```
I = im2double(imread('.\Data\77_8.bmp'));
subplot(2,3,1);imshow(I);
title("原图");
```



计算特征频率图、最大幅度图和方向图(分成 Cos 图和 Sin 图)

```
[W, H] = size(I);

% 由于 8*8 实在太小,造成特征不够突出

% 因此取其邻域 32*32 来当作特征

% 虽然变成 32*32,但主要还是以左上的 8*8 为特征图

% 因此新高宽如下的 M 和 N

M = floor(W/8) - 3;

N = floor(H/8) - 3;

% 矩阵初始化

freq = zeros(M,N); %频率图
```

```
mag = zeros(M,N); % 最大幅度图
angs = zeros(M, N); % 角度图
Sin = zeros(M, N); % Sin 图
Cos = zeros(M, N); \% Cos 
for i = 1:M
    for j = 1:N
         I1 = I(i*8-7:min(i*8 + 24, end), j*8-7:min(j*8 + 24, end));
         dft = fftshift(fft2(I1,32,32));
         dft = abs(dft);
         dft(17,17) = 0;%去除直流分量
         [maxi, maxj] = MaxPoint(dft);
         freq(i, j) = sqrt((maxi - 17)^2 + (maxj - 17)^2);
         mag(i, j) = dft(maxi, maxj);
         % 将角度图分成 Cos 图和 Sin 图
         {\rm angs(i,\,j)} = {\rm atan((maxj\text{-}17)/(maxi\text{-}17))};
         Sin(i, j) = sin(angs(i, j) * 2);
         Cos(i, j) = cos(angs(i, j) * 2);
end
mask = zeros(size(freq));
% 经过调参取得的参数
mask(mag > 10 \& freq < 8 \& freq > 0.9) = 1;
```

抠出指纹区

```
newmask = zeros(size(I));
[W, H] = size(I);
```

```
for i = 1:W

for j = 1:H

x = ceil(i / 8);

y = ceil(j / 8);

if mask(min(x,M),min(y,N)) == 1

newmask(i, j) = 1;

end

end

end

NewI = I .* newmask;

subplot(2,3,2);imshow(NewI);

title("仅有指纹区");

imwrite(NewI, ".\Data\77_8_with_mask.bmp");
```





```
orientimage = zeros(8*M,8*N); % 方向图初始化

for i = 1:M

if mask(i,j) == 1

% 绘制初始方向图

line = zeros(8,8);

line(4:5,:) = 1;

line = imrotate(line, angs(i,j) * 180 / pi, 'bicubic', 'crop');

orientimage(8*i-7:8*i, 8*j-7:8*j) = line;

end

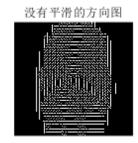
end

end

subplot(2,3,3);imshow(orientimage);
title("没有平滑的方向图");
imwrite(orientimage, "AData\77_8_orientimage.bmp");
```







对 Sin 图、Cos 图和频率图做空域平滑

```
h = ones(3,3) ./ 9;

Sin = imfilter(Sin, h);

Cos = imfilter(Cos, h);

freq = imfilter(freq, h);

angs = atan2(Sin, Cos) / 2;

filterimage = zeros(size(I)); % 新图像初始化

H = ones(32,32);

fori = 1:M

for j = 1:N

if mask(i,j) == 1

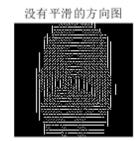
% 绘制平滑后方向图

line = zeros(8.8);
```

```
line(4:5,:) = 1;
              line = imrotate(line, angs(i,j) * 180 / pi, 'bicubic', 'crop');
              orientimage(8*i-7:8*i, 8*j-7:8*j) = line;
              % 利用 Gabor 滤波器进行特征提取
              I1 = I(i*8-7:min(i*8 + 24, end), j*8-7:min(j*8 + 24, end));
              [mag, phase] = imgaborfilt(I1,10, angs(i,j) * 180 / pi - 90);
              % 取中间的滤波结果当作特征
              filterimage(i*8-7:i*8,j*8-7:j*8) = mag(13:20, 13:20) .* cos(phase(13:20, 13:20));
    end
end
subplot(2,3,4);imshow(orientimage);
title("平滑后的方向图");
imwrite(orientimage, ".\Data\77_8_orientimage_smoothing.bmp");
subplot(2,3,5);imshow(filterimage);
title("刚滤波完的图");
imwrite (filterimage, ".\Data\77\_8\_filterimage.bmp");
```







平滑后的方向图



先做像素的线性拉伸

%filterimage = imadjust(filterimage, [0, max(max(filterimage))], [0,1],1);

% 再进行亮度调整

newfilterimage = filterimage;

newfilterimage(filterimage > 0.01) = 1;

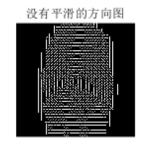
subplot(2,3,6);imshow(newfilterimage);

title("亮度增强图");

imwrite(newfilterimage, ".\Data\77_8_filterimage_final.bmp");







平滑后的方向图





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