

# BAYES CLASSIFIERS

## Probabilistic Setting for Classification

Consider jointly distributed random variables  $X$  and  $Y$  where

$$X \in \mathbb{R}^d$$

feature vector

$$Y \in \{1, \dots, K\}.$$

class label

Let's denote the joint distribution by  $P_{XY}$ . This is a function

that maps subsets of  $\mathbb{R}^d \times \{1, \dots, K\}$  (the sample space)

to  $[0, 1]$ . We will conceptualize  $P_{XY}$  via two decompositions:

$$\textcircled{1} \quad P_{XY} = P_{X|Y} \cdot P_Y$$

$$\textcircled{2} \quad P_{XY} = P_{Y|X} \cdot P_X$$

Let's consider the first one:

$$P_{XY} = P_{X|Y} \cdot P_Y$$

marginal distribution of  $Y$ ,

also called the prior  
class distribution

conditional distribution of  $X|Y$ , aka  
the class-conditional distribution.

Note that  $P_Y$  is a discrete distribution, and can be

represented by the prior probabilities

$$\pi_k = P_y(Y=k), \quad k=1, \dots, K.$$

In practice, the features are usually either discrete or continuous, in which case  $P_{X|Y}$  is represented by  $K$  different pmfs or pdfs, one for each class.

Example Suppose  $K=2$ ,  $d=1$ , and  $X|Y=k$  is Gaussian:

$$X|Y=1 \sim N(\mu_1, \sigma_1^2)$$

$$X|Y=2 \sim N(\mu_2, \sigma_2^2)$$



The decomposition  $P_{XY} = P_{X|Y} \cdot P_Y$  has two primary uses.

▷ Data generation: To simulate a realization of  $(X, Y)$ , first generate a realization  $y$  of  $Y$  using  $P_Y$ , then generate a realization  $x$  of  $X$  using  $P_{X|Y=y}$ . Then  $(x, y)$  is a realization of  $(X, Y)$ .

Example Suppose  $d=2$  and

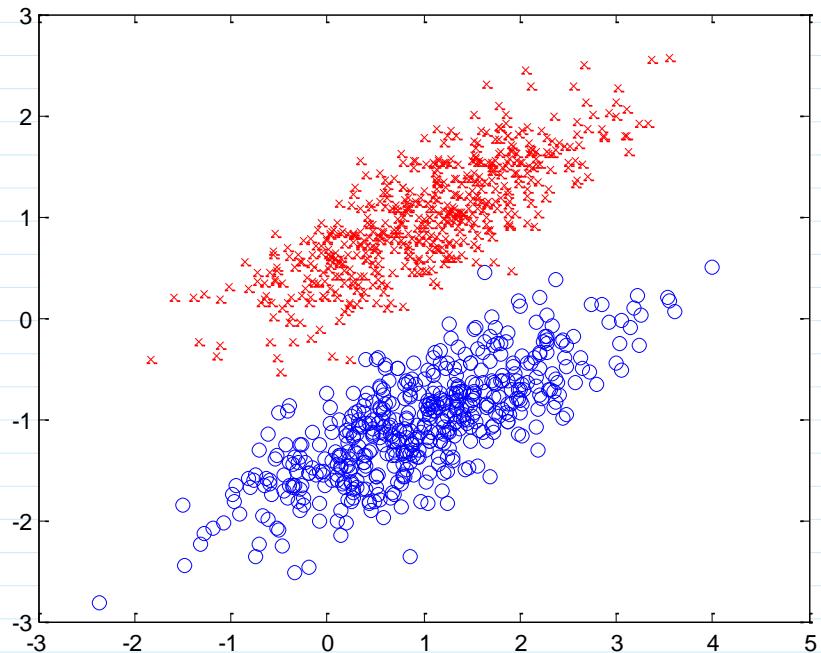
$$X|Y=1 \sim N(\mu_1, \Sigma)$$

$$\mu_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \mu_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$X|Y=2 \sim N(\mu_2, \Sigma)$$

$$\Sigma = \begin{bmatrix} .9 & .4 \\ .4 & .3 \end{bmatrix}$$

If  $\pi_1 = \pi_2 = \frac{1}{2}$ , then training data would look like



▷ Calculating probabilities and expectations using the laws of total probability and total expectation. We'll see an example below.

The other decomposition,

$$P_{XY} = P_{Y|X} \cdot P_X, \quad \text{marginal distribution of } X$$

← posterior distribution of  $Y$  given  $X$   
(a discrete distrib. over labels  
that depends on the observed  $x$ )

can also be used for data generation or calculating probabilities  
and expectations.

## Bayes Classifiers

Given a joint distribution  $P_{XY}$  of  $(X, Y)$ , what is the best  
possible classifier?

A classifier is a function  $f: \mathbb{R}^d \rightarrow \{1, \dots, K\}$ .

The best classifier depends on the performance measure.

The most common performance measure is the probability  
of error, or risk, defined by

$$R(f) = P_{XY}(f(X) \neq Y),$$

i.e., the probability of the event

$$\{(x, y) \in \mathbb{R}^d \times \{1, \dots, K\} \mid f(x) \neq y\}.$$

The Bayes risk is the smallest risk of any classifier, and is

denoted  $R^*$ . If  $R(f) = R^*$ ,  $f$  is called a Bayes classifier.

Let  $\pi_k = P_Y(Y=k)$  denote the prior class probabilities,

$g_k(x)$  the class-conditional pmfs/pdfs of  $X|Y=k$ , and

$$\eta_k(x) = P_{Y|X=x}(Y=k | X=x)$$

the posterior class probabilities. Notice that  $\forall x, \sum_{k=1}^K \eta_k(x) = 1$ .

### Theorem | The classifier

$$f^*(x) = \operatorname{argmax}_{k=1,\dots,K} \eta_k(x)$$

$$= \operatorname{argmax}_{k=1,\dots,K} \pi_k g_k(x)$$

is a Bayes classifier.

Proof | For convenience, assume  $X|Y=k$  has a continuous distribution for each  $k$ . Let  $f$  denote an arbitrary classifier. Denote the decision regions

$$\Gamma_k(f) = \{x \mid f(x) = k\}.$$

Then

$$1 - R(f) = P_{xy}(f(x)=y)$$

[law of total probability]

$$\begin{aligned} &= \sum_{k=1}^K P_y(y=k) \cdot P_{x|y=k}(f(x)=k) \\ &= \sum_{k=1}^K \pi_k \cdot \int_{\Gamma_k(f)} g_k(x) dx \end{aligned}$$

Notice that  $\Gamma_1(f), \dots, \Gamma_K(f)$  form a partition of  $\mathbb{R}^d$ , i.e., every  $x \in \mathbb{R}^d$  belongs to one and only one  $\Gamma_k(f)$ . Thus, to maximize  $1 - R(f)$ , we should choose  $\Gamma_k(f)$  such that

$$x \in \Gamma_k(f) \iff \pi_k g_k(x) \text{ is maximal.}$$

So a Bayes classifier is

$$f^*(x) = \arg \max_k \pi_k g_k(x).$$

The proof is completed by observing

$$\eta_k(x) = \frac{\pi_k g_k(x)}{\sum_{l=1}^K \pi_l g_l(x)}$$

independent of  $k$

which follows by Bayes rule.



In machine learning, we don't know  $P_{XY}$ , so we cannot find a Bayes classifier. As we will see, however, the above result motivates several classification methods.

### To Learn More

Any textbook on machine learning will have a section on the above "decision theoretic" framework for classification.