问题一：

[ WARN] [1662198119.403808714, 4135.292000000]: The origin for the sensor at (-1.16, -0.48, 0.41) is out of map bounds. So, the costmap cannot raytrace for it.

问题二：

[ WARN] [1662198119.662464420, 4135.551000000]: The goal sent to the navfn planner is off the global costmap. Planning will always fail to this goal.