

# Mingxuan Li (李明暄)

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## EDUCATION BACKGROUND

**Master: Tsinghua University**, Beijing, China 09/2023–Present

- Laboratory: [AutoRobot Lab](#), Department of Mechanical Engineering
- GPA: Overall: **3.90/4.00**
- Advisors: Prof. [Yao Jiang](#)

**Visiting: Massachusetts Institute of Technology**, Cambridge, U.S. 01/2025–04/2025

- Laboratory: Computer Science and Artificial Intelligence Lab ([CSAIL](#))
- Supervisor: Prof. [Edward H. Adelson](#)

**Bachelor: Tsinghua University**, Beijing, China 09/2019–07/2023

- Major: Mechanical Engineering
- GPA: Overall: **3.72/4.00**

## PUBLICATIONS & PATENTS

- Research Interests: ***Robotics Tactile Perception & Grasping, Vision-Based Tactile Sensors, Contact Modelling***
- Skills: C/C++, Python, OpenCV, PyTorch, MATLAB, AutoCAD, SolidWorks, Abaqus, Ansys, Unity, PS, PR, *et al.*

### Research Paper & Preprint

- Mingxuan. Li** and Yuxiang. Ma, “Evaluation of viscoelastic contact effects on grasping”, submitted to *IEEE Transactions on Automation Science and Engineering (TASE)*. Jun. 2025.
- Mingxuan. Li**, Lunwei. Zhang, Qiyin. Huang, Tiemin. Li, and Yao. Jiang, “Modeling, simulation, and application of spatio-temporal characteristics detection in incipient slip”, in revision to *IEEE Transactions on Robotics (TRO)*. Feb. 2025. [\[arXiv\]](#) [\[Preprint PDF\]](#)
- Mingxuan. Li**, Lunwei. Zhang, Tiemin. Li, and Yao. Jiang, “Learning gentle grasping from human-free force control demonstration”, *IEEE Robotics and Automation Letters (RA-L)*, vol. 10, no. 3, pp. 2391-2398, Mar. 2025. [\[Publication\]](#) [\[Preprint PDF\]](#) [\[Video\]](#)
- Mingxuan. Li**, Yen. Hang. Zhou, Lunwei. Zhang, Tiemin. Li, and Yao. Jiang, “OneTip: A soft tactile interface for 6-D fingertip pose acquisition in human-computer interaction”, *Sensors and Actuators: A. Physical (SNA)*, vol. 379, Sep. 2024, Art no. 115896. [\[Publication\]](#) [\[Preprint PDF\]](#) [\[Video\]](#)
- Mingxuan. Li**, Lunwei. Zhang, Yen. Hang. Zhou, Tiemin. Li, and Yao. Jiang, “EasyCalib: Simple and low-cost in-situ calibration for force reconstruction with vision-based tactile sensors”, *IEEE Robotics and Automation Letters (RA-L)*, vol. 9, no. 9, pp. 7803-7810, Sep. 2024. [\[Publication\]](#) [\[Preprint PDF\]](#) [\[EasyCalib\]](#)
- Mingxuan. Li**, Yen. Hang. Zhou, Tiemin. Li, and Yao. Jiang, “Incipient slip-based rotation measurement via visuotactile sensing during in-hand object pivoting”, *2024 IEEE International Conference on Robotics and Automation (ICRA)*, pp. 17132-17138, Aug. 2024. [\[Publication\]](#) [\[Preprint PDF\]](#) [\[Video\]](#) [\[Poster\]](#) [\[Slides\]](#)
- Mingxuan. Li**, Yen. Hang. Zhou, Tiemin. Li, and Yao. Jiang, “Real-time and robust feature detection of continuous marker pattern for dense 3-d deformation measurement”, *Measurement*, vol. 221, Nov. 2023, Art no. 113479. [\[Publication\]](#) [\[Preprint PDF\]](#)
- Mingxuan. Li**, Yen. Hang. Zhou, Tiemin. Li, and Yao. Jiang, “Improving the representation and extraction of contact information in vision-based tactile sensors using continuous marker pattern”, *IEEE Robotics and Automation Letters (RA-L)*, vol. 8, no. 2, pp. 1109-1116, Sep. 2023. [\[Publication\]](#) [\[Preprint PDF\]](#)
- Mingxuan. Li**, Tiemin. Li, and Yao. Jiang, “Marker displacement method used in vision-based tactile sensors—from 2D to 3D: A review”, *IEEE Sensors Journal (Sensors J.)*, vol. 23, no. 8, pp. 8042-8059, Apr. 2023. [\[Publication\]](#) [\[Preprint PDF\]](#)
- Mingxuan. Li**, Lunwei. Zhang, Tiemin. Li, and Yao. Jiang, “Continuous marker patterns for representing contact information in vision-based tactile sensor: principle, algorithm, and verification”, *IEEE Transactions on Instrumentation and Measurement (TIM)*, vol. 71, Aug. 2022, Art no. 5018212. [\[Publication\]](#) [\[Preprint PDF\]](#)

## Patent Application

- Yao. Jiang, **Mingxuan. Li**, Lunwei. Zhang, and Tiemin. Li, “Tactile sensor, robot, method and apparatus for achieving tactile information acquisition”, Application No. 202210061023.8, Publish No. CN 114544052B, 2023-03-28.
- **Mingxuan. Li**, Aijun. Yang, Yanping. Xu, Xue. Qi, and Dongqin. Li, “Method, apparatus, and electronic device for detecting image sticking in display screen”, Application No. 202211286586.3, Publish No. CN 115509040A, 2022-12-23.
- **Mingxuan. Li**, Yanping. Xu, Xue. Qi, Dongqin. Li, and Fan. Wang, “Method and apparatus for touch screen detection”, Application No. 202111074563.1, Publish No. CN 113984337A, 2022-01-28.

## SELECTED AWARDS AND HONORS

### Academic Awards

- Awarded the Wang Dazhong Scholarship (**One of the highest awards for students at Tsinghua University**) in 2024 Tsinghua Scholarship Awards Ceremony 12/2024
- **Shortlisted for Tsinghua Top Grade Scholarship (Prestigious Scholarship, 清华大学特等奖学金) in 2024 (five master students per year from all departments and grades)** 11/2024
- Exceptionally awarded the **Comprehensive Excellent First-Class Scholarship** as a first-year graduate 11/2023
- **Excellent Graduates** of Tsinghua University, 2023 06/2023
- Named the **Person of the Year** in the Department of Mechanical Engineering, Tsinghua University 04/2023
- **Neng Ke Scholarship**, Tsinghua University (**Highest amount** in M.E. department, **Top 2%** of 300) 11/2022
- **Comprehensive Outstanding Award Scholarship**, Tsinghua University (**Top 5%** of 126) 11/2021
- **1st Prize** in National Zhou Peiyuan Mechanics Competition, 2021 (**Top 0.2%**) 08/2021
- **1st Prize** in National Undergraduate Physics Competition, 2020 (**Top 1%**) 12/2020

### Research Performances

- **Excellent Oral Presentation**, The 777th Doctoral Academic Forum of Tsinghua University 04/2025
- **Excellent Oral Presentation**, The 734th Doctoral Academic Forum of Tsinghua University 04/2024
- **Excellent academic paper**, The 16th National Conference on Undergraduate Innovation 12/2023
- **Outstanding Graduation Thesis** of Tsinghua University, 2023 06/2023
- **1st Place** in “New Engineering” Undergraduate Graduation Thesis Competition 06/2023
- **Project leader** of iStar Program from the Fundamental Industry Training Center, Tsinghua University (**Excellent rating**) 05/2023
- **Best Poster Award** and **Excellent Oral Presentation Award** at Tsinghua Youth Science and Innovation Forum 03/2023
- **Grand Prize of Outstanding Project** of 2022 Tsinghua University Student Research Training (SRT) Program for Undergraduates (**Top 5 of 1938**, and was **the only single person study** among them) 12/2022
- **Project leader** of National Training Program of Innovation and Entrepreneurship for Undergraduates (**Excellent rating**) 06/2022
- **Project leader** of A-level Tsinghua University Initiative Scientific Research Program (**Excellent rating**) 05/2022
- Served as the co-first author, led the team to win the **only Grand Prize in Tsinghua Craftsmanship Awards, 2022** (Received the award from **the President of Tsinghua University as the only representative**, and was **widely reported by mainstream medias in China**, including the report of **Xinhua News** with over **1.3 million views**) 04/2022
- Selected to **“Spark” Innovative Talent Cultivation Program** (**Top 2%** for outstanding research performance) 03/2022

### Innovation & Entrepreneurship

**Student head** of the ‘*ClearTactile*’ tech startup team

- **Team of Excellence**, 2024 China-U.S. Young Maker Centers Annual Conference 05/2024
- **Grand Prize** in the 2023 “Challenge Cup” Capital Science and Technology College of Extra-curricular Academic Competition 06/2023
- **4th Place** in the “Kunshan Cup” 24th Tsinghua University Entrepreneurship Competition 03/2023
- **Bronze Award** in the 8th China College Students’ “Internet+” Innovation and Entrepreneurship Competition, National Finals 12/2022
- **3rd Place** in the 4th “Beijing-Tianjin-Hebei and Guangdong-Hong Kong-Macao” Youth Innovation Competition 09/2022
- **1st Prize** in the 8th China College Students’ “Internet+” Innovation and Entrepreneurship Competition, Beijing Area 07/2022

- **The Top Ten Teams** in the China College Students' "Internet+" Innovation and Entrepreneurship Competition, Tsinghua University, 2022 (The only undergraduate student team)

06/2022

## **COMMUNITY SERVICE AND LEADERSHIP**

- Reviewer: *ICRA 2024, ICRA 2025 (twice), IEEE Transactions on Instrumentation and Measurement (twice), Measurement, Visual Computer, Scientific Reports (twice), Recent Patents on Mechanical Engineering*
- Serves as **Vice President and Academic Affairs Representative of the Graduate Association**, Department of Mechanical Engineering, Tsinghua University.
- Served as **Chairman of the Sub-forum** "Robotics and Intelligent Manufacturing" and the **Organizational Committee Member**, The 777th Doctoral Academic Forum of Tsinghua University.
- Served as **Chairman of the Sub-forum** "Key Components and Equipment" and the **Organizational Committee Member**, The 734th Doctoral Academic Forum of Tsinghua University.
- **Former Vice President** of Hunan Cultural Student Association of Tsinghua, in charge of science & innovation and lecture activities.
- **Invited to give a keynote speech** at the 2022 Tsinghua Maker's Day New Age Creativity Education Forum.

## **OTHER RESEARCH&STUDY EXPERIENCE**

### **China-Italy Laboratory on Advanced Manufacturing (CILAM) Summer School 2025**

07/2025–08/2025

*University of Bergamo and Federico II University of Naples*

- Participate in lectures on topics such as Sustainability and Circularity, Additive Manufacturing, Robotics, Smart Energy & Electrification, and New Business Models.
- Visit innovation hubs including San Giovanni Academy, CeSMA Laboratory, and the Kilometro Rosso Innovation District

### **Research on designing and building new robot tactile sensors**

01/2025–04/2025

*Visiting Research, MIT CSAIL, supervised by Prof. Edward H. Adelson*

- Design, build, and test novel robot tactile sensors for robotic manipulation.
- Evaluate the effects of viscoelasticity on robotic grasping based on contact modeling.

### **Research on the Artificial Intelligence Industry and Market**

07/2024–09/2024

*Interned in Equity Investment Department, Tsinghua Tongfang Technology Co., Ltd.*

- Research and analyze the development, industrial layout, and investment opportunities of the artificial intelligence industry.
- Write a detailed research report for internal reference within the company.

### **Research on Representation and Extraction of Robotic Tactile information**

04/2021–07/2023

*Student Research Training Program, supervised by Prof. Yao Jiang, Tsinghua University*

- Served as the sole participant (student), focused on improving the representation and extraction of tactile representation.
- Developed tactile sensor prototypes and verified the high-precision, high-resolution, and high-reliability.

*Self-Initiated Research Interest Group for Undergraduates, supervised by Prof. Yao Jiang, Tsinghua University*

- Served as the **student leader** of "Tactile Information Representation and Extraction" undergraduate research group.
- Developed a tactile sensor with the advantages of high information density, 3D information, compactness, etc., and initially realized the adaptive application of robot grasping and control

### **Research on Innovation and Application of Intelligent Software Testing**

01/2021–02/2021, 07/2022–08/2022

*Interned in LCFC Luzhou Laboratory, LCFC (Hefei) Electronics Technology Co., Ltd.*

- Studied the detection device of LCD touch screen based and the detection method of image sticking in LCD screen.
- The first case in the company's patent application that was granted both invention patent and utility model patent.

### **Studying on Under-Actuated Robotic Hands and Soft Robots**

09/2020–04/2021

*Independent Research, supervised by Prof. Wenzhen Zhang, Tsinghua University*

- Studied the basic theory of robotic grasping and manipulation based on the underactuated mechanism and soft brake
- Proposed a soft robot hand based on self-curling underactuated structure and developed the prototypes.