

Helical Wave Propagate Motion for Snake Robot to Across a Branch on a Pipe

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Helical Wave Propagate Motion With ROS

```
/**      仿真环境启动过程 シミュレーション環境を起動する流れ      ***/  
/*  
/* 1,   roslaunch snake_gazebo snake_gazebo_world.launch  
/* 2,   roslaunch joy_handler_hori joy_handler_hori.launch  
/* 3,   roslaunch snake_control snake_control_node  
/*  
/*****/
```

* 注意：ジョイスティックはHORIPAD3 TURBOを使用,