclusion may be strict).

(3)
$$\bigcap_{i \in K} A_i^o = \left(\bigcap_{i \in K} A_i\right)^o$$

$$(4) \ \overline{\bigcup_{i \in K} A_i} = \bigcup_{i \in K} \overline{A_i}.$$

Proof.

Proposition 2.2.7. *Let* $S \subseteq X$.

- (1) $\partial S = \partial S^c$.
- (2) ∂S is closed.
- (3) $\overline{S} = S \cup \partial S$.
- (4) $S \setminus \partial S = S^o$.

Proof. (1) This follows from the characterization of ∂S . (2) We have $\partial S = \overline{S} \setminus S^o = \overline{S} \cap (S^o)^c$, which is closed. (3) Clearly $S \cup \partial S \subseteq \overline{S}$. Let $x \in \overline{S}$. If $x \in S$ we are done. Otherwise $x \in \overline{S} \setminus S \subseteq \overline{S} \setminus S^o = \partial S$. (4) Observe that:

$$S \setminus \partial S = S \cap (\partial S)^{c}$$

$$= S \cap (\overline{S} \setminus S^{o})^{c}$$

$$= S \cap (\overline{S} \cap (S^{o})^{c})^{c}$$

$$= S \cap (\overline{S}^{c} \cup S^{o})$$

$$= S \cap \overline{S}^{c} \cup S \cap S^{o}$$

$$= S^{o}.$$

Definition 2.2.3. Let (X, d) be a metric space.

- (1) A subset $A \subseteq X$ is d-dense if $\overline{A} = X$.
- (2) A subset $N \subseteq X$ is nowhere dense if $(\overline{N})^o = \emptyset$.
- (3) The space (X, d) is separable if there exists a countable dense subset $D \subseteq X$.

Exercise 2.2.4. If $N \subseteq X$ is closed, then N is nowhere dense if and only if N^c is dense.

Proposition 2.2.8. *** Let $A \subseteq X$. The following are equivalent:

- (1) A is dense;
- (2) $(\forall U \in \tau_X), U \cap A \neq \emptyset;$
- (3) $(\forall x \in X)(\forall \epsilon > 0), U(x, \epsilon) \cap A \neq \emptyset;$
- $(4) \ (\forall x \in X)(\forall \epsilon > 0)(\exists a \in A) : d(a, x) < \epsilon.$

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Definition 2.2.4. Let (X, d) be a metric space.

(1) A base for τ_X is a family of open subsets $\mathcal{B} \subseteq \tau_X$ such that:

$$(\forall U \in \tau_X)(\forall x \in U)(\exists B \in \mathcal{B}) : x \in B \subseteq U.$$

Equivalently, for all $U \in \tau_X$, we can write $U = \bigcup_{i \in I} B_i$, where $\{B_i\}_{i \in I} \subseteq \tau_X$.

(2) X is second countable if it has a countable base.

Note that this definition can be generalized to any topological space. Clearly $\mathcal{B} = \{U(x,\epsilon) \mid x \in X, \epsilon > 0\}$ forms a base for any metric space.

Example 2.2.1. The set $\mathcal{B} = \{U(q, \frac{1}{n}) \mid n \geqslant 1, q \in \mathbf{Q}^d\}$ is a base for \mathbf{R}^d .

Proposition 2.2.9. Let (X, d) be a metric space. X is separable if and only if X is second countable.

Proof. Let $\mathcal{B} = \{U_n\}_{n=1}^{\infty}$ be a countable base. Choose any $a_n \in U_n$. Then $\{a_n\}_{n=1}^{\infty}$ is dense. Indeed, given any $x \in X$ and $\epsilon > 0$, there exists U_m with $x \in U_m \subseteq U(x, \epsilon)$ (since $U_m \in \mathcal{B}$). Whence $d(a_m, x) < \epsilon$.

Let $\{a_n\}_{n=1}^{\infty}$ be dense. Consider:

$$\mathcal{B} = \left\{ U(a_n, \frac{1}{m}) \mid n \geqslant 1, m \geqslant 1 \right\}.$$

Clearly \mathcal{B} is countable —it remains to show that it is a base for X. Given $x \in V \in \tau_X$, find $\epsilon > 0$ such that $U(x,\epsilon) \subseteq V$. Then there exists $m \geqslant 1$ with $\epsilon > \frac{1}{m}$. Since $\{a_n\}_{n=1}^{\infty}$ is dense, there exists $a_j \in \{a_n\}_{n=1}^{\infty}$ such that $d(a_j,x) < \frac{1}{2m}$. Let $y \in U(a_j, \frac{1}{2m})$. Observe that:

$$d(x,y) \leq d(x,a_j) + d(a_j,y)$$

$$< \frac{1}{2m} + \frac{1}{2m}$$

$$= \frac{1}{m}$$

$$< \epsilon.$$

So $y \in U(x, \epsilon)$. Thus $x \in U(a_j, \frac{1}{2m}) \subseteq U(x, \epsilon) \subseteq V$, establishing \mathcal{B} as a base.

Example 2.2.2.

(1) The space $(\mathbf{R}^d, \|\cdot\|_p)$ is separable for any $1 \leq p \leq \infty$. Indeed, if $(r_1, ..., r_d) \in \mathbf{R}^d$ and $\epsilon > 0$, find $q_i \in \mathbf{Q}$, j = 1, ..., d with:

$$|r_j - q_j| < \frac{\epsilon}{d}.$$

Then:

$$||r - q||_1 = \sum_{j=1}^{d} |r_j - q_j| < \epsilon.$$

So \mathbf{Q}^d is $\|\cdot\|_1$ -dense in \mathbf{R}^d . For $1 \leq p \leq \infty$, let C > 0 be such that $\|\cdot\|_p \leq C \|\cdot\|_1$. So given $\epsilon > 0$, find $q \in \mathbf{Q}^d$ with $\|r - q\|_1 \leq \frac{\epsilon}{C}$. Then $\|r - q\|_p < \epsilon$.

(2) Similarly, $\mathbf{C}_{\mathbf{Q}}^d\subseteq\mathbf{C}^d$ is $\lVert \cdot \rVert_p\text{-dense, where:}$

$$\mathbf{C}_{\mathbf{Q}} = \{ a + bi \mid a, b \in \mathbf{Q} \}.$$

(3) Recall that $c_{00} = \{(z_k)_k \mid \operatorname{supp}((z_k)_k) < \infty\}$. The space $(c_{00}, \|\cdot\|_u)$ is separable. Note that $c_{00} = \mathbf{C}\operatorname{-span}\{e_k \mid k \in \mathbf{N}\}$. This space is not countable —clearly $\mathbf{C}\operatorname{-span}\{e_1\} = \{\alpha e_1 \mid \alpha \in \mathbf{C}\}$ is not countable, so it must be that c_{00} is also not countable. Instead, consider:

$$\mathbf{C}_{\mathbf{Q}}\operatorname{-span}\{e_k \mid k \in \mathbf{N}\} = \left\{ \sum_{k=1}^{\infty} t_k e_k \mid t_k \in \mathbf{C}_{\mathbf{Q}}, \right\}$$
$$= \bigcup_{k=1}^{\infty} \{C_k \mid C_k = \mathbf{C}_{\mathbf{Q}}\operatorname{-span}\{e_1, ..., e_k\}\}$$

Note that C_k is in bijection with \mathbf{Q}^{2k} , whence $\mathbf{C}_{\mathbf{Q}}$ -span $\{e_k \mid k \in \mathbf{N}\}$ is countable.

Given $z \in c_{00}$, let $z = \sum_{k=1}^{N} z_k e_k$ and $\epsilon > 0$. Find $t_k \in \mathbf{C}_{\mathbf{Q}}$ with $|z_k - t_k| < \epsilon$. Then:

$$||z - t||_{u} = \left\| \sum_{k=1}^{N} z_{k} e_{k} - \sum_{k=1}^{K} t_{k} e_{k} \right\|_{u}$$

$$= \left\| \sum_{k=1}^{N} (z_{k} - t_{k}) e_{k} \right\|_{u}$$

$$= \sup_{k=1}^{N} |z_{k} - t_{k}|$$

Thus $\mathbf{C}_{\mathbf{Q}}$ -span $\{e_k \mid k \in \mathbf{N}\}$ is dense in c_{00} , whence the space $(c_{00}, \|\cdot\|_n)$ is separable.

Proposition 2.2.10. *If* (X,d) *is a separable metric space and* $Y \subseteq X$, *then* (Y,d) *is separable.*

Proof. Let $A = \{a_k\}_{k=1}^{\infty}$ be dense in X. Let:

$$N = \{ (m, n) \mid U(a_m, \frac{1}{n}) \cap Y \neq \emptyset \}.$$

For each $(m,n) \in N$, choose $b_{(m,n)} \in Y \cap U(a_m, \frac{1}{n})$. Claim: the set

$$\{b_{(m,n)} \mid (m,n) \in N\}$$

is dense in Y. Let $y \in Y$ and $\epsilon > 0$. Then there exists $n \ge 1$ with $\frac{\epsilon}{2} > \frac{1}{n}$. Since A is dense, $U(y, \frac{1}{n}) \cap A \ne \emptyset$ (this is because for all $U \in \tau_X$, we have $U \cap A \ne \emptyset$). So $d(a_m, y) < \frac{1}{n}$. Whence:

$$d(b_{(m,n)}, y) \leq d(b_{(m,n)}, a_m) + d(a_m, y)$$

$$< \frac{1}{n} + \frac{1}{n}$$

$$< \epsilon.$$

Example 2.2.3.

(1) The space $(\ell_{\infty}, \|\cdot\|_u)$ is not separable. If it were, consider:

$$E = \{(x_k)_k \mid x_k \in \{0, 1\}\} \subseteq \ell_{\infty}.$$

This set is uncountable, and by the previous proposition $(E, \|\cdot\|_u)$ is also separable. Let $a, b \in E$. We have:

$$\begin{aligned} \|(a_k)_k - (b_k)_k\|_u &= \|(a_k - b_k)_k\|_u \\ &= \sup_{k \geqslant 1} |a_k - b_k| \\ &= \begin{cases} 0, & (a_k)_k = (b_k)_k \\ 1, & (a_k)_k \neq (b_k)_k \end{cases}. \end{aligned}$$

So $(E, \|\cdot\|_u)$ is discrete. Note that a metric space is discrete if and only if its singletons are open. Whence if $(E, \|\cdot\|_u)$ is separable, then $A = \overline{A} = E$, which contradicts the countability of A. It must be that $(\ell_\infty, \|\cdot\|_u)$ is not separable.

(2) The space $(\ell_p, \|\cdot\|_p)$ is separable for $1 \leq p < \infty$. Let $a = (a_k)_k \in \ell_p$ and $\epsilon > 0$. Find N large so that $\sum_{k>N} |a_k|^p < \frac{\epsilon^p}{2}$. Find $b_k \in \mathbf{C}_{\mathbf{Q}}$ with $|a_k - b_k| < \frac{\epsilon}{(2N)^{\frac{1}{p}}}$. Let $b = (b_1, b_2, ..., b_{N-1}, b_N, 0, 0, ...)$. We have:

$$||a - b||_p^p = \sum_{k=1}^{\infty} |a_k - b_k|^p$$

$$= \sum_{k=1}^{N} |a_k - b_k|^p + \sum_{k>N} |a_k|^p$$

$$< N \cdot \frac{\epsilon^p}{2N} + \frac{\epsilon^p}{2}$$

$$= \epsilon$$

Whence the set $\mathbf{C}_{\mathbf{Q}}$ -span $\{e_k \mid k \in \mathbf{N}\}$ is $\|\cdot\|_n$ -dense, giving $(\ell_p, \|\cdot\|_p)$ as separable.

(3) We will eventually show that the set of polynomial functions:

$$P([0,1]) = \left\{ \sum_{k=0}^{n} a_k x^k \mid a_k \in F, n \ge 0 \right\}$$

is $\|\cdot\|_u$ -dense in $C\big([0,1]\big)$ (note that this set is not countable). With this fact, we can show that $C\big([0,1]\big)$ is separable. Indeed, given $f\in C\big([0,1]\big)$ and $\epsilon>0$, find $p\in P\big([0,1]\big)$ with $\|f-p\|_u<\frac{\epsilon}{2}$. Now let $p(x)=\sum_{k=0}^n a_k x^k$. Find $b_k\in\mathbf{C}_\mathbf{Q}$ with $|a_k-b_k|<\frac{\epsilon}{2(n+1)}$ and define $q(x)=\sum_{k=0}^n b_k x^k$. Observe that:

$$||f - q||_{u} = ||f - p + p - q||_{u}$$

$$\leq ||f - p||_{u} + ||p - q||_{u}$$

$$= ||f - p||_{u} + \sum_{k=0}^{n} |a_{k} - b_{k}|$$

$$< \frac{\epsilon}{2} + (n+1) \cdot \frac{\epsilon}{2(n+1)}$$

Thus the set $\mathbf{C}_{\mathbf{Q}}$ -span $\{x^k \mid k \in \mathbf{N}\}$ is $\|\cdot\|_u$ -dense in C([0,1]). In particular, since it is countable, C([0,1]) is separable.

____//___

We have seen that subsets of metric spaces are metric spaces in their own right. Then what are their open sets?

Proposition 2.2.11. Let (X,d) be a metric space and let $Y \subseteq X$ be any subset. Then $V \subseteq Y$ is open in Y if and only if there exists an open set $U \subseteq X$ with $U \cap Y = V$. That is, $\tau_Y = \{U \cap Y \mid U \in \tau_X\}$.

Proof. Let $V \subseteq Y$ be open. Then for every $x \in V$, there exists $\delta_x > 0$ with $U_y(x, \delta_x) \subseteq V$, where:

$$U_y(x, \delta_x) = \{ y \in Y \mid d(y, x) < \delta_x \}$$

= $U(x, \delta_x) \cap Y$.

Set $U = \bigcup_{x \in V} U(x, \delta_x)$. Then U is indeed open in X. Also:

$$U \cap Y = \left(\bigcup_{x \in V} U(x, \delta_x)\right) \cap Y$$
$$= \bigcup_{x \in V} (U(x, \delta_x) \cap Y)$$
$$= \bigcup_{x \in V} U_y(x, \delta_x)$$
$$= V.$$

Conversely, suppose $V=U\cap Y$ for some open $U\in\tau_X$. Let $x\in V$. Since $x\in U$ and U is open, there exists $\delta>0$ such that $U(x,\delta)\subseteq U$. So $U_y(x,\delta)=U(x,\delta)\cap Y\subseteq U\cap Y=V$. Thus V is open in Y.

Example 2.2.4.

- (1) $[0,\frac{1}{2})$ is not open in **R**, but it is open in [0,1].
- (2) ℓ_{∞} is not a discrete metric space, but $\{0,1\}^{\mathbf{N}} \subseteq \ell_{\infty}$ is.

§ 2.3. The Cantor Set

Given the interval [0,1], start by deleting the open middle third $(\frac{1}{3},\frac{2}{3})$, leaving two line segments $[0,\frac{1}{3}] \cup [\frac{2}{3},1]$. Next, the open middle third of each of these remaining segments is deleted, leaving four line segments $[0,\frac{1}{9}] \cup [\frac{2}{9},\frac{1}{3}] \cup [\frac{2}{3},\frac{7}{9}] \cup [\frac{8}{9},1]$.

[0,1]						
	$[0, \frac{1}{3}]$	$[\frac{2}{3}, 1]$				
$[0, \frac{1}{9}]$	$[\frac{2}{9},\frac{1}{3}]$	$[\frac{2}{3}, \frac{7}{9}]$	$[\frac{8}{9}, 1]$			
	_ _	_ _ _ _ _				

We are interested in studying the topological properties of the points which are not deleted at any step of this infinite process. The set of these points have a special name and are defined below.

Definition 2.3.1. Let $C_0 := [0,1]$ and $C_n = \frac{C_{n-1}}{3} \cup \left(\frac{2}{3} + \frac{C_{n-1}}{3}\right)$ for $n \ge 1$. The Cantor set is $\mathfrak{C} = \bigcap_{n=0}^{\infty} C_n$.

Proposition 2.3.1. The Cantor set is closed.

Proof. Since the Cantor set is defined as the intersection of closed sets, it must be closed. \Box

Proposition 2.3.2. The Cantor set is nowhere dense.

Proof. Suppose towards contradiction its not, that is, $\overline{\mathfrak{C}}^o \neq \emptyset$. Then there is some $x \in \overline{\mathfrak{C}}^o$. We can find an $\epsilon > 0$ with $(x - \epsilon, x + \epsilon) \subseteq \mathfrak{C}$, in particular $(x - \epsilon, x + \epsilon) \subseteq C_n$ for all $n \geqslant 1$. Find m large so that $\epsilon > \frac{1}{3^m}$ and consider $(x - \epsilon, x + \epsilon) \subseteq C_m$. We have that $C_m = \bigsqcup_{j=1}^{2^m} C_{m,j}$ where length $(C_{m,j}) = \frac{1}{3^m}$. Since each $C_{m,j}$ is disjoint, it must be the case that $(x - \epsilon, x + \epsilon) \subseteq C_{m,j}$ for some $1 \leqslant j \leqslant 2^m$. But the length of $(x - \epsilon, x + \epsilon)$ is 2ϵ , which is impossible. It must be that \mathfrak{C} is nowhere dense.

Proposition 2.3.3. The total length of the Cantor set is 0.

Proof. The total length of the removed intervals is:

$$\frac{1}{3} + \frac{2}{9} + \frac{4}{27} + \dots = \sum_{k=1}^{\infty} \frac{2^{k-1}}{3^k}$$

$$= \frac{1}{2} \sum_{k=1}^{\infty} \left(\frac{2}{3}\right)^k$$

$$= \frac{1}{2} \cdot \frac{\frac{2}{3}}{1 - \frac{2}{3}}$$

$$= 1.$$

Thus length(\mathfrak{C}) = 0.

Lemma 2.3.4. ***

 \square

Lemma 2.3.5. ***

 \square

Lemma 2.3.6. ***

Proof.

Proposition 2.3.7. *** $\operatorname{card}(\mathfrak{C}) = \mathfrak{c}$.

Proof.

§ 2.4. Convergent Sequences

Definition 2.4.1. Fix a metric space (X, d).

- (1) A sequence in X is a map $x : \mathbb{N} \to X$ defined by $n \mapsto x_n$. We denote a sequence as $(x_n)_{n \ge 1}, (x_n)_{n=1}^{\infty}$, or $(x_n)_n$.
- (2) A natural sequence is a sequence $(x_n)_n$ in **N** with $n_1 < n_2 < n_3 < ...$
- (3) A subsequence of a sequence $(x_n)_n$ is a sequence $(x_{n_k})_k$ where $(n_k)_k$ is a natural sequence. This is equivalent to the composition of maps $\mathbf{N} \xrightarrow{k \mapsto n_k} \mathbf{N} \xrightarrow{n_k \mapsto x_{n_k}} X$.

Definition 2.4.2. A sequence $(x_n)_n$ converges to $x \in X$ if:

$$(\forall \epsilon > 0)(\exists N \in \mathbf{N}) : (\forall n \in \mathbf{N})(n \geqslant N \implies d(x_n, x) < \epsilon).$$

We write $(x_n)_n \stackrel{d}{\to} x$ or limit $x_n = x$.

Exercise 2.4.1. Show that a sequence can have at most one limit.

Proposition 2.4.1. Given $(x_n)_n$ in X and $x \in X$, the following are equivalent:

- (1) $(x_n)_n \to x$ in X;
- (2) $(d(x_n, x))_n \to 0$ in \mathbf{R} ;
- (3) $(\forall V \in \mathcal{N}_x)(\exists N \in \mathbf{N}) : (\forall n \in \mathbf{N})(n \geqslant N \implies x_n \in V).$

Exercise 2.4.2. Let (X,d) be a metric space and $\rho(x,y) = \frac{d(x,y)}{1+d(x,y)}$. Then $(x_n)_n \xrightarrow{d} x$ if and only if $(x_n)_n \xrightarrow{\rho} x$.

Proposition 2.4.2. Convergent sequences are bounded.

Proof. Suppose that $(x_n)_n \to x$ and let $\epsilon = 1$. Find N large so that for $n \ge N$ we have $d(x_n, x) < 1$. Then for all $m, n \ge N$, we have $d(x_m, x_n) \le d(x_m, x) + d(x, x_n) < 2$. Set $C = \max_{1 \le n, m \le N} d(x_m, x_n)$. Now if $n \ge N$ and $m \le N$, we have:

$$d(x_n, x_m) \leqslant d(x_n, x_N) + d(x_N, x_m)$$

$$\leqslant 1 + C.$$

Let $K = \max\{2, 1 + C, C\}$. Then $\operatorname{diam}(\{x_n\}_{n \geqslant 1}) = \sup_{m,n \geqslant 1} d(x_n, x_m) \leqslant K$.

Definition 2.4.3. Let $(f_n)_n$ be a sequence of functions.

(1) $(f_n)_n$ converges pointwise to $f \in \mathcal{F}(\Omega, F)$ if:

$$(\forall x \in \Omega)(\forall \epsilon > 0)(\exists N_{x,\epsilon} \in \mathbf{N}) : (\forall n \in \mathbf{N})(n \geqslant N \implies |f_n(x) - f(x)| < \epsilon).$$

(2) $(f_n)_n$ converges uniformly to $f \in \mathcal{F}(\Omega, F)$ if:

$$(\forall \epsilon > 0)(\exists N_{\epsilon} \in \mathbf{N}) : (\forall n \in \mathbf{N})(\forall x \in \Omega)(n \geqslant N \implies |f_n(x) - f(x)| < \epsilon).$$

Example 2.4.1. Recall that a sequence $(f_n)_n$ converges to f in $Bd(\Omega, Y)$ if:

$$(D(f_n, f))_n \to 0$$
 in **R**.

But this is equivalent to:

$$\sup_{x \in \Omega} d(f_n(x), f(x)) \to 0 \text{ in } \mathbf{R}.$$

Again, we can rewrite this as:

$$(\forall \epsilon > 0)(\exists N \in \mathbf{N}) : (\forall n \in \mathbf{N}) \Big(n \geqslant N \implies \sup_{x \in \Omega} d(f_n(x), f(x)) < \epsilon \Big).$$

But this definition is equivalent to:

$$(\forall \epsilon > 0)(\exists N \in \mathbf{N}) : (\forall n \in \mathbf{N})(\forall x \in \Omega) \Big(n \geqslant N \implies d(f_n(x), f(x)) < \epsilon \Big).$$

This is precisely the definition of uniform convergence. Thus convergence in $c_{00} \subseteq c_0 \subseteq c \subseteq \ell_{\infty} \subseteq \ell_{\infty}(\Omega) = \operatorname{Bd}(\Omega, F)$ is uniform.

Proposition 2.4.3. Let $(d_k)_k$ be a separating family of semi-metrics which are uniformly bounded. Define:

$$d(x,y) := \sum_{k=1}^{\infty} 2^{-k} d_k(x,y).$$

Then $(x_n)_n \xrightarrow{d} x$ if and only if for all k, $(d_k(x_n,x))_n \to 0$.

Proof. Fix k. We have:

$$0 \leqslant 2^{-k} d_k(x_n, x) \leqslant d(x_n, x).$$

Note that $(x_n)_n \xrightarrow{d} x$ implies $(d(x_n, x))_n \to 0$. Multiplying both sides of the above equation by 2^k and applying the squeeze theorem gives $(d_k(x_n, x)) \to 0$.

Now let $\epsilon > 0$. Since each d_k is uniformly bounded, let $C = \sup_{k,x,y} d(x,y)$. Find K large so that:

$$\sum_{k>K} 2^{-k} < \frac{\epsilon}{2C}.$$

We know $(d_k(x_n, x))_n \to 0$ for k = 1, 2, ..., K. So there exists $N_1, N_2, ..., N_K$ with $n \ge N_k$ implying $d_k(x_n, x) < \frac{\epsilon}{2}$. Let $N = \max_{k=1}^K N_k$. For $n \ge N$, we have:

$$d(x_n, x) = \sum_{k=1}^K 2^{-k} d_k(x_n, x) + \sum_{k>K} 2^{-k} d_k(x_n, x)$$

$$= \sum_{k=1}^K 2^{-k} d_k(x_n, x) + \sum_{k>K} 2^{-k} C$$

$$< \sum_{k=1}^K 2^{-k} \frac{\epsilon}{2} + C \cdot \frac{\epsilon}{2C}$$

$$\leq \frac{\epsilon}{2} + \frac{\epsilon}{2}$$

$$= \epsilon.$$

Example 2.4.2. Let $X = C(\mathbf{R})$. How does one define a distance between two functions on this space? For $f, g \in C(\mathbf{R})$, one might naively consider the uniform metric:

$$d(f,g) := \sup_{x \in \Omega} |f(x) - g(x)|.$$

This construction does not guarantee $d(f,g) < \infty$. We can fix this as follows—for each $k \ge 1$, let:

$$P_k(f) = \sup_{x \in [-k,k]} |f(x)|.$$

Then $\{P_k\}_k = 1^{\infty}$ is a separating family of semi-norms which generate a separating family of semi-metrics:

$$\rho_k(f,g) := P_k(f-g).$$

These are not uniformly bounded, so make:

$$d_k(f,g) = \frac{\rho_k(f,g)}{1 + \rho_k(f,g)}.$$

Then $\{d_k\}_{k=1}^{\infty}$ is a family of uniformly bounded semi-metrics. We can now define the *Fréchet metric*:

$$d_F(f,g) := \sum_{k=1}^{\infty} 2^{-k} d_k(f,g).$$

In $(C(\mathbf{R}), d_F)$, observe that:

$$(f_n)_n \xrightarrow{d_F} f \iff \forall k, (d_k(f_n, f))_n \to 0$$

$$\iff \forall k, (\rho_k(f_n, f))_n \to 0$$

$$\iff \forall k, \left(\sup_{x \in [-k, k]} |f_n(x) - f(x)|\right)_n \to 0$$

$$\iff \forall k, (f_n)_n \to f \text{ uniformly on } [-k, k].$$

We've obtained a new type of convergence defined below.

Definition 2.4.4. Let (X, τ) be a topological space and (Y, d_Y) be a metric space. A sequence of functions:

$$f_n: X \to Y; n \in \mathbf{N}$$

converges compactly to $f: X \to Y$ if, for every compact set $K \subseteq X$, the sequence $(f_n|_K)_n \to f|_K$ converges uniformly.

Example 2.4.3. *** x^n does not converge uniformly but it does converge compactly (idk how to do this)

Example 2.4.4. Let (X, d), (Y, ρ) be metric spaces. There are different metrics we may put on $X \times Y$, for example:

- $D_1((x,y),(x',y')) = d(x,x') + \rho(y,y')$
- $D_2((x,y),(x',y')) = \sqrt{d(x,x')^2 + \rho(y,y')^2}$
- $D_{\infty}((x,y),(x',y')) = \max\{d(x,x') + \rho(y,y')\}.$

These metrics are all equivalent. A sequence of points $(x_n, y_n)_n$ converges to (x, y) in $X \times Y$ with respect to any of these metrics if and only if $(x_n)_n \stackrel{d}{\to} x$ and $(y_n)_n \stackrel{\rho}{\to} y$.

Example 2.4.5. Let $\{(X_k, d_k)_k\}_k$ be a family of metric spaces where the d_k are uniformly bounded. We looked at the product:

$$X = \prod_{k=1}^{\infty} X_k$$

with:

$$d(f,g) = \sum_{k=1}^{\infty} 2^{-k} d_k(f(k), g(k)).$$

We have that $(f_n)_n \xrightarrow{d} f$ if and only if $(f_n(k))_n \to f(k)$ for all k (pointwise convergence).

Example 2.4.6. Let $(V, \|\cdot\|)$ be a normed space. Then $(v_n)_n \to v$ if and only if $(\|v_n - v\|)_n \to 0$.

Definition 2.4.5. Let $(v_k)_k$ be a sequence in $(V, \|\cdot\|)$.

- (1) A sequence of partial sums $(s_n)_n$ is defined as $s_n = \sum_{k=1}^n v_k$.
- (2) If $(s_n)_n \to s$ in V we say the series $\sum_{k=1}^{\infty} v_k$ converges and write $\sum_{k=1}^{\infty} v_k = s$.
- (3) The series $\sum v_k$ converges absolutely if $\sum ||v_k||$ converges.

Proposition 2.4.4. Let (X,d) be a metric space and $A \subseteq X$. We have $x \in \overline{A}$ if and only if there exists a sequence $(a_n)_n$ in A with $(a_n)_n \to x$.

Proof. Let $x \in \overline{A}$. For each $n \ge 1$, we have $U(x, \frac{1}{n}) \cap A \ne \emptyset$, so choose $a_n \in U(x, \frac{1}{n}) \cap A$. Then $d(x, a_n) < \frac{1}{n}$, so $(a_n)_n \to x$.

Now suppose $(a_n)_n$ is a sequence in A and $(a_n)_n \to x$. Given $\epsilon > 0$, find N large so $d(x, a_N) < \epsilon$. Then $a_N \in U(x, \epsilon) \cap A$. Since $U(x, \epsilon) \cap A \neq \emptyset$, we have $x \in \overline{A}$.

Proposition 2.4.5. Let (X,d) be a metric space and $A \subseteq X$. The following are equivalent:

- (1) A is closed;
- (2) If $(a_n)_n$ is a sequence in A which converges to $x \in X$, then $x \in A$.

Proof. Consider the sequence $(a_n)_n$ in A with $(a_n)_n \to x$. Then by the previous proposition $x \in \overline{A}$. But since A is closed, $A = \overline{A}$. Thus $x \in A$.

To show A is closed we show $A = \overline{A}$. Clearly $A \subseteq \overline{A}$. Let $x \in \overline{A}$. Then there exists a sequence $(a_n)_n$ in A with $(a_n)_n \to x$. So $x \in A$ by (2). Thus $\overline{A} \subseteq A$.

Exercise 2.4.3. Show $x \in \overline{A}$ if and only if $x \in A$ or there exists a sequence $(a_n)_n$ in $A \setminus \{a\}$ with $(a_n)_n \to x$.

Example 2.4.7. *** The space $c_0 \subseteq \ell_{\infty}$ is closed, and furthermore $\overline{c_{00}} = c_0$. To see this, consider a sequence $(z_n)_n$ in c_0 converging to $f \in \ell_{\infty}$. We will show that $f \in c_0$.

Let $\epsilon > 0$ be given. Find N large so that:

$$||z_N - f||_u < \frac{\epsilon}{2}.$$

Since $z_N \in c_0$, we know $\lim_{k\to\infty} z_N(k) = 0$. So find K large so that for $k \ge K$:

$$|z_N(k)| < \frac{\epsilon}{2}.$$

Putting this all together, for $k \ge K$ we have:

$$|f(k)| = |f(k) - z_N(k) + z_N(k)|$$

$$\leq |f(k) - z_N(k)| + |z_N(k)|$$

$$< \frac{\epsilon}{2} + \frac{\epsilon}{2}$$

$$= \epsilon.$$

Thus $f \in c_0$. By Proposition 2.4.5, c_0 is closed.

Definition 2.4.6. Let (X,d) be a metric space and $A \subseteq X$. The *distance* of an element $x \in X$ to A is a map $\operatorname{dist}_A : X \to [0,\infty)$ defined by $\operatorname{dist}_A(x) = \inf_{a \in A} d(x,a)$.

Proposition 2.4.6. ***

§ 2.5. Continuity

Definition 2.5.1. Let (X, d) and (Y, ρ) be metric spaces. A map $f: X \to Y$ is *continuous* at $x_0 \in X$ if any of the equivalent definitions are satisfied:

$$(1) \ (\forall \epsilon > 0)(\exists \delta > 0) : (\forall x \in X) \Big(d(x, x_0) < \delta \implies \rho \big(f(x), f(x_0) \big) < \epsilon \Big)$$

$$(2) (\forall \epsilon > 0)(\exists \delta > 0) : (\forall x \in X) \Big(x \in U_X(x_0, \delta) \implies f(x) \in U_Y(f(x_0), \epsilon) \Big)$$

(3)
$$(\forall \epsilon > 0)(\exists \delta > 0) : f(U_X(x_0, \delta)) \subseteq U_Y(f(x_0), \epsilon)$$

Proposition 2.5.1. Let $f:(X,d) \to (Y,\rho)$ be a map between metric spaces and $x_0 \in X$. The following are equivalent:

(1) f is continuous at x_0 ;

(2)
$$(\forall V \in \mathcal{N}_{f(x_0)})(\exists U \in \mathcal{N}_{x_0}) : f(U) \subseteq V;$$

(3)
$$(\forall (x_n)_n \in X^{\mathbf{N}})((x_n)_n \to x_0 \implies (f(x_n))_n \to f(x_0))$$

Proof. $(1) \Rightarrow (2)$ follows from Definition 2.5.1.

 $(1)\Rightarrow(3)$ Let $(x_n)_n \to x_0$. Let $\epsilon > 0$. Since f is continuous, find $\epsilon > 0$ do that $x \in U(x,\delta)$ implies $f(x) \in U(f(x_0),\epsilon)$. Whence $d(f(x_n),f(x_0)) < \epsilon$, establishing $(f(x_n))_n \to f(x_0)$.

 $(3)\Rightarrow(1)$ We prove the contrapositive of this statement. If f is not continuous, choose $\epsilon_0 > 0$ so that $d(x_n, x_0) < \frac{1}{n}$ and $d(f(x_n), f(x_0)) \ge \epsilon_0$. Whence $(x_n)_n \to x_0$ and $(f(x_n))_n \not\to f(x_0)$.

Proposition 2.5.2. Let $f:(X,d)\to (Y,\rho)$ be a map of metric spaces. The following are equivalent:

- (1) f is continuous;
- (2) $(\forall V \in \tau_Y), f^{-1}(V) \in \tau_X;$

Proof. Let $V \subseteq Y$ be open. If $f^{-1}(V) = \emptyset$, we're done. If not, let $x \in f^{-1}(V)$. Then $f(x) \in V$. Since V is open, find $\epsilon > 0$ so that $U(f(x), \epsilon) \subseteq V$. Since f is continuous, find $\delta > 0$ so that $f(U(x, \delta)) \subseteq U(f(x), \epsilon) \subseteq V$. Whence $U(x, \delta) \subseteq f^{-1}(V)$.

Let $x \in X$ and $\epsilon > 0$. Since $U(f(x), \epsilon) \in \tau_Y$, we have $f^{-1}(U(f(x)), \epsilon) \in \tau_X$. Note that $x \in f^{-1}(U(f(x)), \epsilon)$. Since this set is open, find $\delta > 0$ so that $U(x, \delta) \subseteq f^{-1}(U(f(x)), \epsilon)$. Thus $f(U(x, \delta)) \subseteq U(f(x), \epsilon)$; i.e., f is continuous.

Proposition 2.5.3. Let $(X,d) \xrightarrow{f} (Y,\rho) \xrightarrow{g} (Z,\gamma)$ be maps of metric spaces. If f is continuous at $x \in X$ and g is continuous at y = f(x), then $g \circ f$ is continuous at x.

Proof. Exercise.
$$\Box$$

Proposition 2.5.4. Let (X,d) be a metric space with $A \subseteq X$ dense. Let $f: X \to F$ be a continuous and bounded function. Then $\sup_{x \in A} f(x) = \sup_{x \in X} f(x)$.

Proof. Since $A \subseteq X$ we have $\sup_{x \in A} f(x) \leqslant \sup_{x \in X} f(x)$. Conversely, let $\epsilon > 0$. Find $x' \in X$ so that $\sup_{x \in X} f(x) - \frac{\epsilon}{2} < f(x')$. Since f is continuous, find $\delta > 0$ so that for all $x \in X$, $d(x,x') < \delta$ implies $|f(x) - f(x')| < \frac{\epsilon}{2}$. Since A is dense, find $a \in A$ so that $d(x',a) < \delta$. This implies $|f(x') - f(a)| < \frac{\epsilon}{2}$, or equivalently $f(x') - \frac{\epsilon}{2} < f(a)$. This gives:

$$\sup_{x \in X} f(x) - \epsilon < f(a).$$

Hence for $\epsilon > 0$ we have:

$$\sup_{x \in X} f(x) < \sup_{x \in A} f(x) + \epsilon.$$

Taking $\epsilon \to 0$ gives $\sup_{x \in X} f(x) \leqslant \sup_{x \in A} f(x)$.

Definition 2.5.2. Let $f:(X,d)\to (Y,\rho)$ be a map of metric spaces.

(1) f is uniformly continuous if:

$$(\forall \epsilon > 0)(\exists \delta > 0) : (\forall x, x' \in X)(d(x, x') < \delta \implies \rho(f(x), f(x')) < \epsilon).$$

(2) f is Lipschitz if there exists C > 0 such that:

$$(\forall x, x' \in X)(\rho(f(x), f(x')) \leqslant Cd(x, x')).$$

If C < 1, we say f is contractive.

(3) f is isometric (or an isometry) if:

$$(\forall x, x' \in X)(\rho(f(x), f(x')) = d(x, x'))$$

Exercise 2.5.1. Show that Lipschitz implies uniform continuity. Show that uniform continuity implies continuity. Show that the converse direction fails in general.

Example 2.5.1. Let $(V, \|\cdot\|)$ be a normed space. Then $V \xrightarrow{\|\cdot\|} [0, \infty)$ is continuous. Indeed, we have $|\|v\| - \|w\|| \le \|v - w\|$, so $\|\cdot\|$ is Lipschitz.

Example 2.5.2. Let (X,d) be a metric space and equip $X \times X$ with the product metric D_1 . Claim: $d: X \times X \to [0,\infty)$ is continuous. Indeed, given $(x,y), (x',y') \in X \times X$, then we have:

$$d(x, y) \leq d(x, x') + d(x', y') + d(y', y).$$

So we have $d(x,y) - d(x',y') \leq d(x,x') + d(y,y')$. But this is equivalent to $|d(x,y) - d(x',y')| \leq D_1((x,y),(x',y'))$. So d is Lipschitz.

Example 2.5.3. If (X, d) is a metric space and $A \subseteq X$, then $\operatorname{dist}_A : X \to [0, \infty)$ is continuous. We've shown that $|\operatorname{dist}_A(x) - \operatorname{dist}_A(y)| \leq d(x, y)$, so dist_A is Lipschitz.

Definition 2.5.3. Let X be a topological space. We say X is *normal* (or T4) if, for any $A, B \subseteq X$ closed satisfying $A \cap B = \emptyset$, then there exists $U, V \in \tau_X$ with $A \subseteq U$, $B \subseteq V$ satisfying $U \cap V = \emptyset$.

Proposition 2.5.5. Metric spaces are normal.

Proof. Let $A, B \subseteq (X, d)$ with $A \cap B = \emptyset$. Define $f: (X, d) \to \mathbf{R}$ by:

$$f(x) = \frac{\operatorname{dist}_{A}(x)}{\operatorname{dist}_{A}(x) + \operatorname{dist}_{B}(x)}.$$

Then f is continuous. Moreover, define:

$$U := f^{-1} \left(\left(-\frac{1}{2}, \frac{1}{2} \right) \right)$$
$$V := f^{-1} \left(\left(-\frac{1}{2}, \frac{3}{2} \right) \right)$$

Then U and V open with $U \cap V = \emptyset$.

Proposition 2.5.6. Let V and W be normed spaces and $T: V \to W$ linear. The following are equivalent:

- (1) T is continuous at 0_V ;
- (2) T is continuous;
- (3) T is uniformly continuous;
- (4) T is Lipschitz;
- (5) there exists $C \ge 0$ such that $||Tv|| \le C ||v||$ for all $v \in V$;

(6) T is bounded.

Proof. We will show $(6)\Leftrightarrow(5)\Rightarrow(4)\Rightarrow(3)\Rightarrow(2)\Rightarrow(1)\Rightarrow(5)$. Let T be bounded. Given $v \in V$, $v \neq 0$, we have:

$$\begin{split} \|T\|_{\text{op}} &= \sup_{v \in B_V} \|Tv\| \\ &\geqslant \left\| T \frac{v}{\|v\|} \right\| \ \text{ for all } v \in V \\ &= \frac{1}{\|v\|} \|Tv\| \ \text{ for all } v \in V. \end{split}$$

Thus $||Tv|| \leq ||T||_{\text{op}} ||v||$ for all $v \in V$. The converse is clear by inspection.

Suppose there exists $C \ge 0$ satisfying (5). We have that $||Tv - Tv'|| \le C ||v - v'||$. Thus T is Lipschitz.

Let T be Lipschitz. Let $\epsilon > 0$ and find $\delta = \frac{\epsilon}{c}$. Then $||v - v'|| < \delta$ implies:

$$||Tv - Tv'|| \leqslant C ||v - v'||$$

$$< c \frac{\epsilon}{c}$$

$$= \epsilon.$$

Thus T is uniformly continuous.

Suppose that T be uniformly continuous. Fix $x \in V$. Given $\epsilon > 0$, we can find $\delta > 0$ so that $||v - x|| < \delta$ implies $||Tv - Tx|| < \epsilon$. Thus T is continuous at $x \in V$. Since x was arbitrary, T is continuous. Moreover, T will be continuous at 0_V , establishing (1).

We will now show (1) implies (5). Let $\epsilon = 1$. We can find a $\delta > 0$ such that $T(U(0,\delta)) \subseteq U(0,1)$. If $v \in V$, $v \neq 0$, then $\frac{\delta v}{2\|v\|} \in U(0,\delta)$. Since T is continuous at 0, we have $T\frac{\delta v}{2\|v\|} \in U(0,1)^1$. This gives $\left\|T\frac{\delta v}{2\|v\|}\right\| < 1$, which is equivalent to $\|Tv\| < \frac{2}{\delta}\|v\|$. This establishes (5).

Corollary 2.5.7. *** Let V be a normed space and $T: \ell_p^n \to V$ linear. Then T is uniformly continuous.

¹Recall that T(0) = 0.

Proof. Let $x \in \ell_p^n$ and $\mathcal{B} = \{e_1, ..., e_n\}$ a basis for ℓ_p^n . Find $\alpha_1, ..., \alpha_n$ so that:

$$||Tv|| = \left\| T \left(\sum_{j=1}^{n} \alpha_{j} e_{j} \right) \right\|$$

$$= \left\| \sum_{j=1}^{n} \alpha_{j} T e_{j} \right\|$$

$$\leqslant \sum_{j=1}^{n} |\alpha_{j}| ||T e_{j}||$$

$$\leqslant c \left\| \sum_{j=1}^{n} \alpha_{j} e_{j} \right\|_{1}$$

$$\leqslant c \cdot c' \left\| \sum_{j=1}^{n} \alpha_{j} e_{j} \right\|_{p},$$

where $c = \max_{j=1}^n ||Te_j||$ and $||\cdot||_1 \leqslant c' ||\cdot||_p$.

Proposition 2.5.8. Let (X,d) be a metric space with $A \subseteq X$ dense. If $f,g: X \to (Y,\rho)$ are continuous with f(a) = g(a) for all $a \in A$, then f = g.

Proof. If $x \in X$, we can find a sequence $(a_n)_n$ in A with $(a_n)_n \xrightarrow{d} x$. Then:

$$(f(a_n))_n \to f(x)$$

$$(g(a_n))_n \to g(x).$$

Thus f(x) = g(x).

Definition 2.5.4. Let (X, d) and (Y, ρ) be metric spaces and $f: X \to Y$.

- (1) f is a homeomorphism if f is bijective with f and f^{-1} continuous. If such an f exists, we say $X \cong Y$ are homeomorphic.
- (2) f is a uniformism if f is bijective with f and f^{-1} uniformly continuous. If such an f exists, we say $X \cong Y$ are uniformly isomorphic.
- (3) f is an metric isomorphism if f is bijective with f and f^{-1} Lipschitz. If such an f exists, we say $X \cong Y$ are metrically isomorphic.
- (4) f is an isometric isomorphism if f and f^{-1} are isometries. We say $X \cong Y$ are isometrically isomorphic.

Example 2.5.4. $(0,1) \cong \mathbf{R}$ are homeomorphic, but not uniformly isomorphic.

Example 2.5.5. *** Let $a = (a_k)_k \in \ell_1$. Define $\varphi_a : c_0 \to F$ by $\varphi_a(z) = \sum_{k \geqslant 1} a_k z_k$. This series converges since:

Definition 2.5.5. Let X be a set with two metrics d_1 and d_2 .

- (1) d_1 and d_2 are metrically equivalent if id: $(X, d_1) \to (X, d_2)$ and id⁻¹: $(X, d_2) \to (X, d_1)$ are Lipschitz.
- (2) d_1 and d_2 are uniformly equivalent if id: $(X, d_1) \to (X, d_2)$ and id⁻¹: $(X, d_2) \to (X, d_1)$ are uniformisms.
- (3) d_1 and d_2 are topologically equivalent if id: $(X, d_1) \to (X, d_2)$ and id⁻¹: $(X, d_2) \to (X, d_1)$ are homeomorphisms.

Example 2.5.6. ***

§ 2.6. Completeness

Definition 2.6.1. A sequence $(x_n)_n$ in a metric space (X,d) is d-Cauchy if:

$$(\forall \epsilon > 0)(\exists N \in \mathbf{N}) : (\forall p, q \in \mathbf{N})(p, q \geqslant N \implies d(x_p, x_q) < \epsilon).$$

Proposition 2.6.1. Let (x_n) be a sequence in (X, d).

- (1) If $(x_n)_n$ converges, then $(x_n)_n$ is Cauchy.
- (2) If $(x_n)_n$ is Cauchy, then $(x_n)_n$ is bounded.

Proof. (1) Let $x \in X$ and suppose $(x_n)_n \to x$. Let $\epsilon > 0$. Find N large so that for $p \ge N$ we have $d(x_p, x) < \frac{\epsilon}{2}$. Then $p, q \ge N$ implies:

$$d(x_p, x_q) \leq d(x_p, x) + d(x, x_q)$$

$$< \frac{\epsilon}{2} + \frac{\epsilon}{2}$$

$$= \epsilon.$$

(2) Let $\epsilon = 1$. Find N large so $p, q \ge N$ implies $d(x_p, x_q) < 1$. Let $C = \max_{1 \le p, q \le N} d(x_p, x_q)$. Without loss of generality, if $p \ge N$ and $q \le N$, then $d(x_p, x_q) \le d(x_p, x_N) + d(x_N, x_q) < 1 + C$. Set $K = \max\{1, 1 + C\}$. Then $\dim(\{x_n\}_{n \ge 1}) = \sup_{p, q \ge 1} d(x_p, x_q) < K$.

Proposition 2.6.2. Let $(x_n)_n$ be a Cauchy sequence in X and suppose there exists a subsequence $(x_{n_k})_k$ converging to $x \in X$. Then $(x_n)_n$ converges to x.

Proof. Let $\epsilon > 0$. Since $(x_n)_n$ is Cauchy, there exists N large so $n, n_k \geqslant N$ implies $d(x_n, x_{n_k}) < \frac{\epsilon}{2}$. This gives:

$$\begin{aligned} d(x_n, x) &= d(x_n, \lim_{k \to \infty} x_{n_k}) \\ &= \lim_{k \to \infty} d(x_n, x_{n_k}) \\ &\leqslant \frac{\epsilon}{2} \\ &\leqslant \epsilon. \end{aligned}$$

Definition 2.6.2. A metric space is said to be *complete* if every Cauchy sequence converges. A complete normed space is called a *Banach space*. A complete inner product space is called a *Hilbert space*.

Lemma 2.6.3. Let $f:(X,d) \to (Y,\rho)$ be uniformly continuous. If $(x_n)_n$ is d-Cauchy then $(f(x_n))_n$ is ρ -Cauchy.

Proof. Let $\epsilon > 0$. Find $\delta > 0$ so that $d(x, x') < \delta$ implies $\rho(f(x), f(x')) < \epsilon$. Pick N sufficiently large so that $p, q \ge N$ implies $d(x_p, x_q) < \delta$. This gives $\rho(f(x_p), f(x_q)) < \epsilon$, whence $(f(x_n))_n$ is ρ -Cauchy.

Corollary 2.6.4. If $f:(X,d) \to (Y,\rho)$ is a uniformism, then (X,d) is complete if and only if (Y,ρ) is complete.

Proof. Let (X,d) be complete. If $(y_n)_n$ is ρ -Cauchy, then $(f^{-1}(y_n))_n$ is d-Cauchy in X. So we can find some $x \in X$ such that $(f^{-1}(y_n))_n \to x$. Then $(f(f^{-1}(y_n)))_n = (y_n)_n \to f(x)$. The converse follows similarly.

Corollary 2.6.5. If d_1 and d_2 are uniformly equivalent metrics on a set X, then (X, d_1) is complete if and only if (X, d_2) is complete.

Proof. Since the map id: $(X, d_1) \to (X, d_2)$ is a uniformism, the previous corollary gives that (X, d_1) is complete if and only if (X, d_2) is complete.

Proposition 2.6.6. ℓ_p^d is a Banach space for $1 \leq p \leq \infty$.

Proof. We only need to show this for ℓ_{∞}^d since all the *p*-norms are equivalent. Let $(x_n)_n$ be $\|\cdot\|_{\infty}$ -Cauchy in ℓ_{∞}^d . Let $\epsilon > 0$. Find N large so for $n, m \ge N$ we have $\|x_n - x_m\|_{\infty} < \epsilon$. Observe that:

$$|x_n(k) - x_m(k)| \leqslant \max_{1 \leqslant k \leqslant d} |x_n(k) - x_m(k)|$$

$$= ||x_n - x_m||_{\infty}$$

$$< \epsilon.$$

where $x_n(k)$ is the k^{th} entry of the d-tuple x_n . So for each k = 1, ..., d, we know $(x_n(k))_n$ is Cauchy in F. Set $\lim_{n \to \infty} x_n(k) = x(k)$ for k = 1, ..., d. This gives:

$$||x - x_n||_{\infty} = \max_{1 \le k \le d} |x(k) - x_n(k)| \xrightarrow{n \to \infty} 0.$$

Whence $(x_n)_n \to x$ in ℓ_{∞}^d . Now set $y = (y_1, ..., y_n)$. We have:

$$\begin{aligned} \|x_n - y\|_p &\leqslant c' \|x_n - y\|_1 \\ &= c' \sum_{j=1}^d |x_n(j) - y_j| \\ &\leqslant c' \max_{1 \leqslant j \leqslant d} |x_n(j) - y_j| \xrightarrow{n \to \infty} 0. \end{aligned}$$

Thus ℓ_p^d is complete.

Proposition 2.6.7. ℓ_p is a Banach space for $1 \leqslant p \leqslant \infty$.

Proof. Suppose that $(f_n)_n$ is $\|\cdot\|_{\ell_n}$ -Cauchy. Observe that

$$|f_n(k) - f_m(k)|^p \le \sum_{j=1}^{\infty} |f_n(j) - f_m(j)|^p$$

= $||f_n - f_m||_{\ell_p}^p$

So $(f_n(k))_n$ is Cauchy in F. Since this space is complete, define $\liminf_{n\to\infty} f_n(k) := f(k)$. Our goal is to find some function $f: \mathbf{N} \to F$ satisfying $f \in \ell_p$ and $\|f_n - f\|_{\ell_p} \to 0$. The f(k) we've just obtained will lead us to the most suitable candidate.

Since $(f_n)_n$ is $\|\cdot\|_{\ell_p}$ -Cauchy, it is bounded by some constant. Fix $K \geqslant 1$ and observe that:

$$\sum_{k=1}^{K} |f(k)|^p = \sum_{k=1}^{K} \left| \lim_{n \to \infty} f_n(k) \right|^p$$

$$= \lim_{n \to \infty} \sum_{k=1}^{K} |f_n(k)|^p$$

$$\leq \sup_{n \geqslant 1} ||f_n||_{\ell_p}^p$$

$$:= C$$

Since the sequence $\left(\sum_{k=1}^K |f(k)|^p\right)_{K=1}^{\infty}$ is increasing and bounded above C, the Monotone Convergence Theorem says that it's limit exists. We obtain:

$$\lim_{K \to \infty} \sum_{k=1}^{K} |f(k)|^p = \sum_{k=1}^{\infty} |f(k)|^p$$
$$= ||f||_{\ell_p}^p$$
$$< \infty.$$

Thus $f \in \ell_p$.

It remains to show that $(f_n)_n$ converges to f. Given $\epsilon > 0$, find N large so that $n, m \ge N$ implies $||f_n - f_m||_p < \epsilon$. For every $n, m \ge N$ we have:

$$\sum_{k=1}^{K} |f_m(k) - f_n(k)|^p \le ||f_m - f_n||_{\ell_p}^p < \epsilon^p.$$

Taking the limit as $m \to \infty$ and considering all $n \geqslant N$ gives:

$$\sum_{k=1}^{K} |f(k) - f_n(k)|^p < \epsilon^p.$$

Finally, taking the limit as $K \to \infty$ and simplifying gives $||f - f_n||_{\ell_p} < \epsilon$. Thus ℓ_p is complete.

Proposition 2.6.8. Let (Y, d) be a complete metric space. The set of bounded functions $Bd(\Omega, Y)$ with $\|\cdot\|_n$ is complete.

Proof. Let $(f_n)_n$ be D_u -Cauchy. Fix $x, x' \in \Omega$ and let $\epsilon > 0$. Find N large so that $n, m \ge N$ implies:

$$d(f_n(x), f_m(x)) \leq D_u(f_n, f_m) < \epsilon.$$

Thus $(f_n(x))_n$ is Cauchy in Y. Since Y is complete, define $\liminf_{n\to\infty} f_n(x) := f(x)$. Now find N_1 large so $n \geqslant N_1$ implies $d(f(x), f_n(x)) < \epsilon$. Find N_2 large so $n \geqslant N_2$ implies $d(f(x'), f_n(x')) < \epsilon$. Observe that:

$$d(f(x), f(x')) \leq d(f(x), f_{N_1}(x)) + d(f_{N_1}(x), f_{N_2}(x')) + d(f_{N_2}(x'), f(x'))$$

$$< 2\epsilon + d(f_{N_1}(x), f_{N_2}(x'))$$

$$\leq 2\epsilon + d(f_{N_1}(x), f_{N_2}(x)) + d(f_{N_2}(x), f_{N_2}(x'))$$

$$\leq 2\epsilon + \sup_{n,m\geqslant 1} d(f_n(x), f_m(x)) + \sup_{x,x'\in\Omega} d(f_{N_2}(x), f_{N_2}(x'))$$

$$= 2\epsilon + \operatorname{diam}(\{f_n(x)\}_{n\geqslant 1}) + \operatorname{diam}(f_{N_2}(\Omega)).$$

Note that the sequence $(f_n(x))_n$ is bounded because it is Cauchy —so there exists $C_1 \ge 0$ such that $\operatorname{diam}(\{f_n(x)\}_{n\ge 1}) < C_1$. Moreover, since $f_{N_2} \in \operatorname{Bd}(\Omega, Y)$, there exists $C_2 \ge 0$ such that $\operatorname{diam}(f_{N_2}(\Omega)) < C_2$. This gives:

$$d(f(x), f(x')) < 2\epsilon + C_1 + C_2.$$

Since this inequality is independent of any n, and since $x, x' \in \Omega$ was arbitrary, we have that $\operatorname{diam}(f(\Omega)) < \infty$; i.e., $f \in \operatorname{Bd}(\Omega, Y)$. With the same ϵ as above, find N_3 large so that for all $n, m \ge N_3$ then $D_u(f_n, f_m) < \frac{\epsilon}{2}$. We know:

$$d(f_n(x), f_m(x)) \leqslant D_u(f_n, f_m) < \frac{\epsilon}{2}.$$

Taking $m \to \infty$ gives $d(f_n(x), f(x)) \leq \frac{\epsilon}{2}$ for all $n \geq N$. But note that N does not depend on our fixed $x \in \Omega$. It follows that $D_u(f_n, f) \leq \frac{\epsilon}{2} < \epsilon$. Thus $(f_n)_n \to f$, establishing $\mathrm{Bd}(\Omega, Y)$ as complete.

Corollary 2.6.9. $\ell_{\infty}(\Omega)$ is complete.

Proposition 2.6.10. Let (X, d) be a complete metric space and $Y \subseteq X$. Y is complete if and only if Y is closed.

Proof. Let $(y_n)_n$ be a sequence in Y converging to $x \in X$. Then $(y_n)_n$ is sequence in X. Since X is complete, $(y_n)_n$ is Cauchy. Since Y is complete, $(y_n)_n$ must converge to some $y \in Y$. Since sequences can have at most one limit, it must be that y = x. Thus $x \in Y$; i.e., Y is closed.

Conversely, if $(y_n)_n$ is Cauchy in Y, then it is Cauchy in X. Since X is complete, there exists $x \in X$ with $(y_n)_n \to x$. Since Y is closed, $x \in Y$. Thus Y is complete.

Proposition 2.6.10 and Proposition 2.4.5 are extremely useful tools for showing a space is complete.

Corollary 2.6.11. Let (X, d) and (Y, ρ) be metric spaces.

- (1) $C_b(X,Y) := C(X,Y) \cap \operatorname{Bd}(X,Y)$ is D_u -complete.
- (2) $C_b(X)$ is a $\|\cdot\|_u$ -Banach space.
- (3) $C_0(\mathbf{R})$ is a $\|\cdot\|_u$ -Banach space.

Proof. (1) Let $(f_n)_n$ be a sequence in $C_b(X,Y)$ converging to $f \in \text{Bd}(X,Y)$. Let $x \in X$ and $\epsilon > 0$. Find N large so that $D_u(f_N,f) < \frac{\epsilon}{3}$. Find $\delta > 0$ so that for all $x' \in X$, $d(x,x') < \delta$ implies $\rho(f_N(x),f_N(x')) < \frac{\epsilon}{3}$. For $d(x,x') < \delta$:

$$\rho(f(x), f(x')) \leq \rho(f(x), f_N(x)) + \rho(f_N(x), f_N(x')) + \rho(f_N(x'), f(x'))$$

$$\leq 2D_u(f_n, f) + \rho(f_N(x), f_N(x'))$$

$$< \frac{2\epsilon}{3} + \frac{\epsilon}{3}$$

$$= \epsilon.$$

Thus $f \in C_b(X,Y)$ because it is bounded and continuous. Since $C_b(X,Y) \subseteq Bd(X,Y)$ is closed, it is complete.

- (2) As we've just shown, the space $C_b(X)$ is complete. It only remains to show it is a vector space.
- (3) Let $(f_n)_n$ be a sequence in $C_0(\mathbf{R})$ converging to $f \in C_b(\mathbf{R})$. Let $\epsilon > 0$ and find N large so that $||f f_N||_u < \frac{\epsilon}{2}$. Since $f_N \in C_0(\mathbf{R})$, we know that $\liminf_{x \to \pm \infty} f_N(x) = 0$. So there exists M > 0 with $|x| \geqslant M$ implying $|f_N(x)| < \frac{\epsilon}{2}$. For $|x| \geqslant M$ observe that:

$$|f(x)| \le |f(x) - f_N(x)| + |f_N(x)|$$

$$\le ||f - f_N||_u + |f_N(x)|$$

$$< \frac{\epsilon}{2} + \frac{\epsilon}{2}$$

$$= \epsilon.$$

Thus $\lim_{x\to\infty} f(x) = 0$; i.e., $f \in C_0(\mathbf{R})$. Since $C_0(\mathbf{R}) \subseteq C_b(\mathbf{R})$ is closed, it is complete. \square

Proposition 2.6.12. Let V be a normed space and W a Banach space. B(V, W) with $\|\cdot\|_{op}$ is a Banach space.

Proof. Let $(T_n)_n$ be $\|\cdot\|_{\text{op}}$ -Cauchy. Let $v \in V$ and $\epsilon > 0$. Find N_1 large so that $n, m \ge N_1$ implies $\|T_n - T_m\|_{\text{op}} < \frac{\epsilon}{\|v\|}$. We can see:

$$||T_n v - T_m v||_W = ||(T_n - T_m)v||_W$$

$$\leq ||T_n - T_m||_{\text{op}} ||v||$$

$$< \frac{\epsilon}{||v||} \cdot ||v||$$

$$= \epsilon.$$

So $(T_n v)_n$ is $\|\cdot\|_W$ -Cauchy. Since W is a Banach space, define $\liminf_{n\to\infty} T_n v = Tv$. We must show that T is linear, bounded, and $\|T_n - T\|_{\text{op}} \to 0$. Given $v_1, v_2 \in V$ and $c \in F$ we

can see:

$$T(v_1 + cv_2) = \lim_{n \to \infty} T_n(v_1 + cv_2)$$

$$= \lim_{n \to \infty} T_n v_1 + cT_n v_2$$

$$= \lim_{n \to \infty} Tv_1 + c \lim_{n \to \infty} Tv_2$$

$$= Tv_1 + cTv_2.$$

Thus T is linear. Now since $(T_n)_n$ is $\|\cdot\|_{\text{op}}$ -Cauchy, it is bounded, so there exists C > 0 with $\|T_n\|_{\text{op}} \leq C$ for all $n \geq 1$. Using the fact norms are continuous, we have:

$$\begin{aligned} \|Tv\|_W &= \left\| \liminf_{n \to \infty} T_n v \right\|_W \\ &= \liminf_{n \to \infty} \|T_n v\|_W \\ &\leq \limsup_{n \to \infty} \|T_n\|_{\mathrm{op}} \|v\| \\ &\leq C \|v\| \,. \end{aligned}$$

Thus $T \in B(V, W)$. With the same epsilon as before, find N_2 so that $n, m \ge N_2$ implies $||T_n - T_m||_{\text{op}} < \frac{\epsilon}{2}$. We can show:

$$||T_n v - T_m v||_W \leqslant ||T_n - T_m||_{\text{op}} < \frac{\epsilon}{2}.$$

Taking $m \to \infty$ gives:

$$||T_n v - Tv||_W \leqslant \frac{\epsilon}{2}.$$

Taking the supremum over all $v \in B_V$ gives:

$$||T_n - T||_{\text{op}} \leqslant \frac{\epsilon}{2} < \epsilon.$$

Thus B(V, W) is complete.

Proposition 2.6.13. Let $(V, \|\cdot\|)$ be a normed space. The following are equivalent:

- (1) V is a Banach space;
- (2) If $(v_k)_k$ is a sequence in V with $\sum_{k=1}^{\infty} ||v_k||$ convergent, then $\sum_{k=1}^{\infty} v_k$ converges.

Proof. Suppose V is a Banach space. Let $s_n = \sum_{k=1}^n v_k$ and $t_n = \sum_{k=1}^n \|v_k\|$. For p > q > 1:

$$||s_p - s_q|| = \left\| \sum_{k=q+1}^p v_k \right\|$$

$$\leqslant \sum_{k=q+1}^p ||v_k||$$

$$= |t_p - t_k|.$$

Since $(t_n)_n$ is convergent, it is Cauchy. So $(s_n)_n$ is Cauchy, implying it is convergent. Thus $\sum_{k=1}^{\infty} v_k$ converges.

Now let $(v_n)_n$ be Cauchy. Find $n_1 \in \mathbf{N}$ such that $p, q \ge n_1$ implies $||v_p - v_q|| < 2^{-1}$. Find $n_2 > n_1$ such that $p, q \ge n_2$ implies $||v_p - v_q|| < 2^{-2}$. Inductively, find $n_k > n_{k-1}$ such that $p, q \ge n_k$ implies $||v_p - v_q|| < 2^{-k}$. Consider the sequence $(v_{n_{k+1}} - v_{n_k})_k$. Then:

$$\sum_{k=1}^{\infty} ||v_{n_{k+1}} - v_{n_k}|| \leqslant \sum_{k=1}^{\infty} 2^{-k} = 1.$$

By our hypothesis, $\sum_{k=1}^{\infty} (v_{n_{k+1}} - v_{n_k})$ converges. So the sequence of partial sums:

$$w_m = \sum_{k=1}^{m} v_{n_{k+1}} - v_{n_k}$$
$$= v_{n_m} - v_{n_1}$$

also converges to some $w \in V$ as $m \to \infty$. However, notice:

$$(v_{n_m})_m = (v_{n_m} - v_{n_1})_m + v_{n_1}$$

$$\xrightarrow{m \to \infty} w + v_{n_1}.$$

Since $(v_n)_n$ is a Cauchy sequence which admits a convergent subsequence, $(v_n)_n$ converges. Thus V is a Banach space.

Example 2.6.1. *** Let \mathcal{H} be a Hilbert space. Suppose $(e_n)_n$ is an orthonormal sequence in \mathcal{H} and $(t_k)_k \in \ell_2$. We will show $\sum_{k=1}^{\infty} t_k e_k$ converges in \mathcal{H} , but not absolutely in general. Let $s_n = \sum_{k=1}^n t_k e_k$. For n > m > 1:

$$||s_n - s_m||^2 = \left\| \sum_{k=m+1}^n t_k e_k \right\|^2$$

= $\sum_{k=m+1}^n |t_k|^2$.

Since $\left(\sum_{k=1}^{n}|t_{k}|^{2}\right)_{n}$ is Cauchy, then $(s_{n})_{n}$ is Cauchy, whence $\sum_{k=1}^{\infty}t_{k}e_{k}$ converges. But notice $\|s_{n}\|^{2} = \sum_{k=1}^{n}|t_{k}|^{2}$. As $n \to \infty$, we see $\|\sum_{k=1}^{\infty}t_{k}e_{k}\|^{2} = \sum_{k=1}^{\infty}|t_{k}|^{2}$.

Recall that if $f:(X,d) \to (Y,\rho)$ is a uniformly continuous map between metric spaces and $(x_n)_n$ is Cauchy, then $(f(x_n))_n$ is Cauchy. Complete spaces have the unique property that, given a map from a dense subset $A \to Y$, we can define an extension of such function.

Theorem 2.6.14. Let (X,d) and (Y,ρ) be metric spaces with Y complete. Suppose $A \subseteq X$ is dense and $f: A \to Y$ is uniformly continuous. There exists a unique uniformly continuous map $\widetilde{f}: X \to Y$ with $\widetilde{f}(x) = f(x)$ for all $x \in A$.

Proof. Let $x \in X$. We know there exists a sequence $(a_n)_n$ in A with $(a_n)_n \to x$. Since $(a_n)_n$ is convergent, it is Cauchy, so $(f(a_n))_n$ is also Cauchy. By the completeness of Y, $(f(a_n))_n$ converges. Define $\widetilde{f}(x) := \lim_{n \to \infty} f(a_n)$.

We must show this extension is well-defined. Suppose $(b_n)_n$ is another sequence in A with $(b_n)_n \to x$. Then the mixed sequence $(a_1, b_1, a_2, b_2, ...)$ will converge to x. The same reasoning as above tells us $(f(a_1), f(b_1), f(a_2), f(b_2), ...)$ converges in Y. The two subsequences $(f(a_n))_n$ and $(f(b_n))_n$ must then converge to the same limit.

We will now show that f is uniformly continuous. Let $\epsilon > 0$. Find $\delta > 0$ so that for all $a,b \in A,\ d(a,b) < \delta$ implies $\rho(f(a),f(b)) < \frac{\epsilon}{2}$. Now let $x,x' \in X$ with $d(x,x') < \frac{\delta}{4}$. Find sequences $(a_n)_n$ and $(b_n)_n$ in A with $(a_n)_n \to x$ and $(b_n)_n \to x'$. Find N large so that $n \geq N$ implies $d(a_n,x) < \frac{\delta}{4}$ and $d(b_n,x) < \frac{\delta}{4}$. The triangle inequality gives $d(a_n,b_n) < \frac{3\delta}{4} < \delta$. So $\rho(f(a_n),f(b_n)) < \frac{\epsilon}{2}$ for all $n \geq N$. Observe that:

$$\rho(\widetilde{f}(x), \widetilde{f}(x')) = \lim_{n \to \infty} \rho(f(a_n), f(b_n))$$

$$\leq \frac{\epsilon}{2}$$

$$< \epsilon.$$

Thus \widetilde{f} is uniformly continuous. It remains to show that \widetilde{f} is unique. Suppose $g: X \to Y$ is also a continuous extension of f. Then g(x) = f(x) = f(x) for all $x \in A$. Since g and \widetilde{f} agree on elements of a dense set, we must have $g = \widetilde{f}$.

Proposition 2.6.15. Let (X,d) and (Y,ρ) be metric spaces with $A \subseteq X$ dense, Y complete, and $f: A \to Y$ an isometry. Then the continuous extension $\widetilde{f}: X \to Y$ is an isometry.

Proof. Let $x, x' \in X$. Let $(a_n)_n$ and $(b_n)_n$ be sequences in A with $(a_n)_n \to x$ and $(b_n)_n \to x'$. We have:

$$\rho(\widetilde{f}(x), \widetilde{f}(x')) = \lim_{n \to \infty} \rho(f(a_n), f(b_n))$$

$$= \lim_{n \to \infty} d(a_n, b_n)$$

$$= d(x, x').$$

Corollary 2.6.16. Let V be a normed space, W a Banach space, and $U \subseteq V$ a dense linear subspace. Let $T_0 \in B(U, W)$. There exists a unique $T \in B(V, W)$ with $||T||_{\text{op}} = ||T_0||_{\text{op}}$. Moreover, if T_0 is isometric, then so if T.

Proof. We only need to show T is linear and $||T||_{\text{op}} = ||T_0||_{\text{op}}$. Let $v, v' \in V$ and $\alpha \in F$. Let $(x_n)_n$ and $(y_n)_n$ be sequences in U with $(x_n)_n \to v$ and $(y_n)_n \to v'$. Observe that:

$$T(v + \alpha v') = \lim_{n \to \infty} T_0(x_n + \alpha y_n)$$

=
$$\lim_{n \to \infty} T_0(x_n) + \alpha \lim_{n \to \infty} T_0(y_n)$$

=
$$T(v) + \alpha T(v').$$

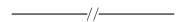
Note that the composition $V \xrightarrow{T} W \xrightarrow{\|\cdot\|_W} F$ will be continuous and bounded, so by

Proposition ?? we have:

$$\begin{split} \|T\|_{\text{op}} &= \sup_{v \in B_{V}} \|T(v)\| \\ &= \sup_{v \in B_{U}} \|T(v)\| \\ &= \sup_{v \in B_{U}} \|T_{0}(v)\| \\ &= \|T_{0}\|_{\text{op}} \,. \end{split}$$

Thus $T \in B(V, W)$.

Example 2.6.2. *** (Something about Hilbert spaces...)



Definition 2.6.3. Let (X,d) be a metric space. A *completion* of (X,d) is a pair $((Z,\rho),\iota)$ where:

- (1) (Z, ρ) is a complete metric space;
- (2) $\iota: X \hookrightarrow Z$ is an isometry;
- (3) $\overline{\iota(X)}^{\rho} = Z$.

Example 2.6.3. $(([0,1], ||\cdot||), \iota(t) = t)$ is a completion of (0,1).

Lemma 2.6.17. Let $f:(X,d)\to (Y,\rho)$ be an isometry between metric spaces. If X is complete, then $f(X)\subseteq Y$ is closed. In particular, if f(X) is dense, then f is onto.

Proof. If $(f(x_n))_n \to y$ in Y, then $(f(x_n))_n$ is ρ -Cauchy. Since f is an isometry, $d(x_n, x_m) = \rho(f(x_n), f(x_m))$, so $(x_n)_n$ is d-Cauchy. Let $x \in X$ such that $(x_n)_n \to x$. Since f is continuous, we have $(f(x_n))_n \to f(x)$. It must be that $y = f(x) \in f(X)$.

Since we've just shown that f(X) is closed, if it were also dense then $f(X) = \overline{f(X)}^{\rho} = Y$, whence f is surjective.

Theorem 2.6.18. Let (X,d) be a metric space. If $((Z,\rho),\iota)$ and $((Z',\rho'),\jmath)$ are completions of X, there exists a unique isometric isomorphism $\varphi:Z\to Z'$ with $\varphi\circ\iota=\jmath$; that is, the following diagram commutes:



Proof. Let $z \in Z$. Since $\iota(X)$ is dense in Z, there exists a sequence $(\iota(x_n))_n$ in $\iota(X)$ such that $(\iota(x_n))_n \to z$. It is clear that $(\iota(x_n))_n$ is ρ -Cauchy, and furthermore we have:

$$\rho'(\jmath(x_n), \jmath(x_m)) = d(x_n, x_m)$$

= $\rho(\iota(x_n), \iota(x_m)).$

So if $(\iota(x_n))_n$ is ρ -Cauchy, then $(\jmath(x_n))_n$ is ρ' -Cauchy. Since $\jmath(X)$ is complete, define $\varphi(z) := \lim_{n \to \infty} \jmath(x_n)$.

We will show that $\varphi: Z \to Z'$ is well-defined, that is, it does not depend on our particular choice of sequence. Let (y_n) be another sequence in X with $(y_n)_n \to z$. We can see that:

$$d(x_n, y_n) = \rho(\iota(x_n), \iota(y_n))$$

$$\leq \rho(\iota(x_n), z) + \rho(z, \iota(y_n))$$

$$\to 0$$

which gives:

$$\rho'(\jmath(y_n), \varphi(z)) \leq \rho'(\jmath(y_n), \jmath(x_n)) + \rho'(\jmath(x_n), \varphi(z))$$

$$= d(y_n, x_n) + \rho'(\jmath(x_n), \varphi(z))$$

$$\to 0.$$

Thus $(j(y_n))_n \to \varphi(z)$, so φ is well-defined.

We will now show that φ is an isometric isomorphism. Given $z_1, x_2 \in Z$, let $(\iota(x_n))_n \to z_1$ and $(\iota(y_n))_n \to z_2$, corresponding to $(\jmath(x_n))_n \to \varphi(z_1)$ and $(\jmath(y_n))_n \to \varphi(z_2)$. Observe that:

$$\rho'(\varphi(z_1), \varphi(z_2)) = \lim_{n \to \infty} \rho'(\jmath(x_n), \jmath(y_n))$$

$$= \lim_{n \to \infty} d(x_n, y_n)$$

$$= \lim_{n \to \infty} \rho(\iota(x_n), \iota(y_n))$$

$$= \rho(z_1, z_2).$$

Since φ is an isometry, it is injective. Clearly $\varphi \circ \iota = \jmath$ holds, so we have $\jmath(X) = \varphi(\iota(X)) \subseteq \varphi(Z)$. Then $Z' = \overline{\jmath(X)}^\rho \subseteq \overline{\varphi(Z)}$. Since Z is complete, by the previous lemma $\varphi(Z)$ is closed, whence $Z' \subseteq \varphi(Z) = \varphi(Z)$. Thus φ is onto.

It remains to show that φ is unique. Let $\psi: Z \to Z'$ be another isometric isomorphism satisfying $\psi \circ \iota = \jmath$. Given $z \in Z$, we can find a sequence $(\iota(x_n))_n$ in $\iota(X)$ such that $(\iota(x_n))_n \to z$. Observe that:

$$\varphi(z) = \lim_{n \to \infty} \varphi(\iota(x_n))$$

$$= \lim_{n \to \infty} \jmath(x_n)$$

$$= \lim_{n \to \infty} \psi(\iota(x_n))$$

$$= \psi(z).$$

Since $z \in Z$ was arbitrary, this proves $\varphi = \psi$.

Lemma 2.6.19. If (X,d) is a metric space and $i:(X,d)\to (Y,\rho)$ is an isometry into a complete metric space (Y,ρ) , then $\left(\overline{(i(X)}^\rho,\rho\right),i\right)$ is a completion of X.

Proof. The space $(\overline{i(X)}^{\rho}, \rho)$ is complete by Proposition 2.6.10. Clearly $i: X \to \overline{i(X)}^{\rho}$ is an isometry because $\overline{i(X)}^{\rho} \subseteq Y$.

Theorem 2.6.20. Every metric space admits a unique completion up to isometric isomorphism.

Proof. Uniqueness was shown in Theorem 2.6.18. Given (X,d), consider the Banach space $(C_b(X), \|\cdot\|_u)$. By the previous lemma we only need to construct an isometry $X \stackrel{i}{\hookrightarrow} C_b(X)$. Fix any $x_0 \in X$. Define $f_x : X \to F$ by $f_x(t) = d(t,x) - d(t,x_0)$. Clearly f_x is continuous, and it is bounded because $|f_x(t)| = |d(t,x) - d(t,x_0)| \le d(x,x_0)$. So $f_x \in C_b(X)$. Now define $i : X \to C_b(X)$ by $x \mapsto f_x$. Observe that:

$$||f_x - f_y||_u = \sup_{t \in X} |f_x(t) - f_y(t)|$$

$$= \sup_{t \in X} |d(t, x) - d(t, x_0) - d(t, y) + d(t, x_0)|$$

$$= \sup_{t \in X} |d(t, x) - d(t, y)|$$

$$= d(x, y).$$

Thus i is an isometry, making $\left(\left(\overline{i(X)}^{\|\cdot\|_u}, \|\cdot\|_u\right), i\right)$ a completion of X.

Theorem 2.6.21. Let (X,d) be a metric space with completion $((Z,\rho),i)$. If $f:X\to Y$ is a uniformly continuous function into a complete metric space Y, then there exists a unique uniformly continuous function $\widetilde{f}:Z\to Y$ such that $\widetilde{f}\circ i=f$; i.e., the following diagram commutes:

$$X \xrightarrow{i} Z$$

$$f \xrightarrow{\widetilde{f}} \widetilde{f}$$

$$Y$$

Proof. Define $g:i(X)\to Z$ by $g=f\circ i^{-1}$. Since g is uniformly continuous and $i(X)\subseteq Z$ is dense, Theorem 2.6.14 says there exists a unique uniformly continuous map $\widetilde{f}:Z\to Y$. Clearly $\widetilde{f}\circ i=f$.

Theorem 2.6.22. Let $(V, \|\cdot\|)$ be a normed space. The metric space completion $((W, \rho), i)$ has the structure of a Banach space with $\rho(w_1, w_2) = \|w_1 - w_2\|_W$.

Proof. We have the first define what the vector space operations of W are. Let $w \in W$ and $\alpha \in F$. We know there exists a sequence $(i(v_n))_n$ in i(V) converging to w. Since this sequence is convergent, it is ρ -Cauchy. From the following:

$$\rho(i(\alpha v_n), i(\alpha v_m)) = \|\alpha v_n - \alpha v_m\|$$

$$= |\alpha| \|v_n - v_m\|$$

$$= |\alpha|\rho(i(v_n), i(v_m)),$$

we can see $(i(\alpha v))_n$ is also ρ -Cauchy, whence it is convergent. Define scalar multiplication by $s: F \times W \to W$ with $s(\alpha, w) = \lim_{n \to \infty} i(\alpha v_n) := \alpha w$. We will first show that this action is well-defined. Let $(i(u_n))_n$ be another sequence in i(V) converging to w. As above, we have:

$$\rho(i(\alpha v_n), i(\alpha u_n)) = |\alpha|\rho(i(v_n), i(u_n))$$

$$\leq \alpha(\rho(i(v_n), w) + \rho(w, i(u_n)))$$

$$\to 0.$$

This gives:

$$\rho(i(\alpha u_n), \alpha w) \leqslant \rho(i(\alpha u_n))$$