<https://blog.csdn.net/qq_32618327/article/details/95969238>

<https://blog.csdn.net/feidaji/article/details/106120004>

是否允许规划器规划穿过未知区域的路径,只修改global planner文件中的allow\_unknown参数为true还不行,还要在costmap\_commons\_params.yaml中设置track\_unknown\_space参数也为true才行