// 先安装依赖

sudo apt-get install ros-melodic-kobuki-\*

sudo apt-get install ros-melodic-ecl-streams

sudo apt-get install libusb-dev

sudo apt-get install libspnav-dev

sudo apt-get install ros-melodic-joystick-drivers

sudo apt-get install bluetooth

sudo apt-get install libbluetooth-dev

sudo apt-get install libcwiid-dev

sudo apt-get install ros-melodic-bfl

gmapping

在编译ROS导航包是提示缺少SDL/SDL\_image.h:

sudo apt-get install libsdl-image1.2-dev

Failed to load nodelet '/cmd\_vel\_mux` of type `yocs\_cmd\_vel\_mux/CmdVelMuxNodelet`

[FATAL] [1663127531.327839238]: Failed to load nodelet '/navigation\_velocity\_smoother`

sudo apt-get install ros-melodic-yocs-velocity-smoother

ROS Failed to create the dwa\_local\_planner/DWAPlannerROS planner

sudo apt-get install ros-melodic-dwa-local-planner