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function varargout = Question1(varargin)
% QUESTION1 MATLAB code for Question1.fig
      QUESTION1, by itself, creates a new QUESTION1 or raises the
existing
%
      singleton*.
      H = QUESTION1 returns the handle to a new QUESTION1 or the
handle to
      the existing singleton*.
      QUESTION1('CALLBACK', hObject, eventData, handles,...) calls the
local
      function named CALLBACK in QUESTION1.M with the given input
arguments.
      QUESTION1('Property','Value',...) creates a new QUESTION1 or
raises the
      existing singleton*. Starting from the left, property value
pairs are
      applied to the GUI before Question1_OpeningFcn gets called. An
      unrecognized property name or invalid value makes property
application
      stop. All inputs are passed to Question1_OpeningFcn via
varargin.
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      *See GUI Options on GUIDE's Tools menu. Choose "GUI allows
only one
      instance to run (singleton)".
% See also: GUIDE, GUIDATA, GUIHANDLES
% Edit the above text to modify the response to help Question1
% Last Modified by GUIDE v2.5 17-Nov-2019 20:09:13
% Begin initialization code - DO NOT EDIT
qui Singleton = 1;
gui_State = struct('gui_Name',
                                     mfilename, ...
                   'gui_Singleton', gui_Singleton, ...
                   'gui_OpeningFcn', @Question1_OpeningFcn, ...
                   'gui_OutputFcn', @Question1_OutputFcn, ...
                   'gui_LayoutFcn', [], ...
                   'gui_Callback',
                                     []);
if nargin && ischar(varargin{1})
   gui_State.gui_Callback = str2func(varargin{1});
end
if nargout
    [varargout{1:nargout}] = gui_mainfcn(gui_State, varargin{:});
   gui_mainfcn(gui_State, varargin{:});
end
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% End initialization code - DO NOT EDIT
% --- Executes just before Question1 is made visible.
function Question1_OpeningFcn(hObject, eventdata, handles, varargin)
% This function has no output args, see OutputFcn.
% hObject
            handle to figure
% eventdata reserved - to be defined in a future version of MATLAB
            structure with handles and user data (see GUIDATA)
% handles
% varargin command line arguments to Question1 (see VARARGIN)
% Choose default command line output for Question1
handles.output = hObject;
DisplayColor(hObject, handles);
DisplayOriginImage(hObject, handles);
DisplayNewImage(hObject, handles);
% Update handles structure
guidata(hObject, handles);
% UIWAIT makes Question1 wait for user response (see UIRESUME)
% uiwait(handles.figure1);
% --- Outputs from this function are returned to the command line.
function varargout = Question1_OutputFcn(hObject, eventdata, handles)
% vararqout cell array for returning output args (see VARARGOUT);
% hObject
            handle to figure
% eventdata reserved - to be defined in a future version of MATLAB
             structure with handles and user data (see GUIDATA)
% handles
% Get default command line output from handles structure
varargout{1} = handles.output;
function DisplayColor(hObject, handles)
    hsv1 = get(handles.hsv1, 'value');
    hsv2 = get(handles.hsv2, 'value');
    h = 50;
    w = 50;
    color = ones(h, w, 3);
    color(:, :, 1) = hsv1 * ones(h, w);
    color(:, :, 2) = hsv2 * ones(h, w);
    axes(handles.axes3);
    imshow(hsv2rqb(color));
function DisplayOriginImage(hObject, handles)
    type = get(handles.listbox1, 'value');
    type = string(type);
    path = '.\Data\'+type+'.jpg';
    I = imread(path);
    axes(handles.axes1);
    imshow(I);
function DisplayNewImage(hObject, handles)
    type = get(handles.listbox1, 'value');
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hsv1 = get(handles.hsv1, 'value');
   hsv2 = get(handles.hsv2, 'value');
   s = string(type);
   path = '.\Data\'+s+'.jpg';
    I = imread(path);
    I = im2double(I);
    a_point = [87 312;209 514;143 377;491 791;1225 2493;218 581;86
 620;84 242];
   rect = [11 189 138 464;10 312 244 682;9 316 195 623;152 968 602
1685;1 2166 1665 3470;1 459 390 775;26 410 300 784;14 185 158 405];
   R = ((50/255)^{(type < 4)}) * ((70 / 255) ^ (type < 6 & type > 3)) *
 ((100 / 255) ^ (type > 5));
    a = [I(a point(type, 2), a point(type, 1), 1)] I(a point(type, 2),
 a_point(type, 1), 2) I(a_point(type, 2), a_point(type, 1), 3)];
   D = (I(:,:,1)-a(1)).^2+(I(:,:,2)-a(2)).^2+(I(:,:,3)-a(3)).^2;
   mask = D <= R * R;
   roi = false(size(mask));
   roi(rect(type, 3):rect(type, 4), rect(type, 1):rect(type, 2)) = 1;
   mask = mask & roi;
   hsv I = rqb2hsv(I);
   hsv = hsv_I(:,:,1);
   hsv(mask>0) = hsv1;
   hsv_I(:,:,1) = hsv;
   hsv = hsv I(:,:,2);
   hsv(mask>0) = hsv2;
   hsv I(:,:,2) = hsv;
   NewI = hsv2rgb(hsv_I);
   axes(handles.axes2);
   imshow(NewI);
% --- Executes on slider movement.
function hsv1 Callback(hObject, eventdata, handles)
% hObject
           handle to hsv1 (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
% handles
           structure with handles and user data (see GUIDATA)
   DisplayColor(hObject, handles);
   DisplayOriginImage(hObject, handles);
   DisplayNewImage(hObject, handles);
% Hints: get(hObject,'Value') returns position of slider
         get(hObject,'Min') and get(hObject,'Max') to determine range
of slider
% --- Executes during object creation, after setting all properties.
function hsv1_CreateFcn(hObject, eventdata, handles)
           handle to hsv1 (see GCBO)
% hObject
% eventdata reserved - to be defined in a future version of MATLAB
% handles
            empty - handles not created until after all CreateFcns
called
% Hint: slider controls usually have a light gray background.
if isequal(get(hObject, 'BackgroundColor'),
get(0,'defaultUicontrolBackgroundColor'))
    set(hObject, 'BackgroundColor',[.9 .9 .9]);
end
```

```
% --- Executes on slider movement.
function hsv2 Callback(hObject, eventdata, handles)
% hObject
           handle to hsv2 (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
            structure with handles and user data (see GUIDATA)
% handles
   DisplayColor(hObject, handles);
   DisplayOriginImage(hObject, handles);
   DisplayNewImage(hObject, handles);
% Hints: get(hObject,'Value') returns position of slider
        get(hObject,'Min') and get(hObject,'Max') to determine range
of slider
% --- Executes during object creation, after setting all properties.
function hsv2_CreateFcn(hObject, eventdata, handles)
% hObject handle to hsv2 (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
            empty - handles not created until after all CreateFcns
% handles
called
% Hint: slider controls usually have a light gray background.
if isequal(get(hObject, 'BackgroundColor'),
get(0,'defaultUicontrolBackgroundColor'))
    set(hObject, 'BackgroundColor',[.9 .9 .9]);
end
% --- Executes on selection change in listbox1.
function listbox1 Callback(hObject, eventdata, handles)
% hObject handle to listbox1 (see GCBO)
% eventdata reserved - to be defined in a future version of MATLAB
% handles
          structure with handles and user data (see GUIDATA)
   DisplayOriginImage(hObject, handles);
   DisplayNewImage(hObject, handles);
% Hints: contents = cellstr(qet(hObject,'String')) returns listbox1
contents as cell array
        contents{get(hObject,'Value')} returns selected item from
listbox1
% --- Executes during object creation, after setting all properties.
function listbox1_CreateFcn(hObject, eventdata, handles)
           handle to listbox1 (see GCBO)
% hObject
% eventdata reserved - to be defined in a future version of MATLAB
% handles empty - handles not created until after all CreateFcns
called
% Hint: listbox controls usually have a white background on Windows.
       See ISPC and COMPUTER.
if ispc && isequal(get(hObject, 'BackgroundColor'),
get(0,'defaultUicontrolBackgroundColor'))
    set(hObject, 'BackgroundColor', 'white');
```

## end



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