```
function varargout = Question1(varargin)
% QUESTION1 MATLAB code for Question1.fig
      QUESTION1, by itself, creates a new QUESTION1 or raises the
existing
%
      singleton*.
      H = QUESTION1 returns the handle to a new QUESTION1 or the
handle to
      the existing singleton*.
      QUESTION1('CALLBACK', hObject, eventData, handles,...) calls the
local
      function named CALLBACK in QUESTION1.M with the given input
arguments.
      QUESTION1('Property','Value',...) creates a new QUESTION1 or
raises the
      existing singleton*. Starting from the left, property value
pairs are
      applied to the GUI before Question1_OpeningFcn gets called. An
      unrecognized property name or invalid value makes property
application
      stop. All inputs are passed to Question1_OpeningFcn via
varargin.
2
      *See GUI Options on GUIDE's Tools menu. Choose "GUI allows
only one
      instance to run (singleton)".
% See also: GUIDE, GUIDATA, GUIHANDLES
% Edit the above text to modify the response to help Question1
% Last Modified by GUIDE v2.5 31-Oct-2019 16:37:19
% Begin initialization code - DO NOT EDIT
qui Singleton = 1;
gui_State = struct('gui_Name',
                                     mfilename, ...
                   'gui_Singleton', gui_Singleton, ...
                   'gui_OpeningFcn', @Question1_OpeningFcn, ...
                   'gui_OutputFcn', @Question1_OutputFcn, ...
                   'gui_LayoutFcn', [], ...
                   'gui_Callback',
                                     []);
if nargin && ischar(varargin{1})
   gui_State.gui_Callback = str2func(varargin{1});
end
if nargout
    [varargout{1:nargout}] = gui_mainfcn(gui_State, varargin{:});
   gui_mainfcn(gui_State, varargin{:});
end
```

1

```
% End initialization code - DO NOT EDIT
% --- Executes just before Question1 is made visible.
function Question1_OpeningFcn(hObject, eventdata, handles, varargin)
% This function has no output args, see OutputFcn.
% hObject
           handle to figure
% eventdata reserved - to be defined in a future version of MATLAB
% handles structure with handles and user data (see GUIDATA)
% varargin command line arguments to Question1 (see VARARGIN)
% Choose default command line output for Question1
handles.output = hObject;
% Update handles structure
quidata(hObject, handles);
% UIWAIT makes Question1 wait for user response (see UIRESUME)
% uiwait(handles.figure1);
% --- Outputs from this function are returned to the command line.
function varargout = Question1_OutputFcn(hObject, eventdata, handles)
% varargout cell array for returning output args (see VARARGOUT);
            handle to figure
% hObject
% eventdata reserved - to be defined in a future version of MATLAB
% handles structure with handles and user data (see GUIDATA)
% Get default command line output from handles structure
varargout{1} = handles.output;
% --- Executes on button press in Inpluse_button.
function Inpluse_button_Callback(hObject, eventdata, handles)
% hObject handle to Inpluse_button (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
% handles
            structure with handles and user data (see GUIDATA)
% Set slide visible and text string.
    set(handles.Inpluse_posx, 'visible', 'on');
    set(handles.Inpluse_posy, 'visible', 'on');
    set(handles.Sin_angle, 'visible', 'off');
    set(handles.Sin freq, 'visible', 'off');
    set(handles.Sin_phrase, 'visible', 'off');
    set(handles.Rect_angle, 'visible', 'off');
    set(handles.Rect_whrate, 'visible', 'off');
    set(handles.Rect_posx, 'visible', 'off');
    set(handles.Rect_posy, 'visible', 'off');
    set(handles.Rect_size, 'visible', 'off');
    set(handles.Gauss_var, 'visible', 'off');
    set(handles.text1, 'String', 'x#'+
 string(floor(get(handles.Inpluse_posx, 'value') * 10 + 1)));
    set(handles.text2, 'String', 'y#'+
 string(floor(get(handles.Inpluse_posy, 'value') * 10 + 1)));
    set(handles.text3, 'String', '');
    set(handles.text4, 'String', '');
```

```
set(handles.text5, 'String', '');
% Display image
   displayInpluse(handles, hObject);
 function displayInpluse(handles, hObject)
    I = zeros(256, 256);
    x = floor(get(handles.Inpluse_posx, 'value') * 10 + 1);
    y = floor(get(handles.Inpluse posy, 'value') * 10 + 1);
    I(x, y) = 1;
    axes(handles.axes1);imshow(I);
    I1 = DFT2D(I);
    axes(handles.axes2);imshow(log(abs(I1)),[]);
    axes(handles.axes3);imshow(angle(I1));
    step = 4;
    axes(handles.axes4);surf(I(1:1:end,1:1:end));
    axes(handles.axes5);surf(log(abs(I1(1:step:end,1:step:end))));
    axes(handles.axes6);surf(angle(I1(1:step:end,1:step:end)));
% --- Executes on button press in Sin Button.
function Sin_Button_Callback(hObject, eventdata, handles)
% hObject
           handle to Sin_Button (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
% handles
            structure with handles and user data (see GUIDATA)
    set(handles.Inpluse_posx, 'visible', 'off');
   set(handles.Inpluse_posy, 'visible', 'off');
   set(handles.Sin_angle, 'visible', 'on');
   set(handles.Sin_freq, 'visible', 'on');
    set(handles.Sin_phrase, 'visible', 'on');
   set(handles.Rect_angle, 'visible', 'off');
   set(handles.Rect whrate, 'visible', 'off');
   set(handles.Rect_posx, 'visible', 'off');
   set(handles.Rect_posy, 'visible', 'off');
   set(handles.Rect_size, 'visible', 'off');
   set(handles.Gauss_var, 'visible', 'off');
    set(handles.text1, 'String', '');
   set(handles.text2, 'String', '');
    set(handles.text3, 'String', '#
##'+string(get(handles.Sin_angle, 'Value')));
    set(handles.text4, 'String', '#
##'+string(get(handles.Sin_freq, 'Value') / 1000));
    set(handles.text5, 'String', '#
##'+string(get(handles.Sin_phrase, 'Value')));
    % Display image
   displaySin(handles, hObject);
function displaySin(handles, hObject)
    [X, Y] = meshgrid(1:256);
   a = get(handles.Sin angle, 'Value') * pi / 180;
   freq = get(handles.Sin_freq, 'Value') / 1000;
   phrase = get(handles.Sin_phrase, 'Value');
    I = cos(2 * pi * freq * (cos(a) * X + sin(a) * Y) + phrase);
   axes(handles.axes1);imshow(I);
   I1 = DFT2D(I);
    axes(handles.axes2);imshow(log(abs(I1)),[-1,5]);
```

```
axes(handles.axes3);imshow(angle(I1));
   step = 4;
   axes(handles.axes4);surf(I(1:step:end,1:step:end));
   axes(handles.axes5);surf(log(abs(I1(1:step:end,1:step:end))));
   axes(handles.axes6);surf(angle(I1(1:step:end,1:step:end)));
% --- Executes on button press in Rect Button.
function Rect_Button_Callback(hObject, eventdata, handles)
% hObject
            handle to Rect Button (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
% handles
            structure with handles and user data (see GUIDATA)
    set(handles.Inpluse_posx, 'visible', 'off');
   set(handles.Inpluse_posy, 'visible', 'off');
   set(handles.Sin angle, 'visible', 'off');
   set(handles.Sin_freq, 'visible', 'off');
    set(handles.Sin_phrase, 'visible', 'off');
   set(handles.Rect_angle, 'visible', 'on');
   set(handles.Rect_whrate, 'visible', 'on');
   set(handles.Rect_posx, 'visible', 'on');
   set(handles.Rect_posy, 'visible', 'on');
   set(handles.Rect_size, 'visible', 'on');
   set(handles.Gauss_var, 'visible', 'off');
    set(handles.text1, 'String', 'x##
##'+string(floor(get(handles.Rect_posx, 'value') * 10)));
    set(handles.text2, 'String', 'y##
##'+string(floor(get(handles.Rect_posy, 'value') * 10)));
    set(handles.text3, 'String', '#
##'+string(get(handles.Rect_angle, 'Value')));
    set(handles.text4, 'String', '##
##'+string(get(handles.Rect_whrate, 'Value')));
    set(handles.text5, 'String', '####
##'+string(floor(get(handles.Rect_size, 'Value'))));
    % Display image
   displayRect(handles, hObject);
function displayRect(handles, hObject)
   center_x = 128 + floor(get(handles.Rect_posx, 'value') * 10);
   center_y = 128 + floor(get(handles.Rect_posy, 'value') * 10);
   a = get(handles.Rect_angle, 'Value');
   whrate = get(handles.Rect whrate, 'Value');
   w = floor(get(handles.Rect_size, 'Value'));
   h = w / whrate;
    I = zeros(256, 256);
    I(\max(floor(center_x - h / 2), 1):\min(floor(center_x + h / 2),
 256), max(floor(center_y - w / 2), 1):min(floor(center_y + w / 2),
 256)) = 1;
    I = imrotate(I, a, 'bicubic', 'crop');
   axes(handles.axes1);imshow(I);
    I1 = DFT2D(I);
   axes(handles.axes2);imshow(log(abs(I1)),[-1,5]);
   axes(handles.axes3);imshow(angle(I1));
   step = 4;
   axes(handles.axes4);surf(I(1:4:end,1:4:end));
```

```
axes(handles.axes5);surf(log(abs(I1(1:step:end,1:step:end))));
   axes(handles.axes6);surf(angle(I1(1:step:end,1:step:end)));
% --- Executes on button press in Gauss Button.
function Gauss_Button_Callback(hObject, eventdata, handles)
           handle to Gauss Button (see GCBO)
% hObject
% eventdata reserved - to be defined in a future version of MATLAB
% handles structure with handles and user data (see
GUIDATA)set(handles.Inpluse_posx, 'visible', 'off');
    set(handles.Inpluse_posx, 'visible', 'off');
   set(handles.Inpluse_posy, 'visible', 'off');
   set(handles.Sin_angle, 'visible', 'off');
    set(handles.Sin freq, 'visible', 'off');
   set(handles.Sin_phrase, 'visible', 'off');
   set(handles.Rect angle, 'visible', 'off');
   set(handles.Rect_whrate, 'visible', 'off');
    set(handles.Rect_posx, 'visible', 'off');
   set(handles.Rect_posy, 'visible', 'off');
   set(handles.Rect_size, 'visible', 'off');
    set(handles.Gauss_var, 'visible', 'on');
   set(handles.text1, 'String', '');
   set(handles.text2, 'String', '');
   set(handles.text3, 'String', '#
##'+string(get(handles.Gauss var, 'Value')));
    set(handles.text4, 'String', '');
    set(handles.text5, 'String', '');
    % Display image
   displayGauss(handles, hObject);
function displayGauss(handles, hObject)
    [X, Y] = meshgrid(-128:1:127);
    sigma = get(handles.Gauss_var, 'Value');
    I = \exp(-(X .* X + Y .* Y) / (2 * sigma * sigma));
   axes(handles.axes1);imshow(I);
    I1 = DFT2D(I);
   axes(handles.axes2);imshow(log(abs(I1)),[-1,5]);
   axes(handles.axes3);imshow(angle(I1));
   step = 4;
   axes(handles.axes4);surf(I(1:4:end,1:4:end));
   axes(handles.axes5);surf(log(abs(I1(1:step:end,1:step:end))));
   axes(handles.axes6);surf(angle(I1(1:step:end,1:step:end)));
% --- Executes on slider movement.
function Inpluse_posx_Callback(hObject, eventdata, handles)
% hObject
            handle to Inpluse posx (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
% handles structure with handles and user data (see GUIDATA)
% Hints: get(hObject,'Value') returns position of slider
        get(hObject,'Min') and get(hObject,'Max') to determine range
of slider
   displayInpluse(handles, hObject);
    set(handles.text1, 'String', 'x#'+
 string(floor(get(handles.Inpluse_posx, 'value') * 10 + 1)));
```

```
set(handles.text2, 'String', 'y#'+
 string(floor(get(handles.Inpluse posy, 'value') * 10 + 1)));
% --- Executes during object creation, after setting all properties.
function Inpluse_posx_CreateFcn(hObject, eventdata, handles)
% hObject
           handle to Inpluse_posx (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
% handles empty - handles not created until after all CreateFcns
called
% Hint: slider controls usually have a light gray background.
if isequal(get(hObject, 'BackgroundColor'),
get(0,'defaultUicontrolBackgroundColor'))
   set(hObject, 'BackgroundColor',[.9 .9 .9]);
end
% --- Executes on slider movement.
function slider2 Callback(hObject, eventdata, handles)
           handle to slider2 (see GCBO)
% hObject
% eventdata reserved - to be defined in a future version of MATLAB
% handles
          structure with handles and user data (see GUIDATA)
% Hints: get(hObject,'Value') returns position of slider
        get(hObject,'Min') and get(hObject,'Max') to determine range
of slider
% --- Executes during object creation, after setting all properties.
function slider2 CreateFcn(hObject, eventdata, handles)
% hObject
            handle to slider2 (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
% handles
          empty - handles not created until after all CreateFcns
called
% Hint: slider controls usually have a light gray background.
if isequal(get(hObject, 'BackgroundColor'),
get(0,'defaultUicontrolBackgroundColor'))
    set(hObject, 'BackgroundColor',[.9 .9 .9]);
end
% --- Executes on slider movement.
function Inpluse_posy_Callback(hObject, eventdata, handles)
% hObject handle to Inpluse posy (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
% handles structure with handles and user data (see GUIDATA)
% Hints: get(hObject,'Value') returns position of slider
        get(hObject,'Min') and get(hObject,'Max') to determine range
of slider
   displayInpluse(handles, hObject);
    set(handles.text1, 'String', 'x#'+
 string(floor(get(handles.Inpluse_posx, 'value') * 10 + 1)));
```

```
set(handles.text2, 'String', 'y#'+
 string(floor(get(handles.Inpluse posy, 'value') * 10 + 1)));
% --- Executes during object creation, after setting all properties.
function Inpluse_posy_CreateFcn(hObject, eventdata, handles)
% hObject
           handle to Inpluse_posy (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
            empty - handles not created until after all CreateFcns
% handles
called
% Hint: slider controls usually have a light gray background.
if isequal(get(hObject, 'BackgroundColor'),
get(0,'defaultUicontrolBackgroundColor'))
    set(hObject, 'BackgroundColor',[.9 .9 .9]);
end
% --- Executes on slider movement.
function Sin angle Callback(hObject, eventdata, handles)
% hObject
            handle to Sin angle (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
            structure with handles and user data (see GUIDATA)
% Hints: get(hObject,'Value') returns position of slider
        get(hObject,'Min') and get(hObject,'Max') to determine range
of slider
   displaySin(handles, hObject);
    set(handles.text3, 'String', '#
##'+string(get(handles.Sin_angle, 'Value')));
    set(handles.text4, 'String', '#
##'+string(get(handles.Sin_freq, 'Value') / 1000));
    set(handles.text5, 'String', '#
##'+string(get(handles.Sin_phrase, 'Value')));
% --- Executes during object creation, after setting all properties.
function Sin angle CreateFcn(hObject, eventdata, handles)
            handle to Sin_angle (see GCBO)
% hObject
% eventdata reserved - to be defined in a future version of MATLAB
% handles
            empty - handles not created until after all CreateFcns
called
% Hint: slider controls usually have a light gray background.
if isequal(get(hObject, 'BackgroundColor'),
get(0,'defaultUicontrolBackgroundColor'))
    set(hObject, 'BackgroundColor',[.9 .9 .9]);
end
% --- Executes on slider movement.
function Sin_freq_Callback(hObject, eventdata, handles)
% hObject
           handle to Sin freq (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
% handles structure with handles and user data (see GUIDATA)
```

```
% Hints: get(hObject,'Value') returns position of slider
        get(hObject,'Min') and get(hObject,'Max') to determine range
of slider
   displaySin(handles, hObject);
    set(handles.text3, 'String', '#
##'+string(get(handles.Sin_angle, 'Value')));
    set(handles.text4, 'String', '#
##'+string(get(handles.Sin freg, 'Value') / 1000));
    set(handles.text5, 'String', '#
##'+string(get(handles.Sin_phrase, 'Value')));
% --- Executes during object creation, after setting all properties.
function Sin_freq_CreateFcn(hObject, eventdata, handles)
           handle to Sin freq (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
% handles
            empty - handles not created until after all CreateFcns
called
% Hint: slider controls usually have a light gray background.
if isequal(get(hObject, 'BackgroundColor'),
get(0,'defaultUicontrolBackgroundColor'))
   set(hObject, 'BackgroundColor',[.9 .9 .9]);
end
% --- Executes on slider movement.
function Sin_phrase_Callback(hObject, eventdata, handles)
           handle to Sin_phrase (see GCBO)
% hObject
% eventdata reserved - to be defined in a future version of MATLAB
            structure with handles and user data (see GUIDATA)
% handles
% Hints: get(hObject,'Value') returns position of slider
        get(hObject,'Min') and get(hObject,'Max') to determine range
of slider
   displaySin(handles, hObject);
   set(handles.text3, 'String', '#
##'+string(get(handles.Sin angle, 'Value')));
    set(handles.text4, 'String', '#
##'+string(get(handles.Sin_freq, 'Value') / 1000));
    set(handles.text5, 'String', '#
##'+string(get(handles.Sin_phrase, 'Value')));
% --- Executes during object creation, after setting all properties.
function Sin_phrase_CreateFcn(hObject, eventdata, handles)
% hObject
           handle to Sin phrase (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
            empty - handles not created until after all CreateFcns
called
% Hint: slider controls usually have a light gray background.
if isequal(get(hObject, 'BackgroundColor'),
get(0,'defaultUicontrolBackgroundColor'))
    set(hObject, 'BackgroundColor',[.9 .9 .9]);
```

```
% --- Executes on slider movement.
function Rect posx Callback(hObject, eventdata, handles)
% hObject
           handle to Rect_posx (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
% handles
            structure with handles and user data (see GUIDATA)
% Hints: get(hObject,'Value') returns position of slider
        get(hObject,'Min') and get(hObject,'Max') to determine range
of slider
    set(handles.text1, 'String', 'x##
##'+string(floor(get(handles.Rect_posx, 'value') * 10)));
    set(handles.text2, 'String', 'y##
##'+string(floor(get(handles.Rect_posy, 'value') * 10)));
    set(handles.text3, 'String', '#
##'+string(get(handles.Rect_angle, 'Value')));
    set(handles.text4, 'String', '##
##'+string(get(handles.Rect_whrate, 'Value')));
   set(handles.text5, 'String', '####
##'+string(floor(get(handles.Rect_size, 'Value'))));
    % Display image
   displayRect(handles, hObject);
% --- Executes during object creation, after setting all properties.
function Rect posx CreateFcn(hObject, eventdata, handles)
% hObject
           handle to Rect_posx (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
            empty - handles not created until after all CreateFcns
% handles
called
% Hint: slider controls usually have a light gray background.
if isequal(get(hObject, 'BackgroundColor'),
get(0,'defaultUicontrolBackgroundColor'))
    set(hObject, 'BackgroundColor',[.9 .9 .9]);
end
% --- Executes on slider movement.
function Rect_posy_Callback(hObject, eventdata, handles)
% hObject
           handle to Rect posy (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
            structure with handles and user data (see GUIDATA)
% handles
% Hints: get(hObject,'Value') returns position of slider
        get(hObject,'Min') and get(hObject,'Max') to determine range
of slider
    set(handles.text1, 'String', 'x##
##'+string(floor(get(handles.Rect posx, 'value') * 10)));
    set(handles.text2, 'String', 'y##
##'+string(floor(get(handles.Rect_posy, 'value') * 10)));
    set(handles.text3, 'String', '#
##'+string(get(handles.Rect angle, 'Value')));
    set(handles.text4, 'String', '##
##'+string(get(handles.Rect_whrate, 'Value')));
```

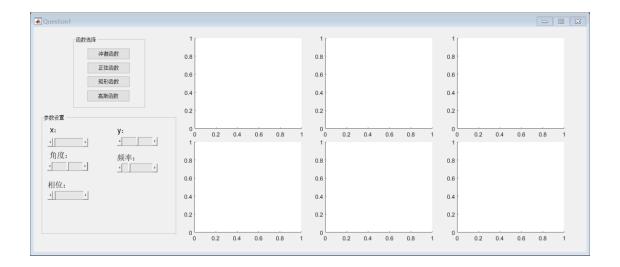
end

```
set(handles.text5, 'String', '####
##'+string(floor(get(handles.Rect size, 'Value'))));
    % Display image
   displayRect(handles, hObject);
% --- Executes during object creation, after setting all properties.
function Rect posy CreateFcn(hObject, eventdata, handles)
            handle to Rect_posy (see GCBO)
% hObject
% eventdata reserved - to be defined in a future version of MATLAB
% handles empty - handles not created until after all CreateFcns
called
% Hint: slider controls usually have a light gray background.
if isequal(get(hObject, 'BackgroundColor'),
get(0,'defaultUicontrolBackgroundColor'))
    set(hObject, 'BackgroundColor',[.9 .9 .9]);
end
% --- Executes on slider movement.
function Rect_angle_Callback(hObject, eventdata, handles)
% hObject
           handle to Rect_angle (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
% handles structure with handles and user data (see GUIDATA)
% Hints: get(hObject,'Value') returns position of slider
        get(hObject,'Min') and get(hObject,'Max') to determine range
of slider
   set(handles.text1, 'String', 'x##
##'+string(floor(get(handles.Rect posx, 'value') * 10)));
    set(handles.text2, 'String', 'y##
##'+string(floor(get(handles.Rect_posy, 'value') * 10)));
    set(handles.text3, 'String', '#
##'+string(get(handles.Rect_angle, 'Value')));
    set(handles.text4, 'String', '##
##'+string(get(handles.Rect_whrate, 'Value')));
    set(handles.text5, 'String', '####
##'+string(floor(get(handles.Rect_size, 'Value'))));
    % Display image
   displayRect(handles, hObject);
% --- Executes during object creation, after setting all properties.
function Rect_angle_CreateFcn(hObject, eventdata, handles)
            handle to Rect angle (see GCBO)
% hObject
% eventdata reserved - to be defined in a future version of MATLAB
% handles
            empty - handles not created until after all CreateFcns
called
% Hint: slider controls usually have a light gray background.
if isequal(get(hObject, 'BackgroundColor'),
get(0,'defaultUicontrolBackgroundColor'))
    set(hObject, 'BackgroundColor',[.9 .9 .9]);
end
```

```
function Rect whrate Callback(hObject, eventdata, handles)
           handle to Rect_whrate (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
% handles structure with handles and user data (see GUIDATA)
% Hints: get(hObject,'Value') returns position of slider
        get(hObject,'Min') and get(hObject,'Max') to determine range
of slider
    set(handles.text1, 'String', 'x##
##'+string(floor(get(handles.Rect_posx, 'value') * 10)));
    set(handles.text2, 'String', 'y##
##'+string(floor(get(handles.Rect_posy, 'value') * 10)));
    set(handles.text3, 'String', '#
##'+string(get(handles.Rect_angle, 'Value')));
    set(handles.text4, 'String', '##
##'+string(get(handles.Rect_whrate, 'Value')));
   set(handles.text5, 'String', '####
##'+string(floor(get(handles.Rect_size, 'Value'))));
    % Display image
   displayRect(handles, hObject);
% --- Executes during object creation, after setting all properties.
function Rect whrate CreateFcn(hObject, eventdata, handles)
% hObject
           handle to Rect_whrate (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
            empty - handles not created until after all CreateFcns
% handles
called
% Hint: slider controls usually have a light gray background.
if isequal(get(hObject, 'BackgroundColor'),
get(0,'defaultUicontrolBackgroundColor'))
    set(hObject, 'BackgroundColor',[.9 .9 .9]);
end
% --- Executes on slider movement.
function Rect_size_Callback(hObject, eventdata, handles)
% hObject handle to Rect size (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
            structure with handles and user data (see GUIDATA)
% handles
% Hints: get(hObject,'Value') returns position of slider
        get(hObject,'Min') and get(hObject,'Max') to determine range
of slider
    set(handles.text1, 'String', 'x##
##'+string(floor(get(handles.Rect posx, 'value') * 10)));
    set(handles.text2, 'String', 'y##
##'+string(floor(get(handles.Rect_posy, 'value') * 10)));
   set(handles.text3, 'String', '#
##'+string(get(handles.Rect angle, 'Value')));
    set(handles.text4, 'String', '##
##'+string(get(handles.Rect_whrate, 'Value')));
```

% --- Executes on slider movement.

```
set(handles.text5, 'String', '####
##'+string(floor(get(handles.Rect size, 'Value'))));
    % Display image
   displayRect(handles, hObject);
% --- Executes during object creation, after setting all properties.
function Rect size CreateFcn(hObject, eventdata, handles)
           handle to Rect size (see GCBO)
% hObject
% eventdata reserved - to be defined in a future version of MATLAB
% handles empty - handles not created until after all CreateFcns
called
% Hint: slider controls usually have a light gray background.
if isequal(get(hObject, 'BackgroundColor'),
get(0,'defaultUicontrolBackgroundColor'))
    set(hObject, 'BackgroundColor',[.9 .9 .9]);
end
% --- Executes on slider movement.
function Gauss_var_Callback(hObject, eventdata, handles)
% hObject
           handle to Gauss_var (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
% handles structure with handles and user data (see GUIDATA)
% Hints: get(hObject,'Value') returns position of slider
        get(hObject,'Min') and get(hObject,'Max') to determine range
of slider
   set(handles.text1, 'String', '');
   set(handles.text2, 'String', '');
    set(handles.text3, 'String', '#
##'+string(get(handles.Gauss_var, 'Value')));
    set(handles.text4, 'String', '');
   set(handles.text5, 'String', '');
    % Display image
   displayGauss(handles, hObject);
% --- Executes during object creation, after setting all properties.
function Gauss_var_CreateFcn(hObject, eventdata, handles)
% hObject handle to Gauss var (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
            empty - handles not created until after all CreateFcns
% handles
called
% Hint: slider controls usually have a light gray background.
if isequal(get(hObject, 'BackgroundColor'),
get(0,'defaultUicontrolBackgroundColor'))
    set(hObject, 'BackgroundColor',[.9 .9 .9]);
end
```



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