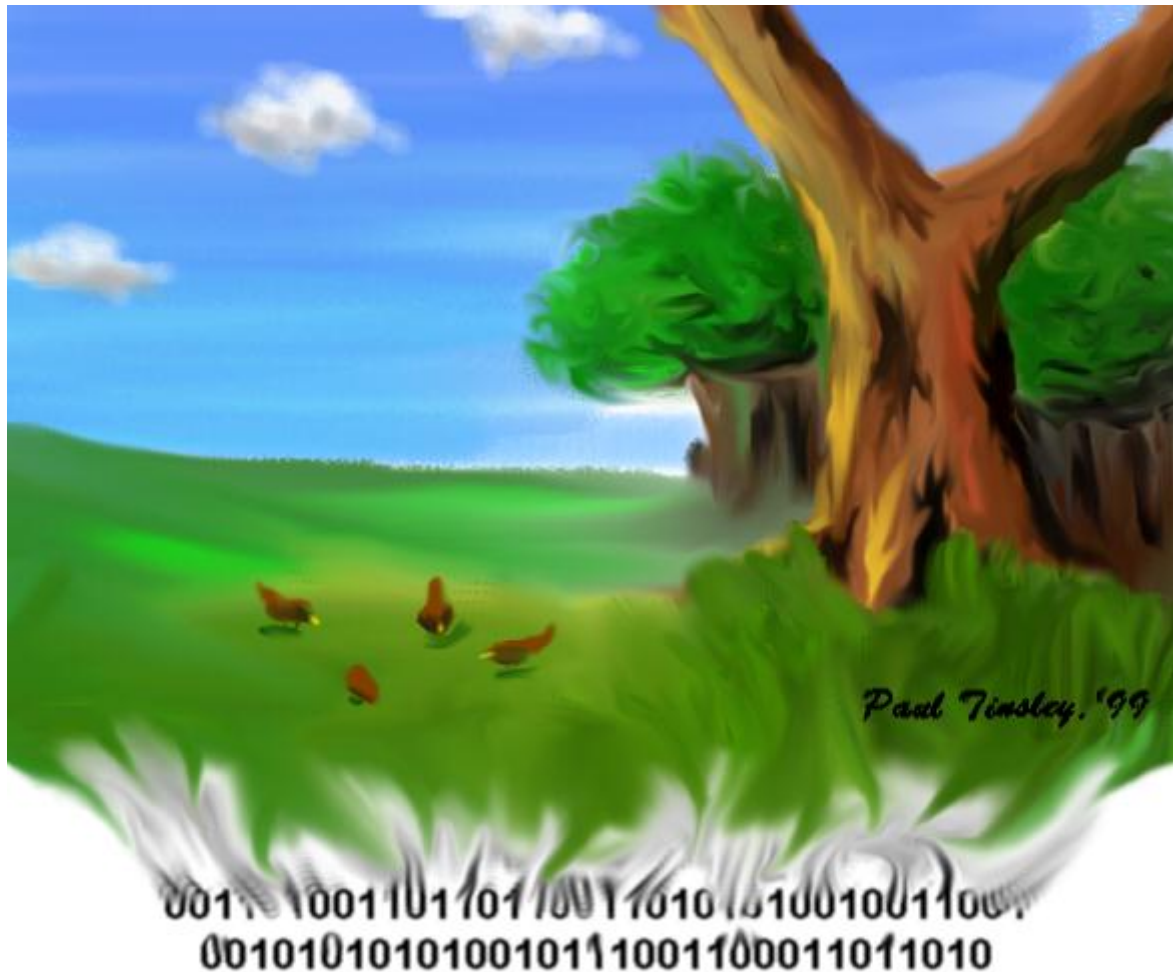


The Emergent Properties of Multi-Agent Systems



A Project Presentation by Paul Tinsley regarding a Real-time Animated Multi-Agent Simulation System called “Animate”

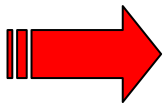
Introduction

Our project involved simulating emergent phenomena within a Multi-Agent System (MAS)

In this presentation we shall . . .

- Identify what emergence means
- Briefly examine the characteristics of the agents
- Illustrate examples of three classes of emergent phenomena
- Discuss how the phenomena arose and whether any were useful
- Highlight the significance of emergence
- Interactively demonstrate Animate's features

Emergence?



It is essential to define what is meant by the word “Emergent.” There are many viewpoints on emergence, but for our purposes, we define it to mean:

***A sum of parts, that exist in a system,
due to the interactions of its
constituent members***

Categories for Emergence

Emergent phenomena tend to fall into three fundamental categories:

- **Emergent Behaviour**

Do non-explicit agent behaviours manifest themselves?

- **Emergent Functionality**

Does a phenomenon have some sort of purpose or effect?

- **Emergent Structure**

Is there a pattern to a phenomenon?

We shall demonstrate examples of all three

Animate's Agents

- Reflex agents with internal state

They react rather than plan

- Production Systems

If / then rules fire from working memory

- Self-interested

No social concepts or social goals

- No inter-agent communication

No communication whatsoever

- Domain: 2D turn-based world

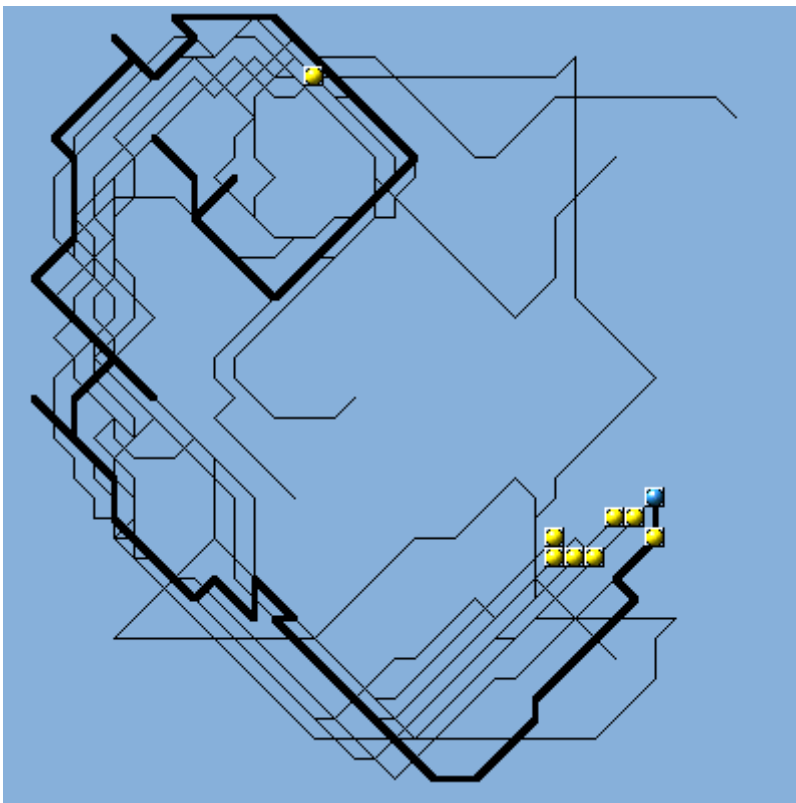
40 by 40 squares – one object per square

- Arbitrated

Agent conflict resolution

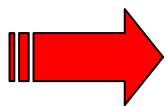
Emergent Behaviour

Using a Predators and Prey scenario, emergent flocking behaviours often developed. A pack of predators formed that chased the prey:



Paths of all agents were tracked and plotted to reveal their movements

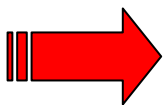
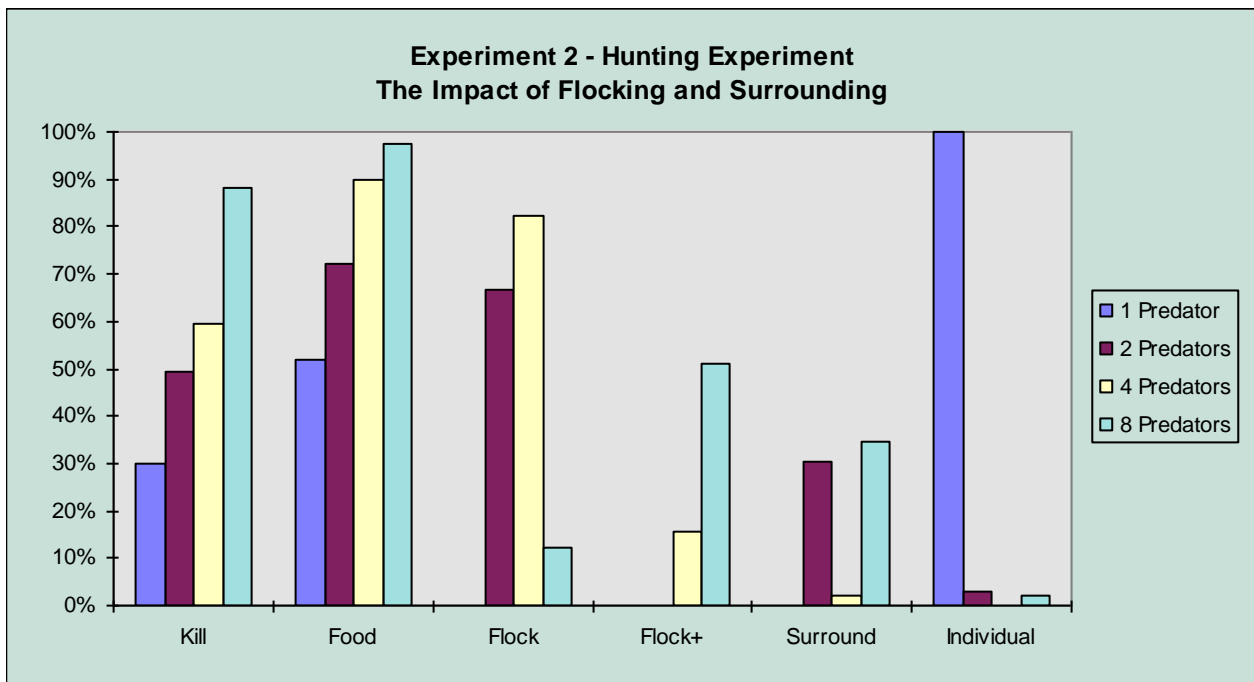
The prey steers the flock of predators



During simulation, the predator agents displayed an **emergent flocking behaviour**. They appeared to co-operate with one another by forming a hunting pack that pursued the prey agent. Yet, there are no co-operative plans, communication or social concepts / social goals!

Emergent Functionality

We also discovered that there were benefits associated with the flocking phenomenon:

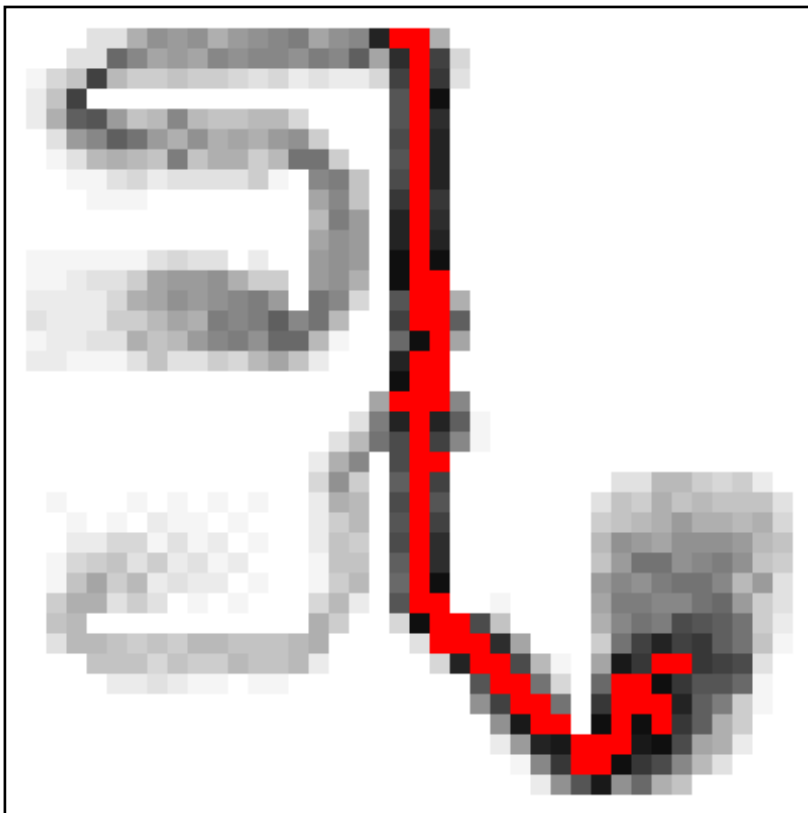


There is an **emergent functionality** of flocking with improvements in the total amount of food gained by the “community” of predator agents

Flocks are beneficial as they put the prey under greater “pressure”. Large predator communities lead to overcrowding. Hence, prey are more often surrounded and pure flocking plays a smaller role

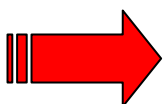
Emergent Structure

Using a building design scenario with “Crowd” agents, we plotted the paths that agents had taken during an escape simulation using a form of colour temperature:



The path densities left by Crowd agents escaping a building to a single exit (North)

A threshold may be set to indicate the strongest paths (red)



The **emergent path structures** were useful in determining where alterations to the building should be made in order to reduce the traffic density of agents and thus improve “safety”

Conclusion

The Results

We successfully demonstrated simple examples of the emergent properties of a Multi-Agent System, identified some causes and illustrated a possible utility of emergent path structures. We have found that our definition for emergence is strong.

The Alife Connection (Inspiration)

Emergence is a consequence of independent objects interacting with each other within a domain. Evolution orders and manages complexity through emergent processes, yielding sophisticated and impressive life-forms. All life on Earth comes from the same ancient factory and was built over billions of years (Natural Selection).

Some final thought provoking musings – can we learn something from this? Have we already made a start – Object-Oriented Programming?